# Data Mining Classification: Basic Concepts,

Lecture Notes for Chapter 4 - 5

Introduction to Data Mining
by
Tan, Steinbach, Kumar

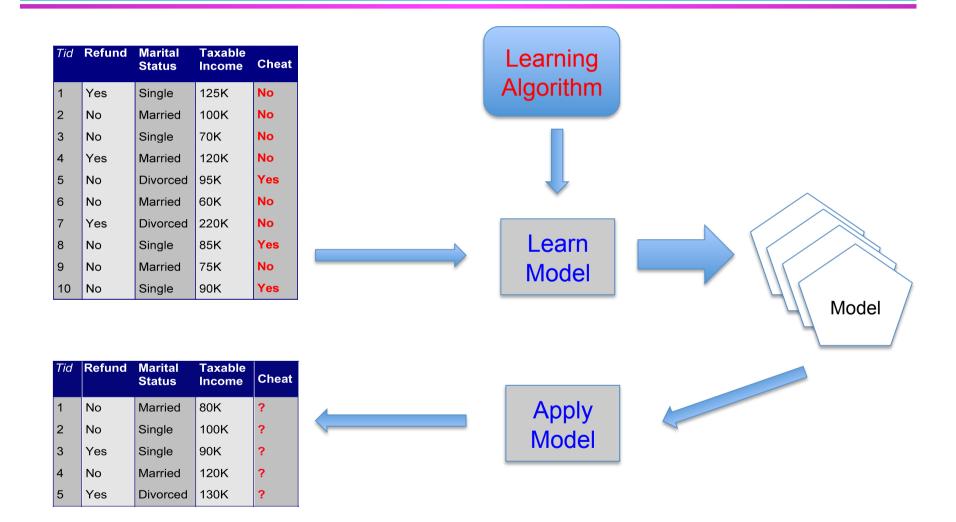
#### Classification: Definition

- Given a collection of records (training set)
  - Each record contains a set of attributes, one of the attributes is the class.
- Find a model for class attribute as a function of the values of other attributes.

#### Classification: Definition

- Goal: <u>previously unseen</u> records should be assigned a class as accurately as possible.
  - A test set is used to determine the accuracy of the model. Usually, the given data set is divided into training and test sets, with training set used to build the model and test set used to validate it.
- When the class is numerical, the problem is a regression problem.

## Illustrating Classification Task



## **Examples of Classification Task**

- Predicting tumor cells as benign or malignant
- Classifying credit card transactions as legitimate or fraudulent
- Classifying secondary structures of protein as alpha-helix, beta-sheet, or random coil
- Categorizing news stories as finance, weather, entertainment, sports, etc

## Classification Techniques

- Decision Tree
- Naïve Bayes
- Instance Based Learning
- Rule-based Methods
- Neural Networks
- Bayesian Belief Networks
- Support Vector Machines

### Classification: Measure the quality

Usually the Accuracy measure is used:

Number of Correctly Classified record

Accuracy =

Total Number of record in the test set

#### **Decision Tree**

 Uses a tree structure to model the training set

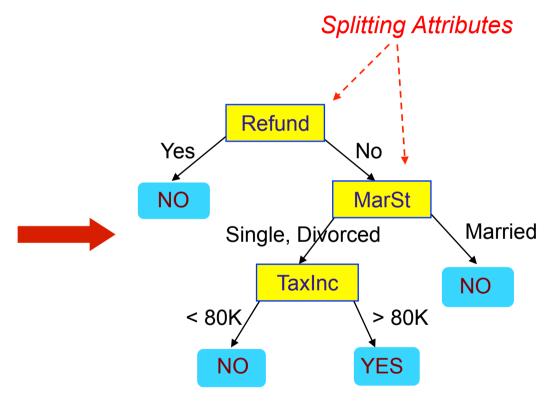
 Classifies a new record following the path in the tree

 Inner nodes represent attributes and leaves nodes represent the class

# Example of a Decision Tree

categorical continuous

Tid	Refund	Marital Status	Taxable Income	Cheat
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes



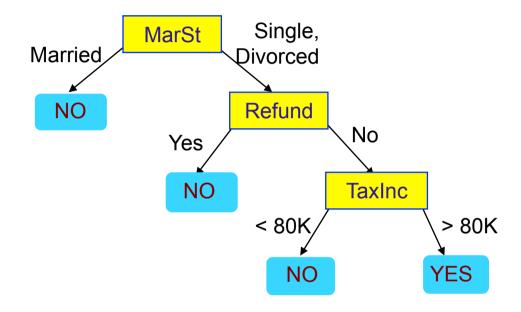
**Training Data** 

Model: Decision Tree

### Another Example of Decision Tree

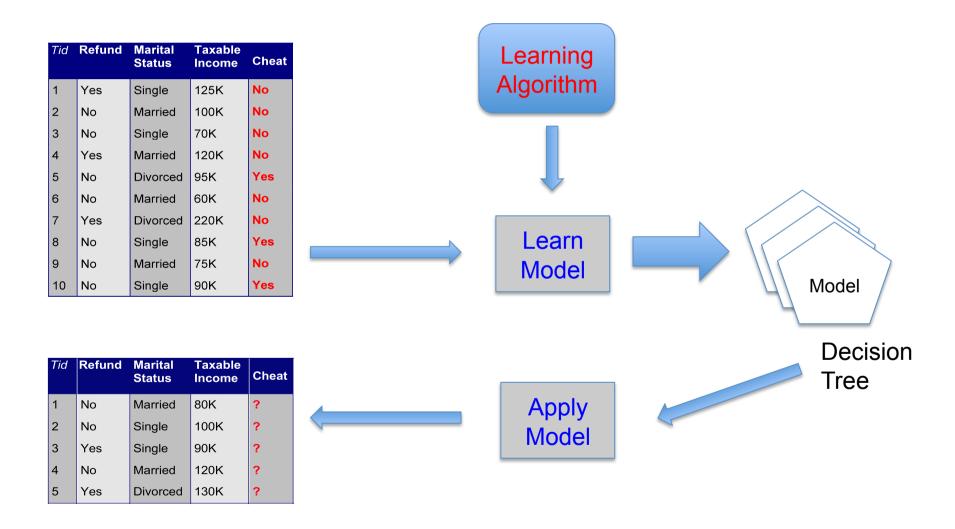
categorical continuous

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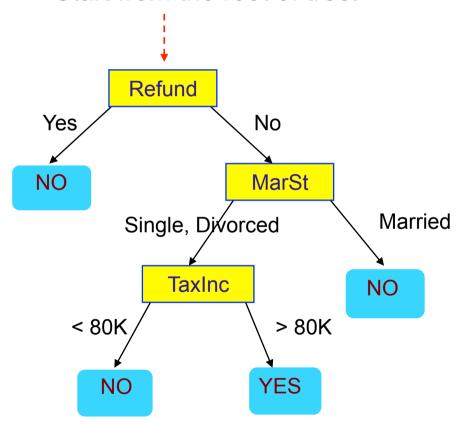


There could be more than one tree that fits the same data!

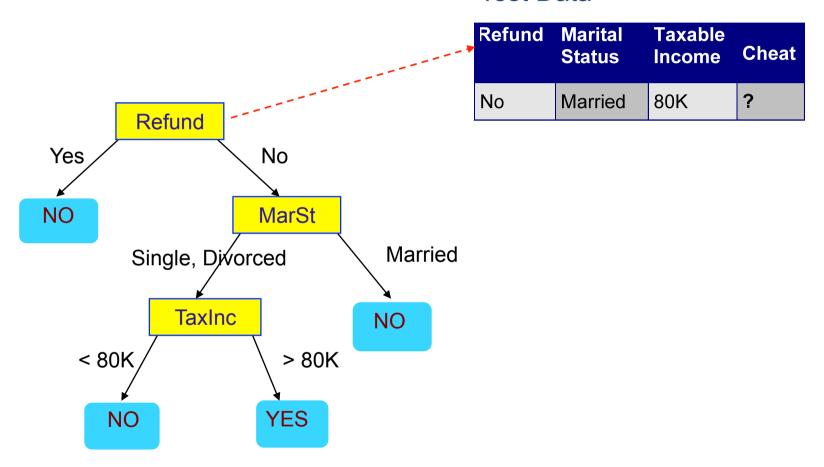
#### **Decision Tree Classification Task**

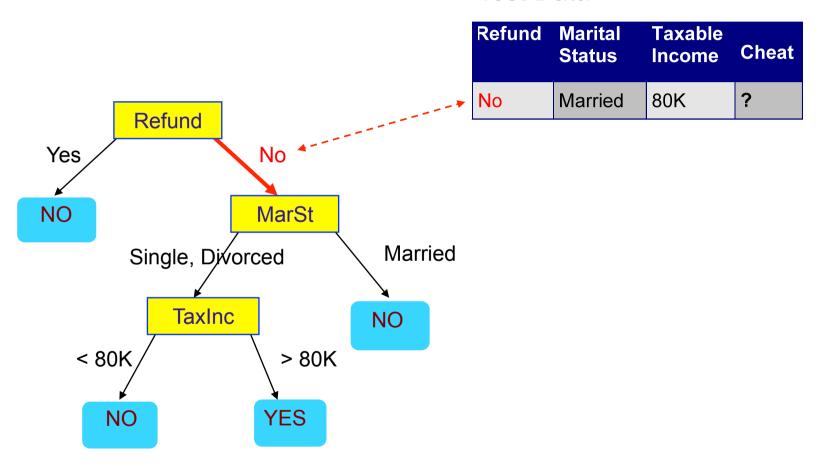


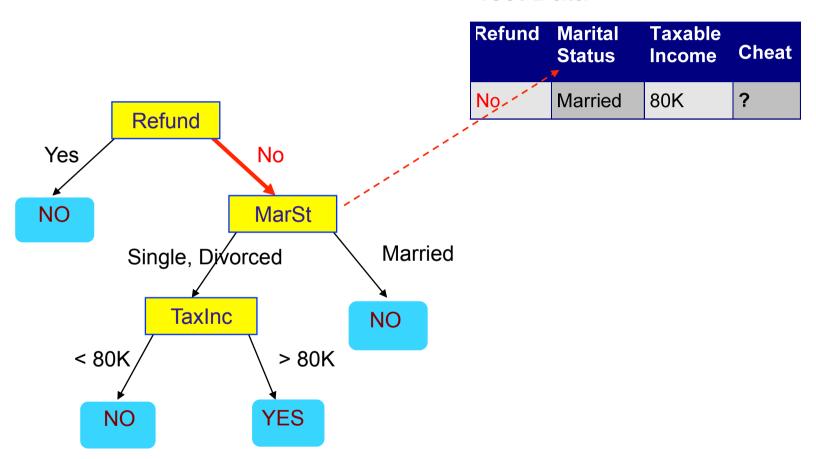
Start from the root of tree.

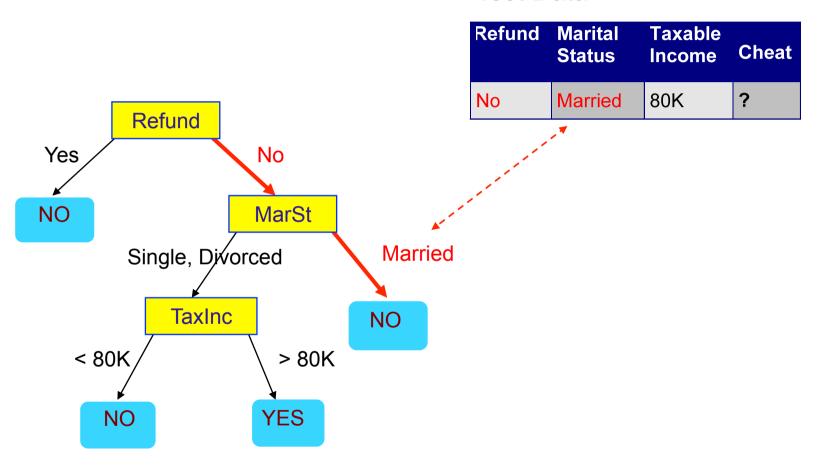


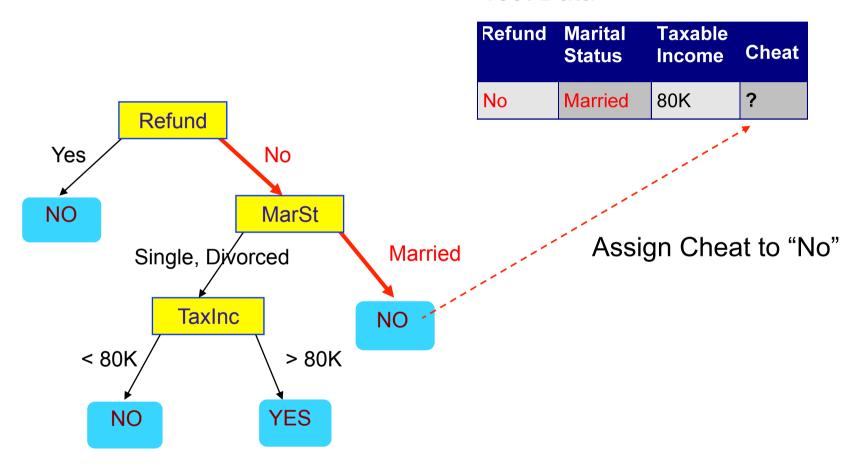
Refund	Marital Status	Taxable Income	Cheat
No	Married	80K	?



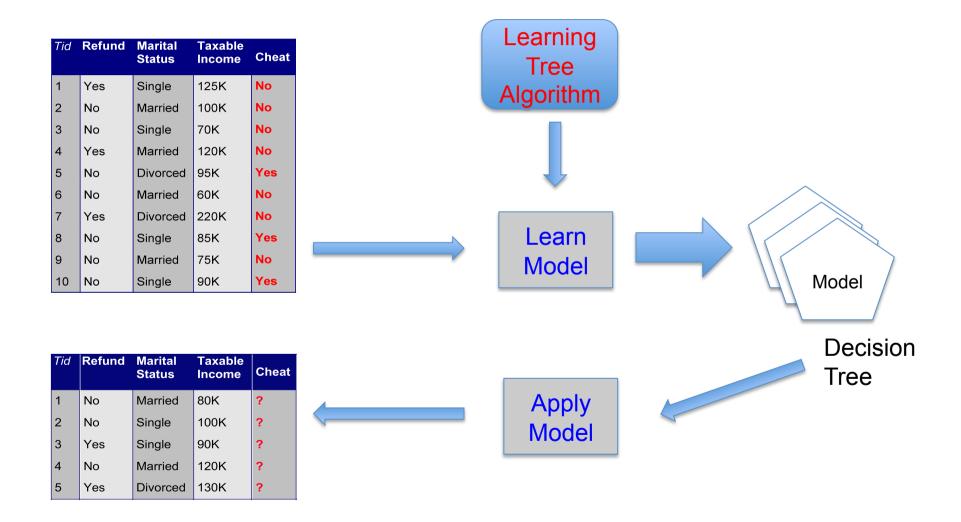








#### **Decision Tree Classification Task**



#### **Decision Tree Induction**

- Many Algorithms:
  - Hunt's Algorithm (one of the earliest)
  - CART
  - ID3, C4.5 (J48 on WEKA)
  - SLIQ, SPRINT

#### Tree Induction

- Greedy strategy.
  - Split the records based on an attribute test that optimizes certain criterion.
- Issues
  - Determine how to split the records
    - How to specify the attribute test condition?
    - How to determine the best split?
  - Determine when to stop splitting

#### Tree Induction

- Greedy strategy.
  - Split the records based on an attribute test that optimizes certain criterion.
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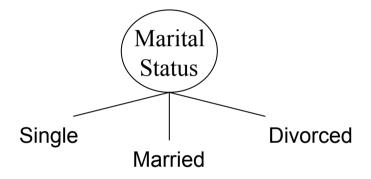
# How to Specify Test Condition?

- Depends on attribute types
  - Nominal
  - Ordinal
  - Continuous

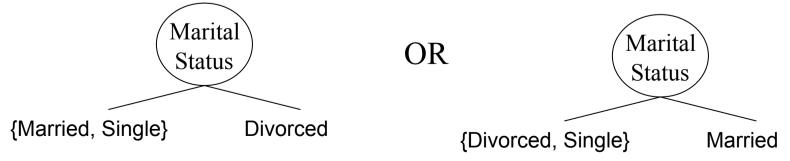
- Depends on number of ways to split
  - 2-way split
  - Multi-way split

### Splitting Based on Nominal Attributes

Multi-way split: Use as many partitions as distinct values.



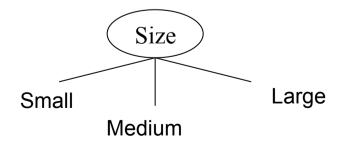
Binary split: Divides values into two subsets.
 Need to find optimal partitioning.



# Splitting Based on Ordinal Attributes

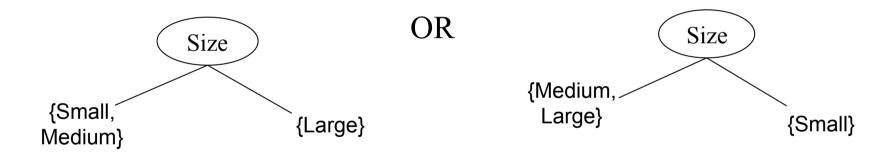
We can imagine an attribute SIZE defined over the ordered set {Small, Medium, Large}

Multi-way split: Use as many partitions as distinct values.

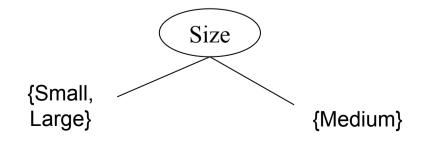


# Splitting Based on Ordinal Attributes

Binary split: Divides values into two subsets. Need to find optimal partitioning.



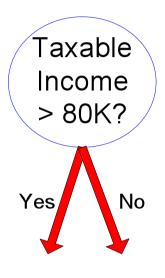
What about this split?



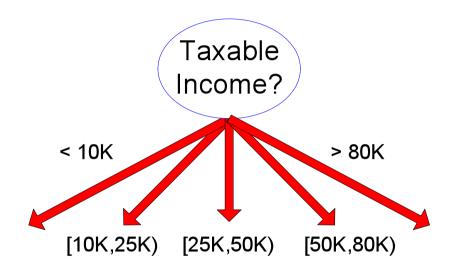
# Splitting Based on Continuous Attributes

- Different ways of handling
  - Discretization to form an ordinal categorical attribute
    - Static discretize once at the beginning
    - Dynamic ranges can be found by equal interval bucketing, equal frequency bucketing (percentiles), or clustering.
  - Binary Decision: (A < v) or (A ≥ v)</li>
    - consider all possible splits and finds the best cut
    - can be more compute intensive

# Splitting Based on Continuous Attributes



(i) Binary split



(ii) Multi-way split

#### Tree Induction

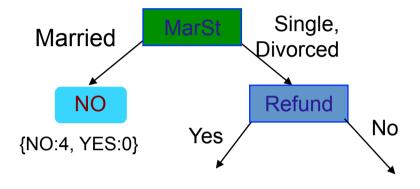
- Greedy strategy.
  - Split the records based on an attribute test that optimizes certain criterion.
- Issues
  - Determine how to split the records
    - How to specify the attribute test condition?
    - How to determine the best split?
  - Determine when to stop splitting

Tic	Refund	Marital Status	Taxable Income	Cheat
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
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9	No	Married	75K	No
10	No	Single	90K	Yes



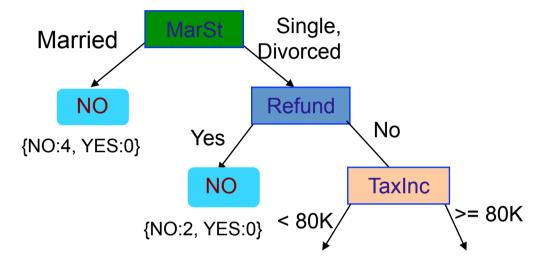
	Yes	No
Married	0	4
Single, Divorced	3	3

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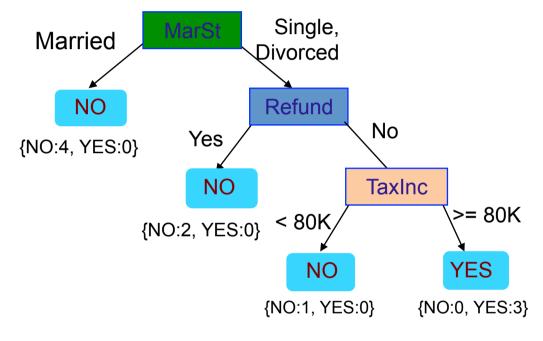
		YES	NO
Single, Divorced	Refund = NO	3	1
Single, Divorced	Refund = Yes	0	2

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7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes



			YES	NO
Single, Divorced	Refund = NO	Taxinc = < 80k	0	1
Single, Divorced	Refund = NO	Taxinc = >= 80k	3	0

Tid	Refund	Marital Status	Taxable Income	Cheat
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9	No	Married	75K	No
10	No	Single	90K	Yes



# How to determine the Best Split

- Greedy approach:
  - Nodes with homogeneous class distribution are preferred
- Need a measure of node impurity:

C0: 5 C1: 5 C0: 9 C1: 1

Non-homogeneous,

Homogeneous,

High degree of impurity

Low degree of impurity

# Measures of Node Impurity

#### Given a node t

Gini Index

$$GINI(t) = 1 - \sum_{j} [p(j \mid t)]^{2}$$

• Entropy  $Entropy(t) = -\sum_{j} p(j|t) \log_2 p(j|t)$ 

Misclassification error

$$Error(t) = 1 - \max_{j} P(j \mid t)$$

#### Tree Induction

- Greedy strategy.
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- Issues
  - Determine how to split the records
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    - How to determine the best split?
  - Determine when to stop splitting

### Stopping Criteria for Tree Induction

 Stop expanding a node when all the records belong to the same class

 Stop expanding a node when all the records have similar attribute values

#### **Decision Tree Based Classification**

- Advantages:
  - Inexpensive to construct
  - Extremely fast at classifying unknown records
  - Easy to interpret for small-sized trees
  - Accuracy is comparable to other classification techniques for many simple data sets

## **Naive Bayes**

Uses probability theory to model the training set

Assumes independence between attributes

Produces a model for each class

## **Bayes Theorem**

#### **Conditional Probability:**

$$P(C \mid A) = \frac{P(A, C)}{P(A)}$$

$$P(A \mid C) = \frac{P(A,C)}{P(C)}$$

#### Bayes theorem:

$$P(C \mid A) = \frac{P(A \mid C)P(C)}{P(A)}$$

## **Example of Bayes Theorem**

#### Given:

- A doctor knows that meningitis causes stiff neck 50% of the time
- Prior probability of any patient having meningitis is 1/50,000
- Prior probability of any patient having stiff neck is 1/20
- If a patient has stiff neck, what's the probability he/she has meningitis?

$$P(M \mid S) = \frac{P(S \mid M)P(M)}{P(S)} = \frac{0.5 \times 1/50000}{1/20} = 0.0002$$

## Bayesian Classifiers

- Consider each attribute and class label as random variables
- Given a record with attributes (A<sub>1</sub>, A<sub>2</sub>,...,A<sub>n</sub>)
  - Goal is to predict class C
  - Specifically, we want to find the value of C that maximizes P(C| A<sub>1</sub>, A<sub>2</sub>,...,A<sub>n</sub>)
- Can we estimate P(C| A<sub>1</sub>, A<sub>2</sub>,...,A<sub>n</sub>) directly from data?

## Bayesian Classifiers

- Approach:
  - compute the posterior probability P(C | A<sub>1</sub>, A<sub>2</sub>, ..., A<sub>n</sub>) for all values of C using the Bayes theorem

$$P(C \mid A_{1}A_{2} \mathbf{K} A_{n}) = \frac{P(A_{1}A_{2} \mathbf{K} A_{n} \mid C)P(C)}{P(A_{1}A_{2} \mathbf{K} A_{n})}$$

- Choose value of C that maximizes
   P(C | A<sub>1</sub>, A<sub>2</sub>, ..., A<sub>n</sub>)
- Equivalent to choosing value of C that maximizes
   P(A<sub>1</sub>, A<sub>2</sub>, ..., A<sub>n</sub>|C) P(C)
- How to estimate P(A<sub>1</sub>, A<sub>2</sub>, ..., A<sub>n</sub> | C)?

## Naïve Bayes Classifier

- Assume independence among attributes A<sub>i</sub> when class is given:
  - $P(A_1, A_2, ..., A_n | C) = P(A_1 | C_j) P(A_2 | C_j)... P(A_n | C_j)$
  - Can estimate  $P(A_i | C_j)$  for all  $A_i$  and  $C_j$ .
  - New point is classified to  $C_j$  if  $P(C_j)$   $\Pi$   $P(A_i|C_j)$  is maximal.

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• Class:  $P(C) = N_c/N$ 

- e.g., 
$$P(No) = 7/10$$
,  $P(Yes) = 3/10$ 

For discrete attributes:

$$P(A_i \mid C_k) = |A_{ik}| / N_c$$

- where |A<sub>ik</sub>| is number of instances having attribute A<sub>i</sub> and belongs to class C<sub>k</sub>
- Examples:

- For continuous attributes:
  - Discretize the range into bins
    - one ordinal attribute per bin
    - violates independence assumption
  - Two-way split: (A < v) or (A > v)
    - choose only one of the two splits as new attribute
  - Probability density estimation:
    - Assume attribute follows a normal distribution
    - Use data to estimate parameters of distribution (e.g., mean and standard deviation)
    - Once probability distribution is known, can use it to estimate the conditional probability P(A<sub>i</sub>|c)

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#### Compute:

P(Status=Married|Yes) = ?

P(Refund=Yes|No) = ?

P(Status=Divorced|Yes) = ?

P(TaxableInc > 80K|Yes) = ?

P(TaxableInc > 80K|NO) = ?

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8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes

#### Compute:

P(Status=Married|Yes) = 0/3

P(Refund=Yes|No) = 3/7

P(Status=Divorced|Yes) = 1/3

P(TaxableInc > 80K|Yes) = 3/3

P(TaxableInc > 80K|NO) = 4/7

#### Example of Naïve Bayes Classifier

Given a Test Record: X = (Refund = No, Married, Income >= 80K)

REFUND	P(Refund=Yes No) = 3/7 P(Refund=No No) = 4/7 P(Refund=Yes Yes) = 0 P(Refund=No Yes) = 1
MARITAL STATUS	P(Marital Status=Single No) = 2/7 P(Marital Status=Divorced No) = 1/7 P(Marital Status=Married No) = 4/7 P(Marital Status=Single Yes) = 2/7 P(Marital Status=Divorced Yes) = 1/7 P(Marital Status=Married Yes) = 0
TAXABLE INCOMING	P(TaxableInc >= 80K Yes) = 3/3 P(TaxableInc >= 80K NO) = 4/7 P(TaxableInc < 80K Yes) = 0/3 P(TaxableInc < 80K NO) = 3/7

Class=No	7/10
Class=Yes	3/10

$$P(C_j|A_1, ..., A_n) = P(A_1, ..., A_n|C_j) P(C_j) = P(A_1|C_j)... P(A_n|C_j) P(C_j)$$

#### Example of Naïve Bayes Classifier

```
    P(X|Class=No) = P(Refund=No|Class=No)
    × P(Married| Class=No)
    × P(Income>=80K| Class=No)
    = 4/7 × 4/7 × 4/7 = 0.1865
```

**P(X|No)P(No)** = 0.1865 \* 0.7 = 0.1306

```
    P(X|Class=Yes) = P(Refund=No| Class=Yes)
    × P(Married| Class=Yes)
    × P(Income>=80K| Class=Yes)
    = 1 × 0 × 1 = 0
```

Since P(X|No)P(No) > P(X|Yes)P(Yes)

#### Example of Naïve Bayes Classifier(2)

Given a Test Record: X = (Refund = No, Single, Income >= 80K)

REFUND	P(Refund=Yes No) = 3/7 P(Refund=No No) = 4/7 P(Refund=Yes Yes) = 0 P(Refund=No Yes) = 3/3
MARITAL STATUS	P(Marital Status=Single No) = 2/7 P(Marital Status=Divorced No) = 1/7 P(Marital Status=Married No) = 4/7 P(Marital Status=Single Yes) = 2/7 P(Marital Status=Divorced Yes) = 1/7 P(Marital Status=Married Yes) = 0
TAXABLE INCOMING	P(TaxableInc >= 80K Yes) = 3/3 P(TaxableInc >= 80K NO) = 4/7 P(TaxableInc < 80K Yes) = 0/3 P(TaxableInc < 80K NO) = 3/7

Class=No	7/10
Class=Yes	3/10

$$P(A_1, A_2, ..., A_n | C) P(C) = P(A_1 | C_j) P(A_2 | C_j)... P$$
  
 $(A_n | C_j) P(C)$ 

### Example of Naïve Bayes Classifier(2)

```
    P(X|Class=No) = P(Refund=No|Class=No)
    × P(Single| Class=No)
    × P(Income>=80K| Class=No)
    = 4/7 × 2/7 × 4/7 = 0.0933
```

**P(X|No)P(No)** = 0.0933 \* 0.7 = 0.06531

```
    P(X|Class=Yes) = P(Refund=No| Class=Yes)
    × P(Single| Class=Yes)
    × P(Income>=80K|Class=Yes)
    = 1 × 2/3 × 1 = 0.666
```

**P(X|Yes)P(Yes)** = 0.666\* 0.3 = 0.08571

Since P(X|No)P(No) < P(X|Yes)P(Yes)

Therefore P(No|X) < P(Yes|X) => Class = Yes

## Naïve Bayes (Summary)

- Robust to isolated noise points
- Model each class separately
- Robust to irrelevant attributes
- Use the whole set of attribute to perform classification
- Independence assumption may not hold for some attributes

#### Instance-Based Classifier

Lazy approach to classification

 Uses all the training set to peform classification

 Uses distances between training and test records

# K-nearest neighbors

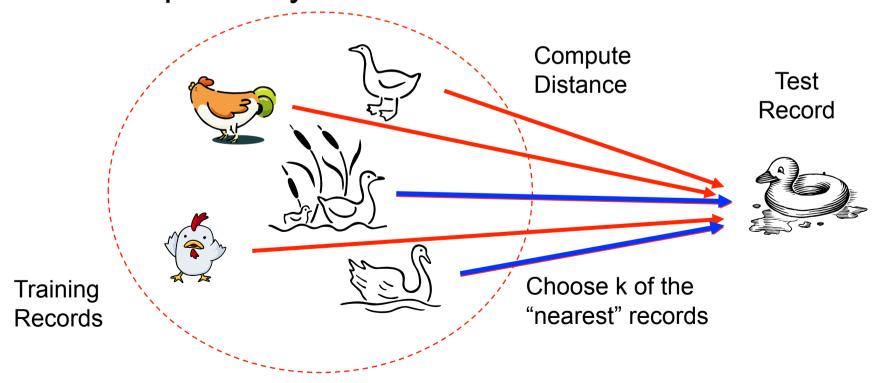
Uses k "closest" points (nearest neighbors) for performing classification

Set of Stored Cases

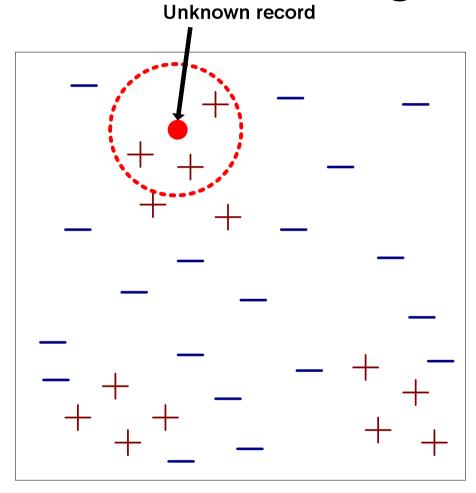
Atr1	• • • • • • • • • • • • • • • • • • • •	AtrN	Class				
			A	•			
			В				
			В		Uns	seen C	Case
			С				
			A		Atr1		AtrN
			С				
			В				

## Nearest Neighbor Classifiers

- Basic idea:
  - If it walks like a duck, quacks like a duck, then it's probably a duck

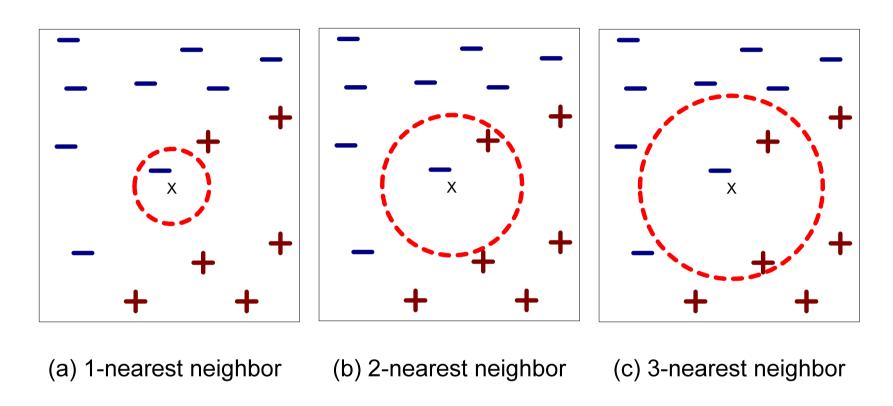


## Nearest-Neighbor Classifiers



- Requires three things
  - The set of stored records
  - Distance Metric to compute distance between records
  - The value of k, the number of nearest neighbors to retrieve
- To classify an unknown record:
  - Compute distance to other training records
  - Identify k nearest neighbors
  - Use class labels of nearest neighbors to determine the class label of unknown record (e.g., by taking majority vote)

## Definition of Nearest Neighbor



K-nearest neighbors of a record x are data points that have the k smallest distance to x

## Nearest Neighbor Classification

- Compute distance between two points:
  - Euclidean distance

$$d(p,q) = \sqrt{\sum_{i} (p_{i} - q_{i})^{2}}$$

- Determine the class from nearest neighbor list
  - take the majority vote of class labels among the k-nearest neighbors
  - Weigh the vote according to distance
    - weight factor, w = 1/d<sup>2</sup>

#### Training set

Id record	Attr1	Attr2	Class
1	10	2	Yes
2	4	4	No
3	1	9	Yes
4	3	10	Yes
5	4	6	No
6	8	8	No
7	1	8	Yes

#### Test set

ld Record	Attr1	Attr2	Class
8	2	7	?
9	7	7	?
10	1	11	?

Use K = 3

<b>Euclidean Dist</b>	8	9	10
1	9.43	5.83	12.72
2	3.61	4.24	7.62
3	2.2	6.32	2.0
4	3.16	5.0	2.24
5	2.23	3.16	5.83
6	6.08	1.41	7.62
7	1.41	6.08	3.0

		•	
$3-NN(8) = \{7,3,5\}$	$S = \{Yes$	s, Yes,	No} = Yes
3-NN(9) = ?			

$$3-NN(10) = ?$$

Id record	Class
1	Yes
2	No
3	Yes
4	Yes
5	No
6	No
7	Yes

Use K = 3

<b>Euclidean Dist</b>	8	9	10
1	9.43	5.83	12.72
2	3.61	4.24	7.62
3	2.2	6.32	2.0
4	3.16	5.0	2.24
5	2.23	3.16	5.83
6	6.08	1.41	7.62
7	1.41	6.08	3.0

$$3-NN(8) = \{7,3,5\} = \{Yes, Yes, No\} = Yes$$

$$3-NN(9) = \{6,5,2\} = \{No, No, No\} = No$$

$$3-NN(10) = {3,4,7} = {Yes,Yes,Yes} = Yes$$

Id record	Class
1	Yes
2	No
3	Yes
4	Yes
5	No
6	No
7	Yes

Use K = 5

<b>Euclidean Dist</b>	8	9	10
1	9.43	5.83	12.72
2	3.6	4.24	7.62
3	2.2	6.32	2.0
4	3.16	5.0	2.24
5	2.23	3.16	5.83
6	6.08	1.41	7.62
7	1.41	6.08	3.0

Id record	Class
1	Yes
2	No
3	Yes
4	Yes
5	No
6	No
7	Yes

 $3-NN(8) = \{7,3,5,4,2\} = \{Yes, Yes, No, Yes, No\} = Yes$ 

3-NN(9) = ?

3-NN(10) = ?

Use K = 5

<b>Euclidean Dist</b>	8	9	10
1	9.43	5.83	12.72
2	3.61	4.24	7.62
3	2.2	6.32	2.0
4	3.16	5.0	2.24
5	2.23	3.16	5.83
6	6.08	1.41	7.62
7	1.41	6.08	3.0

Id record	Class
1	Yes
2	No
3	Yes
4	Yes
5	No
6	No
7	Yes

 $3-NN(8) = \{7,3,5,4,2\} = \{Yes, Yes, No, Yes, No\} = Yes$ 

 $3-NN(9) = \{6,5,2,4,1\} = \{No, No, No, Yes, Yes\} = No$ 

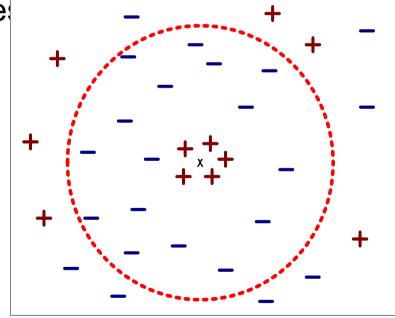
 $3-NN(10) = {3,4,7,5,2} = {Yes,Yes,No,No} = {Yes}$ 

#### Nearest Neighbor Classification...

- Choosing the value of k:
  - If k is too small, sensitive to noise points

If k is too large, neighborhood may include points

from other classes



#### Nearest Neighbor Classification...

#### Scaling issues

 Attributes may have to be scaled to prevent distance measures from being dominated by one of the attributes

#### – Example:

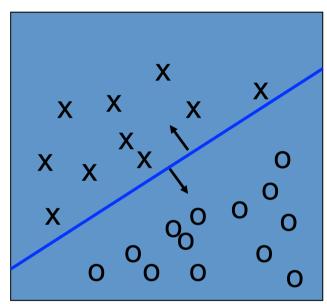
- height of a person may vary from 1.5m to 1.8m
- weight of a person may vary from 90lb to 300lb
- income of a person may vary from \$10K to \$1M

#### Nearest neighbor Classification...

- k-NN classifiers are lazy learners
  - It does not build models explicitly
  - Unlike eager learners such as decision tree induction and rule-based systems
  - Classifying unknown records are relatively expensive

#### Classification: A Mathematical Mapping

- Classification: predicts categorical class labels
  - E.g., Personal homepage classification
    - $x_i = (x_1, x_2, x_3, ...), y_i = +1 \text{ or } -1$
    - x<sub>1</sub>: # of word "homepage"
    - x<sub>2</sub>: # of word "welcome"
- Mathematically,  $x \in X = \Re^n$ ,  $y \in Y = \{+1, -1\}$ ,
  - We want to derive a function f:  $X \rightarrow Y$
- Linear Classification
  - Binary Classification problem
  - Data above the blue line belongs to class 'x'
  - Data below blue line belongs to class 'o'
  - Examples: SVM, Perceptron, Probabilistic Classifiers



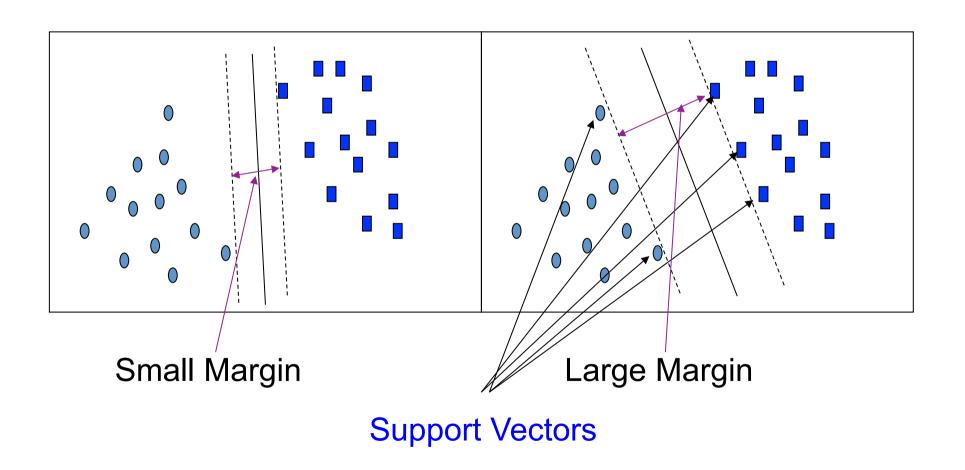
#### **SVM**—Support Vector Machines

- A relatively new classification method for both <u>linear and nonlinear</u> data
- It uses a <u>nonlinear mapping</u> to transform the original training data into a higher dimension
- With the new dimension, it searches for the linear optimal separating hyperplane (i.e., "decision boundary")
- With an appropriate nonlinear mapping to a sufficiently high dimension, data from two classes can always be separated by a hyperplane
- SVM finds this hyperplane using support vectors ("essential" training tuples) and margins (defined by the support vectors)

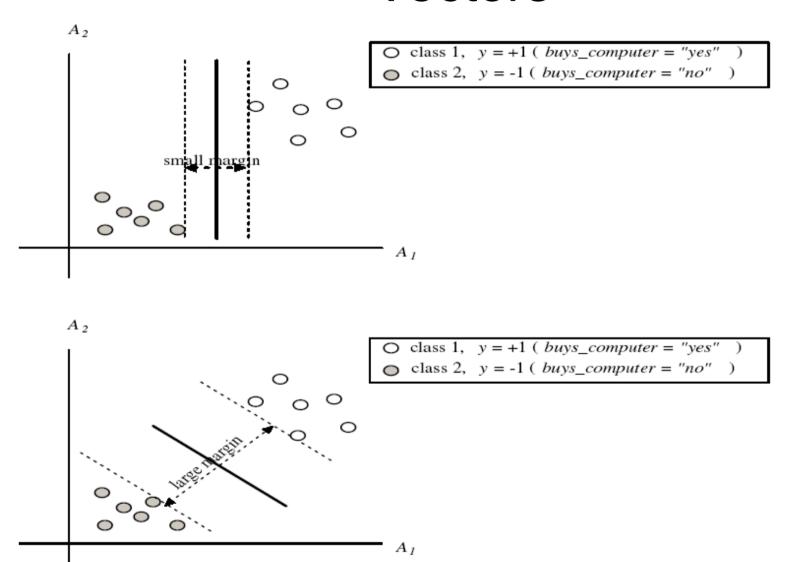
## SVM—History and Applications

- Vapnik and colleagues (1992)—groundwork from Vapnik & Chervonenkis' statistical learning theory in 1960s
- <u>Features</u>: training can be slow but accuracy is high owing to their ability to model complex nonlinear decision boundaries (margin maximization)
- <u>Used for</u>: classification and numeric prediction
- Applications:
  - handwritten digit recognition, object recognition, speaker identification, benchmarking time-series prediction tests

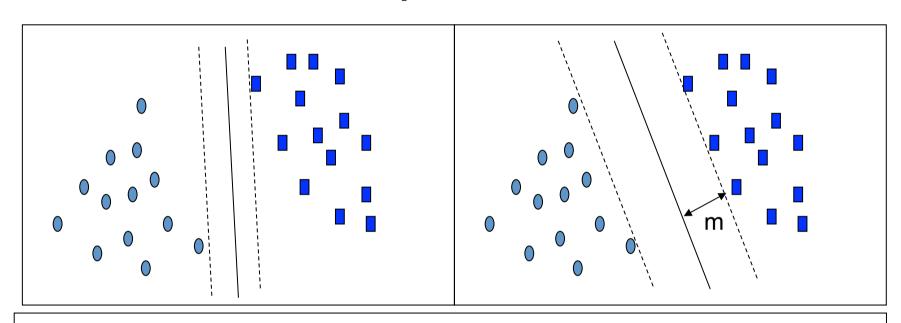
### SVM—General Philosophy



# SVM—Margins and Support Vectors



# SVM—When Data Is Linearly Separable



Let data D be  $(\mathbf{X}_1, \mathbf{y}_1), \ldots, (\mathbf{X}_{|D|}, \mathbf{y}_{|D|})$ , where  $\mathbf{X}_i$  is the set of training tuples associated with the class labels  $\mathbf{y}_i$ 

There are infinite lines (<u>hyperplanes</u>) separating the two classes but we want to <u>find the best one</u> (the one that minimizes classification error on unseen data)

SVM searches for the hyperplane with the largest margin, i.e., maximum marginal hyperplane (MMH)

#### **SVM**—Linearly Separable

A separating hyperplane can be written as

$$\mathbf{W} \bullet \mathbf{X} + \mathbf{b} = 0$$

where  $\mathbf{W} = \{w_1, w_2, ..., w_n\}$  is a weight vector and b a scalar (bias)

For 2-D it can be written as

$$W_0 + W_1 X_1 + W_2 X_2 = 0$$

The hyperplane defining the sides of the margin:

H<sub>1</sub>: 
$$w_0 + w_1 x_1 + w_2 x_2 \ge 1$$
 for  $y_i = +1$ , and  
H<sub>2</sub>:  $w_0 + w_1 x_1 + w_2 x_2 \le -1$  for  $y_i = -1$ 

- Any training tuples that fall on hyperplanes H<sub>1</sub> or H<sub>2</sub> (i.e., the sides defining the margin) are support vectors
- This becomes a constrained (convex) quadratic optimization problem: Quadratic objective function and linear constraints → Quadratic Programming (QP) → Lagrangian multipliers

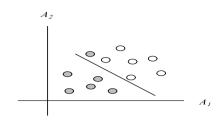
#### Why Is SVM Effective on High Dimensional Data? (I)

- The complexity of trained classifier is characterized by the # of support vectors rather than the dimensionality of the data
- The support vectors are the <u>essential or critical training examples</u> —they lie closest to the decision boundary (MMH)
- If all other training examples are removed and the training is repeated, the same separating hyperplane would be found

#### Why Is SVM Effective on High Dimensional Data? (II)

- The number of support vectors found can be used to compute an (upper) bound on the expected error rate of the SVM classifier, which is independent of the data dimensionality
- Thus, an SVM with a small number of support vectors can have good generalization, even when the dimensionality of the data is high

# SVM—Linearly Inseparable



Transform the original input data into a higher dimensional space

Example 6.8 Nonlinear transformation of original input data into a higher dimensional space. sider the following example. A 3D input vector  $\mathbf{X} = (x_1, x_2, x_3)$  is mapped into a 6D space Z using the mappings  $\phi_1(X) = x_1, \phi_2(X) = x_2, \phi_3(X) = x_3, \phi_4(X) = (x_1)^2, \phi_5(X) = x_1x_2, \text{ and } \phi_6(X) = x_1x_3.$  A decision hyperplane in the new space is  $d(\mathbf{Z}) = \mathbf{W}\mathbf{Z} + b$ , where W and Z are vectors. This is linear. We solve for W and b and then substitute back so that we see that the linear decision hyperplane in the new (Z) space corresponds to a nonlinear second order polynomial in the original 3-D input space,

$$d(Z) = w_1x_1 + w_2x_2 + w_3x_3 + w_4(x_1)^2 + w_5x_1x_2 + w_6x_1x_3 + b$$
  
=  $w_1z_1 + w_2z_2 + w_3z_3 + w_4z_4 + w_5z_5 + w_6z_6 + b$ 

Search for a linear separating hyperplane in the new space

#### **SVM: Different Kernel functions**

- Instead of computing the dot product on the transformed data, it is math. equivalent to applying a kernel function K (X<sub>i</sub>, X<sub>j</sub>) to the original data, i.e., K(X<sub>i</sub>, X<sub>j</sub>) = Φ(X<sub>i</sub>) Φ(X<sub>j</sub>)
- Typical Kernel Functions

Polynomial kernel of degree  $h: K(X_i, X_j) = (X_i \cdot X_j + 1)^h$ 

Gaussian radial basis function kernel:  $K(X_i, X_i) = e^{-\|X_i - X_j\|^2 / 2\sigma^2}$ 

Sigmoid kernel:  $K(X_i, X_j) = \tanh(\kappa X_i \cdot X_j - \delta)$ 

 SVM can also be used for classifying multiple (> 2) classes and for regression analysis (with additional parameters)

#### SVM Classification...

 Hard to learn – learned in batch mode using quadratic programming techniques

Using kernels can learn very complex functions

Deterministic algorithm

Nice generalization properties

#### Discriminative Classifiers

- Advantages
  - Prediction accuracy is generally high
    - As compared to Bayesian methods in general
  - Robust, works when training examples contain errors
  - Fast evaluation of the learned target function
- Criticism
  - Long training time
  - Difficult to understand the learned function (weights)
  - Not easy to incorporate domain knowledge
    - Easy in the form of priors on the data or distributions

#### Model Evaluation

- Metrics for Performance Evaluation
  - How to evaluate the performance of a model?
- Methods for Performance Evaluation
  - How to obtain reliable estimates?
- Methods for Model Comparison
  - How to compare the relative performance among competing models?

#### Model Evaluation

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#### Metrics for Performance Evaluation

- Focus on the predictive capability of a model
  - Rather than how fast it takes to classify or build models, scalability, etc.

#### Confusion Matrix:

	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL	Class=Yes	а	b
CLASS	Class=No	С	d

a: TP (true positive)

b: FN (false negative)

c: FP (false positive)

d: TN (true negative)

# Metrics for Performance Evaluation...

	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL CLASS	Class=Yes	a (TP)	b (FN)
	Class=No	c (FP)	d (TN)

Most widely-used metric:

Accuracy = 
$$\frac{a+d}{a+b+c+d} = \frac{TP+TN}{TP+TN+FP+FN}$$

# Limitation of Accuracy

- Consider a 2-class problem
  - Number of Class 0 examples = 9990
  - Number of Class 1 examples = 10
- If model predicts everything to be class 0, accuracy is 9990/10000 = 99.9 %
  - Accuracy is misleading because model does not detect any class 1 example

### **Cost Matrix**

	PREDICTED CLASS		
	C(i j)	Class=Yes	Class=No
ACTUAL CLASS	Class=Yes	C(Yes Yes)	C(No Yes)
	Class=No	C(Yes No)	C(No No)

C(i|j): Cost of misclassifying class j example as class i

Computing Cost of Classification

Cost Matrix	PREDICTED CLASS		
ACTUAL CLASS	C(i j)	+	-
	+	-1	100
	•	1	0

Model M <sub>1</sub>	PREDICTED CLASS		
ACTUAL CLASS		+	-
	+	150	40
	-	60	250

Model M <sub>2</sub>	PREDICTED CLASS		
ACTUAL CLASS		+	•
	+	250	45
	•	5	200

Accuracy = 80%

Cost = 3910

Accuracy = 90%

Cost = 4255

### Cost vs Accuracy

Count	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL CLASS	Class=Yes	а	b
	Class=No	С	d

Accuracy is p	proportional	to cost if
---------------	--------------	------------

1. 
$$C(Yes|No)=C(No|Yes)=q$$

2. 
$$C(Yes|Yes)=C(No|No) = p$$

$$N = a + b + c + d$$

Accuracy = 
$$(a + d)/N$$

#### **Cost-Sensitive Measures**

Count	PREDICTED CLASS			
		Class=Yes	Class=No	
ACTUAL CLASS	Class=Yes	а	b	
	Class=No	С	d	

Precision (p) = 
$$\frac{a}{a+c}$$

Recall (r) = 
$$\frac{a}{a+b}$$

F - measure (F) = 
$$\frac{2a}{2a+b+c}$$

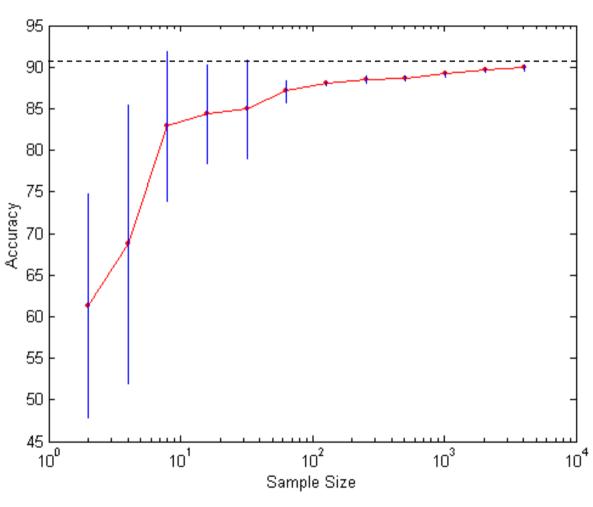
#### Model Evaluation

- Metrics for Performance Evaluation
  - How to evaluate the performance of a model?
- Methods for Performance Evaluation
  - How to obtain reliable estimates?
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## Methods for Performance Evaluation

- How to obtain a reliable estimate of performance?
- Performance of a model may depend on other factors besides the learning algorithm:
  - Class distribution
  - Cost of misclassification
  - Size of training and test sets

# Learning Curve



- Learning curve shows how accuracy changes with varying sample size
- Requires a sampling schedule for creating learning curve:
  - Arithmetic sampling (Langley, et al)
  - Geometric sampling (Provost et al)

Effect of small sample size:

- Bias in the estimate
- Variance of estimate

#### Methods of Estimation

- Holdout
  - Reserve 2/3 for training and 1/3 for testing
- Random subsampling
  - Repeated holdout
- Cross validation
  - Partition data into k disjoint subsets
  - k-fold: train on k-1 partitions, test on the remaining one
  - Leave-one-out: k=n

#### Model Evaluation

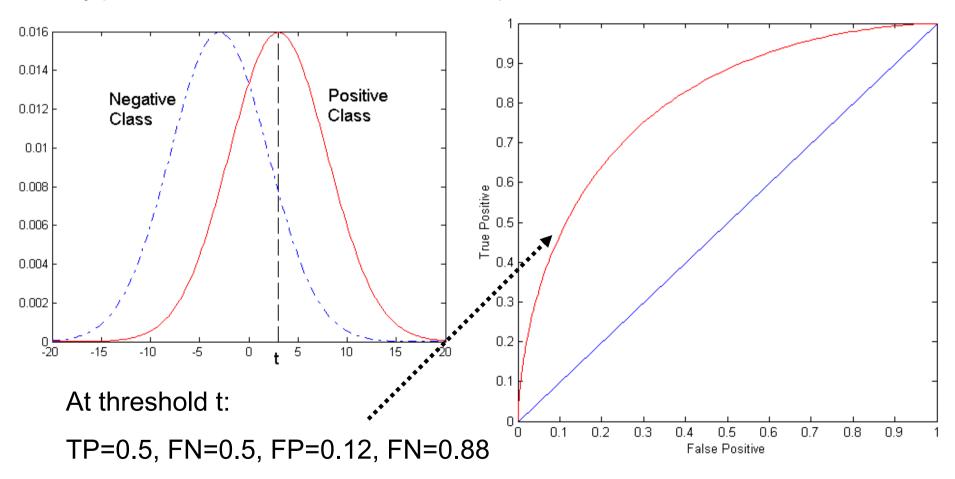
- Metrics for Performance Evaluation
  - How to evaluate the performance of a model?
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  - How to compare the relative performance among competing models?

# ROC (Receiver Operating Characteristic)

- Developed in 1950s for signal detection theory to analyze noisy signals
  - Characterize the trade-off between positive hits and false alarms
- ROC curve plots TP (on the y-axis) against FP (on the x-axis)
- Performance of each classifier represented as a point on the ROC curve
  - changing the threshold of algorithm, sample distribution or cost matrix changes the location of the point

### **ROC Curve**

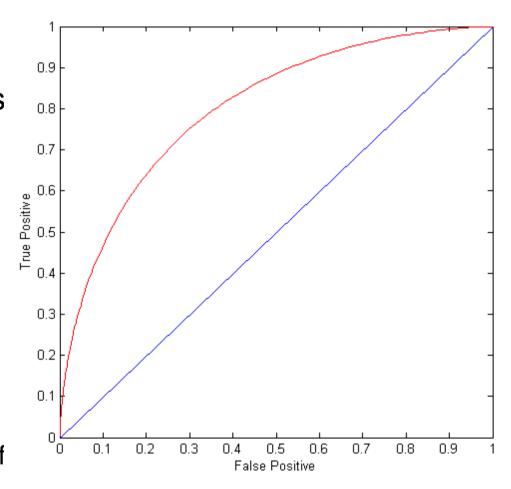
- 1-dimensional data set containing 2 classes (positive and negative)
- any points located at x > t is classified as positive



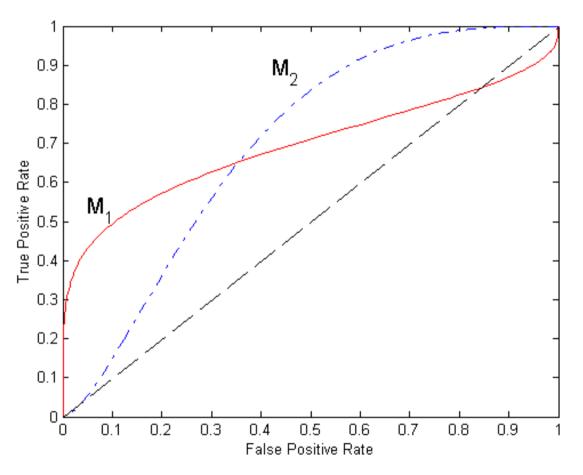
#### **ROC Curve**

#### (TP,FP):

- (0,0): declare everything to be negative class
- (1,1): declare everything to be positive class
- (1,0): ideal
- Diagonal line:
  - Random guessing
  - Below diagonal line:
    - prediction is opposite of the true class



# Using ROC for Model Comparison



- No model consistently outperform the other
  - M<sub>1</sub> is better for small FPR
  - M<sub>2</sub> is better for large FPR
- Area Under the ROC curve
  - Ideal:
    - Area = 1
  - Random guess:
    - Area = 0.5