Hi Anthony,

It turns out your idea basically works.

However, there are some subtleties occurring in finite populations with design-based inference. In a standard setting this may not be a big deal, but it could be if inference is on a "small" population such as schools and/or if the number of possible samples from a population under a sampling design is small. A simple solution would be to do the procedure several times and take the average of estimates as the estimate. A nice plus is that this "automatically" happens with replicate weights.

Here follows a (perhaps somewhat overly detailed) description of why.

- Daniel

## **Definitions**

- Let U be the population of units, with unit i any element of U, and |U| the size of the population.
- Let A be a subset of the population U and let A be the collection of subsets of U that contains all possible samples.
- let the sampling design p(a) assign a probability measure to any sample  $a \in \mathcal{A}$ , i.e. p(a) = P(A = a) and denote by  $E_p$  the expectation over the probability space  $\mathcal{A}$  under design p(a).
- Let  $I_i$  be an indicator variable for whether unit  $i \in A$ , and let  $\pi_i := E_p(I_i)$
- Assume  $\pi_i$  and  $\pi_{ij} := E_p(I_i I_j)$  are known for any  $\{i, j\} \in A$

## Procedure

Create weights

$$w_i := \pi_i^{-1} + e_i,$$

where  $e_i$  is drawn from an i.i.d. probability distribution  $\xi$ , with mean  $\mu_e$  and standard deviation  $\sigma_e$ . For example  $e_i \sim \mathcal{N}(0, \sigma_e^2)$ 

• Define the linear estimator

$$T_A := \sum_{i \in A} w_i y_i$$

To be shown: Under the definitions above,

 $T_A$  is unbiased in the sense that

$$\lim_{|U| \to \infty} E_p(T_A) = T_U := \sum_{i \in U} y_i$$

## Proof of design-unbiasedness in the limit

$$E_{p}(T_{A}) = E_{p} \left( \sum_{i \in A} w_{i} y_{i} \right)$$

$$= E_{p} \left( \sum_{i \in U} I_{i} w_{i} y_{i} \right)$$

$$= E_{p} \left( \sum_{i \in U} I_{i} (\pi_{i}^{-1} + e_{i}) y_{i} \right)$$

$$= E_{p} \left( \sum_{i \in U} I_{i} \pi_{i}^{-1} y_{i} \right) + E_{p} \left( \sum_{i \in U} e_{i} y_{i} \right)$$

$$= \sum_{i \in U} E_{p}(I_{i}) \pi_{i}^{-1} y_{i} + \sum_{i \in U} E_{p} \left( e_{i} y_{i} \right)$$

$$= T_{U} + \sum_{i \in U} E_{p} \left( e_{i} y_{i} \right),$$

$$(1)$$

that is, the design bias  $E_p(T_A) - T_U$  equals  $\sum_{i \in U} E_p(e_i y_i)$ . The bias is therefore close to zero but not exactly equal to zero.

To see this, it is possible to imagine two processes for  $e_i$  leading to slightly different results:

- i.  $e_i$  is fixed over  $\mathcal{A}$  (i.e. drawn once);
- ii.  $e_i$  is random over  $\mathcal{A}$  (i.e. drawn separately for each possible sample). For fixed  $e_i$ ,

$$\sum_{i \in U} E_p(e_i y_i) = \sum_{i \in U} e_i y_i \tag{2}$$

The design bias can then be recognized as the maximum likelihood estimator (MLE) of the cross-product moment under the probability distribution  $\xi$ , that is,

$$\sum_{i \in U} e_i y_i = |U| \hat{\text{Cov}}_{\xi}(ey_i) - \hat{\mu}_e T_U, \tag{3}$$

where, collecting the parameters  $\hat{\theta} := [\hat{\mu}, \hat{\sigma}_e \hat{\text{Cov}}_{\xi}(ey_i)]$ , the population MLE is

$$\hat{\theta} = \arg\max_{\Theta} \xi \left[ \theta; \left\{ (y_i, e_i) : i \in U \right\} \right]. \tag{4}$$

If the researcher chooses  $\xi$  such that  $\mu_e = 0$  and  $Cov_{\xi}(ey_i) = 0$ , as is the case for  $\xi = \mathcal{N}(0, \sigma_e)$ , then

$$\lim_{|U| \to \infty} \left[ E_p(T_A) - T_U \right] = 0 \tag{5}$$

by Equation 3 and the standard result in maximum-likelihood theory that the probability limit of a quantity can be obtained by replacing parameter estimates by their probability limits. This demonstrates design-unbiasedness in the limit.

**Remarks** You can wonder how far away from 0 the design bias  $E_p(T_A) - T_U$  is likely to be. Again, applying standard results on ML estimation of covariances, it follows that as  $|U| \to \infty$  the design bias will follow, over  $\xi$ , a Normal distribution with variance proportional to the fourth-order central moment of  $e_i$ , i.e.  $\operatorname{Var}[E_p(T_A) - T_U] = |U|^{-1} E_{\varepsilon}[(e - \mu_e)^4]$ .

 $e_i$ , i.e.  $\operatorname{Var}[E_p(T_A) - T_U] = |U|^{-1} E_{\xi}[(e - \mu_e)^4]$ . Since  $\xi$  is likely to be known, it is reasonable to use the result for the finite population. For example, when choosing  $\xi = \mathcal{N}(\mu_e, \sigma_e)$ ,

$$\operatorname{Var}_{\xi}[E_p(T_A) - T_U] = |U|^{-1} 3\sigma^4.$$

What happens when we consider  $e_i$  random rather than fixed over  $\mathcal{A}$ ? For random  $e_i$ , each  $E_p\left(e_iy_i\right)$  is itself an aggregate of numbers converging to 0 as the number of draws from  $\xi$  increases, while  $\sum_{i\in U} E_p\left(e_iy_i\right)$  is an aggregate of aggregates. For example, if  $e_i$  is drawn once from  $\mathcal{N}(0, \sigma_e^2)$  for each sample A,

$$\operatorname{Var}_{\xi}[E_{p}(T_{A}) - T_{U}] \approx (|U| + |A|)^{-1} 3\sigma^{4}.$$

Thus, the more draws of  $e_i$ , the closer the design bias will be to 0.