INTRO TO DEEP LEARNING

SUPERVISED LEARNING

INPUT: X

HOME FEATURES

HIDDEN AYER IAYER OUTPUT AREA LAYER #ROOMS - PRICE 1 IX ATTON WEALTH

NNS CAN DEAL WITH BOTH STRUCTURED & UNSTRUCTURED DATA







STRUCTURED

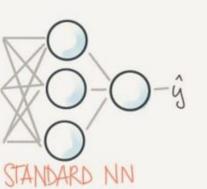
THE QUICK BROWN FOX" UNSTRUCTURED

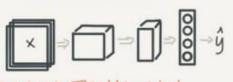
HUMANS ARE 6000 ATTHIS

AD+USER INFO	WILL CLICK ON AD (0/1)	MN
IMA6E	OBJECT (11006)	CONV. NN (CNN)
ANDID ENGLISH	TEXT TRANSCRIPT CHINESE	RECURRENT NN (RNN)
IMAGE/RADAR	POS OF OTHER CARS	CUSTOM/HYBRID

GUTPUT: 9

PRICE



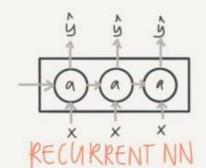


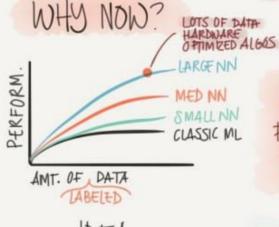
CONVOLUTIONAL NN

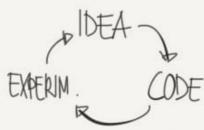
NETWORK ARCHITECTURES

NN TYPE

STANDARD

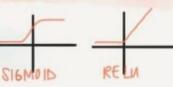






FASTER COMPUTATION IS IMPORTANT TO SPEED UP THE ITERATIVE PROCESS

ONE OF THE RIG BREAKTHRONGED HAS BEEN MOVING FROM SIGMOID TO RELU FOR FASTER GRADIENT DESCENT



C Tessferrandez

TRAIN US DEV/TEST

MISMATCH

AVAILABLE DATA

200 K PROCAT PICS FROM INTERNET

10 K BLURRY CATPICS FROM
APP WHATWE

HOW DO WE SPUT->TRAIN/DEV/TEST?

OPTION 1: SHUFFLE ALL

205 K (TRAIN) D

PROBLEM: DEV/TEST IS NOW

MOSTLY WEB IMB (NOT REPRES.)

SOLUTION: LET DEV/TEST COME FROM APP. THEN SHUTTLE 5K OF APP PICS WEB FOR TRAIN

205 k 25 25

BIAS & VARIANCE W MISMATCHED TRAIN/DEV

HUMANS ~0%
TRAIN 1% &
DEVERR 10%

DUE TO THE MODEL
NOT GENERALIZING
OR IS DEV DIATIA
MUCH HARDER

A: CREATE A TRAIN DEV SET THAT WE DON'T TRAIN ON

TRAIN

DEV	UP%.	TRAINY DEV	12:/·	BIAS+ DATA MISMATCH
TRAIN TRAIN-DEV	9%	1%	0% 1%	10%
	A	B.	(D.

ADDRESSING DATA MISMATCH

EX. CAR GPS · TRAINING DATA IS 10.000H OF GENERAL SPEECH DATA

- 1. CARRY OUT MANUAL ERROR ANALYSIS TO UNDERSTAND THE DIFFERENCE (EX NOWE, STREET NUMBERS)
- 2. TRY TO MAKE TRAIN MOKE SIMILAR TO DEV OR GATHER MORE DEV. LIKE TRAIN. DATA

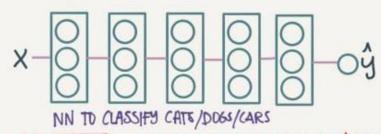


NOTE BE CAREFUL. IF YOU ONLY HAVE 1 HR OF CAR NOISE & APPLY IT TO LOK HR SPEECH YOU MAY OVERFIT TO THE CAR NOISE

EXTENDED LFARNING

RANSFER LEARNING

PROBLEM: YOU WANT TO CLASSIFY SOME MEDICAL IMB. YOU HAVE AN NN THAT CHASSITIES CATS



OPTION 11: YOU ONLY HAVE A FEW RADIOLOGY IMAGES

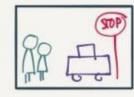
SOLUTION: INIT W. WELGHTS FROM CAT NN ONLY RETRAIN LAST LAYER (S) ON RADIOLOGS

SDUTTON: INIT WITH WEIGHTS FROM CAT NN RETRAIN ALL LAYERS

> THIS IS MICROSOFT CUSTOM VISION

MULTITASK (EARNING TRAINING ON MULT. TASKS AT

ONCE DETECT CAR



UNLIKE SOFMAX . MANY THINGS CAN BE TRUE

SHIMMING OVER ALL

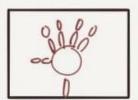
WE COULD HAVE DUST TRAINED 4 NNS INSTEAD BUT .. MT LEARNING MAKES SENSE WHEN

- A. THE LEARNING DATA YOU HAVE FOR THE DIFF TASKS IS QUITE SIMILAR - & THE AMOUNTS (EG. 1K CARS, 1K STOPSIGNS)
- OPTION 2 YOU HAVE LOTS OF RADIOLOGY ING. B. THE SUM OF THE DATA ALLOWS NN TO DO WELL ON ALL TIASKS

IN REALITY TRANSFER LEARNING IS USED MORE OFFEN

END-TO-END LEARNING

FROM X-RAY OF CHILDS HAND TELL ME THE AGE OF THE CHILD



TYPICAL SIW:

- 1. LOCATE BONES TO FIND LENGTHS USING ML
- 2. TRAIN MODEL TO PREDICT AGE BASED ON BONFLENGTH

END-TO-END

RADIOLOGY CHILD AGE IM6

PRDS:

- · I ET'S THE DATA SPEAK (MAYRE IT FINDS RELATIONS WE'RE UNAWARE OF)
- · LESS HAND · DESIGNING OF COMPONENTS NEEDED

CONS:

LABLED · NEEDS LARGE AMISOF YDATA (X->Y)

· EXCLUDES POTENTIALLY USEFUL HAND-MADE COMPONENTS

RUCTURING ML PROJECTS · COURSERA

ERROR ANALYSIS

YOU HAVE ID ? ERRORS, SOME ARE DOGS MISCLASSIFIED AS CATS. SHOULD YOU TRAIN ON MORE DOG PICS?

- 1. PICK 100 MIS-LABLED
- 2. COUNT ERROR REASONS

	D06	BLURY	INSTA- FILER	BUG	***
1	1		1		
2				t	
3		1			
• • •					
100			1		
	5 R	5/0	FALL	ERRO	RS

FOCUSING ON DOGS. THE BEST WE CAN HOPE FOR 18 9.5% ERROR YOU FIND SOME INCORR. LABUED DATA IN THE DEV SET. SHOULD YOU FIX IT?



DL ALGORITHMS ARE PRETTY ROBUST TO RANDOM ERRORS.

BUT NOT TO SYSTEMATIC ERR.

(EX. ALL WHITE CATS INCORR LABLED AS MICE)

ADD EXTRA COL. IN ERROR ANALYSIS AND USE SAME CRITERIA

NOTE IF YOU FIX DEV YOU SHOULD FIX TEST AS WELL.

FOR NEW PROJ.
BUILD IST SYSTEM QUICK
E ITERATE

EX: SPEECH RECOGNITION

M m/mm m

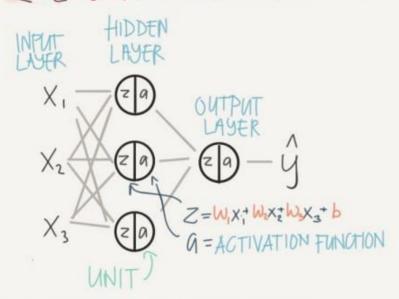
WHAT SHOULD YOU FOCUS ON?

NOISE ACCENTS FAR FROM MIKE

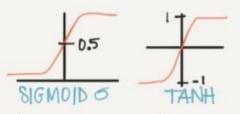
- 1. START QUICKLY DEV/TEST METRICS
- Q. GET TRAIN-SET
- M. TRAIN
 - 4. BIAS/VARIANCE ANAL
 - 5. ERROR ANALYSIS
 - 6. PRIORITIZE NEXT STEP

OTESSFET andez

2 LAYER NEURAL NET



ACTIVATION FUNCTIONS



BINARY CLASSIFIER NORMALIZED - ONLY USED FOR ⇒ GRADIENT OUTPUT LAYER DESCENTIS FASTER SLDW GRAD DESCENT SINCE

SLOPE IS SMALL

FOR LARGE/SMALL VAL



DEFAULT CHOICE FOR ACTI VATION SLOPE = 1/0



AVOIDS UNDEF SLOPE AT @ BUT RARELY USED IN PRACTICE

NEURAL NETS

WHY ACTIVATION FUNCTIONS? EX. WITH NO ACTIVATION - Q = Z

$$a^{\text{Ti}} = Z^{\text{Ti}} = w^{\text{Ti}} \times + b^{\text{Ti}}$$
 LAYER 1
 $a^{\text{Ti}} = Z^{\text{Ti}} = w^{\text{Ti}} \alpha^{\text{Ti}} + b^{\text{Ti}}$ LAYER 2
PLUG IN α^{Ti}

$$Q_{[5]} = M_{[5]} M_{[1]} X + P_{[1]} + P_{[5]}$$

$$= M_{[5]} M_{[1]} X + P_{[1]} + P_{[5]}$$

INITIALIZING W+b

WHAT IF: INIT TO Ø

THIS WILL CANNE ALL THE UNITS TO BE THE SAME AND LEARN EXACILY THE SAME FEATURES

SOLUTION: RANDOM INIT BUT ALSO WANT THEM HIPERPARAM SMALL SO RAND # 0.01

WE COULD & UST AS WELL HAVE SKIPPED THE WHOLE NEURAL NET & USED LIN. REGR.

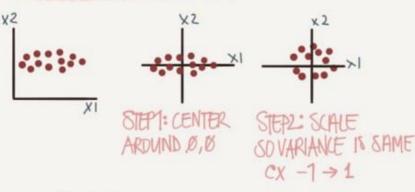
FUNCTION

C Tessferrandez

MPPOVING DEEP NEWRAL NETS-COURSERA

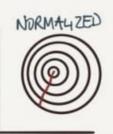
OPTIMIZING TRAINING

NORMAUZING INPUTS



WHY DO WE DO THIS?





IF WE NORMALIZE, WE CAN USE A MUCH LARGER LEARNING RATE OF

DEALING WITH VANISHING/EXPLODING GRADIENTS

Ex: DEEP NW (LIAVERS) $\hat{y} = W^{L-1}W^{L-2} \cdots W^{EX} + b$ IF $W = \begin{bmatrix} 0.5 & 0 \\ 0 & 0.5 \end{bmatrix} \Rightarrow 0.5^{L-1} \Rightarrow VANDHING$ OR $W = \begin{bmatrix} 1.5 & 0 \\ 0 & 1.5 \end{bmatrix} \Rightarrow 1.5^{L-1} \Rightarrow EXPLOYING$

IN BOTH CASES GRADIENT DESCENT TAKES A VERY LONG TIME

PARTIAL SOLUTION: CHOOSE INMAL
VALUES CAREFULLY

WITH Yand * \ \frac{2}{n^2-1} (\frac{1}{12})

#Inputs

XAVIER TANH

SETS THE VARIANCE

GRADIENT CHECKING

IF YOUR COST DOES NOT DECREASE ON EACH ITER YOU MAY HAVE A BACKPROP BUG.

GRADIENT CHECKING APPROXIMATES THE GRADIENTS SO YOU CAN VERIFY CALC.

NOTE ONLY USE WHEN DEBUGGING SINCE IT'S SLOW



STRUCTURING 40 IN ML PRODECTS

SETTING YOUR GOAL

A GOAL SHOULD BE A SINGLE #

	PRELITON		=
A	95%	90%	K) ISA OR
₿	98%	857.	B BEST?

-	PRELITION	REFAIL	1 +1 N	
A	95%	90%	92.4%	A 18
₿	98%	85%	91%	BEST

F1= HARMONIC MEAN BETTO. RECALL & PRECISION

A DEFINE OPTIMIZING VS SATISTICING METRICS

	ACCURACI	PUNTIME
A	90%	80ms
\$(927.)	95ms
C	95%	1500 ms

MAXIMIZE ACC.

GIVEN TIME < | DOMS

A CCURACY =

OPTIMIZING

RUNTIME =

SATISFICING

SELECTING YOUR DEV/TEST SETS

DATA

US

OPTION1:

UK

DEV=UK, US, EUR

TEST= REST

S.AM

INDIA
CHINA
AUST.

IF DEV & TEST ARE DIFF & WE OPTIMIZE FOR DEV WE WILL MISS THE TEST-TARGET

HUMAN LEVEL PERF

MEDICAL IMB CLASS
TYPICAL HUMAN 3%
EXPERIENCED DR. 0.7%
TEAM OF EAP DRS. 0.5%
LEVEL PERF?
THUMAN LEV PRF

(PROJY FOR BAYES)

OFTEN CLOSE TO BAYES

2. A HUMAN CAN NO LONGER HELP IMPROVE (INSIGHTS)

3. DIFFICULT TO ANALYSE BIAS/VARIANCE

CAT CLASSIFICATION

	A	B	BLURRY
HUMAN	17.	7.5%	AVOIDABLE
TRAIN FRR	8%	8./	RIMP
DEV ERR	10%	10%	-VARIANCE
	HOLUS ON BIAS	FOCUS ON VARIAN	[E

HUMAN - TRAIN BIGGER NETW.

| AND DABLE | TRAIN LONGER | BETTER OFT. (RIMEPTOP) |

TRAIN | CHANGE NN ARCH OR HYDERPARAMO

| VARIANCE | MORE DATTA (TRAIN) |

REGULARIZATION | NN ARCHITECTURE

14	A	B	
HUMAN	0.5	0.5	AVOIDABLE
TRAIN FRR	ab	0.3	BINS
DEV ERR	0.8	0.4	VARIANCE
AVOID. BIAS	0.1	? -	DON'T KNO IF WE OVER
			OR IF WE'KE

OPTIONS TO PROCEED ARE

OTESTATANDEZ

Hyperfaram

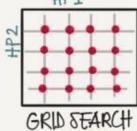
TUNING

WHICH HYPERPARAMS ARE MOST IMPORTANT?

CX LEARNING RATE # HIDDEN UNITS MINIBATCH SIZE 6 MOMENTUM TURN=09 # LAYERS EARNING RATE DECAY b1=0.9 B2=0.999 E=10 8 (ADAM)

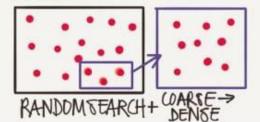
TEUTING VALLUES

CLASSICML



PROBLEM: ONE ITERATION TAKES A LONG TIME & IN 16 GO'S WE HAVE ONLY TRIED 40 - BUT 4 DIFF EX

SOLUTION



USE AN APPROPRIATE SCALE # HIDDEN UNITS UNIFORMLY RANDOM & LEARNING RATE 0. 0.0601 0.001 0.01 r= -4.rand [-4,0] \a= 10" (DEXP WEIGHT AVE 0.999 0.0 r=-3-rand [-3,-17 B= (1-10°) RE-EVALUATE YOUR HYP-PARAMS EVERY FEW MONTHS NOTAS IMPORTANT

CAVIAR PANDA



SPAWN LDTS OF MODELS W DIFF HP

MISC. EXTRAS

BATCH NORMALIZATION

NORMALIZE LAYER DUTPUT

- -SPEEDS UP TRAINING
- MAKES WEIGHTS DEEPER IN NW MORE ROBUST (COVARIATE)
- SUGHT REGULARIZING EFFECT

MULTICLASS CLASSIFIC.

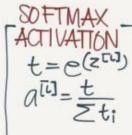




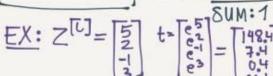




C=#CLASSES=4

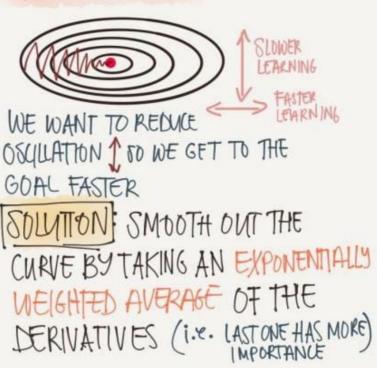


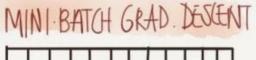




OPTIMIZATION A 160RITHMS JUST A SHORT WHILE

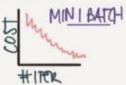
GRADENT DESCENT W. MOMENTUM





SPUT YOUR DATH INTO MINI BATCHES E DO GRAD DESCENT AFTER FACH BATCH THIS WAY YOU CAN PROGRESS AFFER





CHOOSING THE MINIBATCH SIZE

SIZE=M → BATCH GRAD DESC. SIZE=1 → STOCHASTIC GRAD DESC

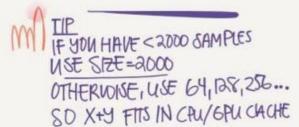


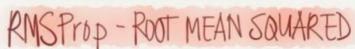
STOCHASTIC

DO LONG

LIDSE ALMUST ALL (FIET) FROM VECTORIBATION

- SHORTITER. - WIFE VECT.







NORMALIZE GRADLENT USING A MOVING AVG.

Saw + (1-15) dw2 Sab = 5 Sab + (1-1) db2

M=M-Xam p=p-xap

ADAM OPTIMIZATION

COMBO OF GD W MOMENTUM & RMSProp

EARNING RATE DECAY

DEA: USE A LARGE X IN THE BEGINNING. THEN DECREASE AS WE GET CLUSTR TO GOAL

OPTION 1: X= 1+DELAYRATE . CACH

EXPONENTIAL: X=0.95 EPOCH

OPTION 3: X = K

OPTION4: X = K XO

OPTIONS: DISCRETE STAIRCASE



OPTON 6: MANUAL

EPOCH=1 PASS THROUGH THE DATIO

O TessFerrandez

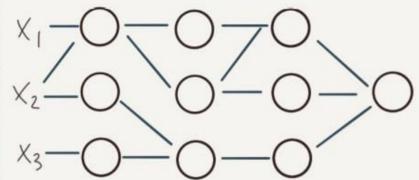
REGULARIZATION PREVENTING OVERFITTING

LZ REGULARIZATION

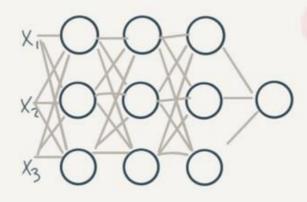
LT. REGULARIZATION

COST: $J(w,b) = \frac{1}{m} \sum_{i=1}^{m} \xi(\hat{y},y) + \frac{\lambda}{m} |w|$

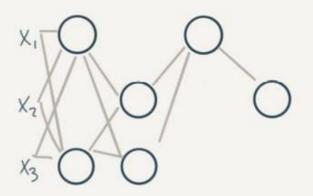
BOTH PENALIZE LARGE WEIGHTS => SOME WILL BE CLOSE TO Ø => SIMPLER NETWORKS



DROPOUT



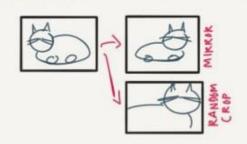
FOR EACH ITERATION & SAMPLE SOME NODES ARE RANDOMLY DROPPED (BASED IN KEEP-PROB)



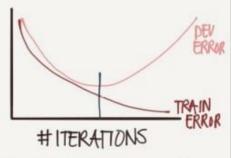
WE GET SIMPLER NWS ELESS CHANCE TO RELY ON SINGLE FEATURES

OTHER REGULARIZATION TECHNIQUES

DATA AUGMENTATION GENERATE NEW PICS FROM EXISTING



EARLY STUPPING



PROBLEM: AFFECTS BOTH BIASE VARIANCE

CHASSIC ML 100-10000 SAMPLES DEEP LEARNING 1M SAMPLES

TRAIN DEV JEST 60% 20% 20%.

TRAIN DT 1/. 1%

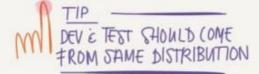
ALL FROM SAME PLACE,
DISTRIBUTION

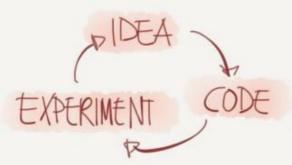
EX:TRAIN



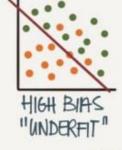








BIAT/VARIANCE







11.7.	16% HIGH	30% HIGH	1%
VARIANCE	RIAS	HIGH BIASE VARIANCE	BIASE VARIANCE
	H16H	H16H H16H	11 % 16% 30%. HIGH HIGH HIGH VARIAN/F BIAS BIAS &

HUMANSGET OZ ERROR

THE ML RECIPE

HIGH

BIGGER NETWORK

TRAIN LONGER

(DIFF NN ARCHITECTURE)



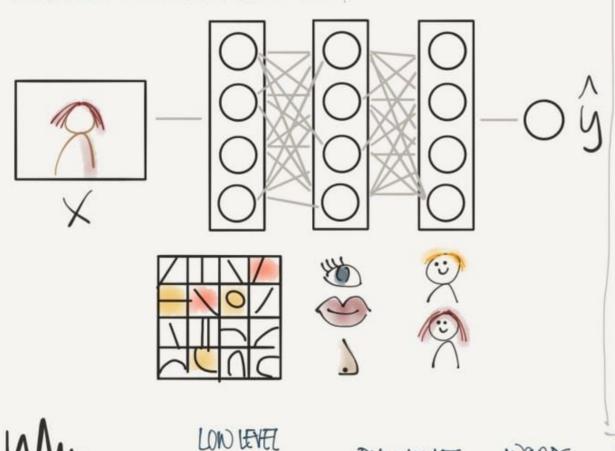
MORE DATA (TRAIN)
REGULARIZATION
(DIFF NN ARCHITECTURE)

OTESTERANDEZ



THERE ARE FUNCTIONS A SMALL DEEP NET GAN COMPLITE THAT SHALDIN NETS NEED EXP. MORE UNITS TO COMP.

WHY DEEP NEURAL NETS?



AMPID WAVE

FEATURES

1 SPICH

VERY DATA HUNGRY

NEED GFS COMPUTER POWER

ALWAYS VECTORIZE

VECTOR MULT-CHEAPER THAN FOR LODDS

COMPUTE ON GPUS

LOTS OF HYPERPARAMS

LEARNING RATE OF

ITERATIONS

HIDDEN LAYERS

HIDDEN UNITS CHOICE OF ACTIVATION MOMENTUM

MINI BATCH SIZE REGULARIZATION

CAT

PHONENES - WORDS - SENTENCES

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