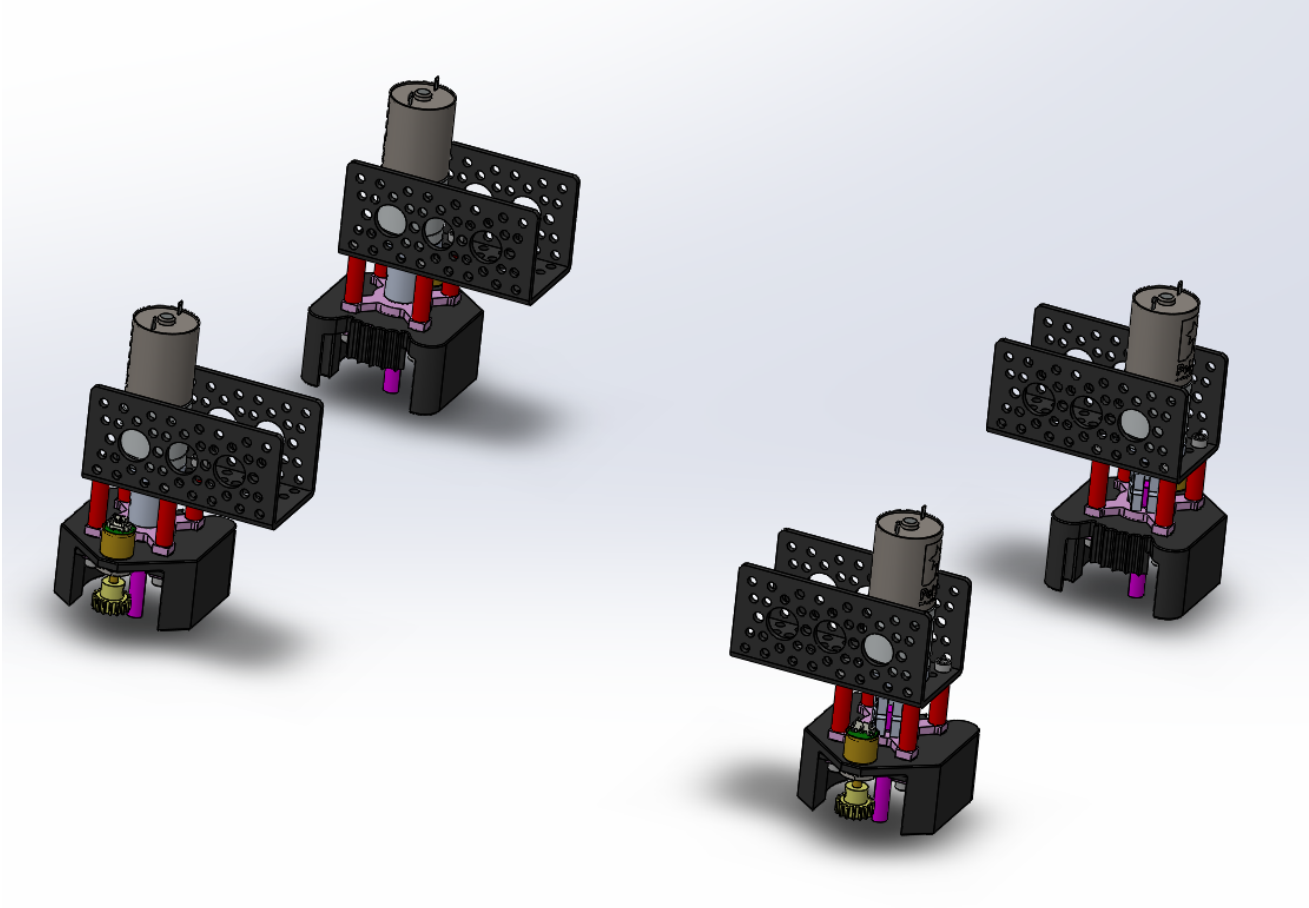

Open Source Rover: Corner Steering Assembly Instructions

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Contents

1 3D printing

First, print the 3D printed encoder mounts. The STL files for this are located in the Corner Steering Assembly folder, under 3D Printed Parts. If you do not have a 3D printer there are many online 3D printing services available. One such service is:

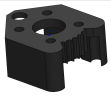
- https://www.makexyz.com

To order these parts from Makexyz upload the STL file, select FDM under process, and PLA for Material, and then your desired color. **You will need a total of 4 of these encoder mount pieces**.

2 Mechanical/Structural Assembly

The Corner Steering assembly contains the steering motors which allow the rover to utilize Ackerman steering. One important aspect of this assembly is the use of the bearing blocks. These blocks help to take forces on the motor shaft against the gearbox and minimize lateral moments applied against the motor shaft. By using the bearing blocks, we help protect the motor and motor shaft from these forces that could otherwise damage the motor and its gearbox. The lever arm for the corner steering system is much farther away from the motor than at the drive motors, where we can get away with directly attaching the load path to the motor shaft.

Table 1: Parts/Tools Necessary

Item	Ref	Qty	Image	Item	Ref	Qty	Image
3" Channel	S2	4		Motor (Corner Motor)	E6	4	
Motor Mount F	S9	4		Absolute Encoder	E7	4	
0.25" Pillow Block	S10	8		#6-32x1/4" Spacer	T1	16	
0.25" D-Shaft	S15	4		#6-32 x 1.25" Threaded Standoff	T9	16	
0.25" to 6mm Clamping Shaft Coupler	S38	4		#6-32x1/4" Button Head Screw	B1	24	
1/8" Bore Pinion Gear	S27	4		#6-32x3/4" Button Head Screw	B5	16	
3D Printed Encoder Mount	S31	4		Allen Key Set	D2		

1. **Motor Mount:** Begin by mounting the motor **E6** to the 3 inch channel **S2** using the motor mount F **S9** and screws **B1** as shown.

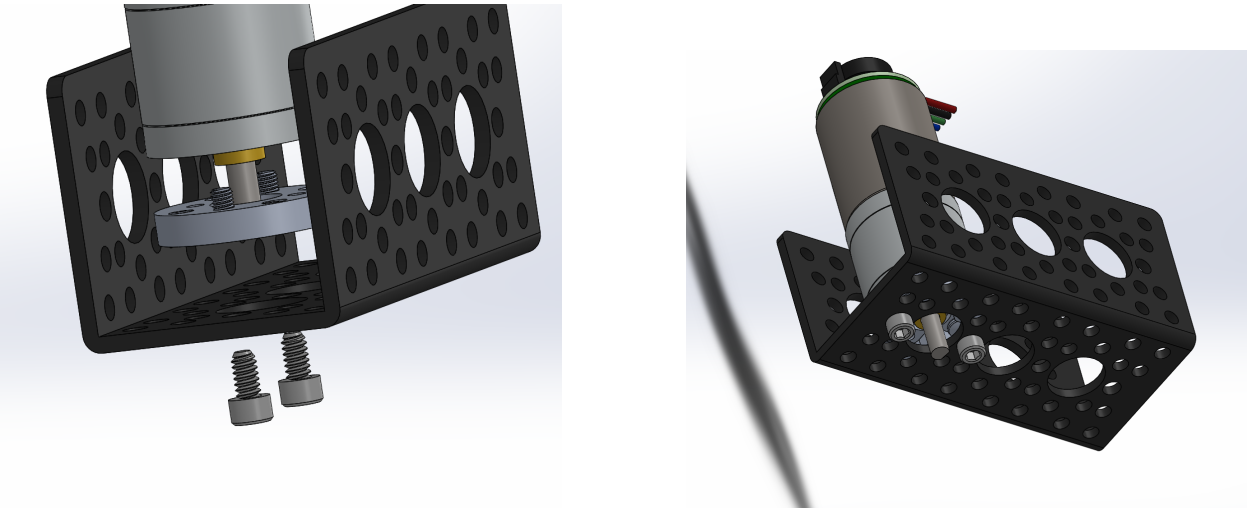


Figure 1: Corner Steering Step 1

2. **Shaft Coupler/Standoffs Attachment:** Attach the motor shaft to the 0.25 inch D-shaft **S15** using the shaft coupler **S23**. Also take the 0.75inch long standoffs **T5** and attach them to the bottom of the channel centered around the motor using screws **B1** as shown in Figure 2.

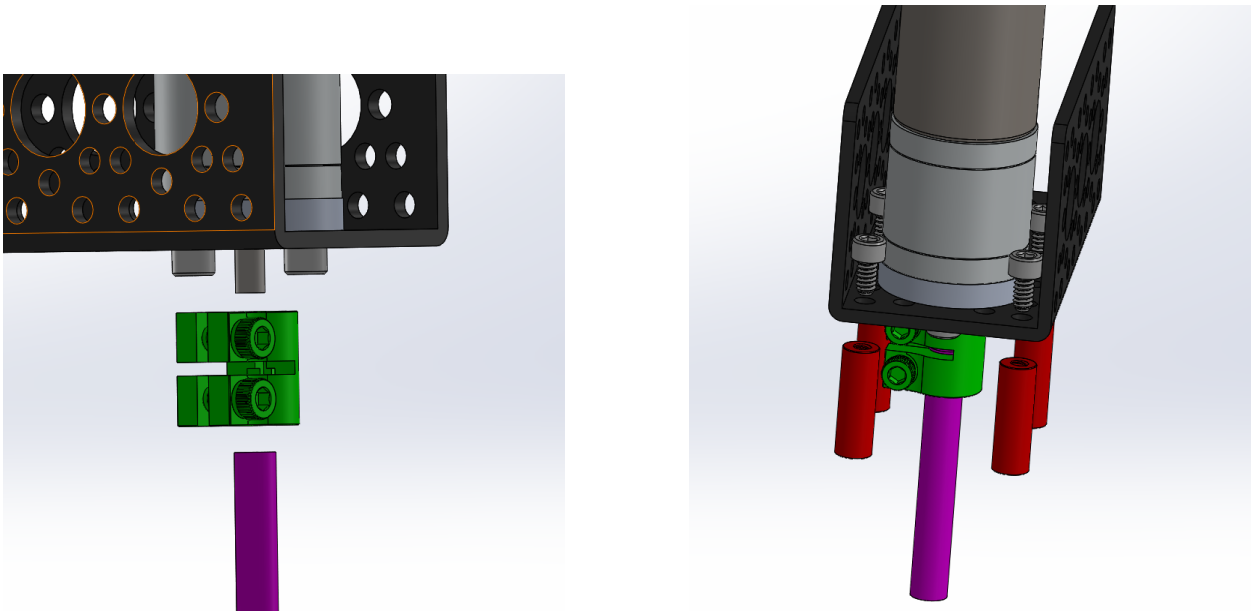


Figure 2: Corner Steering Step 2

3. **Encoder Mount:** Press the 0.25inch Spacers **T1** into the 3D printed encoder mount **S31**. If they do not fit, you can drill or file out the holes slightly until the spacers fit as shown in Figure 3 (The size and tolerance of the holes will vary slightly based on different 3D printers and materials). Attach the encoder mount and bearings to the threaded standoffs **T3** using screws **B5** and 0.25 inch pillow bearing blocks **S10**.

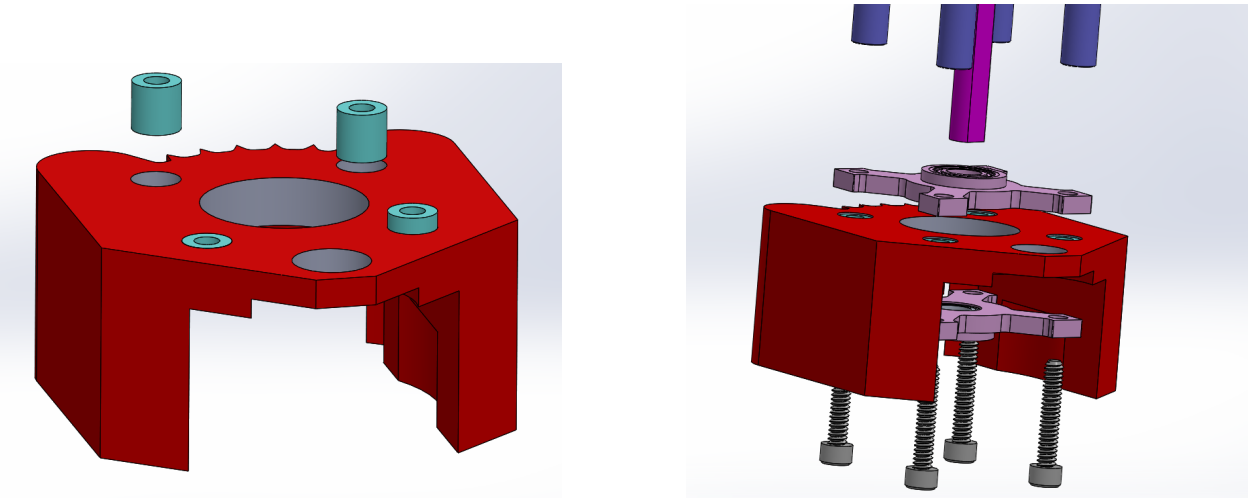


Figure 3: Corner Steering Step 3

4. **Encoder:** Attach the encoder **E7** to the encoder mount **S31** and then attach the 12-tooth gear **S27** to the encoder shaft. We will worry about its exact position later on. You should now have one finished corner steering assembly. Repeat the steps above to build the other 3 corner steering assemblies. **Note that unlike other assemblies, this assembly isn't identical for all four of them! You will need to build two versions where the encoder mount is mirrored about the motor shaft (see Figure 4 for an example).**

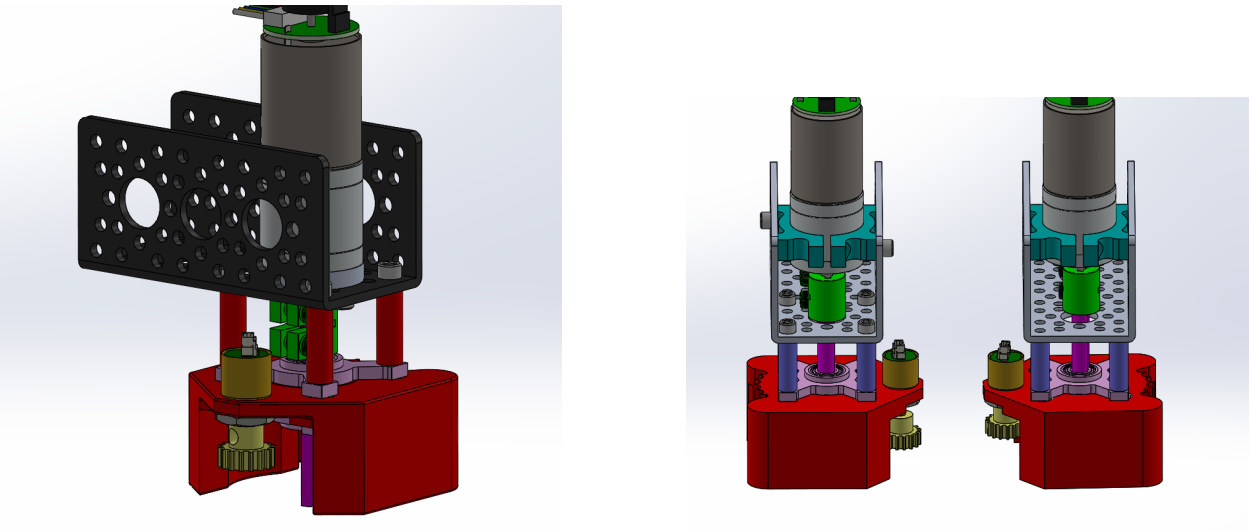


Figure 4: Corner Steering Step 4