

5/1/2022

Agenda items

- * Diagonalization of matrices
- * Similarity transformation
- # Spectral decomposition of matrices

Last Lecture

- evs & EVs (def, meaning, etc)
- trace of a matrix & its relⁿ w/ evs; det \leftrightarrow evs.

Diagonalizable matrices

Certain forms of matrices are convenient to work with - - - - -

→ Upper/Lower triangular forms
Way?

→ Diagonal forms Way?

think Lts,
think computing powers of
matrices, ...

Diagonalizable matrices . . .

wouldn't it be nice if

$$A \xrightarrow{\quad} D$$

(any $n \times n$ matrix)

(diagonal form)

the evs of
A and D
will be same.

$A \in M_{n \times n}(F)$ is "diagonalizable over F if there exists an invertible matrix S over F s.t. $\boxed{A = SDS^{-1}}$ or equivalently $D = S^{-1}AS$ \leftarrow Similarity transformation

Q) When is a matrix diagonalizable?

Ans) $A \in M_{n \times n}(F)$ is diagonalizable
if and only if A has n linearly independent EVs in F^n

* An $n \times n$ complex matrix that
has n distinct evs is diagonalizable.

Example:

Q) Find a matrix that diagonalizes

$$A = \begin{pmatrix} 2 & -1 \\ 2 & 4 \end{pmatrix}$$

Ans Solve $|A - \lambda I| = 0$ to obtain

$$\lambda_{1,2} = \frac{3 \pm i}{2}$$

then use $\vec{Ax}_j = \lambda_j \vec{x}_j$; $j=1,2$

check if
 $S^{-1}AS$ is D ?

$$\vec{x}_1 = \begin{pmatrix} \frac{-1+i}{2} \\ 1 \end{pmatrix}; \vec{x}_2 = \begin{pmatrix} \frac{-1-i}{2} \\ 1 \end{pmatrix}$$

to obtain

$$S = \begin{pmatrix} \frac{-1+i}{2} & \frac{-1-i}{2} \\ 1 & 1 \end{pmatrix}$$

diagonalizes A .

$$S^{-1}AS = \begin{pmatrix} -i & \frac{1-i}{2} \\ +i & \frac{1+i}{2} \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} \frac{-1+i}{2} & \frac{-1-i}{2} \\ -1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 3+i & 0 \\ 0 & 3-i \end{pmatrix}$$

$$= D!$$

* the Col^m vectors of S form an eigenbasis for A & the diagonal entries of D are the associated evs.

Ques) What are the evs and EVs
of the $n \times n$ identity matrix
 I_n ?

Is there an eigenbasis for I_n ?

Which matrix diagonalizes I_n ?


this is in some sense a silly & yet-
a conceptually trick question !!

Example

Q) Find the eigenspace of $A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$.

Is A diagonalizable?



Aus the EVs are along the diagonal.

$$\lambda_{1,2} = 1, 0 \quad \begin{matrix} \text{alg.-mult. 1} \\ \text{alg.-mult. 2} \end{matrix}$$

To find EVs: $\vec{x}_1 = \text{Ker}(A - 1\mathbb{I}_3)$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \vec{0}$$

$$\Rightarrow \begin{pmatrix} x_2 \\ x_3 \\ 0 \end{pmatrix} = \vec{0}$$

$$\Rightarrow x_2, x_3 = 0$$

and $x_1 = 1$ (actually any arbitrary const.)

$$\begin{aligned} \vec{x}_1 &= \text{Ker} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \\ &= \text{Ker} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \text{sp} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \end{aligned}$$

$$\vec{x}_2 = \text{sp} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

By inspection span only

b/c we are able to find only 2 indep. EVs!

\therefore We cannot find

\vec{x}_3 to diagonalize A !

\vec{x}_1 & \vec{x}_2 the x_1 - x_2 plane

Geometric multiplicity of ev

$$\begin{aligned}\text{gemu}(\lambda) &= \dim (\ker(A - \lambda \mathbb{I}_n)) \\ &= \text{nullity}(A - \lambda \mathbb{I}_n) \\ &= n - \text{rank}(A - \lambda \mathbb{I}_n)\end{aligned}$$

In prev. example

$$\begin{aligned}\text{gemu}(1) &= \dim (\ker(A - \mathbb{I}_3)) = \dim \begin{pmatrix} 1 & & \\ 0 & 1 & \\ 0 & 0 & 1 \end{pmatrix} \\ &= 1\end{aligned}$$

$$\begin{aligned}\neq \text{almu}(1) \\ = 2.\end{aligned}$$

* Spectral thm

A matrix A is orthogonally diagonalizable ($D = Q^{-1}AQ \equiv Q^T A Q$)
iff A is symmetric ($A^+ = A$)

* Spectral decomposition

Let A be a real symmetric $n \times n$ matrix
w/ EVs $\lambda_1, \lambda_2, \dots, \lambda_n$ and corresponding
Orthonormal EVs $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$; then

$$A = (\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n) \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix} \begin{matrix} \leftarrow \vec{v}_1 \rightarrow \\ \leftarrow \vec{v}_2 \rightarrow \\ \vdots \\ \leftarrow \vec{v}_n \rightarrow \end{matrix}$$
$$A = Q D Q^+$$

this concludes the life
and theory of a Matrix
in FM 112