

Matrix and vector norms

(1)

Let $\vec{x} \in \mathbb{R}^n$ i.e. $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$

A vector norm on \mathbb{R}^n is a function $\|\cdot\| : \mathbb{R}^n \rightarrow \mathbb{R}$

w/ the following properties

$$(1) \|\vec{x}\| \geq 0 \quad \forall \vec{x}$$

$$(2) \|\vec{x}\| = 0 \iff \vec{x} = \vec{0}$$

$$(3) \|\alpha \vec{x}\| = |\alpha| \|\vec{x}\| \quad \forall \alpha \in \mathbb{R}, \forall \vec{x} \in \mathbb{R}^n$$

$$(4) \|\vec{x} + \vec{y}\| \leq \|\vec{x}\| + \|\vec{y}\| \quad \forall \vec{x}, \vec{y} \in \mathbb{R}^n$$

There are many types of norms

$$(1) \|\vec{x}\|_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2} \quad * \text{All norms are equivalent!}$$

$$(2) \|\vec{x}\|_\infty = \max_{1 \leq i \leq n} |x_i|$$

Cauchy-Schwarz inequality

(2)

$$|\langle \vec{x}, \vec{y} \rangle| = |\vec{x}^T \vec{y}| = \left| \sum_{i=1}^n x_i y_i \right| \leq \|\vec{x}\|_2 \|\vec{y}\|_2$$

What is the use of norms?

(1) To measure distance b/w 2 pts. in space

(2) Convergence of sequences (e.g. analysis/
monitoring of
error of
iterative methods)

A sequence $\{\vec{x}_{(k)}\}_{k=1}^{\infty}$ of vectors in \mathbb{R}^n converges w.r.t.

the norm $\|\cdot\|$ if for any small $\epsilon > 0$,

$\exists N(\epsilon)$ s.t. $\|\vec{x}_{(k)} - \vec{x}\| < \epsilon \quad \forall k \geq N(\epsilon)$

Thm $\{\vec{x}_{(k)}\} \rightarrow \vec{x}$ in R^n w.r.t. $\|\cdot\|_\infty \Leftrightarrow$ (3)

$\lim_{k \rightarrow \infty} x_{i(k)} = x_i$ for each $i = 1, 2, \dots, n$

Thm for each $\vec{x} \in R^n$

$$\|\vec{x}\|_\infty \leq \|x\|_2 \leq \sqrt{n} \|\vec{x}\|_\infty$$

X
Matrix norms

def $A \in M_{n \times n}$; $\|\cdot\|$ is a f^n that maps A in $M_{n \times n}$ to a real-valued no.

Properties of matrix norms

(4)

(1) $\|A\| \geq 0$

(2) $\|A\| = 0 \Leftrightarrow A$ is a '0' matrix
w/ all entries = 0.

(3) $\|\alpha A\| = |\alpha| \|A\|$

(4) $\|A + B\| \leq \|A\| + \|B\|$

(5) $\|AB\| \leq \|A\| \|B\|$

tr^m (Induced matrix norm)

If $\|\cdot\|$ is a vector norm on \mathbb{R}^n then

$$\|A\| := \max_{\|\vec{x}\|=1} \|A\vec{x}\|$$
 is a matrix norm
$$\max_{\vec{z} \neq 0} \|A(\frac{\vec{z}}{\|\vec{z}\|})\| = \max_{\vec{z} \neq 0} \frac{\|A\vec{z}\|}{\|\vec{z}\|}$$

(5)

\mathbb{R}^m ($\|\cdot\|_\infty$ matrix norm).

$\det A = (a_{ij}) \in \mathbb{M}_{n \times n};$

$$\|A\|_\infty = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|$$

e.g. $A = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 3 & -1 \\ 5 & -1 & 1 \end{pmatrix}$

$\sum_{j=1}^3 |a_{1j}| = |1| + |2| + |-1| = 4$

$\sum_{j=1}^3 |a_{2j}| = |0| + |3| + |-1| = 4$

$\sum_{j=1}^3 |a_{3j}| = |5| + |-1| + |1| = 7$

$$\begin{aligned} \|A\|_\infty &= \max\{4, 4, 7\} \\ &= 7 \end{aligned}$$

Spectral radius of a matrix (1)

$$\rho(A) := \max_{1 \leq i \leq n} |\lambda_i|, \text{ where } \lambda_1, \dots, \lambda_n \text{ are evs of } A \in M_{n \times n}$$

* spectral radius is closely related to the norm of a matrix!

thm :- Let $A \in M_{n \times n}$;

$$(i) \|A\|_2 = \sqrt{\rho(A^T A)}$$

$$(ii) \rho(A) \leq \|A\| \text{ where } \|\cdot\| \text{ is an induced matrix norm.}$$

(2)

A simple matrix decomposition

Consider any matrix, say

$$A = \begin{pmatrix} 2 & -1 & 5 \\ 0 & 1 & -2 \\ 1 & 5 & -1 \end{pmatrix}$$

Can always do this splitting!

$$A = \underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}}_D + \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 5 & 0 \end{pmatrix}}_L + \underbrace{\begin{pmatrix} 0 & -1 & 5 \\ 0 & 0 & -2 \\ 0 & 0 & 0 \end{pmatrix}}_U$$

(strictly lower triangular) (strictly upper triangular)

$$= D - (-L) - (-U)$$

(3)

Iterative Schemes to solve systems of linear eqns.

Jacobi iterative method

Eg. Let us consider the system of linear eqns

$$E_1: 10x_1 - x_2 + 2x_3 = 6$$

$$E_2: -x_1 + 11x_2 - x_3 + 3x_4 = 25$$

$$E_3: 2x_1 - x_2 + 10x_3 - x_4 = -11$$

$$E_4: 3x_2 - x_3 + 8x_4 = 15$$

which has a unique soln $\vec{x} = \begin{pmatrix} 1 \\ 2 \\ -1 \\ 1 \end{pmatrix}$.

Consider this in the form $A\vec{x} = \vec{b}$
 where $A = \begin{pmatrix} 10 & -1 & 2 & 0 \\ -1 & 11 & -1 & 3 \\ 2 & -1 & 10 & -1 \\ 0 & 3 & -1 & 8 \end{pmatrix}$ and $\vec{b} = \begin{pmatrix} 6 \\ 25 \\ -11 \\ 15 \end{pmatrix}$

The idea is to solve

$$A\vec{x} = \vec{b}$$

by rewriting it in the form

$$\vec{x} = T\vec{x} + \vec{c}$$

& then using an iterative scheme of the form

$$\vec{x}_{(k)} = T\vec{x}_{(k-1)} + \vec{c}$$

where $k=1, 2, 3, \dots$

Let us re-write $A\vec{x} = b$ as $\vec{x} = T\vec{x} + \vec{c}$ thusly (4)

$$\begin{aligned}x_1 &= \frac{1}{10}x_2 - \frac{1}{5}x_3 + \frac{3}{5} \\x_2 &= \frac{1}{11}x_1 + \frac{1}{11}x_3 - \frac{3}{11}x_4 + \frac{25}{11} \\x_3 &= -\frac{1}{5}x_1 + \frac{1}{10}x_2 + \frac{1}{10}x_4 - \frac{11}{10} \\x_4 &= -\frac{3}{8}x_2 + \frac{1}{8}x_3 + \frac{15}{8}\end{aligned}$$

$\Rightarrow \vec{x} = \begin{pmatrix} 0 & \frac{1}{10} & -\frac{1}{5} & 0 \\ \frac{1}{11} & 0 & \frac{1}{11} & -\frac{3}{11} \\ -\frac{1}{5} & \frac{1}{10} & 0 & \frac{1}{10} \\ 0 & -\frac{3}{8} & \frac{1}{8} & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} + \begin{pmatrix} \frac{3}{5} \\ \frac{25}{11} \\ -\frac{11}{10} \\ \frac{15}{8} \end{pmatrix}$

These unknowns were already computed in the eqns above.

$$\vec{x} = T\vec{x} + \vec{c}$$

initial guess (say) $\vec{x}_{(0)} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$ then $\vec{x}_{(0)} = \begin{pmatrix} 0.6 \\ 2.2727 \\ -1.1000 \\ 1.8750 \end{pmatrix}$

(5)

Carry forth the computations iteratively

$$\dots \vec{x}_{(10)} = \begin{pmatrix} 1.0001 \\ 1.9998 \\ -0.9998 \\ 0.9998 \end{pmatrix}$$

Whence $\frac{\|\vec{x}_{(10)} - \vec{x}_{(9)}\|}{\|\vec{x}_{(10)}\|} < 10^{-3}$

Stop!

Jacobi iteration (in matrix form)

(6)

$$\begin{aligned}
 & A\vec{x} = b \\
 \Rightarrow & (D + L + U)\vec{x} = b \\
 \Rightarrow & D\vec{x} = -(L + U)\vec{x} + \vec{b} \\
 \Rightarrow & \vec{x} = -D^{-1}(L + U)\vec{x} + D^{-1}\vec{b}
 \end{aligned}$$

TYPO: There is a $\text{inv}(D)$ missing here!

Hence the iteration

$$\vec{x}_{(k)} = -D^{-1}(L + U)\vec{x}_{(k-1)} + \vec{b}$$

in the form of iterates we have

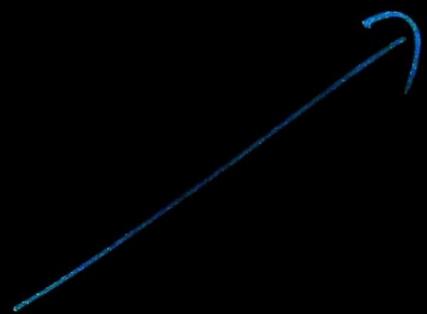
$$x_{i(k)} = \frac{\sum_{j=1, j \neq i}^n (-a_{ij}x_{j(k-1)}) + b_i}{a_{ii}} ; \quad i = 1, 2, \dots, n$$

$a_{ii} \neq 0 \Rightarrow D$ is invertible!

Gauss - Seidel iterative Scheme

(7)

$$x_{i(k)} = \frac{-\sum_{j=1}^{i-1} a_{ij} x_{j(k)} - \sum_{j=i+1}^n a_{ij} x_{j(k-1)} + b_i}{a_{ii}} ; \quad i = 1, 2, \dots, n$$



Why is this a good idea?

Compare w.r.t. the example
at the beginning of this lecture!

(8)

in matrix form

$$A \vec{x} = \vec{b}$$

$$(D+L) \vec{x} = -U \vec{x} + \vec{b}$$

as iterates $(D+L) \vec{x}_{(k)} = -U \vec{x}_{(k-1)} + \vec{b}$

or $\vec{x}_{(k)} = -(D+L)^{-1} U \vec{x}_{(k-1)} + (D+L)^{-1} \vec{b} ; k=1, 2,$

Gauss-Seidel iteration

*9. Next lecture, we will talk about
Convergence of iterative schemes & also
SOR scheme!