Machine Learning

in 2018... Deep Learning!

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Convolutional Neural Nets

Exploiting stationarity, locality, and compositionality of natural data

Signals can be represented as vectors



$$\boldsymbol{x} = [x_1 \ x_2 \ x_3 \ \dots \ x_t \ \dots]^{\top}$$

 x_t are waveform heights



$$\boldsymbol{x} = [x_{11} \ x_{12} \ \dots \ x_{1n} \ x_{21} \ x_{22} \ \dots]^{\top}$$

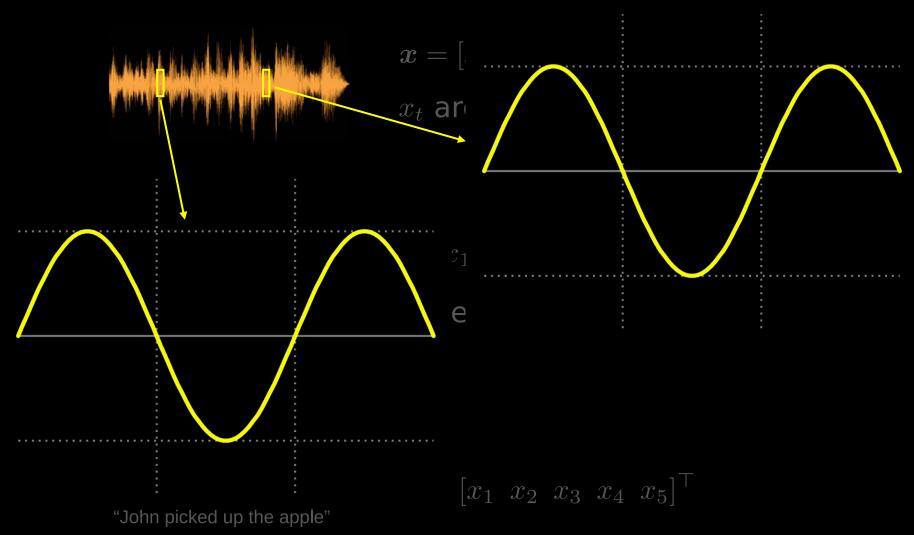
 x_{ij} are pixel values

"John picked up the apple"

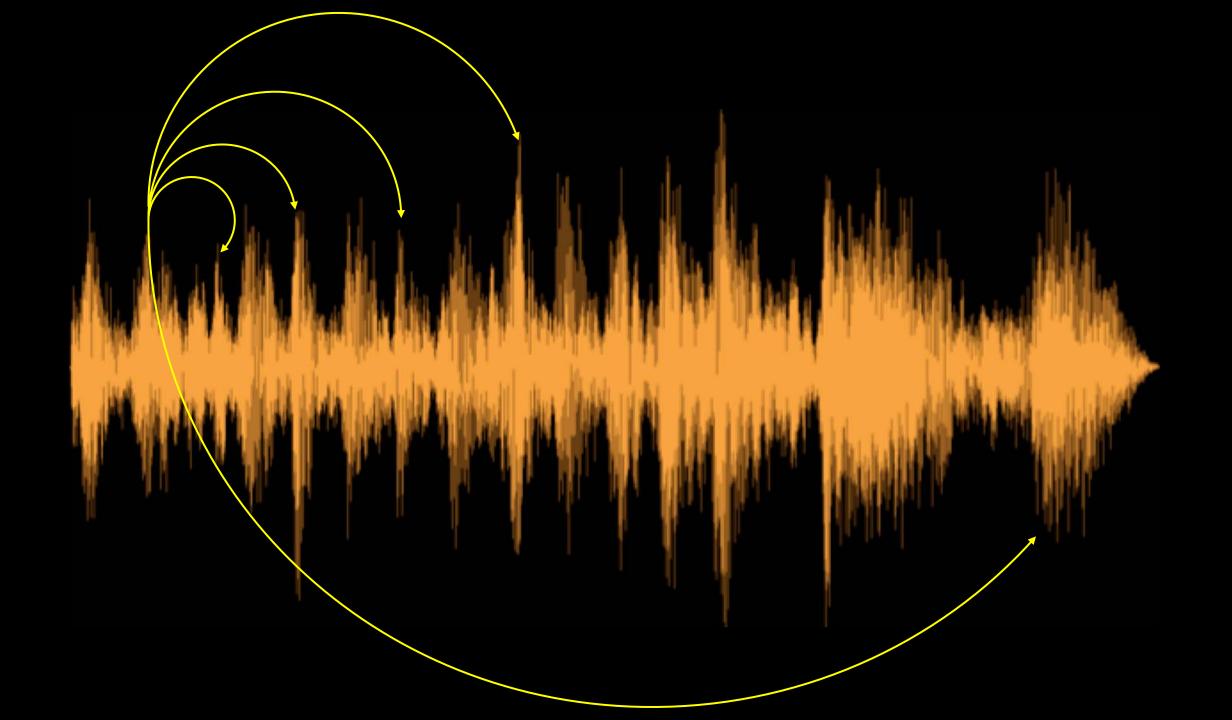
$$\boldsymbol{x} = [x_1 \ x_2 \ x_3 \ x_4 \ x_5]^{\top}$$

 x_t are one-hot vectors

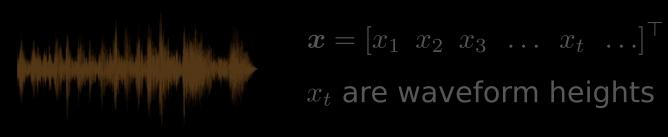
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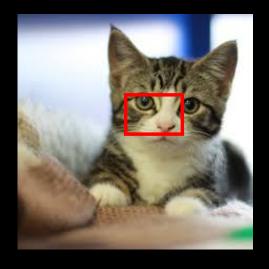


Signals can be represented as vectors



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 x_t are waveform heights



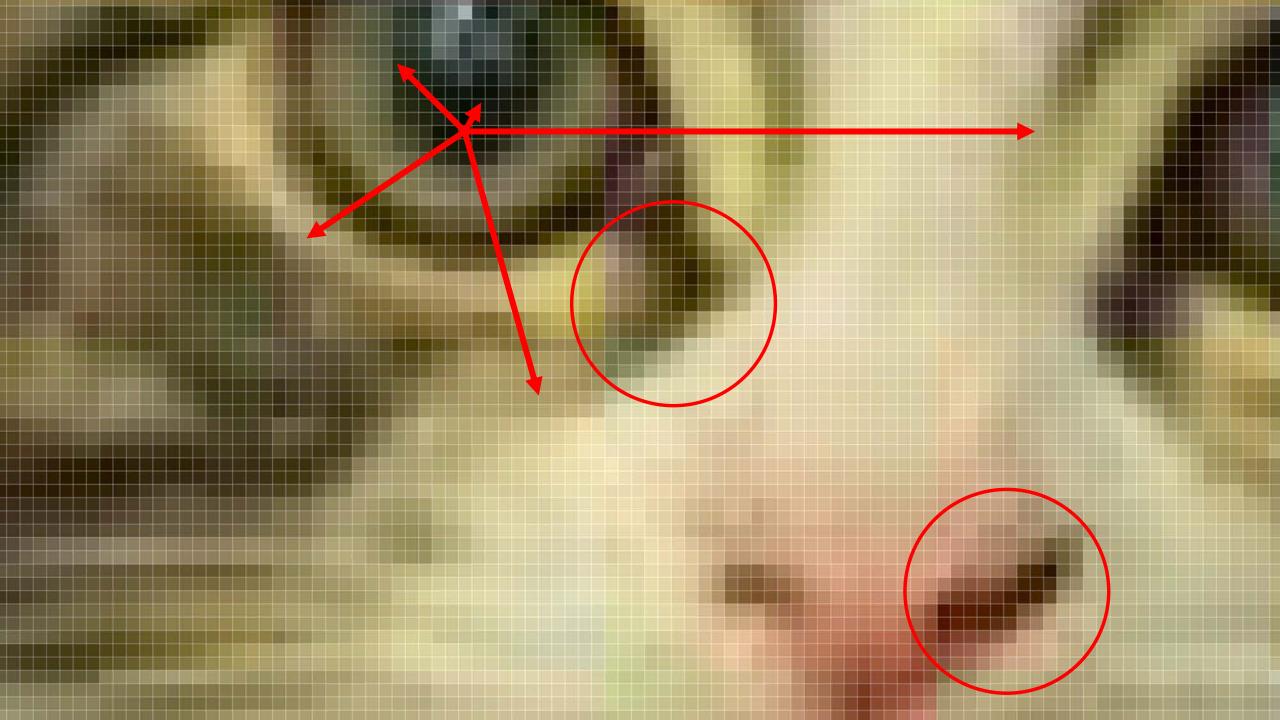
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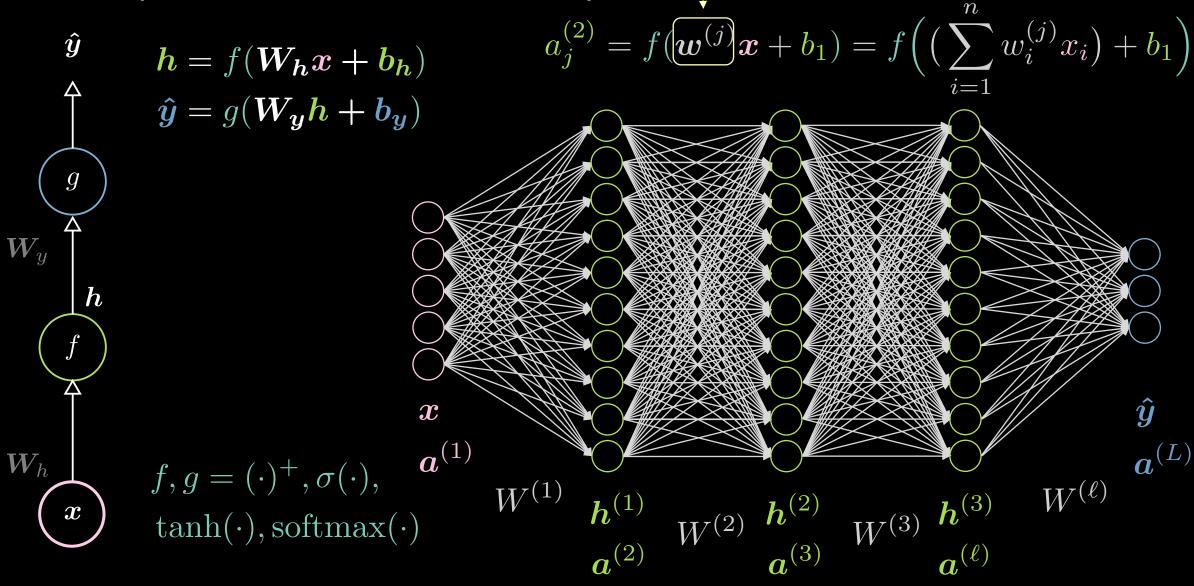
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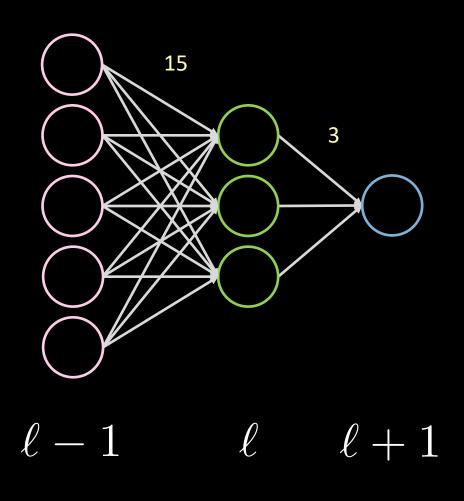


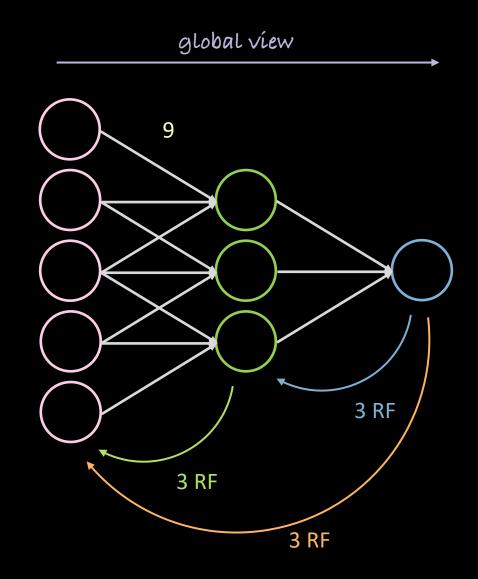
j-th row of $W^{(1)}$

Fully connected (FC) layer

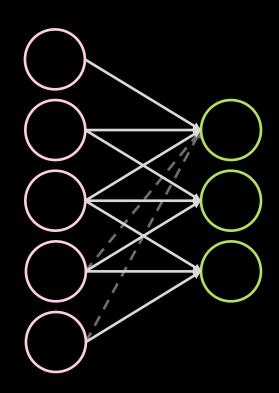


Locality ⇒ sparsity





Stationarity ⇒ parameters sharing

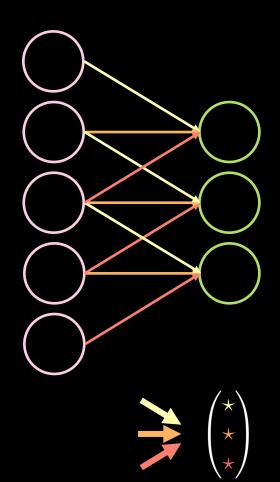


Parameters sharing

- faster convergence
- better generalisation
- not constrained to input size
- kernel independence
 - \Rightarrow high parallelisation

Connection sparsity

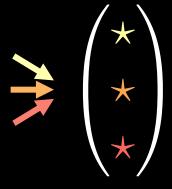
reduced amount of computation

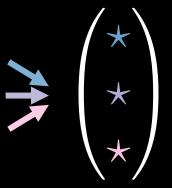


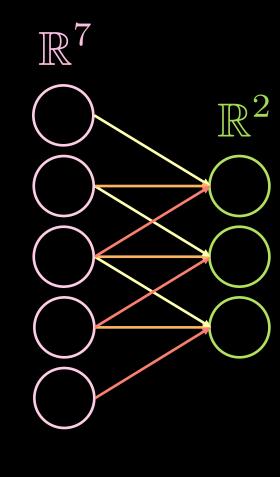
Kernels – 1D data

kernel size: $2 \times 7 \times 3$

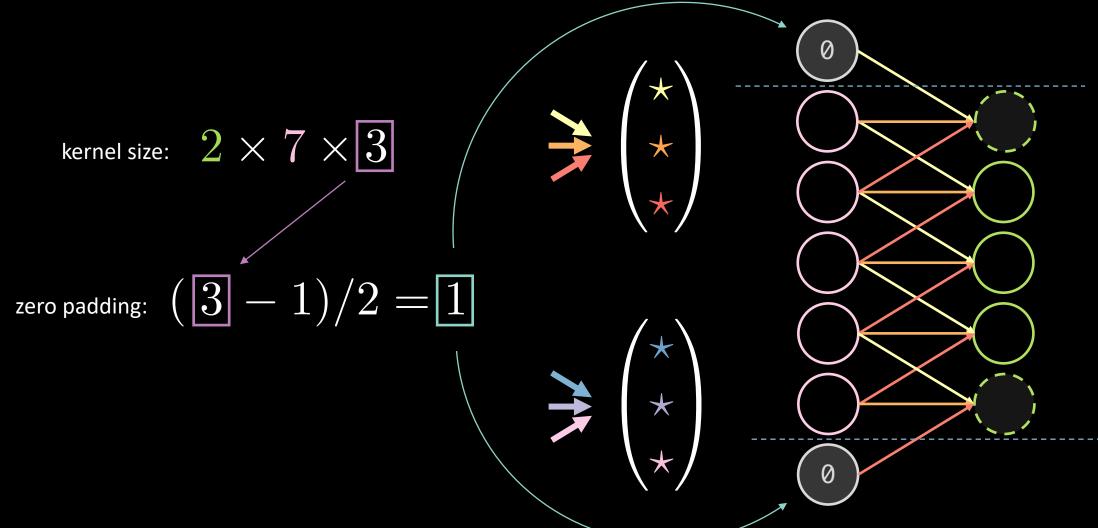
1D data uses 3D kernels!





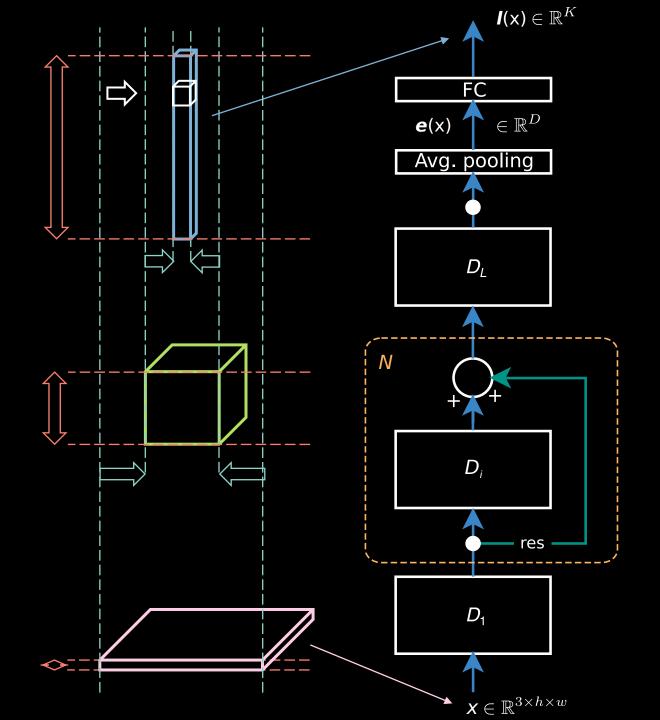


Padding – 1D data



Standard spatial CNN

- Multiple layers
 - Convolution
 - Non-linearity
 - Pooling
 - Batch normalisation
- Residual bypass connection



n/2

