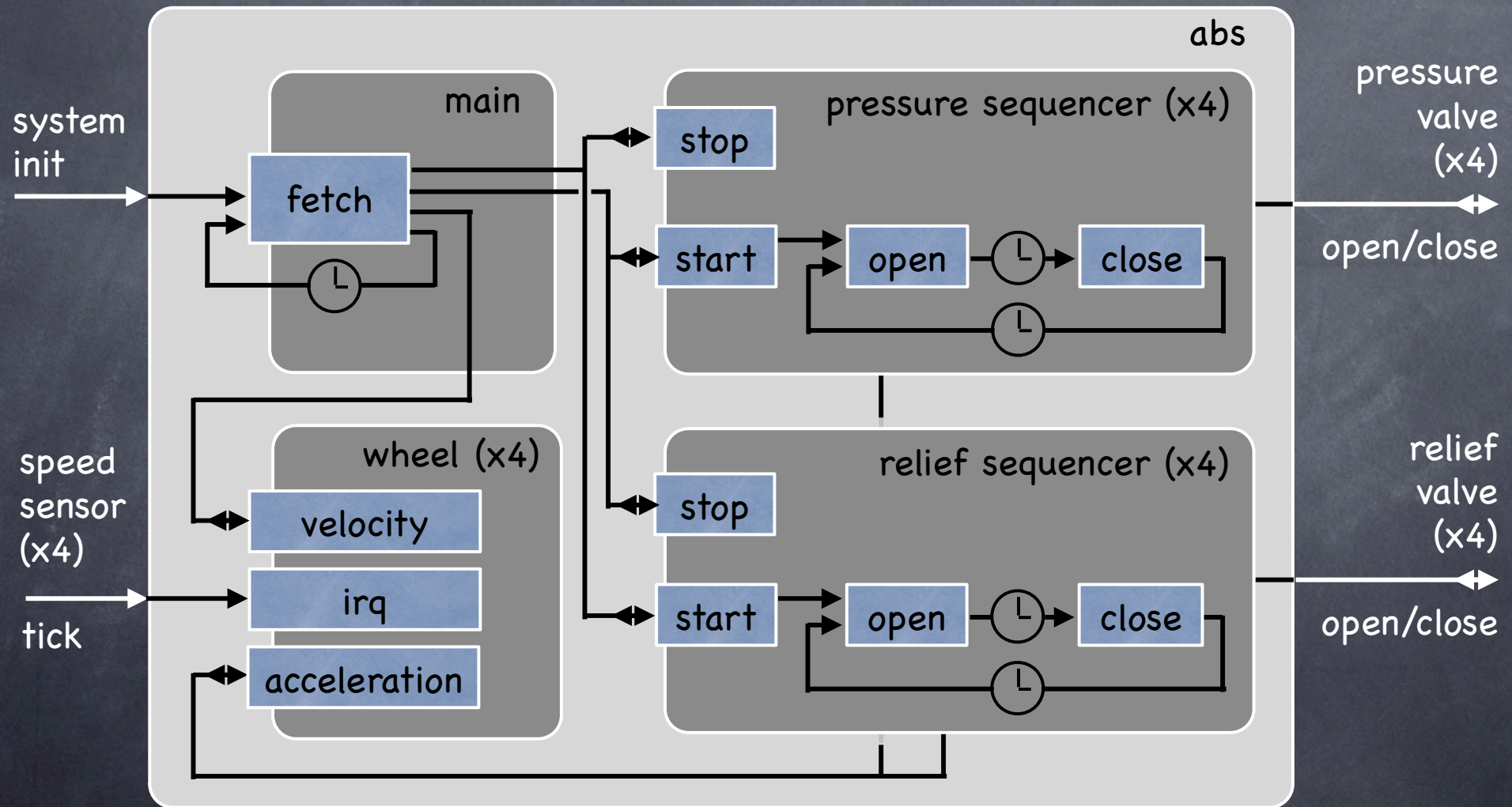


An ABS in Timber



An ABS in Timber

relief wheel valve = class

msg := null

Encapsulated state variable

stop = request

abort msg

valve.write cCLOSED

Synchronous method

start = request

abort msg

Asynchronous call

Mutation

msg := send open

open = action

Asynchronous method

a ← wheel.acceleration

if a < 0 then

Synchronous call

valve.write cOPEN

msg := send after (millisec (a*10)) close

else

msg := send after (millisec 5) open

close = action

Delayed asynchronous call

valve.write cCLOSED

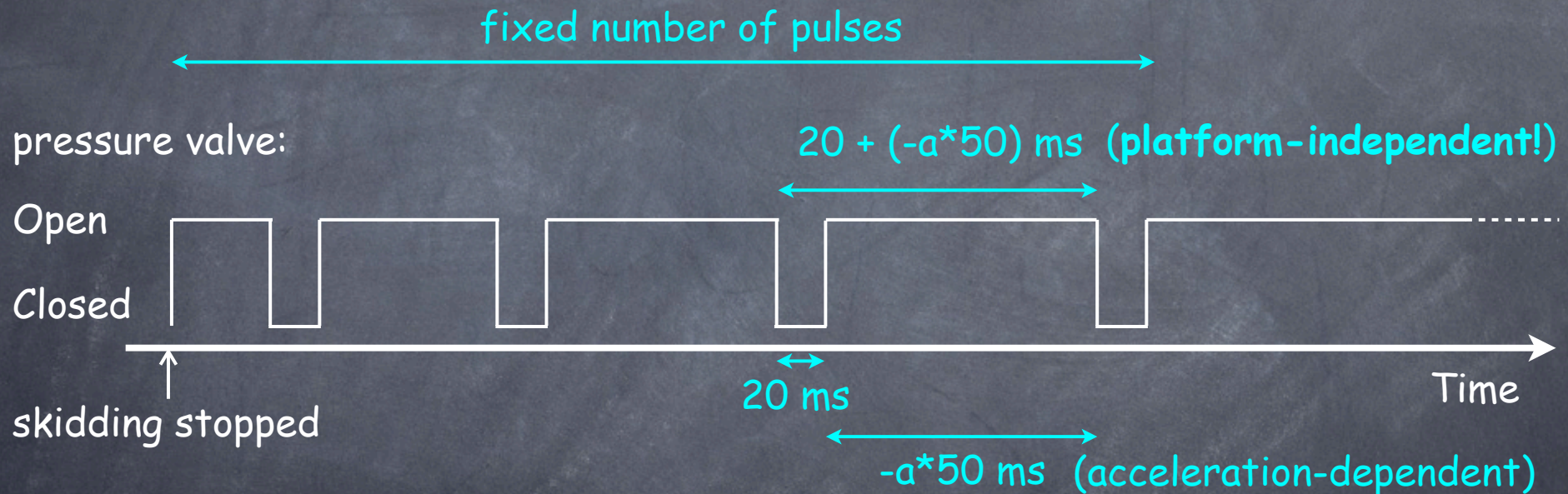
msg := send after (millisec 5) open

Returned object interface

result Sequencer {...}

An ABS in Timber

Reapplying brake pressure



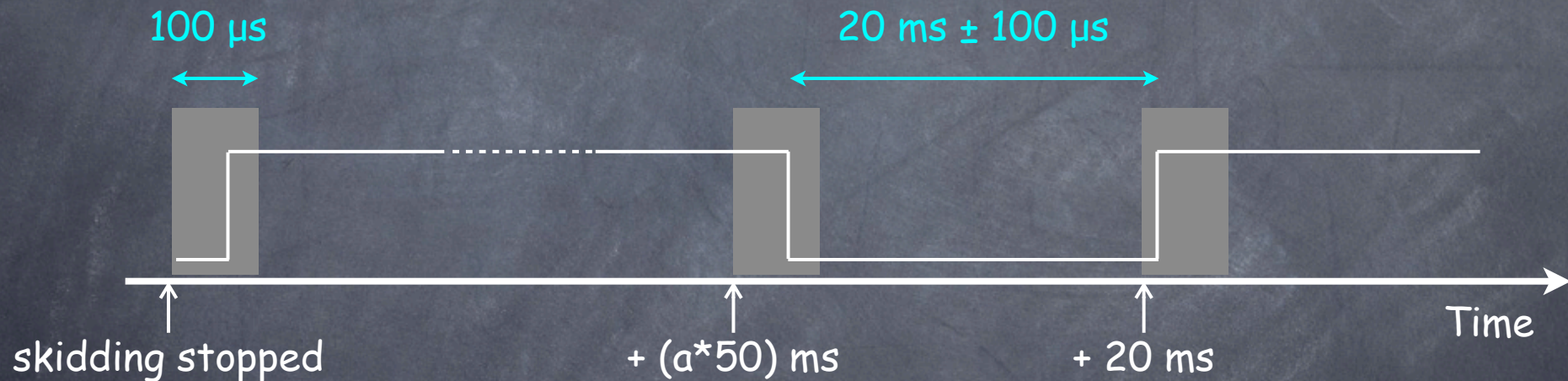
after (millisec 20) (open n)

a ← wheel.acceleration

after (millisec $(-a \cdot 50)$) (close (n-1))

An ABS in Timber

Reapplying brake pressure



open = **before** microsec 100 **action** ...

close = **before** microsec 100 **action** ...

open = **before** microsec 100 **action** ...