

- [4.0K] **asl\_gremlin\_msgs**
  - [6.8K] CMakeLists.txt
  - [4.0K] **include**
    - [4.0K] **asl\_gremlin\_msgs**
    - [4.0K] **msg**
      - [ 36] MotorAngVel.msg
      - [ 44] MotorCmd.msg
      - [ 36] MotorPwm.msg
      - [ 145] RefTraj.msg
      - [ 48] VehicleState.msg
  - [2.5K] package.xml
  - [4.0K] **src**
- [4.0K] **asl\_gremlin\_pkg**
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  - [4.0K] **config**
    - [ 656] rover\_parameters.yaml
  - [4.0K] **include**
    - [4.0K] **asl\_gremlin\_pkg**
      - [1.4K] GetParam.h
      - [1.3K] SubscribeTopic.h
  - [4.0K] **launch**
    - [1.9K] asl\_gremlin\_launch.launch
  - [2.3K] package.xml
  - [4.0K] **src**
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      - [ 678] GetParam.cpp
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- [4.0K] **controller**
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    - [ 733] **controllerGainSet.cfg**
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    - [4.0K] **controller**
      - [2.8K] BackSteppingController.h
      - [5.5K] BackSteppingController\_main.h
      - [ 525] ControllerBase.h
      - [3.6K] controller\_utilities.h
      - [8.1K] **hdg\_correct\_final\_v2.txt**
      - [ 715] OmegaToPWM.h
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    - [1.8K] backstepping\_controller\_node.cpp
    - [4.0K] **controller**
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      - [ 39] ControllerBase.cpp
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- [4.0K] **state\_feedback**
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    - [ 797] **feedbackSelect.cfg**
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      - [1.4K] EncoderDataToOmega.h
      - [4.2K] FeedbackSelected.h
      - [ 914] ForwardEuler.h
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      - [6.5K] vector\_arithmetic.h
  - [2.7K] package.xml
  - [4.0K] **src**
    - [2.2K] encoder\_data\_stamped.cpp
    - [1.5K] encoder\_data\_to\_omega.cpp
    - [3.7K] encoder\_to\_pose.cpp
    - [ 487] feedback\_selected.cpp
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    - [4.0K] **state\_feedback**
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- [4.0K] **test\_asl\_gremlin**
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  - [4.0K] **include**
    - [4.0K] **test\_asl\_gremlin**
  - [4.0K] **launch**
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  - [2.8K] package.xml
  - [4.0K] **src**
    - [4.0K] **cpp\_output\_data**
      - [6.8K] converted\_encoder\_to\_omega.dat
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    - [ 17K] **omega\_from\_encoder.txt**
    - [ 19K] **pose\_encoder.txt**
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- [4.0K] **trajectory\_generation**
  - [4.0K] **cfg**
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  - [4.0K] **include**
    - [4.0K] **trajectory\_generation**
      - [ 691] DistanceToWaypoint.h
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  - [4.0K] **launch**
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    - [4.0K] **trajectory\_generation**
      - [1.2K] DistanceToWaypoint.cpp
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- [ 0] tree\_view.html
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- [4.0K] **utility\_pkg**
  - [6.8K] CMakeLists.txt
  - [4.0K] **include**
    - [4.0K] **utility\_pkg**
      - [ 656] CmdArgParser.h
      - [1.3K] custom\_algorithms.h
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  - [4.0K] **src**
    - [4.0K] **utility\_pkg**
      - [1.8K] CmdArgParser.cpp
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