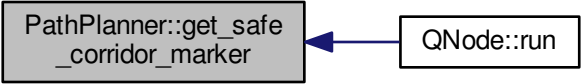


PathPlanner::get\_safe  
\_corridor\_marker



```
graph LR; QNode[QNode::run] --> PathPlanner[PathPlanner::get_safe_corridor_marker];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The box on the left is shaded gray and contains the text 'PathPlanner::get\_safe' on the top line and '\_corridor\_marker' on the bottom line. The box on the right is white and contains the text 'QNode::run'. A dark blue arrow points from the right side of the white box to the left side of the gray box.

QNode::run