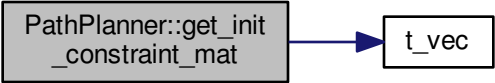


PathPlanner::get_init
_constraint_mat



```
graph LR; A[PathPlanner::get_init_constraint_mat] --> B[t_vec]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is gray with a black border and contains the text 'PathPlanner::get_init' on the top line and '_constraint_mat' on the bottom line. The right box is white with a black border and contains the text 't_vec'. A blue arrow points from the right side of the gray box to the left side of the white box.

t_vec