

电原复习

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L08 Port

- Port
Two terminals s.t. the current flowing into one terminal equals to one flowing out of the other.
An abstract notion, to simplify as we only focus on:
Port condition
- Passive/active one-port
$$\int_0^t u(\tau)i(\tau)d\tau \geq 0 (\forall t) \text{ or } < 0 (\exists t)$$

Passive/active sign convention

L16 Equivalent Resistance of two-terminal network

- Solution Process
 - 1st. Serial/Parallel
 - 2nd. Balanced Bridge
 - 3rd. Δ -Y Transform
 - 4th. u->i/i->u method

L55 Serial RLC Second-order Circuits

- Review
$$\frac{dx}{dt} + 2x = 0, x = Ae^{-2t}$$

$$\frac{dx}{dt} + 2x = t^2, x = x' + x'' = (Ae^{-2t}) + (Bt^2 + Ct + D)$$
- Math
$$\frac{d^2x}{dt^2} + 3\frac{dx}{dt} + 2x = 0, x = Ae^{-2t} + Be^{-t}$$

$$(A + Bt)e^{-\lambda t}$$

U+ -> output eqn

L61 Phasor

"Vector with information of phase"

- Introduction
Charles Steinmetz: father of phasor method
- Review of Complex Numbers
 $A = |A|e^{j\theta} = |A|\angle\theta$
 $A_1 \cdot A_2 = |A_1||A_2|\angle(\psi_1 + \psi_2)$
- Representing Sinusoids with Complex Numbers
rms: effective value don't forget to divide sqrt2
initial: initial angle
- Calculation of phasors
- Why Phasor Matters
SSS: sinusoidal steady state analysis

L62 Phasor Form of Circular Constraints

- Topological Constraints
直接替换即可
- Element Constraints
 - Resistors
 - Inductors $j\omega = X_L$
 - U leads I 90度
 - Capacitors $X_C = -1/j\omega$ Notice the negative sign
 - I leads U 90度
- Time Domain -> Phasor Domain
ODE -> Algebraic eqns with complex coefficients

L63 Impedance and Admittance

- Impedance
 $Z = R + jX = |Z|\angle\phi$
Phasor graph: reference phasor, head-to-tail (good for solving the circuit)
etc
- Admittance
 $Y = G + jB = |Y|\angle\phi'$

$$Ae^{\lambda t}\cos t + Be^{\lambda t}\sin t = Ke^{\lambda t}\sin(t + \theta)$$

3. ZIR RLC serial circuit

- Equation
$$\frac{d^2u_c}{dt^2} + \frac{R}{L}\frac{du_c}{dt} + \frac{1}{LC}u_c = 0$$

$$\lambda^2 + 2\alpha\lambda + \omega_0^2 = 0$$
- Natural response

$\alpha^2 ? \omega_0^2$	>	=	<	$\alpha = 0$
$\lambda_{1,2}$	$-\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$	$-\alpha$	$-\alpha \pm j\sqrt{\omega_0^2 - \alpha^2}$	$\pm j\omega_0$
u_c	$Ae^{\lambda_1 t} + Be^{\lambda_2 t}$	$Ae^{-\alpha t} + Bte^{-\alpha t}$	$Ke^{-\alpha t}\sin(\omega_d t + \theta)$ $\omega_d = \sqrt{\omega_0^2 - \alpha^2}$	$K\sin(\omega_0 t + \theta)$
	Over-damping	Critical-damping	Under-damping	No-damping

- Numerical examples

L56 Parallel RLC Second-order Circuits

$$\frac{d^2i_L}{dt^2} + \frac{1}{RC}\frac{di_L}{dt} + \frac{1}{LC}i_L = 0$$

Use duality

L57 Intuitive method for second-order circuits

- State Equation and Output Equations
Set u_c and i_L as state variables
Use u_c , i_L (and u_s) to express u_L , i_C - State eqn (ODE)
Other variables expressed - Output eqn (algebraic)
- Substitution Method for State Equations and Output Equations
- State Equation -> Characteristic Equation
 $|sI - A|$
- Output Equation -> Initial Value of the First-order Differentiation
- Three Elements Method for Second-order Circuits
Find ZSR (using substitution method)
广义三要素:
How -> state eqn
 ∞ -> output eqn

- Impedance and Admittance
 $Z = \frac{1}{Y} (R \neq \frac{1}{G}, X \neq \frac{1}{B})$
- Serial/parallel Connection
- Phasor Graph
- Z Matrix and Y Matrix

L64 Phasor Method for Sinusoidal Steady State Circuits

7 example problems

L65 Instantaneous Power

- Why NOT multiply directly?
The result is not physical, i.e. has no physical meaning
- Definition
 $p_a = ui$
- Resistors
 $i(t) = \sqrt{2}I\sin\omega t, u(t) = \sqrt{2}U_R\sin\omega t$
 $p_a(t) = u(t)i(t) = 2U_RI\sin^2\omega t = U_RI(1 - \cos 2\omega t) \geq 0$
- Inductors
 $i(t) = \sqrt{2}I\sin\omega t, u(t) = \sqrt{2}U_L\sin(\omega t + 90^\circ)$
 $p_a(t) = u(t)i(t) = 2U_LI\sin\omega t\cos\omega t = U_LI(\sin 2\omega t)$
- Capacitors consider duality, different reference initial angle
 $u(t) = \sqrt{2}U\sin\omega t, i(t) = \sqrt{2}I_C\sin(\omega t + 90^\circ)$
 $p_a(t) = u(t)i(t) = 2U I_C\sin\omega t\cos\omega t = U I_C(\sin 2\omega t)$
- Any one-port
 $u(t) = \sqrt{2}U\sin\omega t, i(t) = \sqrt{2}I\sin(\omega t - \phi)$
 $p_a(t) = u(t)i(t) = 2UI\sin\omega t\sin(\omega t - \phi)$
 $= UI\cos\phi - UI\cos(2\omega t - \phi)$
 $p_a(t) = UI\cos\phi - UI\cos(2\omega t - \phi)$
Constant Reversible
 $p_a(t) = UI\cos\phi(1 - \cos 2\omega t) - UI\sin\phi\sin 2\omega t$
Irreversible Reversible

L66 Average Power

L60 Average Power

1. Average Power
 $UI\cos\phi$ power factor; power factor angle
Only consumed on resistor
 $X > 0, \phi > 0$, lag, inductive
 $X > 0, \phi > 0$, lead, capacitive
2. Wattmeter measuring active power
 $\phi = \psi_u - \psi_i$
3. Maximum Power Transfer
Conjugate match $Z_L = Z_i^*$

L67 Reactive Power and Apparent Power

1. Reactive Power
 $UI\sin\phi$, var(voltage ampere reactive)
R: $Q = UI\sin\phi = 0$
L: $Q_L = UI\sin\phi = -UI$
C: $Q_C = UI\sin\phi = UI$
Maximum energy exchange rate
2. Apparent Power
 $S = UI$, va
Power supplies' ability to provide power
3. Increase the power factor
To decrease I along the transmission line when U at user end remain constant

L68 Complex Power

Derived from exponential functions
 $\vec{S} = \vec{U}\vec{I}^* = P + jQ$
Conservation of complex/reactive/active power

L69 Mutual inductance and mutual voltage

$$k = \frac{M}{\sqrt{L_1 L_2}} \leq 1$$

L70 Dot convention

$$\frac{j\omega M}{Z_{11}} \vec{I}_1, \frac{(\omega M)^2}{Z_{11}} Z_{22}$$

- c) Decoupled 在电机学中所采用的主要电路
Impedance converting 🍌

L82 Unity-coupled Transformer

全耦合，无损
(Recall) $L_1 \propto N_1^2, L_2 \propto N_2^2, M \propto N_1 N_2$
Turns ratio $n = N_1/N_2$

$\vec{I}_1 = \frac{\vec{U}_1}{j\omega L_1} - \frac{1}{n} \vec{I}_2$ 相当于还是有一部分要给一个阻抗供电（第一项），剩下的做电流变换（第二项）
 $\vec{U}_1 = n\vec{U}_2$

L83 Ideal Transformer

$\vec{I}_1 = -\frac{1}{n} \vec{I}_2$ 留神这个负号,并定义的电流方向相向流入的
实际应用中，常定义电流一个方向，这样表述简便，于是便没有负号
认为第一项趋近于 ∞ （认为匝数很多，磁导率够大，所以L1够大）

2. Properties of Ideal Transformer
 - a) Impedance converting
 - b) Power consumption

$$p_a = u_1 i_1 + u_2 i_2 = nu_2 \left(-\frac{1}{n} i_2 \right) + u_2 i_2 = 0$$

2. The usage of dot convention

$$u_{21} = M \frac{di_1}{dt}$$

i_1 flowing into the dot $\rightarrow u_{21}$ is positive (from dot to the other terminal)
Can be applied to SSS seamlessly

L80 Decoupling equivalence of mutual inductance

Serial, Parallel, Single point

1. Serial
 - a) Ordinal
 $u = (L_1 + L_2 + 2M) \frac{di}{dt}$
 - b) Reversed
 $u = (L_1 + L_2 - 2M) \frac{di}{dt}$
2. Parallel
构造【去偶】等效电路(分干路电流和指路电流)
 - a) Ordinal M
 - b) Reversed -M
3. Single Point Connection
 - a) M
 - b) -M

E2 use generalized KCL (变压器间引入一条线 \rightarrow 单点连)
4. Decoupling is NOT omnipotent
e.g. If two coils don't have any public terminal
But have electrical connection

L81 Air-core transformer

1. Transformer
Primary side, Secondary side
2. Air-core Transformer
def. $Z_{11} = R_1 + j\omega L_1, Z_{22} = (R_L + R) + j(\omega L_2 + X)$
 - a) Seen from source
Reflected impedance
(total) $Z_{11}, Z_l = \frac{(\omega M)^2}{Z_{22}}$
 - b) Seen from load

电路原理易错点(期中总结)

源变换前后的电阻、电压电流数值
源能不能变

MOSFET数字电路：非！非！非！

小信号电阻是动态电阻

二极管导通时两端电压为零！断路时才“保持原样”(错两遍了！)

Tellegen定理中，“注意参考方向”意指计算时要不都按absorb，要不都按deliver

注意电压标的是哪两端电压！

注意电容换路等效成理想电压源后的参考方向

电流源置零是断路！算等效电阻时易错！
求Req时也尤其注意受控源 严格写出加压求流/加流求压式

注意运放有源 输出端后电流不再可由虚短虚断确定（不要下意识地在运放输出端用KCL！！）

模拟题tip：严格列**KVL**，以防电压升降加減出錯

节点电压/回路电流标准方程，矩阵形式的等式右边(对应常数)也要检查降低笔误

别落“m”“k”（尤其对应于电流、电阻）

注意二端口的囊括范围（前后有没有变化）

接地端 (真正的而非定义的，如运放) 可能有流向地的电流，因此不要在运放外用广义KCL