



chap 5 ①

rest of chap 5 see by next time

**Multiprogramming** - multiple processes single CPU

process1

process2

process3

**Multiprocessing** - multiple processes, multiple cores

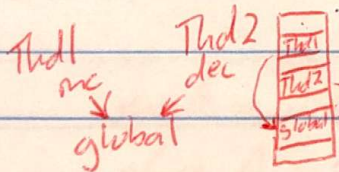
core1 p1  
p2

core2 p3  
p4

note p2, p3 concurrent

**Distributed**: multiple processors w/ multiple processes (difficult to coordinate, not discussed in this course)

① **race condition**: outcome depends on who gets done first, <sup>often tough</sup> might want to reproduce & debug



thread Atomic crit sec! .cpp

show thread prog with <sup>not include</sup> ~~critical sections~~

② **critical section** - code that accesses shared resource that must complete w/o interrupt

thread ex. increment is the critical section but can be arbitrarily large.

Question: what if 100 threads <sup>read</sup> access a global  
No you need to protect it. worry about competition?  
No, if never changed then no need ~~wait for it~~



- atomic operation - sequence of 1 or more instructions that appear indivisible, i.e. other process can see an intermediate state or interrupt it.

thread-  
atomic-  
critical section  
.cpp

show std; atomic end? solution to  
above, show how mi. net is 3  
assembly net. interrupt anywhere.

Things go wrong. Memo

Things go wrong. Memo.

```
get it    mov, eax, dword ptr [global (0B9...)]
ret it    add  eax, 1
store it  mov  dword ptr [global (0B9...)], eax
          ret  global = 0
```

In the end 1

Acht.

Mid 2

get of eax = 0

get 2 cars = 10

me  $A \cdot e_{ax} = 0 + 1 = 1$

store it global = 1

mult cas = 0 x 1

store of global = 1

what happened to  $1+1=2$ ?

show how atoms solve this. But only

But crafts for single instructions only!  
what if you need to have a whole bunch  
of code ~~written~~ atomic?  
takes much longer!

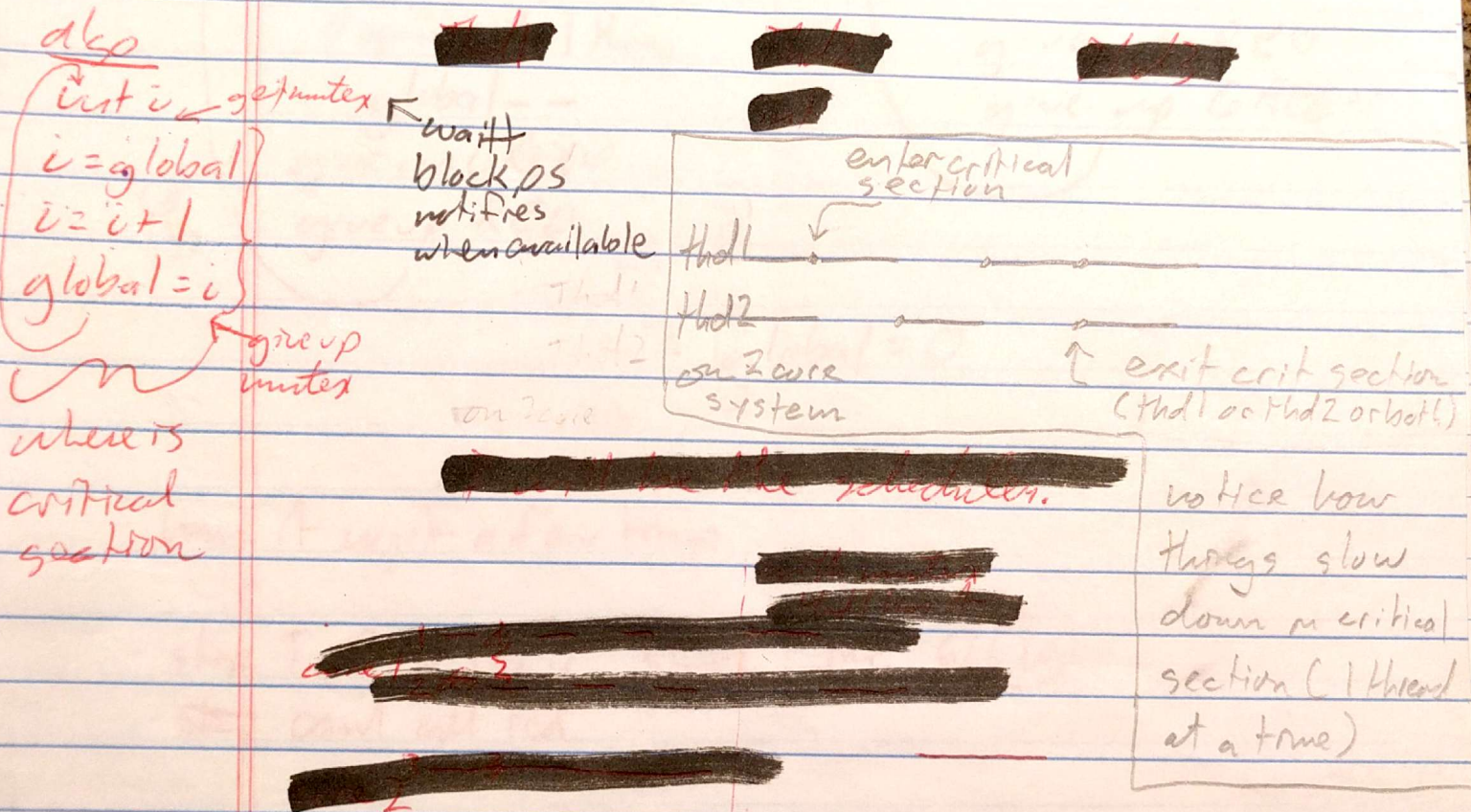


- single versus multi versus distributed processes
- race condition & atomic operations (w/ examples)  
atomics are single line only!
- critical section - code accesses shared resource that must complete without interrupt  
(will see more)

mutual



- ④ mutual exclusion - traffic cop as long as ~~the~~ everyone accesses using this. then only 1 can use at a time  
global = 3



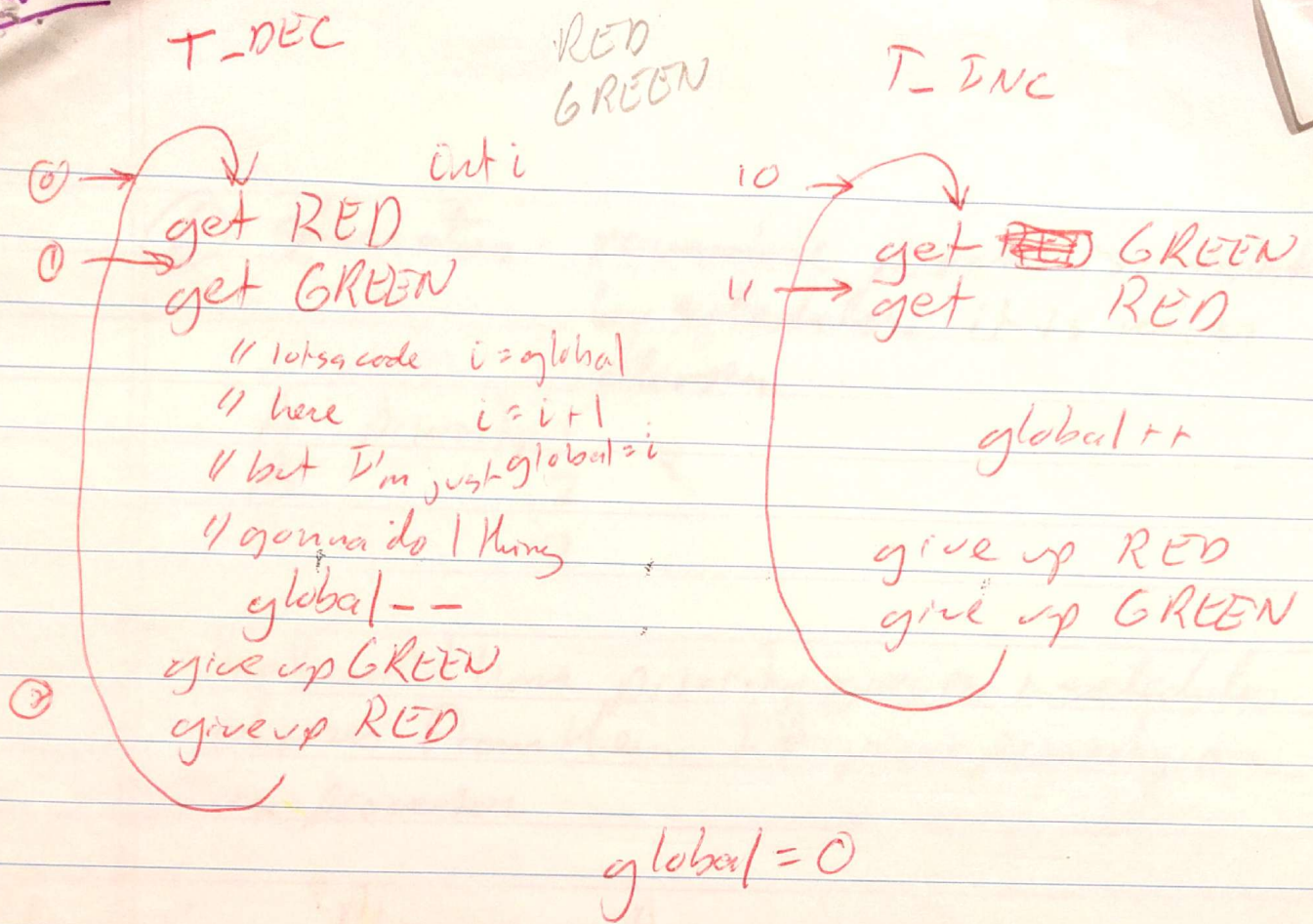
so it will slow things down

- ⑤ Deadlock - 2 or more processes are waiting to proceed because each has something other wants.

do demo



# dead lock



- have it work a few times

- stop T\_DEC @ ① start T\_inc @ ⑩  
stop can't get red.



⑥ Starvation - runnable process is overlooked by scheduler. it is never chosen.

A	priority 1
B	2
C	2

real world have priority queues & scheduler chooses from them. If A more priority on uniprocessor.

P1 queue - A  
P2 queue - B - C

↑ ↑

scheduler always chooses these. A will not run until B & C done.

Race condition <sup>(back to)</sup> - when program output depends on what gets done first, tough to reproduce & debug

ex. `int global = 2;`

```
⑦ void func1() {  
    if (global == 0) doZero(); ③  
    else doFail(); ④  
}  
  
int main() {  
    global thread myt(func1);  
    global = 0;  
}  
① critical section {
```

race condition,  
if ① happens before 2  
then ③  
else ④

what's gonna win?

[PSA - you may see  
code that "solves"  
this with delays.  
(sleep-for(), sleep-until())  
This is a non-scalable  
solution.]



Race Condition (Find it)

int balance = 50;

```
1 void withdraw (int amount) {  
2     if (balance > amount) {  
3         cout << "approved";  
4         balance -= amount;  
5     }  
}
```

2 threads start w balance \$50

Thread T1 withdraw 40 } 65 > 50!  
Thread T2 withdraw 25 }

Balance after

50 T1 starts gets to 3 (past the filter)  
50 preempted by T2,  
25 T2 runs to end  
-15 T1 switched back on finishes

go to slides 16

Hardware

Hardware - interrupt disable (slide 17)

10/31/17

Finished races, starvation, critical sections, deadlock  
demonstrated mutexes (deadlock, non-reentrant)  
showed how they effect code speed and correctness  
show how in the wrong places causes deadlock  
also efficiency  
Show them lock-guard next.