view_frames Result Recorded at time: 1130.307 base_link world gripper_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /link1_broadcaster Broadcaster: /robot_state_publisher Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 10.200 Hz Most recent transform: 1130.276 (0.031 sec old) Most recent transform: 1130.276 (0.031 sec old) Most recent transform: 1130.276 (0.031 sec old) Most recent transform: 1130.356 (-0.049 sec old) Buffer length: 4.920 sec Buffer length: 4.920 sec Buffer length: 4.920 sec Buffer length: 4.804 sec link_1 left_gripper_finger_link base_footprint right_gripper_finger_link Broadcaster: /robot_state_publisher Average rate: 50.203 Hz Most recent transform: 1130.276 (0.031 sec old) Buffer length: 4.920 sec link_2 Broadcaster: /robot_state_publisher Average rate: 50.203 Hz Most recent transform: 1130.276 (0.031 sec old) Buffer length: 4.920 sec link_3 Broadcaster: /robot_state_publisher Average rate: 50.203 Hz Most recent transform: 1130.276 (0.031 sec old) Buffer length: 4.920 sec link_4 Broadcaster: /robot_state_publisher Average rate: 50.203 Hz Most recent transform: 1130.276 (0.031 sec old) Buffer length: 4.920 sec link_5 Broadcaster: /robot_state_publisher Average rate: 50.203 Hz Most recent transform: 1130.276 (0.031 sec old) Buffer length: 4.920 sec