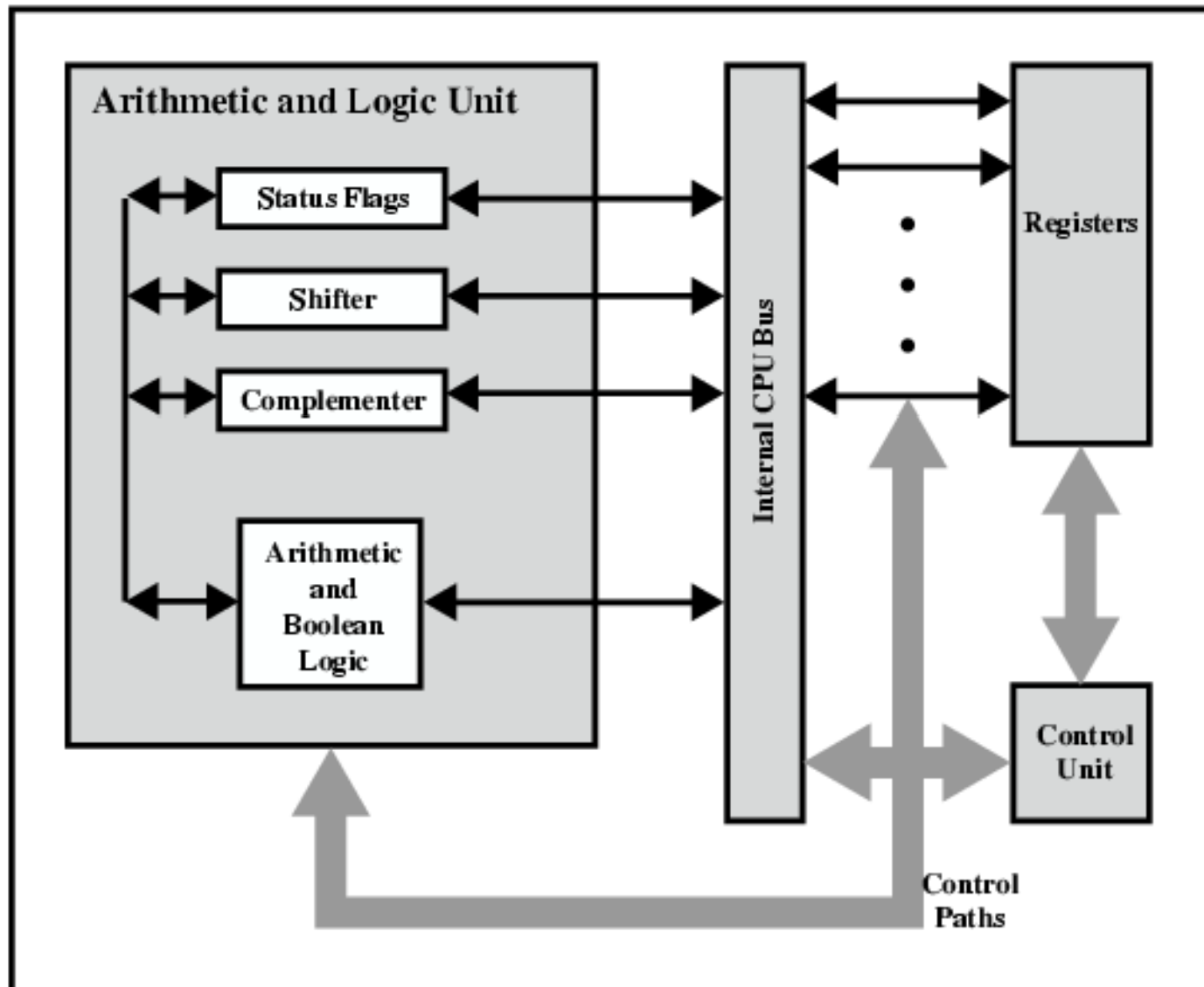


---

# **Instruction Sets: Characteristics and Functions**

# CPU Internal Structure

---



# Registers

---

- CPU must have some working space (temporary storage)
- Called registers
- Number and function vary between processor designs
- One of the major design decisions
- Top level of memory hierarchy

# **User Visible Registers**

---

- General Purpose
- Data
- Address
- Condition Codes

## How Many GP Registers?

---

- Between 8 - 32
- Fewer = more memory references
- More does not reduce memory references and takes up processor space
- Large enough to hold full address
- Large enough to hold full word
- Often possible to combine two data registers
  - C programming
  - double int a;
  - long int a;

## **Control & Status Registers**

---

- Program Counter
- Instruction Decoding Register
- Memory Address Register
- Memory Buffer Register

# Condition Code Registers

---

- Sets of individual bits
  - e.g. result of last operation was zero
- Can be read (implicitly) by programs
  - e.g. Jump if zero
- Can not (usually) be set by programs
- Needs for conditional instructions

## **Program Status Word**

---

- A set of bits
- Includes Condition Codes
- Sign of last result
- Zero
- Carry
- Equal
- Overflow
- Interrupt enable/disable
- Supervisor



## **Function of Control Unit**

---

- For each operation a unique code is provided
  - e.g. ADD, MOVE
- A hardware segment accepts the code and issues the control signals

# **What is an Instruction Set?**

---

- The complete collection of instructions that are understood by a CPU
- Machine Code
  - Binary
- Usually represented by assembly codes

# Elements of an Instruction

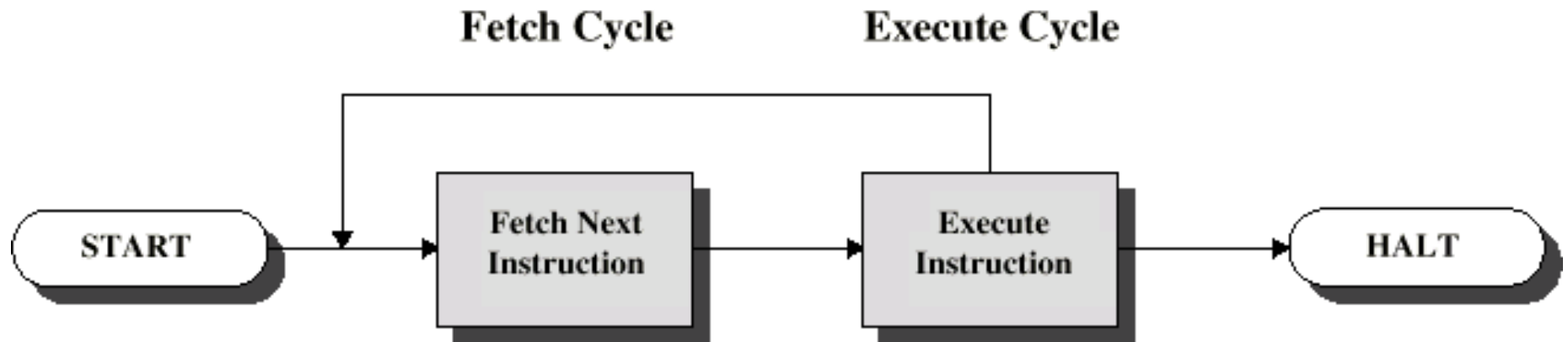
---

- Operation code (Op code)
  - Do this
- Source Operand reference
  - To this
- Result Operand reference
  - Put the answer here
- Next Instruction Reference
  - When you have done that, do this...

# Instruction Cycle

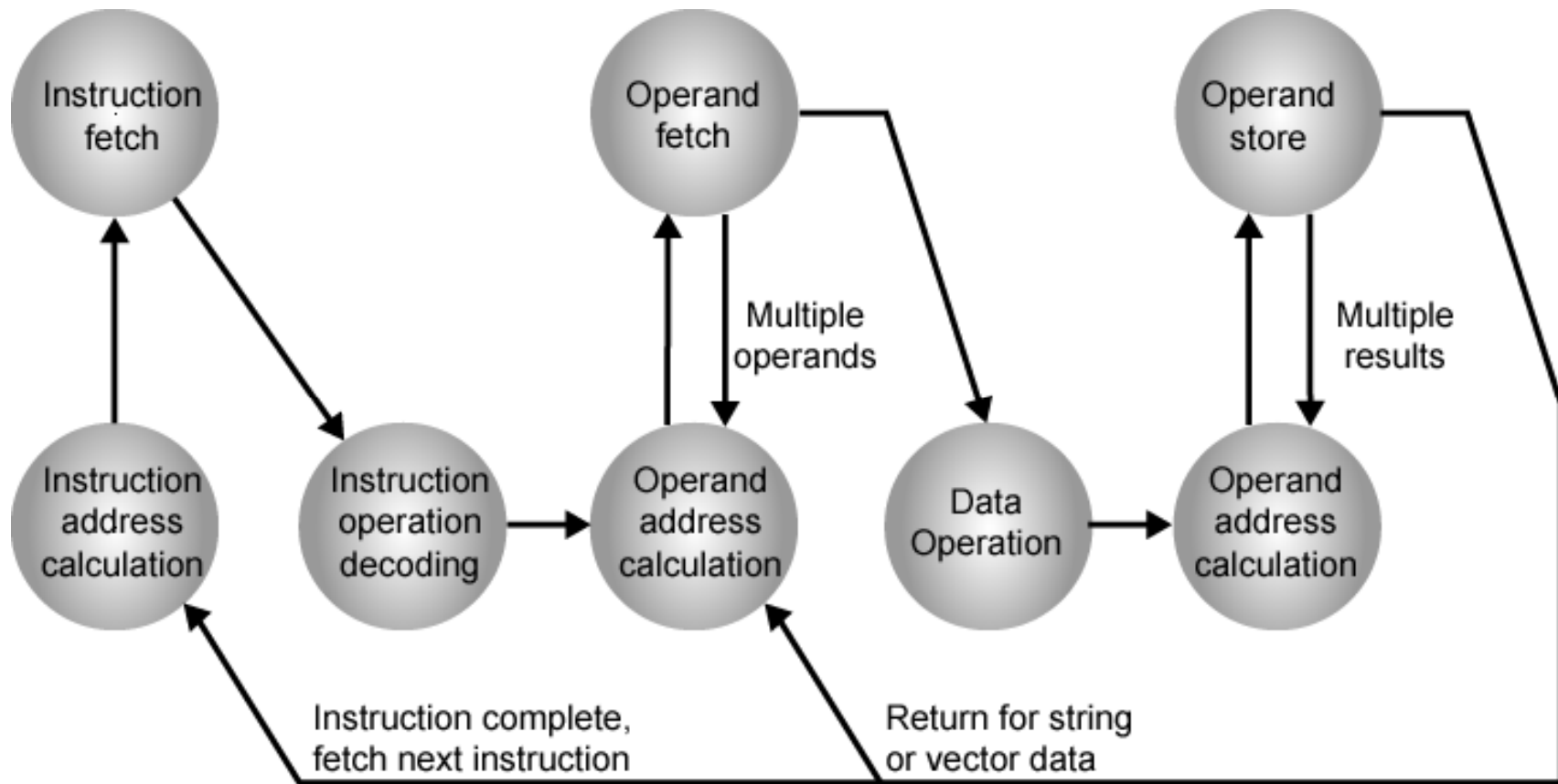
---

- Two steps:
  - Fetch
  - Execute

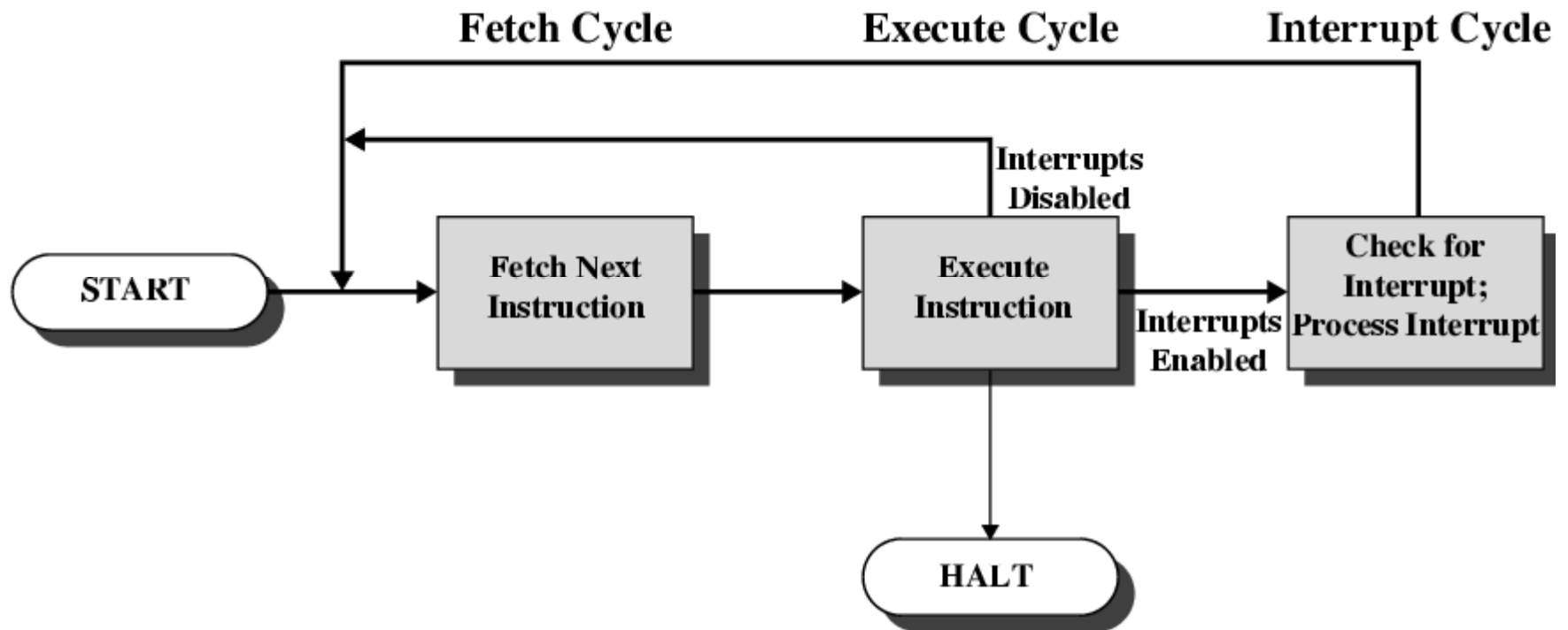


# Instruction Cycle State Diagram

---

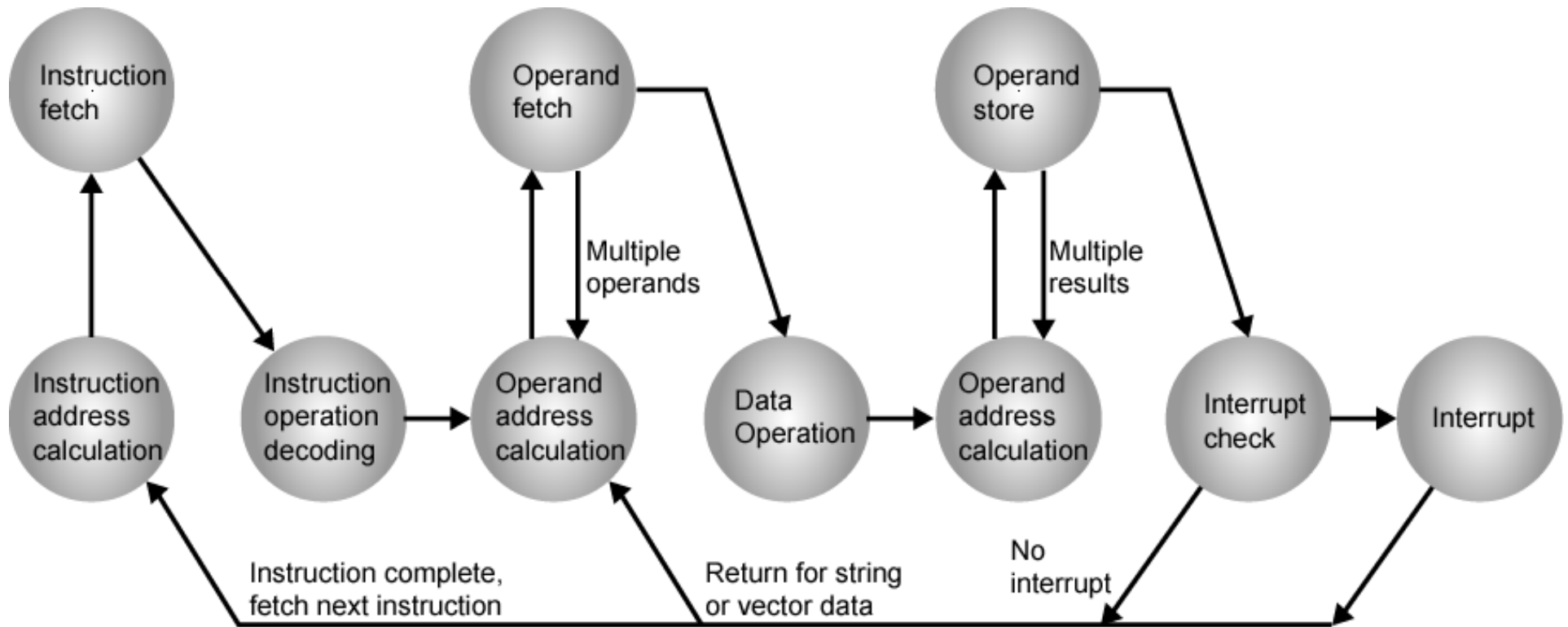


# **Instruction Cycle with Interrupts**



# Instruction Cycle (with Interrupts) - State Diagram

---



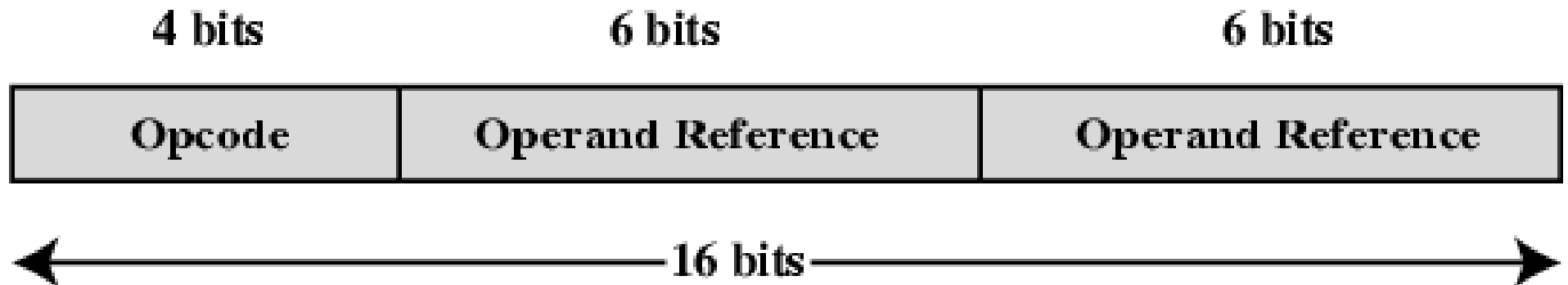
# Instruction Representation

---

- In machine code each instruction has a unique bit pattern
- For human consumption (well, programmers anyway) a symbolic representation is used
  - e.g. ADD, SUB, LOAD
- Operands can also be represented in this way
  - ADD A,B



# **Simple Instruction Format**



# **Instruction Types**

---

- Data processing
- Data storage (main memory)
- Data movement (I/O)
- Program flow control

## Number of Addresses (a)

---

- 3 addresses
  - Operand 1, Operand 2, Result
  - $a = b + c;$
  - May be a forth - next instruction (usually implicit)
  - Not common
  - Needs very long words to hold everything

## Number of Addresses (b)

---

- 2 addresses
  - One address doubles as operand and result
  - $a = a + b$
  - Reduces length of instruction
  - Requires some extra work
    - Temporary storage to hold some results

## **Number of Addresses (c)**

---

- 1 address
  - Implicit second address
  - Usually a register (accumulator)
  - Common on early machines

# Number of Addresses (d)

Instruction		Comment
SUB	Y, A, B	$Y \leftarrow A - B$
MPY	T, D, E	$T \leftarrow D \times E$
ADD	T, T, C	$T \leftarrow T + C$
DIV	Y, Y, T	$Y \leftarrow Y \div T$

(a) Three-address instructions

Instruction		Comment
MOVE	Y, A	$Y \leftarrow A$
SUB	Y, B	$Y \leftarrow Y - B$
MOVE	T, D	$T \leftarrow D$
MPY	T, E	$T \leftarrow T \times E$
ADD	T, C	$T \leftarrow T + C$
DIV	Y, T	$Y \leftarrow Y \div T$

(b) Two-address instructions

Instruction		Comment
LOAD	D	$AC \leftarrow D$
MPY	E	$AC \leftarrow AC \times E$
ADD	C	$AC \leftarrow AC + C$
STOR	Y	$Y \leftarrow AC$
LOAD	A	$AC \leftarrow A$
SUB	B	$AC \leftarrow AC - B$
DIV	Y	$AC \leftarrow AC \div Y$
STOR	Y	$Y \leftarrow AC$

(c) One-address instructions

Figure 10.3 Programs to Execute  $Y = \frac{A - B}{C + (D \times E)}$

## Number of Addresses (e)

---

- 0 (zero) addresses
  - All addresses implicit
  - Uses a stack
  - e.g. push a
  - push b
  - add
  - pop c
  - $c = a + b$

# How Many Addresses

---

- More addresses
  - More complex instructions
  - More registers
    - Inter-register operations are quicker
  - Fewer instructions per program
- Fewer addresses
  - Less complex instructions
  - More instructions per program
  - Faster fetch/execution of instructions



# Design Decisions (1)

---

- Operation repertoire
  - How many ops?
  - What can they do?
  - How complex are they?
- Data types
- Instruction formats
  - Length of op code field
  - Number of addresses

## **Design Decisions (2)**

---

- Registers
  - Number of CPU registers available
  - Which operations can be performed on which registers?
- Addressing modes

# Types of Operand

---

- Addresses
- Numbers
  - Integer/floating point
- Characters
  - ASCII etc.
- Logical Data
  - Bits or flags

## **Specific Data Types**

---

- General - arbitrary binary contents
- Integer - single binary value
- Ordinal - unsigned integer
- Unpacked BCD - One digit per byte
- Packed BCD - 2 BCD digits per byte
- Near Pointer - 32 bit offset within segment
- Bit field
- Byte String
- Floating Point

# **Types of Operation**

---

- Data Transfer
- Arithmetic
- Logical
- Conversion
- I/O
- System Control
- Transfer of Control

# Data Transfer

---

- Specify
  - Source
  - Destination
  - Amount of data
- May be different instructions for different movements
  - e.g. IBM 370
- Or one instruction and different addresses
  - e.g. VAX

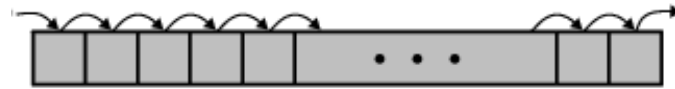
# Arithmetic

---

- Add, Subtract, Multiply, Divide
- Signed Integer
- Floating point
- May include
  - Increment (`a++`)
  - Decrement (`a--`)
  - Negate (`-a`)

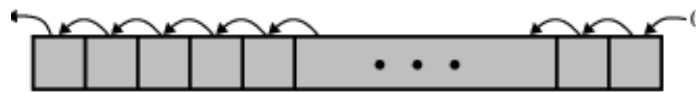
# Shift and Rotate Operations

---



(a) Logical right shift

SHR



(b) Logical left shift

SHL



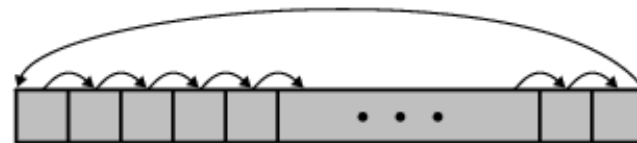
(c) Arithmetic right shift

ASR



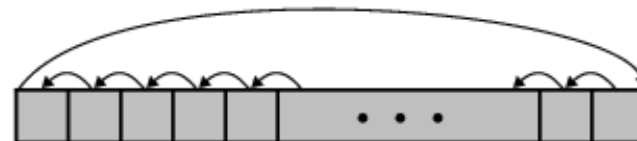
(d) Arithmetic left shift

ASL



(e) Right rotate

ROR



(f) Left rotate

ROL



# Logical

---

- Bitwise operations
- AND, OR, NOT

# **Input/Output**

---

- May be specific instructions
- May be done using data movement instructions (memory mapped)
- May be done by a separate controller (DMA)

# **Systems Control**

---

- Privileged instructions
- CPU needs to be in specific state
- For operating systems use

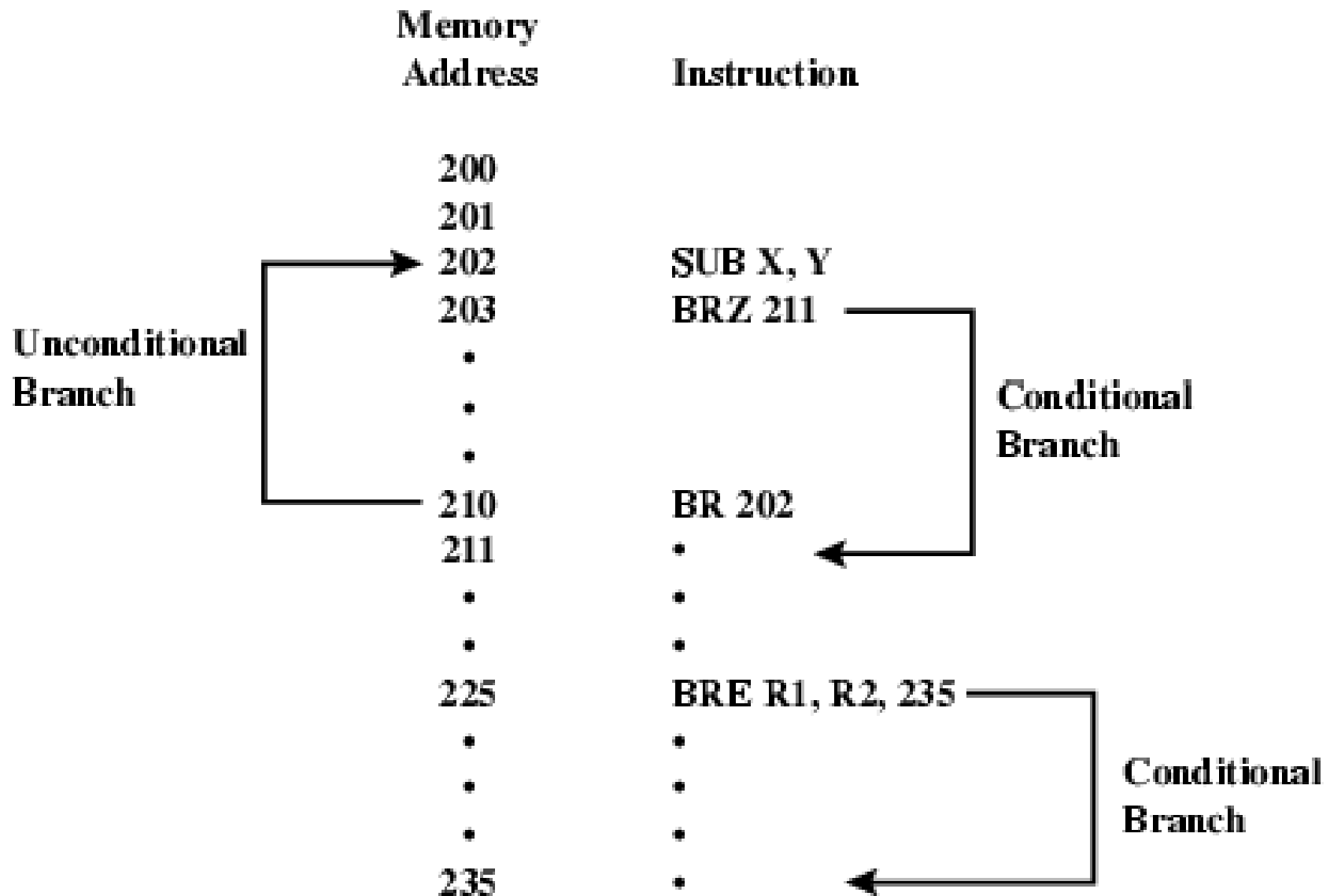
# Transfer of Control

---

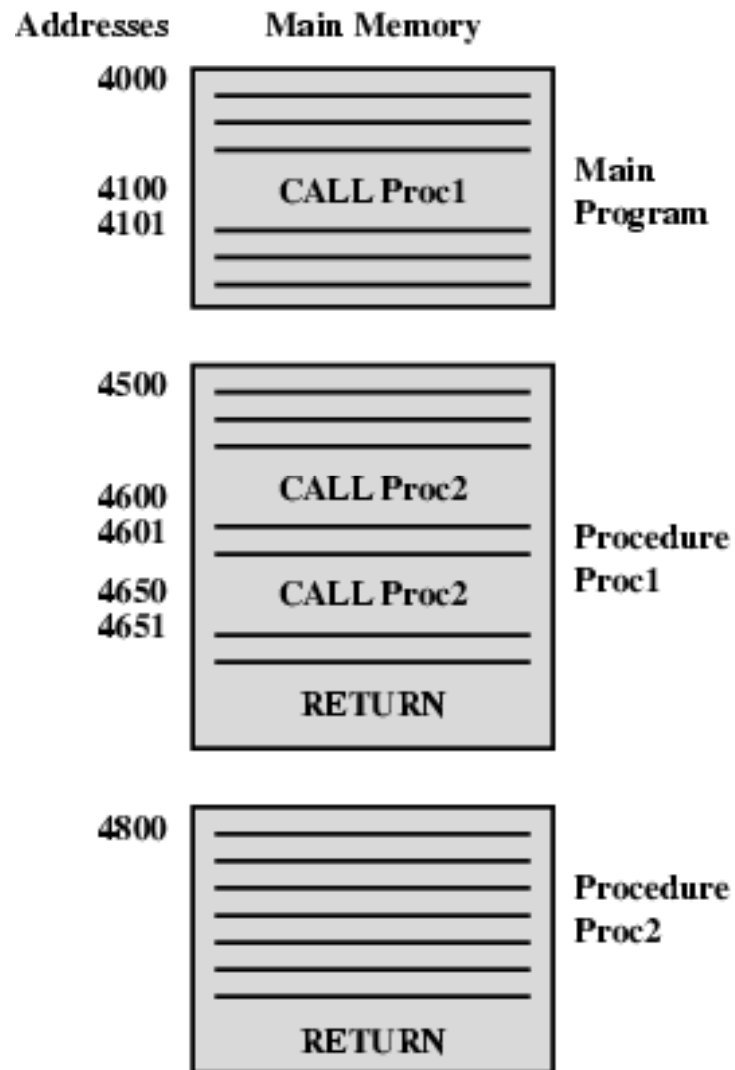
- Branch
  - e.g. branch to x if result is zero
- Skip
  - e.g. increment and skip if zero
  - ISZ Register1
  - Branch xxxx
  - ADD A
- Subroutine call
  - c.f. interrupt call

# Branch Instruction

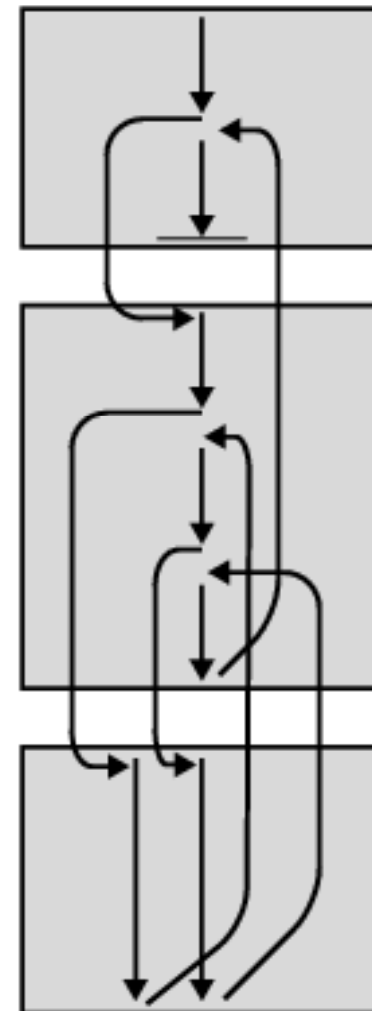
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# Nested Procedure Calls



(a) Calls and returns



(b) Execution sequence

# Byte Order

---

- What order do we read numbers that occupy more than one byte
- e.g. (numbers in hex to make it easy to read)
- 12345678 can be stored in 4x8bit locations as follows

## Byte Order (example)

---

- | • Address | Value (1) | Value(2) |
|-----------|-----------|----------|
| • 184     | 12        | 78       |
| • 185     | 34        | 56       |
| • 186     | 56        | 34       |
| • 187     | 78        | 12       |
- i.e. read top down or bottom up?



## Byte Order Names

---

- The problem is called Endian
- The system on the right has the least significant byte in the lowest address
  - This is called little-endian
- The system on the left has the least significant byte in the highest address
  - This is called big-endian

# Example of C Data Structure

```

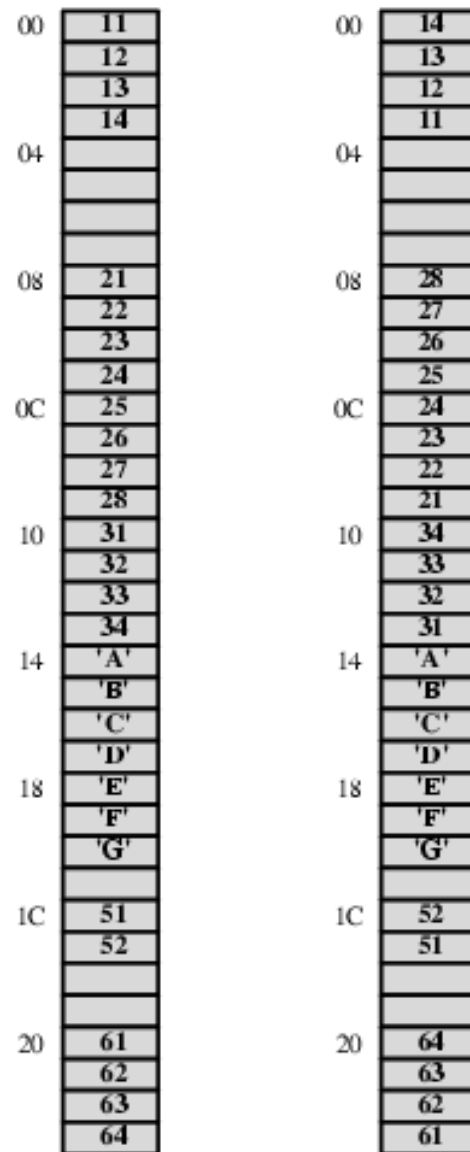
struct{
    int      a;      //0x1112_1314           word
    int      pad;    //
    double   b;      //0x2122_2324_2526_2728  doubleword
    char*    c;      //0x3132_3334           word
    char     d[7];   //'A','B','C','D','E','F','G' byte array
    short    e;      //0x5152           halfword
    int      f;      //0x6161_6364           word
} s;
  
```

Big-endian address mapping																	
Byte Address																	
00	<table><tr><td>11</td><td>12</td><td>13</td><td>14</td><td colspan="4"></td></tr><tr><td>00</td><td>01</td><td>02</td><td>03</td><td>04</td><td>05</td><td>06</td><td>07</td></tr></table>	11	12	13	14					00	01	02	03	04	05	06	07
	11	12	13	14													
00	01	02	03	04	05	06	07										
08	<table><tr><td>21</td><td>22</td><td>23</td><td>24</td><td>25</td><td>26</td><td>27</td><td>28</td></tr><tr><td>08</td><td>09</td><td>0A</td><td>0B</td><td>0C</td><td>0D</td><td>0E</td><td>0F</td></tr></table>	21	22	23	24	25	26	27	28	08	09	0A	0B	0C	0D	0E	0F
	21	22	23	24	25	26	27	28									
08	09	0A	0B	0C	0D	0E	0F										
10	<table><tr><td>31</td><td>32</td><td>33</td><td>34</td><td>'A'</td><td>'B'</td><td>'C'</td><td>'D'</td></tr><tr><td>10</td><td>11</td><td>12</td><td>13</td><td>14</td><td>15</td><td>16</td><td>17</td></tr></table>	31	32	33	34	'A'	'B'	'C'	'D'	10	11	12	13	14	15	16	17
	31	32	33	34	'A'	'B'	'C'	'D'									
10	11	12	13	14	15	16	17										
18	<table><tr><td>'E'</td><td>'F'</td><td>'G'</td><td></td><td>51</td><td>52</td><td colspan="2"></td></tr><tr><td>18</td><td>19</td><td>1A</td><td>1B</td><td>1C</td><td>1D</td><td>1E</td><td>1F</td></tr></table>	'E'	'F'	'G'		51	52			18	19	1A	1B	1C	1D	1E	1F
	'E'	'F'	'G'		51	52											
18	19	1A	1B	1C	1D	1E	1F										
20	<table><tr><td>61</td><td>62</td><td>63</td><td>64</td><td colspan="4"></td></tr><tr><td>20</td><td>21</td><td>22</td><td>23</td><td colspan="4"></td></tr></table>	61	62	63	64					20	21	22	23				
	61	62	63	64													
20	21	22	23														

Little-endian address mapping								Byte Address
				11	12	13	14	00
07	06	05	04	03	02	01	00	
21	22	23	24	25	26	27	28	08
0F	0E	0D	0C	0B	0A	09	08	
'D'	'C'	'B'	'A'	31	32	33	34	10
17	16	15	14	13	12	11	10	
		51	52		'G'	'F'	'E'	18
1F	1E	1D	1C	1B	1A	19	18	
				61	62	63	64	20
				23	22	21	20	

# Alternative View of Memory Map

---



## **Standard...What Standard?**

---

- Pentium (80x86), VAX are little-endian
- IBM 370, Motorola 680x0 (Mac), and most RISC are big-endian
- Internet is big-endian