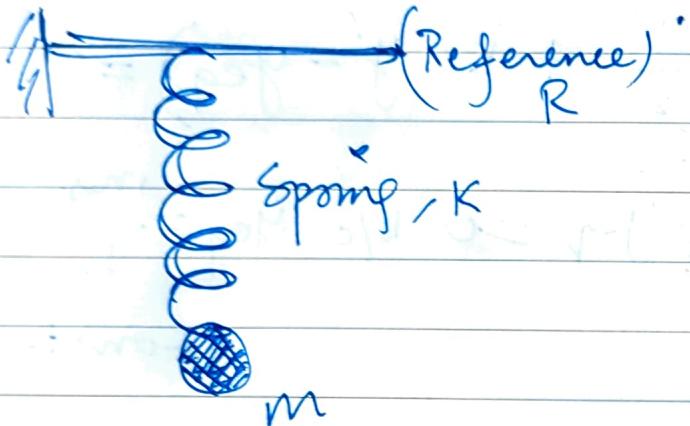


Q) Why do we study $A\vec{y} = \vec{b}$?

Single.

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Lec-1: Spring-mass system



$$F_{net} = mg - Ky; \quad y \text{ is displ. of mass}$$

$$\text{At eq}^m, F_{net} = 0 \Rightarrow y_{eq} = \frac{mg}{K} \rightarrow ①$$

Now, pull the mass down further by y so that total elongation of spring is $(y + y_{eq})$

$$F_{net} = mg - K(y + y_{eq})$$

$$m \frac{d^2y}{dt^2} = mg - Ky - mg \quad (\text{b/c of eq(1)})$$

$$m \frac{d^2y}{dt^2} + Ky = 0 \rightarrow ② \quad \text{this is}$$

If we want to write an eqⁿ for displacement of mass w.r.t. the reference pos, R; change variables $y' = y + y_{eq}$ $\rightarrow ③$

$$\text{or } y = y' - y_{\text{eq}}$$

$$\text{from eq(2): } m \frac{d^2 y'}{dt^2} + k(y' - y_{\text{eq}}) = 0$$

$$m c \frac{d^2}{dt^2} y_{\text{eq}} = 0 \quad m c y_{\text{eq}} = \frac{mg}{k}$$

$\Rightarrow \text{const.}$

$$m \frac{d^2 y'}{dt^2} + k y' = k y_{\text{eq}} = k \frac{mg}{K}$$

$$\text{or } m \frac{d^2 y'}{dt^2} + k y' = mg$$

$$\text{or } \frac{d^2 y'}{dt^2} + \omega^2 y' = g$$

$$\text{where } \omega^2 = \frac{k}{m}$$

Now that we have derived the model; we can just relabel y' as x ; so,

$$\frac{d^2 x}{dt^2} + \omega^2 x = g$$

(4)

Let's now write eq (4) in matrix-vector form:

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$$\vec{q} = \begin{pmatrix} x \\ \frac{dx}{dt} \end{pmatrix} = \begin{pmatrix} x \\ v \end{pmatrix}$$

So eq (4) \equiv the following:

$$\frac{d\vec{q}}{dt} = \begin{pmatrix} 0 & 1 \\ -\omega^2 & 0 \end{pmatrix} \vec{q} + \begin{pmatrix} 0 \\ g \end{pmatrix} \rightarrow (5)$$

$$\frac{d\vec{q}}{dt} = A\vec{q} + \vec{b}_g$$

for steady state response of the spring-mass system,

demanded $\frac{d\vec{q}}{dt} = 0$

i.e. $A\vec{q} = \vec{b}$ (6)

this is how the linear-sys. $A\vec{q} = \vec{b}$ emerges

in a simple-spring mass system.

Where $\vec{b} = -\vec{b}_g$

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* Soln \vec{q} w/ oscillatory modes exist
if A^{-1} exists.

* A is invertible if

$$\det(IA) = \omega^2 \neq 0$$

(True whenever $R \neq 0$
or $m \neq b$)

* eigenvalue of A = $i\omega$.

$$\Rightarrow \text{if } \omega = 0 \Rightarrow \lambda(A) = 0$$

$\Rightarrow A$ is NOT invertible.

\Rightarrow No oscillatory solns!

* Check out the python simulations & animations available on the course website



In the next lecture, we will study a linear chain of 10-spring mass system!