

Hadamard Transform \rightarrow

\Rightarrow The 1-D, forward Hadamard Kernel is given by the relation

$$g(x, u) = \frac{1}{N} (-1)^{\sum_{i=0}^{n-1} b_i(x) b_i(u)}$$

i.e. $g(x, u) = \frac{1}{N} (-1)^{\sum_{i=0}^{n-1} b_i(x) b_i(u)}$

\Rightarrow The 1-D Hadamard transform is given by

$$H(u) = \frac{1}{N} \sum_{x=0}^{N-1} f(x) (-1)^{\sum_{i=0}^{n-1} b_i(x) b_i(u)}$$

where $N=2^n$, and u has values in the range $0, 1, 2, \dots, N-1$

\Rightarrow The Hadamard Kernel forms a matrix having orthogonal rows and columns

\Rightarrow The inverse Hadamard Kernel is given by

$$h(x, u) = (-1)^{\sum_{i=0}^{n-1} b_i(x) b_i(u)}$$

\Rightarrow The inverse Hadamard Transform

$$f(x) = \sum_{u=0}^{N-1} H(u) (-1)^{\sum_{i=0}^{n-1} b_i(x) b_i(u)}$$

for $x=0, 1, 2, \dots, N-1$

$$[0 \dots N-1]$$

The 2-D kernels are given by

$$g(x, y, u, v) = \frac{1}{N} (-1)^{\sum_{i=0}^{n-1} [b_i(x)b_i(u) + b_i(y)b_i(v)]}$$

and

$$h(x, y, u, v) = \frac{1}{N} (-1)^{\sum_{i=0}^{n-1} [b_i(x)b_i(u) + b_i(y)b_i(v)]}$$

⇒ The 2-D Hadamard transform pair

$$H(u, v) = \frac{1}{N} \sum_{x=0}^{N-1} \sum_{y=0}^{N-1} f(x, y) (-1)^{\sum_{i=0}^{n-1} [b_i(x)b_i(u) + b_i(y)b_i(v)]}$$

and

$$f(x, y) = \frac{1}{N} \sum_{u=0}^{N-1} \sum_{v=0}^{N-1} H(u, v) (-1)^{\sum_{i=0}^{n-1} [b_i(x)b_i(u) + b_i(y)b_i(v)]}$$

⇒ The Hadamard matrix of lowest order ($N=2$) is

$$H_2 = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

⇒ Letting H_N represent the matrix of order N , the recursive relationship is

$$H_{2N} = \begin{bmatrix} H_N & H_N \\ H_N & -H_N \end{bmatrix}$$

where H_{2N} is the Hadamard matrix of order $2N$ and $N=2^n$ is assumed

The transformation matrix is given by

$$A = \frac{1}{\sqrt{N}} H_N$$

$$H_4 = \begin{bmatrix} H_2 & H_2 \\ H_2 & -H_2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix}$$

and

$$H_8 = \begin{bmatrix} H_4 & H_4 \\ H_4 & -H_4 \end{bmatrix}$$

$$H_8 = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 & 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 & 1 & -1 & -1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 1 & -1 & 1 & -1 & -1 & 1 & -1 & 1 \\ 1 & 1 & -1 & -1 & -1 & -1 & 1 & 1 \\ 1 & -1 & -1 & 1 & -1 & 1 & 1 & -1 \end{bmatrix}$$

THE HAAR TRANSFORM

The Haar functions $h_k(x)$ are defined on a continuous interval, $x \in [0, 1]$, and for $k = 0, \dots, N-1$, where $N = 2^n$. The integer k can be uniquely decomposed as

$$k = 2^p + q - 1$$

PAGE 3

where $0 \leq p \leq n-1$; $q = 0, 1$ for $p = 0$ and $1 \leq q \leq 2^p$ for $p \neq 0$. For eg: \rightarrow when $N=4$, we have

k	0	1	2	3
p	0	0	1	1
q	0	1	1	2

$$\begin{aligned}
 N &= 2^n \\
 N &= 4 \\
 2^1 &= 4 \\
 2^0 &= 2 \\
 2^0 &= 2 \\
 2^0 &= 2
 \end{aligned}$$

Representing k by (p, q) , the Haar functions are defined as

$$h_0(x) \equiv h_{0,0}(x) = \frac{1}{\sqrt{N}}, \quad x \in [0, 1]$$

$$h_k(x) = h_{p,q}(x) = \frac{1}{\sqrt{N}} \begin{cases} 2^{p/2}, & 0 \leq \frac{q-1}{2^p} \leq x \leq \frac{q}{2^p} \\ -2^{p/2}, & \frac{q-1}{2^p} \leq x < \frac{q}{2^p} \\ 0 & \text{otherwise} \end{cases}$$

Haar Transform when $N=2$

$\therefore k=0, 1$

k	0	1
p	0	0
q	0	1

\Rightarrow The first row is ~~computed~~ of 2×2 Haar matrix is computed by using $h_0(x)$ with $x = 0/2, 1/2$

$\Rightarrow h_0(x)$ is equal to $1/\sqrt{2}$, independent of x

\Rightarrow So the first row of the matrix has two identical elements $1/\sqrt{2}$

\Rightarrow The second row is obtained by computing $h_1(x)$ for $x = 0/2, 1/2$

\Rightarrow When $k=1, p=0 \& q=1$

So,

$$h_1(x) = h_{01}(x) = \frac{1}{\sqrt{2}} \begin{cases} 1 & 0 \leq x < 1/2 \\ -1 & 1/2 \leq x < 1 \\ 0 & \text{otherwise for } x \in [0, 1] \end{cases}$$

$$\therefore h_1(0/2) = h_1(0) = 1/\sqrt{2}$$

$$h_1(1/2) = -1/\sqrt{2}$$

$$\therefore A_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

Following similar procedure yield the matrix for $N=4$

$$A_4 = \frac{1}{\sqrt{4}} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ \sqrt{2} & -\sqrt{2} & 0 & 0 \\ 0 & 0 & \sqrt{2} & -\sqrt{2} \end{bmatrix}$$

$$H_8 = \frac{1}{\sqrt{8}} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} \\ 2 & -2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 & -2 \end{bmatrix} \begin{matrix} \varphi_0(t) \\ \psi_0(t) \\ \psi_{1,0}(t) \\ \psi_{1,1}(t) \\ \psi_{2,0}(t) \\ \psi_{2,1}(t) \\ \psi_{2,2}(t) \\ \psi_{2,3}(t) \end{matrix}$$

The Cosine Transform \rightarrow

The $N \times N$ cosine transform matrix $C = \{c(k, n)\}$ also called the discrete cosine transform (DCT) is defined as

$$c(k, n) = \begin{cases} \frac{1}{\sqrt{N}} & k=0, 0 \leq n \leq N-1 \\ \sqrt{\frac{2}{N}} \cos \frac{\pi(n+1)k}{2N} & 1 \leq k \leq N-1, \\ & 0 \leq n \leq N-1 \end{cases}$$

The one-dimensional DCT of a sequence $\{u(n), 0 \leq n \leq N-1\}$ is defined as

$$U(k) = \alpha(k) \sum_{n=0}^{N-1} u(n) \cos \left[\frac{\pi (2n+1)k}{2N} \right],$$
$$0 \leq k \leq N-1$$

where

$$\alpha(0) = \sqrt{\frac{1}{N}} \quad \alpha(k) = \sqrt{\frac{2}{N}} \text{ for } 1 \leq k \leq N-1$$

The inverse transformation is given by

$$u(n) = \sum_{k=0}^{N-1} \alpha(k) U(k) \cos \left[\frac{\pi (2n+1)k}{2N} \right],$$
$$0 \leq n \leq N-1$$

Properties \Rightarrow

- ① The cosine transform is real and orthogonal
i.e., $C = C^* \Rightarrow C^{-1} = C^T$
- ② The cosine transform has excellent energy compaction for highly correlated data

Properties of Hadamard Transform:

- (1) It is real, symmetric and orthogonal
ie

$$H = H^* \Rightarrow H^{-1} = H^T$$

- (2) It is a fast transform and 1-D Hadamard Transform can be implemented in $O(N \log_2 N)$ addition and subtraction.
- (3) It has only binary values ie 1 or -1 in its kernel matrix. No multiplications are required in the transform.
- (4) It is used for digital image processing and digital signal processing.
- (5) It has good energy compaction for highly co-related image.

Properties of Haar Transform:

- (1) It is symmetric, seperable unitary transform that uses haar function for its basis.

- (2) It is orthogonal and real.
ie

$$T^{-1} = T^T \Rightarrow H_T = H_T^*$$

- (3) It is a fast transform and can be implemented in $O(N)$ operation. Where, N is a number of samples.
- (4) It exist for $N = 2^n$, where 'n' is an integer.
- (5) It has poor energy compaction property.