Contents Contest Setup Gauss Jordan C++ template Java template 1.5.1 Java Issues 13 Geometry System Testing 14 Math Reminder Topic list Leap year Etaponentiation O(log(exp)) Mod Inverse GCD O(log(a+b)) Extended Euclidean Algorithm GCD O(log(a+b)) 重複組合 17 Chinese remainder theorem 17 2-Circle relations 17 15 Dynamic Programming - Problems collection 5.7.2Contest Setup Algorithm 5.7.45.7.5Priority Queue 5.7.61.1 vimrc Search set number " Show line numbers 折半完全列舉 Two-pointer 爬行法(右跑左追) " Enable inaction via mouse set mouse=a set showmatch " Highlight matching brace " Show underline set cursorline 1D BIT " highlight vertical column set cursorcolumn 2D BIT Union Find Segment Tree Sparse Table filetype on "enable file detection syntax on "syntax highlight Tree set autoindent " Auto-indent new lines Tree Center Treap set shiftwidth=4 " Number of auto-indent spaces set smartindent " Enable smart-indent set smarttab " Enable smart-tabs Graph set tabstop=4 " Number of spaces per Tab 16 -----Optional-----9.2.2SCC 9.2.3set undolevels=10000 " Number of undo levels Dijkatra set scrolloff=5 " Auto scroll 9.3.29.3.3 set hlsearch Highlight all search results 9.3.4 9.3.5set smartcase " Enable smart-case search Kruskal MST set ignorecase " Always case-insensitive " Searches for strings incrementally set incsearch highlight Comment ctermfg=cyan 10 Flow set showmode 10.2 Min Cost Flow 10 10.3 Bipartite Matching 11 set encoding=utf-8 set fileencoding=utf-8 scriptencoding=utf-8

1.2 bashrc

```
1 alias g++="g++ -Wall -Wextra -std=c++11 -02"
```

1.3 Grep Error and Warnings

```
| g++ main.cpp 2>&1 | grep -E 'warning|error'
```

1.4 C++ template

```
#include <bits/stdc++.h>

using namespace std;

typedef long long int ll;
typedef pair<int, int> ii;

int main()
{
    return 0;
}
```

1.5 Java template

```
import java.io.*;
 import java.util.*;
  public class Main
       public static void main(String[] args)
           MyScanner sc = new MyScanner();
           out = new PrintWriter(new BufferedOutputStream(System.out));
           // Start writing your solution here.
           // Stop writing your solution here.
           out.close();
       public static PrintWriter out;
       public static class MyScanner
18
19
           BufferedReader br;
           StringTokenizer st;
21
22
23
           public MyScanner()
               br = new BufferedReader(new InputStreamReader(System.in));
25
           boolean hasNext()
```

```
while (st == null || !st.hasMoreElements()) {
                         st = new StringTokenizer(br.readLine());
32
                    } catch (Exception e) {
33
                         return false;
34
35
                return true;
38
39
40
           String next()
41
                if (hasNext())
42
                    return st.nextToken();
43
                return null:
44
47
           int nextInt()
                return Integer.parseInt(next());
           long nextLong()
52
                return Long.parseLong(next());
56
57
           double nextDouble()
                return Double.parseDouble(next());
59
60
61
           String nextLine()
63
                String str = "";
                try {
65
66
                    str = br.readLine();
                } catch (IOException e) {
67
                    e.printStackTrace();
69
70
                return str;
71
72
73
```

1.5.1 Java Issues

- 1. Random Shuffle before sorting: Random rnd = new Random(); rnd.nextInt();
- 2. Use StringBuilder for large output
- 3. Java has strict parsing rules. e.g. using sc.nextInt() to read a long will result in RE

2 System Testing

- 1. Setup bashrc and vimrc
- 2. Install Java 8, Eclipse 32-bit, g++ compiler
- 3. Remove Chinese input method
- 4. Look for compilation parameter and code it into bashrc

- 5. Test if c++ and java templates work properly on local and judge machine
- 6. Test "divide by $0" \to RE/TLE$?
- 7. Make a complete graph and run Floyd warshall, to test time complexity upper bound
- 8. Make a linear graph and use DFS to test stack size
- 9. Print output with extra newline and spaces

3 Reminder

- 1. 隊友的建議, 要認真聽! 通常隊友的建議都會突破你盲點
- 2. Read the problem statements carefully. Input and output specifications and constraints are crucial!
- 3. Estimate the **time complexity** and **memory complexity** carefully.
- 4. Time penalty is 20 minutes per WA, don't rush!
- 5. Sample test cases must all be tested and passed before every submission!
- 6. Test the corner cases, such as 0, 1, -1. Test all edge cases of the input specification.
- 7. Bus error: the code has scanf, fgets but have nothing to read! Check if you have early termination but didn't handle it properly.
- 8. Binary search? 數學算式移項合併後查詢?
- 9. Two Pointer <-> Binary Search
- 10. Directed graph connectivity -> DFS. Undirected graph -> Union Find
- 11. Check connectivity of the graph if the problem statement doesn't say anything
- 12. longlong = int * int won't work!
- 13. Shifting for longlongint should be something like $1LL \ll 35$
- 14. For continuous input problems, be sure to read in all input BEFORE terminating and start processing next the input.
- 15. Don't use anonymous struct
- 16. 因式分解
- 17. 有時候,從答案推回來會容易些!
- 18. 寫出數學式,有時就馬上出現答案了!

4 Topic list

- 1. enumeration
- 2. greedy
- 3. sorting, topological sort
- 4. binary search
- 5. 離散化
- 6. Dynamic programming, 矩陣快速幂
- 7. Pigeonhole
- 8. LCA (倍增法, LCA 轉 RMQ)

5 Useful code

5.1 Leap year

```
1 | year % 400 == 0 | | (year % 4 == 0 && year % 100 != 0)
```

5.2 Fast Exponentiation O(log(exp))

Fermat's little theorem: 若 m 是質數, 則 $a^{m-1} \equiv 1 \pmod{m}$

```
return ans;

| }
```

5.3 Mod Inverse

```
Case 1: gcd(a, m) = 1: ax + my = gcd(a, m) = 1 (use ext_gcd)
Case 2: m is prime: a^{m-2} \equiv a^{-1}mod m
```

5.4 GCD O(log(a+b))

注意負數的 case! C++ 是看被除數決定正負號的。

5.5 Extended Euclidean Algorithm GCD O(log(a + b))

Bezout identity ax + by = gcd(a, b), where gcd(a, b) is the smallest positive integer that can be written as ax + by, and every integer of the form ax + by is a multiple of gcd(a, b).

5.6 Prime Generator

5.7 C++ Reference

5.7.1 scanf/printf reference

5.7.2 Map

```
map<T1, T2> m; // iterable
void clear();
void erase(T1 key);
it find(T1 key); // <key, val>
void insert(pair<T1, T2> P);
T2 &[](T1 key); // if key not in map, new key will be inserted with default val
it lower_bound(T1 key); // = m.end() if not found, *it = <key, val>
it upper_bound(T1 key); // = m.end() if not found, *it = <key, val>
```

5.7.3 Set

```
set<T> s; // iterable
void clear();
size_t count(T val); // number of val in set
void erase(T val);
it find(T val); // = s.end() if not found
void insert(T val);
it lower_bound(T val); // = s.end() if not found, *it = <key, val>
it upper_bound(T val); // = s.end() if not found, *it = <key, val>
```

5.7.4 Algorithm

```
|| / / return if i is smaller than j
 |comp| = [\&](const T \&i, const T \&j) -> bool;
  vector<T> v;
  bool any_of(v.begin(), v.end(), [&](const T &i) -> bool);
  bool all of(v.begin(), v.end(), [&](const T &i) -> bool);
  void copy(inp.begin(), in.end(), out.begin());
  int count(v.begin(), v.end(), int val); // number of val in v
 it unique(v.begin(), v.end());
                                        // it - v.begin() = size
  | // after calling, v[nth] will be n-th smallest elem in v
void nth element(v.begin(), nth it, bin comp);
void merge(in1.begin(), in1.end(), in2.begin(), in2.end(), out.begin(),
12 // include union, intersection, difference, symmetric difference(xor)
void set union(in1.begin(), in1.end(), in2.begin(), in2.end(), out.
       begin(), comp);
14 bool next permutation(v.begin(), v.end());
15 / v1, v2 need sorted already, whether v1 includes v2
bool inclues(v1.begin(), v1.end(), v2.begin(), v2.end());
if find(v.begin(), v.end(), T val); // = v.end() if not found
it search(v1.begin(), v1.end(), v2.begin(), v2.end());
19 it lower bound(v.begin(), v.end(), T val);
it upper bound(v.begin(), v.end(), T val);
bool binary_search(v.begin(), v.end(), T val); // exist in v?
void sort(v.begin(), v.end(), comp);
void stable_sort(v.begin(), v.end(), comp);
```

5.7.5 String

5.7.6 Priority Queue

```
bool cmp(ii a, ii b)

if(a.first == b.first)
    return a.second > b.second;

return b.first > a.first;

priority_queue< ii, vector<ii>, function<bool(ii, ii) > pq(cmp);
```

6 Search

6.1 Ternary Search

6.2 折半完全列舉

能用 vector 就用 vector

6.3 Two-pointer 爬行法 (右跑左追)

7 Basic data structure

7.1 1D BIT

```
1 // BIT is 1-based
  const int MAX N = 20000; //這個記得改!
  11 \text{ bit}[MAX N + 1];
  11 sum(int i) {
       int s = 0;
       while (i > 0) {
           s += bit[i];
           i = (i \& -i);
       return s;
12 }
13
  void add(int i, ll x) {
15
       while (i \le MAX N) {
           bit[i] += x;
16
           i += (i \& -i);
17
18
19||}
```

7.2 2D BIT

```
11 s = 0;
for (int i = a; i > 0; i -= (i & -i))
for (int j = b; j > 0; j -= (j & -j))
s += bit[i][j];
return s;
}

void add(int a, int b, ll x) {
// MAX_N, MAX_M 須適時調整!
for (int i = a; i <= MAX_N; i += (i & -i))
for (int j = b; j <= MAX_M; j += (j & -j))
bit[i][j] += x;
}
```

7.3 Union Find

```
#define N 20000 // 記得改
struct UFDS {
    int par[N];

    void init() {
        memset(par, -1, sizeof(par));
    }

int root(int x) {
        return par[x] < 0 ? x : par[x] = root(par[x]);
}

void merge(int x, int y) {
        x = root(x);
        y = root(y);

    if (x != y) {
        if (par[x] > par[y])
            swap(x, y);
        par[y] = x;
    }
}

year[y] = x;
}

}
```

7.4 Segment Tree

```
const int MAX_N = 100000;
const int MAX_NN = (1 << 20); // should be bigger than MAX_N

int N;
il inp[MAX_N];

int NN;
11 seg[2 * MAX_NN - 1];
11 lazy[2 * MAX_NN - 1];
// lazy[u] != 0 : the subtree of u (u not included) is not up-to-date</pre>
```

```
12 void seg gather(int u)
13 {
       seg[u] = seg[u * 2 + 1] + seg[u * 2 + 2];
14
15
  void seg push(int u, int 1, int m, int r)
       if (lazy[u] != 0) {
           seg[u * 2 + 1] += (m - 1) * lazy[u];
20
           seg[u * 2 + 2] += (r - m) * lazy[u];
21
23
           lazy[u * 2 + 1] += lazy[u];
24
           lazy[u * 2 + 2] += lazy[u];
           lazy[u] = 0;
25
26
27
  void seg init()
30
31
       NN = 1:
       while (NN < N)
           NN *= 2;
34
       memset(seq, 0, sizeof(seq)); // val that won't affect result
       memset(lazy, 0, sizeof(lazy)); // val that won't affect result
36
       memcpy(seg + NN - 1, inp, sizeof(11) * N); // fill in leaves
38
  void seg build(int u)
       if (u >= NN - 1) { // leaf}
43
           return;
       }
       seg build(u * 2 + 1);
       seg build(u * 2 + 2);
       seg gather(u);
49
  void seg update(int a, int b, int delta, int u, int l, int r)
       if (1 >= b | r <= a) {
54
           return;
56
       if (a \le 1 \&\& r \le b) {
           seg[u] += (r - 1) * delta;
           lazy[u] += delta;
           return;
60
61
62
       int m = (1 + r) / 2;
64
       seg push(u, 1, m, r);
       seg_update(a, b, delta, u * 2 + 1, 1, m);
       seg\_update(a, b, delta, u * 2 + 2, m, r);
66
67
       seg gather(u);
```

```
68 }
70 11 seg query(int a, int b, int u, int 1, int r)
71 {
       if (1 >= b || r <= a) {
           return 0;
       if (a <= 1 && r <= b) {</pre>
76
77
           return seg[u];
78
       int m = (1 + r) / 2;
       seg_push(u, 1, m, r);
       11 \text{ ans} = 0;
       ans += seg_query(a, b, u * 2 + 1, 1, m);
       ans += seg_query(a, b, u * 2 + 2, m, r);
       seg_gather(u);
       return ans;
```

7.5 Sparse Table

8 Tree

8.1 LCA

```
const int MAX_N = 10000;
const int MAX_LOG_N = 14; // (1 << MAX_LOG_N) > MAX_N

int N;
int root;
int dep[MAX_N];
```

```
int par[MAX_LOG_N][MAX_N];
  vector<int> child[MAX N];
  void dfs(int u, int p, int d) {
      dep[u] = d;
      for (int i = 0; i < int(child[u].size()); i++) {</pre>
           int v = child[u][i];
           if (v != p) {
               dfs(v, u, d + 1);
  void build() {
      // par[0][u] and dep[u]
      dfs(root, -1, 0);
       // par[i][u]
      for (int i = 0; i + 1 < MAX_LOG_N; i++) {</pre>
           for (int u = 0; u < N; u++) {
               if (par[i][u] == -1)
                   par[i + 1][u] = -1;
                   par[i + 1][u] = par[i][par[i][u]];
  int lca(int u, int v) {
      if (dep[u] > dep[v]) swap(u, v); // 讓 v 較深
      int diff = dep[v] - dep[u]; // 將 v 上移到與 u 同層
       for (int i = 0; i < MAX_LOG_N; i++) {</pre>
          if (diff & (1 << i)) {</pre>
               v = par[i][v];
      if (u == v) return u;
      for (int i = MAX_LOG_N - 1; i >= 0; i--) { // 必需倒序
           if (par[i][u] != par[i][v]) {
              u = par[i][u];
               v = par[i][v];
51
52
       return par[0][u];
54
```

8.2 Tree Center

```
int diameter = 0, radius[N], deg[N]; // deg = in + out degree
int findRadius()
{
    queue<int> q; // add all leaves in this group
```

 \neg

```
for (auto i : group)
           if (deg[i] == 1)
               q.push(i);
       int mx = 0;
       while (q.empty() == false) {
           int u = q.front();
           q.pop();
13
           for (int v : g[u]) {
14
15
               deg[v]--;
               if (deg[v] == 1) {
                   q.push(v);
                   radius[v] = radius[u] + 1;
                   mx = max(mx, radius[v]);
           }
21
22
       }
23
       int cnt = 0; // crucial for knowing if there are 2 centers or not
       for (auto j : group)
           if (radius[j] == mx)
               cnt++;
       // add 1 if there are 2 centers (radius, diameter)
       diameter = max(diameter, mx * 2 + (cnt == 2));
       return mx + (cnt == 2);
```

8.3 Treap

```
1 // Remember srand(time(NULL))
 struct Treap { // val: bst, pri: heap
      int pri, size, val;
      Treap *lch, *rch;
      Treap() {}
      Treap(int v) {
          pri = rand();
          size = 1;
          val = v;
           lch = rch = NULL;
12 };
14 inline int size(Treap* t) {
      return (t ? t->size : 0);
17 // inline void push(Treap* t) {
18 //
      push lazy flag
19 // }
inline void pull(Treap* t) {
    t->size = 1 + size(t->lch) + size(t->rch);
_{24} | int NN = 0;
```

```
25 Treap pool[30000];
  Treap* merge(Treap* a, Treap* b) { // a < b</pre>
       if (!a | !b) return (a ? a : b);
       if (a->pri > b->pri) {
           // push(a);
          a->rch = merge(a->rch, b);
          pull(a);
          return a;
34
      }
      else {
35
           // push(b);
          b->lch = merge(a, b->lch);
          pull(b);
38
          return b:
41
  void split(Treap* t, Treap*& a, Treap*& b, int k) {
      if (!t) { a = b = NULL; return; }
45
       // push(t);
46
      if (size(t->lch) < k) {
          a = t;
48
          split(t->rch, a->rch, b, k - size(t->lch) - 1);
49
          pull(a);
50
      else {
          b = t;
          split(t->lch, a, b->lch, k);
          pull(b);
58 // get the rank of val
59 // result is 1-based
int get_rank(Treap* t, int val) {
      if (!t) return 0;
      if (val < t->val)
63
           return get_rank(t->lch, val);
64
          return get rank(t->rch, val) + size(t->lch) + 1;
68 // get kth smallest item
  // k is 1-based
70 Treap* get kth(Treap*& t, int k) {
     Treap *a, *b, *c, *d;
      split(t, a, b, k - 1);
      split(b, c, d, 1);
      t = merge(a, merge(c, d));
      return c;
76
78 void insert(Treap*& t, int val) {
      int k = get_rank(t, val);
    Treap *a, *b;
```

```
split(t, a, b, k);
pool[NN] = Treap(val);
Treap* n = &pool[NN++];
t = merge(merge(a, n), b);

// Implicit key treap init
void insert() {
    for (int i = 0; i < N; i++) {
        int val; scanf("%d", &val);
        root = merge(root, new_treap(val)); // implicit key(index)
}

root = merge(root, new_treap(val)); // implicit key(index)
}
</pre>
```

8.4 Merge Tree

9 Graph

- 9.1 Articulation point / edge
- 9.2 CC
- 9.2.1 BCC vertex
- 9.2.2 BCC edge
- 9.2.3 SCC

First of all we run DFS on the graph and sort the vertices in decreasing of their finishing time (we can use a stack).

Then, we start from the vertex with the greatest finishing time, and for each vertex v that is not yet in any SCC, do: for each u that v is reachable by u and u is not yet in any SCC, put it in the SCC of vertex v. The code is quite simple.

9.3 Shortest Path

Time complexity notations: V = vertex, E = edge

9.3.1 Dijkatra

密集圖別用 priority queue!

```
#define st first
#define nd second

typedef pair<int, int> pii; // <d, v>
struct Edge {
    int to, w;
};

const int MAX_V = ...;
const int INF = 0x3f3f3f3f;

int V, S; // V, Source
vector<Edge> g[MAX_V];
int d[MAX_V];
int cnt[MAX_V];
```

```
bool spfa() { // 回傳有無負環
       fill(d, d + V, INF);
       fill(cnt, cnt + V, 0);
20
       priority queue< pii, vector<pii>, greater<pii> > pq;
21
       d[S] = 0;
       pq.push(pii(0, S));
23
       cnt[S] = 1;
24
25
26
       while (!pq.empty()) {
           pii top = pq.top(); pq.pop();
27
28
           int u = top.nd;
29
30
           if (d[u] < top.st) continue;</pre>
           // for (const Edge& e : q[u]) {
           for (size_t i = 0; i < g[u].size(); i++) {</pre>
               const Edge& e = g[u][i];
               if (d[e.to] > d[u] + e.w) {
                    d[e.to] = d[u] + e.w;
                    pq.push(pii(d[e.to], e.to));
                    cnt[e.to]++;
                    if (cnt[e.to] >= V)
41
                        return true;
42
43
       return false;
```

9.3.2 Dijkatra (next-to-shortest path)

```
struct Edge {
       int to, cost;
  typedef pair<int, int> P; // <d, v>
  const int INF = 0x3f3f3f3f;
  int N, R;
  vector<Edge> g[5000];
  int d[5000];
  int sd[5000];
  int solve() {
      fill(d, d + N, INF);
      fill(sd, sd + N, INF);
      priority queue< P, vector<P>, greater<P> > pq;
18
      d[0] = 0;
20
       pq.push(P(0, 0));
```

```
22
       while (!pq.empty()) {
23
           P p = pq.top(); pq.pop();
           int v = p.second;
24
25
26
           if (sd[v] < p.first) // 比次短距離還大, 沒用, 跳過
               continue;
           for (size t i = 0; i < g[v].size(); i++) {</pre>
               Edge& e = g[v][i];
               int nd = p.first + e.cost;
31
               if (nd < d[e.to]) { // 更新最短距離
                   swap(d[e.to], nd);
                   pq.push(P(d[e.to], e.to));
               if (d[e.to] < nd && nd < sd[e.to]) { // 更新次短距離
                   sd[e.to] = nd;
                   pq.push(P(sd[e.to], e.to));
               }
40
41
       return sd[N-1];
```

9.3.3 SPFA

```
1 typedef pair<int, int> ii;
 vector< ii > g[N];
  bool SPFA()
       vector<ll> d(n, INT_MAX);
       d[0] = 0; // origin
       queue<int> q;
       vector<bool> inqueue(n, false);
       vector<int> cnt(n, 0);
       q.push(0);
       inqueue[0] = true;
       cnt[0]++;
       while(q.empty() == false) {
           int u = q.front();
17
           q.pop();
           inqueue[u] = false;
20
           for(auto i : g[u]) {
               int v = i.first, w = i.second;
22
23
               if(d[u] + w < d[v]) {
                   d[v] = d[u] + w;
                   if(inqueue[v] == false) {
26
                       q.push(v);
                       inqueue[v] = true;
                       cnt[v]++;
                       if(cnt[v] == n) { // loop!
```

9.3.4 Bellman-Ford O(VE)

```
| vector<pair<ii, int>> edge; // store graph by edge: ((u, v), w)
  void BellmanFord()
       11 d[n]; // n: total nodes
       fill(d, d + n, INT MAX);
       d[0] = 0; // src is 0
       bool loop = false;
       for (int i = 0; i < n; i++) {
           // Do n - 1 times. If the n-th time still has relaxation, loop
       exists
           bool hasChange = false;
           for (int j = 0; j < (int)edge.size(); j++) {</pre>
12
               int u = edge[j].first.first, v = edge[j].first.second, w =
       edge[j].second;
               if (d[u] != INT MAX && d[u] + w < d[v]) {
14
                   hasChange = true;
                   d[v] = d[u] + w;
16
17
               }
           }
19
           if (i == n - 1 && hasChange == true)
20
               loop = true;
21
           else if (hasChange == false)
22
               break;
23
24
25 }
```

9.3.5 Floyd-Warshall $O(V^3)$

The graph is stored using adjacency matrix. The initial state is diagnal = 0 and others = INF. (If INF is int, use long long for the matrix) If diagonal numbers are negative \leftarrow cycle.

```
for(int k = 0; k < N; k++)

for(int i = 0; i < N; i++)

for(int j = 0; j < N; j++)

dp[i][j] = min(dp[i][j], dp[i][k] + dp[k][j]);</pre>
```

9.4 MST

9.4.1 Kruskal

1. Store the graph by (weight, (from, to))

10

- 2. Sort the graph by weight
- 3. Start from the smallest weight, and keep adding edges that won't form a cycle with the current MST set.
- 4. Early termination condition: n-1 edges has been added, NOT size of the union-find set

9.4.2 Prim

10 Flow

10.1 Max Flow (Dinic)

```
struct Edge {
       int to, cap, rev;
       Edge(int a, int b, int c) {
           to = a;
           cap = b;
           rev = c;
 8||};
10 const int INF = 0x3f3f3f3f3f;
12 // vector<Edge> g[MAX_V];
vector< vector<Edge> > g(MAX_V);
int level[MAX V];
15 int iter[MAX_V];
inline void add edge(int u, int v, int cap) {
       g[u].push_back((Edge){v, cap, (int)g[v].size()});
       g[v].push_back((Edge){u, 0, (int)g[u].size() - 1});
void bfs(int s) {
      memset(level, -1, sizeof(level));
       queue<int> q;
25
      level[s] = 0;
       q.push(s);
28
       while (!q.empty()) {
29
           int v = q.front(); q.pop();
           for (int i = 0; i < int(g[v].size()); i++) {</pre>
31
               const Edge& e = g[v][i];
32
               if (e.cap > 0 && level[e.to] < 0) {</pre>
                  level[e.to] = level[v] + 1;
                  q.push(e.to);
               }
37
38
41 int dfs(int v, int t, int f) {
      if (v == t) return f;
       for (int& i = iter[v]; i < int(g[v].size()); i++) {</pre>
           Edge& e = g[v][i];
```

```
if (e.cap > 0 && level[v] < level[e.to]) {</pre>
                int d = dfs(e.to, t, min(f, e.cap));
                if (d > 0) {
48
                    e.cap = d;
                    g[e.to][e.rev].cap += d;
49
50
                    return d;
51
54
       return 0;
  int max_flow(int s, int t) { // dinic
       int flow = 0;
       for (;;) {
           bfs(s);
           if (level[t] < 0) return flow;</pre>
           memset(iter, 0, sizeof(iter));
           int f;
63
           while ((f = dfs(s, t, INF)) > 0) {
                flow += f;
65
66
67
68 }
```

10.2 Min Cost Flow

```
#define st first
  #define nd second
  typedef pair<double, int> pii;
  const double INF = 1e10;
  struct Edge {
       int to, cap;
       double cost;
       int rev;
  };
  const int MAX V = 2 * 100 + 10;
  int V;
  vector<Edge> g[MAX V];
  double h[MAX V];
  double d[MAX V];
  int prevv[MAX V];
  int preve[MAX_V];
  // int match[MAX_V];
  void add edge(int u, int v, int cap, double cost) {
       g[u].push back((Edge){v, cap, cost, (int)g[v].size()});
       g[v].push_back((Edge){u, 0, -cost, (int)g[u].size() - 1});
24
25
27 double min_cost_flow(int s, int t, int f) {
```

31

32

```
double res = 0;
fill(h, h + V, 0);
fill(match, match + V, -1);
while (f > 0) {
    // dijkstra 找最小成本增廣路徑
    // without h will reduce to SPFA = O(V*E)
    fill(d, d + V, INF);
    priority_queue< pii, vector<pii>, greater<pii> > pq;
   d[s] = 0;
    pq.push(pii(d[s], s));
    while (!pq.empty()) {
       pii p = pq.top(); pq.pop();
        int v = p.nd;
       if (d[v] < p.st) continue;</pre>
        for (size_t i = 0; i < g[v].size(); i++) {</pre>
            const Edge& e = g[v][i];
            if (e.cap > 0 \&\& d[e.to] > d[v] + e.cost + h[v] - h[e.
to]) {
                d[e.to] = d[v] + e.cost + h[v] - h[e.to];
                prevv[e.to] = v;
                preve[e.to] = i;
                pq.push(pii(d[e.to], e.to));
    // 找不到增廣路徑
    if (d[t] == INF) return -1;
    // 維護 h[v]
    for (int v = 0; v < V; v++)
       h[v] += d[v];
    // 找瓶頸
    int bn = f;
    for (int v = t; v != s; v = prevv[v])
        bn = min(bn, g[prevv[v]][preve[v]].cap);
    // // find match
    // for (int v = prevv[t]; v != s; v = prevv[prevv[v]]) {
           int u = prevv[v];
           match[v] = u;
           match[u] = v;
    // }
    // 更新剩餘圖
    res += bn * h[t]; // SPFA: res += bn * d[t]
    for (int v = t; v != s; v = prevv[v]) {
        Edge& e = g[prevv[v]][preve[v]];
        e.cap -= bn;
        g[v][e.rev].cap += bn;
```

```
83 return res;
84 }
```

10.3 Bipartite Matching

```
const int MAX_V = ...;
  int V;
  vector<int> g[MAX_V];
  int match[MAX V];
  bool used[MAX_V];
  void add_edge(int u, int v) {
      g[u].push_back(v);
      g[v].push_back(u);
  // 回傳有無找到從 v 出發的增廣路徑
  //(首尾都為未匹配點的交錯路徑)
  // [待確認] 每次遞迴都找一個末匹配點 v 及匹配點 u
  | bool dfs(int v) {
      used[v] = true;
      for (size_t i = 0; i < g[v].size(); i++) {</pre>
          int u = g[v][i], w = match[u];
          // 尚未配對或可從 w 找到增廣路徑 (即路徑繼續增長)
          if (w < 0 \mid | (!used[w] && dfs(w))) {
              // 交錯配對
              match[v] = u;
              match[u] = v;
              return true;
      return false;
  | int bipartite_matching() { // 匈牙利演算法
      int res = 0;
      memset(match, -1, sizeof(match));
      for (int v = 0; v < V; v++) {
          if (match[v] == -1) {
              memset(used, false, sizeof(used));
              if (dfs(v)) {
                  res++;
38
39
41
      return res;
42
```

11 String

11.1 Rolling Hash

1. Use two rolling hashes if needed.

2. The prime for pre-calculation can be 137 and 257, for modulo can be 1e9 + 7 and 0xdefaced

```
#define N 1000100
  #define B 137
   #define M 1000000007
  typedef long long 11;
  char inp[N];
  int len;
  ll p[N], h[N];
11 void init()
12 { // build polynomial table and hash value
      p[0] = 1; // b to the ith power
      for (int i = 1; i <= len; i++) {
          h[i] = (h[i-1] * B % M + inp[i-1]) % M; // hash value
15
           p[i] = p[i - 1] * B % M;
17
18 }
20 11 get hash(int 1, int r) // [1, r] of the inp string array
21 | {
      return ((h[r+1] - (h[1] * p[r-1+1])) % M + M) % M;
```

11.2 KMP

```
void fail()
       int len = strlen(pat);
       f[0] = 0;
       int j = 0;
       for (int i = 1; i < len; i++) {
           while (j != 0 && pat[i] != pat[j])
               j = f[j - 1];
           if (pat[i] == pat[j])
               j++;
           f[i] = j;
16 }
18 int match()
       int res = 0;
20
       int j = 0, plen = strlen(pat), tlen = strlen(text);
21
22
23
       for (int i = 0; i < tlen; i++) {
24
           while (j != 0 && text[i] != pat[j])
               j = f[j - 1];
           if (text[i] == pat[j]) {
               if (j == plen - 1) { // find match}
```

```
res++;

j = f[j];

} else {
    j++;

}

return res;

}
```

11.3 Z Algorithm

```
int len = strlen(inp), z[len];
  z[0] = 0; // initial
   int 1 = 0, r = 0; // z box bound [1, r]
  for (int i = 1; i < len; i++)
       if (i > r) { // i not in z box
           1 = r = i; // z box contains itself only
           while (r < len && inp[r - l] == inp[r])
                r++;
           z[i] = r - 1;
           r--;
13
       } else \{ // i \text{ in } z \text{ box } \}
           if (z[i-1] + i < r) // over shoot R bound
               z[i] = z[i - 1];
           else {
16
               1 = i;
               while (r < len && inp[r - 1] == inp[r])
                    r++;
               z[i] = r - 1;
20
21
                r--;
22
23
24 }
```

11.4 Trie

注意 count 的擺放位置, 視題意可以擺在迴圈外

```
struct Node {
    int cnt;
    Node* nxt[2];
    Node() {
        cnt = 0;
        fill(nxt, nxt + 2, nullptr);
    }
};

const int MAX_Q = 200000;
int Q;
int Q;
int NN = 0;
```

```
14 Node data[MAX_Q * 30];
15 Node* root = &data[NN++];
17 void insert(Node* u, int x) {
       for (int i = 30; i >= 0; i--) {
           int t = ((x >> i) & 1);
           if (u->nxt[t] == nullptr) {
               u->nxt[t] = &data[NN++];
23
           u = u->nxt[t];
           u->cnt++;
27
  void remove(Node* u, int x) {
       for (int i = 30; i >= 0; i--) {
           int t = ((x >> i) \& 1);
           u = u->nxt[t];
           u->cnt--;
int query(Node* u, int x) {
       int res = 0;
       for (int i = 30; i >= 0; i--) {
           int t = ((x >> i) \& 1);
           // if it is possible to go the another branch
           // then the result of this bit is 1
           if (u->nxt[t ^ 1] != nullptr && u->nxt[t ^ 1]->cnt > 0) {
               u = u - nxt[t ^ 1];
               res |= (1 << i);
           }
           else {
               u = u - nxt[t];
       return res;
```

11.5 Suffix Array

12 Matrix

12.1 Gauss Jordan

```
typedef long long ll;
typedef vector<ll> vec;
typedef vector<vec> mat;

vec gauss_jordan(mat A) {
   int n = A.size(), m = A[0].size();
   for (int i = 0; i < n; i++) {
        // float: find j s.t. A[j][i] is max
        // mod: find min j s.t. A[j][i] is not 0</pre>
```

```
int pivot = i;
           for (int j = i; j < n; j++) {
               // if (fabs(A[j][i]) > fabs(A[pivot])) {
12
                     pivot = j;
              // }
              if (A[pivot][i] != 0) {
                  pivot = j;
                   break;
              }
           swap(A[i], A[pivot]);
          if (A[i][i] == 0) { // if (fabs(A[i][i]) < eps)</pre>
               // 無解或無限多組解
               // 可改成 continue, 全部做完後再判
               return vec();
          11 divi = inv(A[i][i]);
           for (int j = i; j < m; j++) {
               // A[i][j] /= A[i][i];
              A[i][j] = (A[i][j] * divi) % MOD;
           for (int j = 0; j < n; j++) {
              if (j != i) {
                   for (int k = i + 1; k < m; k++) {
                       // A[j][k] = A[j][i] * A[i][k];
                       11 p = (A[j][i] * A[i][k]) % MOD;
39
                       A[j][k] = (A[j][k] - p + MOD) % MOD;
40
41
      vec x(n);
       for (int i = 0; i < n; i++)
          x[i] = A[i][m - 1];
47
48
       return x;
```

12.2 Determinant

```
for (int k = 0; k < n; k++)
                        m[a][k] = m[a][k] - m[b][k] * q;
                    swap(a, b);
               }
17
               if (a != i) {
                    swap(m[i], m[j]);
                    det = -det;
21
               }
23
24
           if (m[i][i] == 0)
25
               return 0;
           else
26
27
                det *= m[i][i];
28
29
       return det;
```

13 Geometry

- 1. Keep things in integers as much as possible!
- 2. Try not to divide
- 3. If you have decimals, if they are fixed precision, you can usually just multiply all the input and use integers instead

13.1 EPS

```
=0: fabs \le eps
<0: <-eps
>0: >+eps
```

13.2 Template

```
typedef long long 11;

typedef pair<11, 11> pt; // points are stored using long long
typedef pair<pt, pt> seg; // segments are a pair of points

#define x first
#define y second

#define EPS 1e-9

pt operator+(pt a, pt b)
{
    return pt(a.x + b.x, a.y + b.y);
}

pt operator-(pt a, pt b)
{
    return pt(a.x - b.x, a.y - b.y);
}

return pt(a.x - b.x, a.y - b.y);
}
```

```
pt operator*(pt a, int d)
       return pt(a.x * d, a.y * d);
25
26
28
  ll cross(pt a, pt b)
       return a.x * b.y - a.y * b.x;
30
31
  int ccw(pt a, pt b, pt c)
       11 \text{ res} = \text{cross}(b - a, c - a);
       if (res > 0) // left turn
           return 1:
       else if (res == 0) // straight
           return 0;
       else // right turn
41
           return -1;
42
  double dist(pt a, pt b)
       double dx = a.x - b.x;
       double dy = a.y - b.y;
       return sqrt(dx * dx + dy * dy);
49
50
  bool zero(double x)
       return fabs(x) <= EPS;</pre>
54
  bool overlap(seg a, seg b)
       return ccw(a.x, a.y, b.x) == 0 && ccw(a.x, a.y, b.y) == 0;
60
61
  bool intersect(seg a, seg b)
62
       if (overlap(a, b) == true) { // non-proper intersection
           double d = 0;
           d = max(d, dist(a.x, a.y));
           d = max(d, dist(a.x, b.x));
           d = max(d, dist(a.x, b.y));
67
68
           d = max(d, dist(a.y, b.x));
           d = max(d, dist(a.y, b.y));
69
           d = max(d, dist(b.x, b.y));
           // d > dist(a.x, a.y) + dist(b.x, b.y)
72
           if (d - (dist(a.x, a.y) + dist(b.x, b.y)) > EPS)
73
               return false;
74
75
           return true;
77
       // Equal sign for ---- case
```

15

```
// non geual sign => proper intersection
       if (ccw(a.x, a.y, b.x) * ccw(a.x, a.y, b.y) \le 0 &&
           ccw(b.x, b.y, a.x) * ccw(b.x, b.y, a.y) <= 0)
           return true:
       return false;
  double area(vector<pt> pts)
87 {
       double res = 0;
       int n = pts.size();
       for (int i = 0; i < n; i++)
           res += (pts[i].y + pts[(i + 1) % n].y) * (pts[(i + 1) % n].x -
       pts[i].x);
       return res / 2.0;
93 }
94
95 vector<pt> halfHull(vector<pt> &points)
96 {
97
       vector<pt> res;
       for (int i = 0; i < (int)points.size(); <math>i++) {
           while ((int)res.size() >= 2 &&
                   ccw(res[res.size() - 2], res[res.size() - 1], points[i])
        < 0)
                res.pop back(); // res.size() - 2 can't be assign before
        size() >= 2
            // check, bitch
           res.push back(points[i]);
       return res;
vector<pt> convexHull(vector<pt> &points)
112 {
       vector<pt> upper, lower;
114
       // make upper hull
       sort(points.begin(), points.end());
       upper = halfHull(points);
118
       // make lower hull
       reverse(points.begin(), points.end());
120
       lower = halfHull(points);
121
122
       // merge hulls
       if ((int)upper.size() > 0) // yes sir~
124
            upper.pop back();
125
       if ((int)lower.size() > 0)
126
127
           lower.pop_back();
       vector<pt> res(upper.begin(), upper.end());
       res.insert(res.end(), lower.begin(), lower.end());
130
```

```
return res;
133
134
   | bool completelyInside(vector<pt> &outer, vector<pt> &inner)
       int even = 0, odd = 0;
        for (int i = 0; i < (int)inner.size(); i++) {
            // y = slope * x + offset
            int cntIntersection = 0;
            11 slope = rand() % INT MAX + 1;
141
            ll offset = inner[i].y - slope * inner[i].x;
           11 farx = 1111111 * (slope >= 0 ? 1 : -1);
            11 fary = farx * slope + offset;
145
            seg a = seg(pt(inner[i].x, inner[i].y), pt(farx, fary));
146
            for (int j = 0; j < (int)outer.size(); j++) {</pre>
                seg b = seg(outer[j], outer[(j + 1) % (int)outer.size()]);
148
149
                if ((b.x.x * slope + offset == b.x.y)
                    (b.y.x * slope + offset == b.y.y)) { // on-line}
                    i--;
                    break:
                if (intersect(a, b) == true)
                    cntIntersection++;
157
158
159
            if (cntIntersection % 2 == 0) // outside
                even++;
161
            else
                odd++;
163
165
        return odd == (int)inner.size();
166
167
   // srand(time(NULL))
170 // rand()
```

14 Math

14.1 Euclid's formula (Pythagorean Triples)

```
a = p^2 - q^2

b = 2pq (always even)

c = p^2 + q^2
```

14.2 Difference between two consecutive numbers' square is odd

```
(k+1)^2 - k^2 = 2k+1
```

14.3 Summation

```
\sum\nolimits_{k=1}^{n}1=n
\sum_{k=1}^{n-1} k = \frac{n(n+1)}{2}\sum_{k=1}^{n} k^2 = \frac{n(n+1)(2n+1)}{6}
```

14.4 FFT

```
| typedef unsigned int ui;
 typedef long double ldb;
  const ldb pi = atan2(0, -1);
  struct Complex {
      ldb real, imag;
      Complex(): real(0.0), imag(0.0) {;}
      Complex(ldb a, ldb b) : real(a), imag(b) {;}
      Complex conj() const {
           return Complex(real, -imag);
       Complex operator + (const Complex& c) const {
           return Complex(real + c.real, imag + c.imag);
       Complex operator - (const Complex& c) const {
           return Complex(real - c.real, imag - c.imag);
       Complex operator * (const Complex& c) const {
           return Complex(real*c.real - imag*c.imag, real*c.imag + imag*c.
       real);
       Complex operator / (ldb x) const {
           return Complex(real / x, imag / x);
       Complex operator / (const Complex& c) const {
           return *this * c.conj() / (c.real * c.real + c.imag * c.imag);
26
27 };
29 inline ui rev bit(ui x, int len){
      x = ((x \& 0x555555555) << 1) | ((x \& 0xAAAAAAA)) >> 1);
      x = ((x \& 0x33333333u) << 2)
                                       ((x \& 0xCCCCCCCu) >> 2);
31
      x = ((x \& 0x0F0F0F0Fu) << 4)
                                    ((x \& 0xF0F0F0F0u) >> 4);
      x = ((x \& 0x00FF00FFu) << 8) | ((x \& 0xFF00FF00u) >> 8);
      x = ((x \& 0x0000FFFFu) << 16) | ((x \& 0xFFFF0000u) >> 16);
       return x \gg (32 - len);
36 }
37
| // flag = -1 if ifft else +1 
void fft(vector<Complex>& a, int flag = +1) {
      int n = a.size(); // n should be power of 2
41
      int len = builtin ctz(n);
       for (int i = 0; i < n; i++) {
           int rev = rev bit(i, len);
```

```
if (i < rev)
                swap(a[i], a[rev]);
       for (int m = 2; m \le n; m \le 1) { // width of each item
           auto wm = Complex(\cos(2 * pi / m), flag * \sin(2 * pi / m));
            for (int k = 0; k < n; k += m) { // start idx of each item
               auto w = Complex(1, 0);
               for (int j = 0; j < m / 2; j++) { // iterate half</pre>
                    Complex t = w * a[k + j + m / 2];
                   Complex u = a[k + j];
                   a[k + j] = u + t;
                    a[k + j + m / 2] = u - t;
                    w = w * wm;
       if (flag == -1) { // if it's ifft
           for (int i = 0; i < n; i++)
               a[i].real /= n;
   }
   vector<int> mul(const vector<int>& a, const vector<int>& b) {
       int n = int(a.size()) + int(b.size()) - 1;
       int nn = 1;
       while (nn < n)
           nn <<= 1;
       vector<Complex> fa(nn, Complex(0, 0));
       vector<Complex> fb(nn, Complex(0, 0));
       for (int i = 0; i < int(a.size()); i++)</pre>
           fa[i] = Complex(a[i], 0);
       for (int i = 0; i < int(b.size()); i++)
           fb[i] = Complex(b[i], 0);
       fft(fa, +1);
       fft(fb, +1);
       for (int i = 0; i < nn; i++) {
           fa[i] = fa[i] * fb[i];
       fft(fa, -1);
       vector<int> c;
       for(int i = 0; i < nn; i++) {
           int val = int(fa[i].real + 0.5);
           if (val) {
               while (int(c.size()) <= i)</pre>
                   c.push back(0);
               c[i] = 1;
       return c;
101 }
```

48

49

54

59

63

64

68

74

76

77

79 80

82

83

85

90

92

97

98

100

14.5 Combination

14.5.1 Pascal triangle

14.5.2 線性

14.6 重複組合

14.7 Chinese remainder theorem

```
typedef long long ll;

struct Item {
    ll m, r;
};

ll extgcd(ll a, ll b, ll &x, ll &y)

if (b == 0) {
    x = 1;
    y = 0;
    return a;
} else {
```

```
11 d = extgcd(b, a % b, y, x);
           y = (a / b) * x;
           return d;
17
18 }
  Item extcrt(const vector<Item> &v)
21
      11 m1 = v[0].m, r1 = v[0].r, x, y;
22
23
       for (int i = 1; i < int(v.size()); i++) {</pre>
24
           11 m2 = v[i].m, r2 = v[i].r;
25
           11 g = extgcd(m1, m2, x, y); // now x = (m/g)^{(-1)}
26
27
28
           if ((r2 - r1) % q != 0)
               return {-1, -1};
30
31
           11 k = (r2 - r1) / g * x % (m2 / g);
32
           k = (k + m2 / g) % (m2 / g); // for the case k is negative
33
           11 m = m1 * m2 / g;
34
35
           11 r = (m1 * k + r1) % m;
37
           r1 = (r + m) % m; // for the case r is negative
38
39
40
41
       return (Item) {
           m1, r1
42
43
       };
44 }
```

14.8 2-Circle relations

d= 圓心距, R, r 為半徑 $(R \ge r)$ 內切: d=R-r 外切: d=R+r 內能: d < R-r 外離: d > R+r 相交: d > R-r

14.9 Fun Facts

1. 如果 $\frac{b}{a}$ 是最簡分數,則 $1-\frac{b}{a}$ 也是 2.

Trig Cheat Sheet

Definition of the Trig Functions

Right triangle definition

For this definition we assume that

$$0 < \theta < \frac{\pi}{2} \text{ or } 0^{\circ} < \theta < 90^{\circ}.$$



$$\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$$
 $\csc \theta = \frac{\text{hypotenuse}}{\text{opposite}}$ $\csc \theta = \frac{\text{hypotenuse}}{\text{adjacent}}$ $\sec \theta = \frac{\text{hypotenuse}}{\text{adjacent}}$ $\tan \theta = \frac{\text{opposite}}{\text{opposite}}$ $\cot \theta = \frac{\text{adjacent}}{\text{adjacent}}$

Unit circle definition

For this definition θ is any angle.



$$\sin \theta = \frac{y}{1} = y \qquad \csc \theta = \frac{1}{y}$$

$$\cos \theta = \frac{x}{1} = x \qquad \sec \theta = \frac{1}{x}$$

$$\tan \theta = \frac{y}{x} \qquad \cot \theta = \frac{x}{y}$$

Facts and Properties

opposite

Domain

The domain is all the values of θ that can be plugged into the function.

 $\sin \theta$, θ can be any angle $\cos \theta$, θ can be any angle

adjacent

$$\tan \theta$$
, $\theta \neq \left(n + \frac{1}{2}\right)\pi$, $n = 0, \pm 1, \pm 2, \dots$

 $\csc \theta$, $\theta \neq n\pi$, $n = 0, \pm 1, \pm 2, \dots$

$$\sec \theta$$
, $\theta \neq \left(n + \frac{1}{2}\right)\pi$, $n = 0, \pm 1, \pm 2, \dots$

 $\cot \theta$, $\theta \neq n\pi$, $n = 0, \pm 1, \pm 2, ...$

Range

The range is all possible values to get out of the function.

$$-1 \le \sin \theta \le 1 \qquad \csc \theta \ge 1 \text{ and } \csc \theta \le -1$$

$$-1 \le \cos \theta \le 1 \qquad \sec \theta \ge 1 \text{ and } \sec \theta \le -1$$

$$-\infty < \tan \theta < \infty \qquad -\infty < \cot \theta < \infty$$

Period

The period of a function is the number, T, such that $f(\theta+T)=f(\theta)$. So, if ω is a fixed number and θ is any angle we have the following periods.

$$\sin(\omega\theta) \rightarrow T = \frac{2\pi}{\omega}$$

$$\cos(\omega\theta) \rightarrow T = \frac{2\pi}{\omega}$$

$$\tan(\omega\theta) \rightarrow T = \frac{\pi}{\omega}$$

$$\csc(\omega\theta) \rightarrow T = \frac{2\pi}{\omega}$$

$$\sec(\omega\theta) \rightarrow T = \frac{2\pi}{\omega}$$

$$\cot(\omega\theta) \rightarrow T = \frac{\pi}{\omega}$$

Formulas and Identities

Tangent and Cotangent Identities

$$\tan \theta = \frac{\sin \theta}{\cos \theta}$$

$$\cot \theta = \frac{\cos \theta}{\sin \theta}$$

Reciprocal Identities

$$\csc\theta = \frac{1}{\sin\theta}$$

$$\sin\theta = \frac{1}{\csc\theta}$$

$$\sec\theta = \frac{1}{\cos\theta}$$

$$\cos\theta = \frac{1}{\sec\theta}$$

$$\cot \theta = \frac{1}{\tan \theta}$$

$$\tan \theta = \frac{1}{\cot \theta}$$

Pythagorean Identities

$$\sin^2\theta + \cos^2\theta = 1$$

$$\tan^2 \theta + 1 = \sec^2 \theta$$

$$1 + \cot^2 \theta = \csc^2 \theta$$

Even/Odd Formulas

$$\sin(-\theta) = -\sin\theta$$
 $\csc(-\theta) = -\csc\theta$

$$\cos(-\theta) = \cos\theta$$
 $\sec(-\theta) = \sec\theta$

$$\tan(-\theta) = -\tan\theta \qquad \cot(-\theta) = -\cot\theta$$

Periodic Formulas

If *n* is an integer.

$$\sin(\theta + 2\pi n) = \sin\theta \quad \csc(\theta + 2\pi n) = \csc\theta$$

$$\cos(\theta + 2\pi n) = \cos\theta \quad \sec(\theta + 2\pi n) = \sec\theta$$

$$\tan(\theta + \pi n) = \tan\theta \quad \cot(\theta + \pi n) = \cot\theta$$

Double Angle Formulas

$$\sin(2\theta) = 2\sin\theta\cos\theta$$

$$\cos(2\theta) = \cos^2 \theta - \sin^2 \theta$$
$$= 2\cos^2 \theta - 1$$

$$\tan(2\theta) = \frac{2\tan\theta}{1-\tan^2\theta}$$

Degrees to Radians Formulas

 $=1-2\sin^2\theta$

If x is an angle in degrees and t is an angle in radians then

$$\frac{\pi}{180} = \frac{t}{x} \implies t = \frac{\pi x}{180} \quad \text{and} \quad x = \frac{180t}{\pi} \qquad \frac{\csc\left(\frac{\pi}{2} - \theta\right) = \sec\theta}{\tan\left(\frac{\pi}{2} - \theta\right) = \cot\theta} \qquad \frac{\sec\left(\frac{\pi}{2} - \theta\right) = \csc\theta}{\cot\left(\frac{\pi}{2} - \theta\right) = \tan\theta}$$

Half Angle Formulas (alternate form)

$$\sin\frac{\theta}{2} = \pm\sqrt{\frac{1-\cos\theta}{2}} \qquad \sin^2\theta = \frac{1}{2}(1-\cos(2\theta))$$

$$\cos\frac{\theta}{2} = \pm\sqrt{\frac{1+\cos\theta}{2}}$$
 $\cos^2\theta = \frac{1}{2}(1+\cos(2\theta))$

$$\tan\frac{\theta}{2} = \pm\sqrt{\frac{1-\cos\theta}{1+\cos\theta}} \qquad \tan^2\theta = \frac{1-\cos(2\theta)}{1+\cos(2\theta)}$$

Sum and Difference Formulas

$$\sin(\alpha \pm \beta) = \sin\alpha \cos\beta \pm \cos\alpha \sin\beta$$

$$\cos(\alpha \pm \beta) = \cos\alpha \cos\beta \mp \sin\alpha \sin\beta$$

$$\tan(\alpha \pm \beta) = \frac{\tan\alpha \pm \tan\beta}{1 \mp \tan\alpha \tan\beta}$$

Product to Sum Formulas

$$\sin \alpha \sin \beta = \frac{1}{2} \Big[\cos (\alpha - \beta) - \cos (\alpha + \beta) \Big]$$

$$\cos \alpha \cos \beta = \frac{1}{2} \left[\cos (\alpha - \beta) + \cos (\alpha + \beta) \right]$$

$$\sin \alpha \cos \beta = \frac{1}{2} \left[\sin (\alpha + \beta) + \sin (\alpha - \beta) \right]$$

$$\cos \alpha \sin \beta = \frac{1}{2} \left[\sin(\alpha + \beta) - \sin(\alpha - \beta) \right]$$

Sum to Product Formulas

$$\sin \alpha + \sin \beta = 2 \sin \left(\frac{\alpha + \beta}{2}\right) \cos \left(\frac{\alpha - \beta}{2}\right)$$

$$\sin \alpha - \sin \beta = 2\cos \left(\frac{\alpha + \beta}{2}\right) \sin \left(\frac{\alpha - \beta}{2}\right)$$

$$\cos \alpha + \cos \beta = 2 \cos \left(\frac{\alpha + \beta}{2} \right) \cos \left(\frac{\alpha - \beta}{2} \right)$$

$$\cos \alpha - \cos \beta = -2 \sin \left(\frac{\alpha + \beta}{2} \right) \sin \left(\frac{\alpha - \beta}{2} \right)$$

Cofunction Formulas

$$\sin\left(\frac{\pi}{2} - \theta\right) = \cos\theta$$
 $\cos\left(\frac{\pi}{2} - \theta\right) = \sin\theta$

$$\csc\left(\frac{\pi}{2} - \theta\right) = \sec \theta$$
 $\sec\left(\frac{\pi}{2} - \theta\right) = \csc \theta$

$$\tan\left(\frac{\pi}{2} - \theta\right) = \cot\theta \qquad \cot\left(\frac{\pi}{2} - \theta\right) = \tan\theta$$

Unit Circle



For any ordered pair on the unit circle (x, y): $\cos \theta = x$ and $\sin \theta = y$

Example

$$\cos\left(\frac{5\pi}{3}\right) = \frac{1}{2} \qquad \sin\left(\frac{5\pi}{3}\right) = -\frac{\sqrt{3}}{2}$$

Inverse Trig Functions

Definition

 $y = \sin^{-1} x$ is equivalent to $x = \sin y$

 $y = \cos^{-1} x$ is equivalent to $x = \cos y$

 $y = \tan^{-1} x$ is equivalent to $x = \tan y$

Inverse Properties

 $\cos(\cos^{-1}(x)) = x \qquad \cos^{-1}(\cos(\theta)) = \theta$

 $\sin(\sin^{-1}(x)) = x \qquad \sin^{-1}(\sin(\theta)) = \theta$

 $\tan(\tan^{-1}(x)) = x \qquad \tan^{-1}(\tan(\theta)) = \theta$

Domain and Range

Function	Domain	Range
$y = \sin^{-1} x$	$-1 \le x \le 1$	$-\frac{\pi}{2} \le y \le \frac{\pi}{2}$
$y = \cos^{-1} x$	$-1 \le x \le 1$	$0 \le y \le \pi$

 $y = \tan^{-1} x$ $-\infty < x < \infty$ $-\frac{\pi}{2} < y < \frac{\pi}{2}$

Alternate Notation

 $\sin^{-1} x = \arcsin x$

 $\cos^{-1} x = \arccos x$

 $\tan^{-1} x = \arctan x$

Law of Sines, Cosines and Tangents



Law of Sines

$$\frac{\sin \alpha}{\alpha} = \frac{\sin \beta}{h} = \frac{\sin \beta}{c}$$

Law of Cosines

$$a^{2} = b^{2} + c^{2} - 2bc \cos \alpha$$

$$b^{2} = a^{2} + c^{2} - 2ac \cos \beta$$

$$c^{2} = a^{2} + b^{2} - 2ab \cos \gamma$$

Mollweide's Formula

$$\frac{a+b}{c} = \frac{\cos\frac{1}{2}(\alpha-\beta)}{\sin\frac{1}{2}\gamma}$$

Law of Tangents

$$\frac{a-b}{a+b} = \frac{\tan\frac{1}{2}(\alpha-\beta)}{\tan\frac{1}{2}(\alpha+\beta)}$$

$$\frac{b-c}{b+c} = \frac{\tan\frac{1}{2}(\beta-\gamma)}{\tan\frac{1}{2}(\beta+\gamma)}$$

$$\frac{a-c}{a+c} = \frac{\tan\frac{1}{2}(\alpha-\gamma)}{\tan\frac{1}{2}(\alpha+\gamma)}$$

15 Dynamic Programming - Problems collection

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