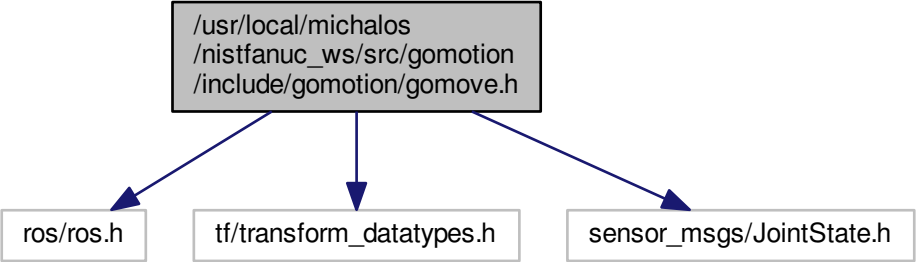


/usr/local/michalos
/nistfanuc_ws/src/gomotion
/include/gomotion/gomove.h



```
graph TD; A["/usr/local/michalos  
/nistfanuc_ws/src/gomotion  
/include/gomotion/gomove.h"] --> B["ros/ros.h"]; A --> C["tf/transform_datatypes.h"]; A --> D["sensor_msgs/JointState.h"];
```

ros/ros.h

tf/transform_datatypes.h

sensor_msgs/JointState.h