

PathPlanner::get_knots
_marker



```
graph RL; QNode_run[QNode::run] --> PathPlanner_get_knots_marker[PathPlanner::get_knots_marker];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The box on the left is shaded gray and contains the text 'PathPlanner::get_knots' on the top line and '_marker' on the bottom line. The box on the right is white and contains the text 'QNode::run'. A dark blue arrow points from the right side of the white box to the left side of the gray box.

QNode::run