

```
graph LR; A[QNode::run] --> B[QNode::rosShutdown];
```

QNode::rosShutdown

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'QNode::rosShutdown'. The box on the right is white and contains the text 'QNode::run'. A dark blue arrow points from the right side of the white box to the left side of the gray box, indicating a call or relationship from 'QNode::run' to 'QNode::rosShutdown'.

QNode::run