A Proof of Theorem 1

Proof. As discussed above, we have two cases as follows.

Case 1: First we consider the case that w,u,v are from left to right, with their stationary points $x_k^{(w)*} < x_k^{(u)*} < x_k^{(v)*}$. A standard gradient descent update is $\tilde{x} \leftarrow \tilde{x} - \eta \nabla_{x_k} f_y^{(u)}|_{x_k = \tilde{x}}$. To ensure one step update could make \tilde{x} jump from u to v, we obtain:

$$\tilde{x} - \eta \nabla_{x_k} f_y^{(u)}|_{x_k = \tilde{x}} \ge x_k^{(v)*}$$

$$\Rightarrow \tilde{x} - \eta \sum_{j=p}^{p+q} 2(\tilde{x} - y_j) \ge x_k^{(v)*} \text{ (use Equation 5)}$$

$$\Rightarrow (1 - 2\eta(q+1))\tilde{x} + 2\eta(q+1) \frac{1}{q+1} \sum_{j=p}^{p+q} y_j \ge x_k^{(v)*}$$

$$\Rightarrow (1 - 2\eta(q+1))\tilde{x} \ge x_k^{(v)*} - 2\eta(q+1)x_k^{(u)*} \text{ (use Equation 7)}$$
(11)

Now we have two possibilities:

Possibility (a): $1 - 2\eta(q+1) > 0$:

Inequality
$$11 \Rightarrow \tilde{x} \ge \frac{x_k^{(v)*} - 2\eta(q+1)x_k^{(u)*}}{1 - 2\eta(q+1)}$$

To guarantee the gradient direction points to neighbor v, the starting point \tilde{x} has to be to the left of $x_k^{(u)*}$, thus:

$$\frac{x_k^{(v)*} - 2\eta(q+1)x_k^{(u)*}}{1 - 2\eta(q+1)} \le \tilde{x} < x_k^{(u)*}$$

$$\Rightarrow x_k^{(v)*} - 2\eta(q+1)x_k^{(u)*} < (1 - 2\eta(q+1))x_k^{(u)*}$$

$$\Rightarrow x_k^{(v)*} < x_k^{(u)*}$$
(12)

This is contradictory to the assumption that $x_k^{(w)*} < x_k^{(u)*} < x_k^{(v)*}$, and thus is not valid.

Possibility (b): $1 - 2\eta(q+1) < 0$:

Inequality
$$11 \Rightarrow \tilde{x} \le \frac{x_k^{(v)*} - 2\eta(q+1)x_k^{(u)*}}{1 - 2\eta(q+1)}$$

Due to the fact that \tilde{x} is inside region u, which must be somewhere to the right of $x_k^{(w)*}$ (with the assumption that w has a bowl-shape), we have:

$$\frac{x_k^{(v)*} - 2\eta(q+1)x_k^{(u)*}}{1 - 2\eta(q+1)} \ge \tilde{x} > x_k^{(w)*}$$

$$\Rightarrow x_k^{(v)*} - 2\eta(q+1)x_k^{(u)*} < (1 - 2\eta(q+1))x_k^{(w)*}$$

$$\Rightarrow x_k^{(v)*} - x_k^{(w)*} < 2\eta(q+1)(x_k^{(u)*} - x_k^{(w)*})$$

$$\Rightarrow \eta > \frac{1}{2(q+1)} \left(\frac{x_k^{(v)*} - x_k^{(w)*}}{x_k^{(u)*} - x_k^{(w)*}}\right)$$
(13)

Recall that q is an integer and $q \ge 0$, thus

$$1 - 2\eta(q+1) < 0 \Rightarrow \eta > \frac{1}{2(q+1)} \tag{14}$$

Also notice that

$$x_k^{(w)*} < x_k^{(u)*} < x_k^{(v)*} \Rightarrow \frac{x_k^{(v)*} - x_k^{(w)*}}{x_{l_*}^{(u)*} - x_{l_*}^{(w)*}} > 1$$
(15)

Putting Inequalities 13, 14 and 15 together, we obtain $\eta > \frac{1}{2(q+1)}$.

Case 2: here w,u,v are from right to left, and $x_k^{(w)*}>x_k^{(u)*}>x_k^{(v)*}$. This is very similar to Case 1, so we omit the details and provide the final result as

$$\eta > \frac{1}{2(q+1)} \left(\frac{x_k^{(w)*} - x_k^{(v)*}}{x_k^{(u)*} - x_k^{(v)*}} \right) \text{ and } \frac{x_k^{(w)*} - x_k^{(v)*}}{x_k^{(u)*} - x_k^{(v)*}} > 1$$
 (16)

We will arrive at the same result: $\eta > \frac{1}{2(q+1)}$.

Note that the length of the pattern x is l and the length of input y is n. As a result, the expected number of elements in y aligned to a single x_i , $i \in [0, l-1]$ should be n/l, i.e. $\mathbb{E}[q] = n/l - 1$. Taking expectation on both sides of the above inequality, we obtain $\mathbb{E}[\eta] > \frac{1}{2(n/l-1+1)} = \frac{l}{2n}$. \square

Corollary 1. With the same assumption of Theorem 1, let pattern x and input y have the same length, i.e., n = l. In order to make one step jumping out of local region u, we should have $\mathbb{E}[\eta] > \frac{1}{2}$.

B Detailed Experimental Results for Multivariate DTWNet

Multivariate DTWs are often computed in two forms: MDTW-I and MDTW-D [21]. MDTW-I treats each dimension independently, so it is simply a stack of multiple univariate DTWs, thus directly applies to our method. MDTW-D needs to compute multivariate distance $\text{mdtw}^2 = \sum ||\mathbf{x_i} - \mathbf{y_j}||^2$, $\mathbf{x_i} \in \mathbf{R^m}$, $\mathbf{y_j} \in \mathbf{R^m}$ in the Dynamic Programming step, instead of the scaler version $\sum ||x_i - y_j||^2$. As long as the norm is well defined, e.g., Euclidean distance, the forward pass and the backpropagation are performed in the same manner. We can even define other distances, as long as their gradients w.r.t. to the vector \mathbf{x} can be computed.

We run a 3-dim multivariate time series classification task here, using MDTW-D and Euclidean distance in our approach. The experiment settings follow Section 6.1 in the paper. The following figures show: one sample data (3-variate series) from each category, the learned kernel, test loss and test acc comparison. Our method (DTW) outperforms others.

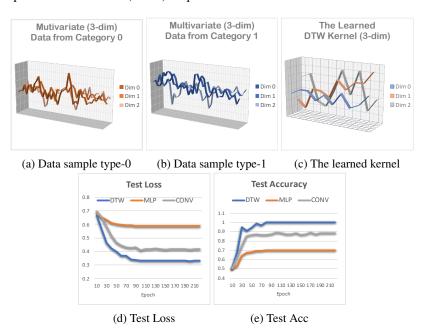


Figure 6: Multivariate DTWNet Experiment

C Detailed Experimental Results for Barycenter Experiment

Table 2: Barycenter Experiment, Average DTW Loss on Training Set

Solition		C CDTW	C CDWW	C CDMW	O CDWW			
Sovensh		SoftDTW $\gamma = 1$	SoftDTW $\gamma = 0.1$	SoftDTW $\gamma = 0.01$	SoftDTW $\gamma = 0.001$	SSG	DBA	Ours
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Table 3: Barycenter Experiment, Average DTW Loss on Testing Set

	SoftDTW	SoftDTW	SoftDTW	SoftDTW			
	$\gamma = 1$	$\gamma = 0.1$	$\gamma = 0.01$	$\gamma = 0.001$	SSG	DBA	Ours
50words Adiac	13.770 0.838	11.642 0.305	11.031 0.285	10.913	11.162 0.245	11.195	10.709 0.564
ArrowHead	5.427	4.402	3.690	0.585 3.478	3.766	0.256 3.688	4.009
Beef	14.946	14.178	9.814	11.599	14.822	12.016	8.813
BeetleFly	53.030	38.986	36.598	38.443	41.506	40.907	36.863
BirdChicken	43.657	19.897	22.499	20.594	36.865	30.522	22.585
CBF	24.343	15.210	17.237	15.566	14.194	14.596	13.755
Car	4.355	3.072	2.723	2.753	2.654	2.462	2.573
ChlorineConcentration CinC_ECG_torso	25.474 180.663	17.345 141.548	18.659 141.753	17.919 132.553	16.459 166.838	17.341 136.126	16.492 128.023
Coffee	1.226	0.826	1.293	1.577	0.658	0.654	1.045
Computers	176.868	157.962	148.396	153.658	146.668	153.739	159.314
Cricket_X	51.207	37.780	38.551	37.916	36.245	37.398	36.214
Cricket_Y	43.451	34.059	33.094	33.679	32.414	33.642	32.629
Cricket_Z	48.466	36.712	36.351	37.211	36.525	36.586	35.056
DiatomSizeReduction	4.010	4.024	3.902	3.896	3.899	3.907	4.246
DistalPhalanxOutlineAgeGroup DistalPhalanxOutlineCorrect	1.523 2.785	1.304 2.351	1.526 2.750	2.036 2.557	1.061 1.958	1.065 1.956	1.841 1.979
DistalPhalanxTW	1.405	0.997	1.977	1.705	0.806	0.806	1.179
ECG200	9.344	7.555	8.911	8.784	7.780	8.422	6.959
ECG5000	26.295	22.558	22.592	24.241	25.302	27.389	22.372
ECGFiveDays	8.767	10.175	10.589	10.965	7.422	7.336	8.647
Earthquakes	156.759	110.492	108.953	109.385	106.678	102.084	107.288
ElectricDevices	43.261	37.808	37.130	37.421	36.852	36.939	35.069
FISH	1.808	1.661	1.535	1.682	1.464	1.422	1.652 19.027
FaceAll FaceFour	20.162 38.929	18.590 38.416	19.029 40.709	20.625 40.024	17.536 36.045	17.428 39.897	39.898
FacesUCR	20.339	19.555	20.671	20.296	17.635	17.090	18.105
FordA	65.742	56.997	55.973	55.459	53.513	53.965	52.667
FordB	69.145	60.406	61.231	59.489	57.921	58.954	56.693
Gun_Point	8.030	2.816	2.478	2.428	3.172	2.796	2.315
Ham	31.478	28.953	26.317	30.149	26.639	26.455	25.510
HandOutlines Haptics	25 421	22.077	20.694	21.066	10.864	10.794	7.733
Herring	25.431 1.465	22.077 1.385	20.684 1.331	21.966 1.462	17.196 0.915	17.926 0.948	24.014 1.372
InlineSkate	127.648	65.537	48.215	45.301	58.181	55.270	40.608
InsectWingbeatSound	17.576	16.680	15.102	15.010	16.210	15.079	15.493
ItalyPowerDemand	2.523	2.578	2.523	2.820	2.147	2.705	2.369
LargeKitchenAppliances	118.456	114.174	107.120	107.325	122.776	131.369	110.499
Lighting2	86.450	75.184	72.139	81.725	78.196	78.350	73.070
Lighting7	48.326	37.158	36.557	38.376	37.673	37.747	41.663
MALLAT Meat	6.002 0.593	4.692 0.259	4.717 0.438	6.280 1.569	3.668 0.041	3.379 0.041	4.938 0.470
MedicalImages	8.252	8.807	9.334	8.741	7.194	6.916	7.762
MiddlePhalanxOutlineAgeGroup	0.835	0.770	1.540	1.158	0.723	0.733	0.962
MiddlePhalanxOutlineCorrect	1.235	1.223	1.145	2.254	1.187	1.200	0.998
MiddlePhalanxTW	0.836	0.729	1.054	1.051	0.592	0.570	0.694
MoteStrain	22.970	23.938	22.080	24.643	21.964	21.094	25.032
NonInvasiveFatalECG_Thorax1 NonInvasiveFatalECG_Thorax2	2.745 2.384	2.919 2.888	3.560 3.146	3.890 3.711	1.548 1.465	1.509 1.521	3.561 2.955
OSULeaf	35.193	26.392	23.544	24.177	25.619	23.188	23.352
OliveOil	0.961	0.747	2.107	2.002	0.020	0.020	1.082
PhalangesOutlinesCorrect	2.067	1.556	1.782	1.487	1.254	1.239	1.251
Phoneme	315.058	291.260	286.486	286.661	319.069	311.551	289.715
Plane	1.171	0.752	1.247	1.572	0.534	0.553	1.109
ProximalPhalanxOutlineAgeGroup	0.595	0.461	0.735	1.230	0.356	0.351	0.521
ProximalPhalanxOutlineCorrect ProximalPhalanxTW	0.704	0.587	0.659 0.707	1.020 1.699	0.432 0.343	0.435 0.348	0.536 0.815
RefrigerationDevices	0.775 198.045	0.586 167.040	162.204	164.149	164.174	174.493	156.454
ScreenType	143.046	119.853	126.123	124.484	123.647	136.127	135.216
ShapeletSim	243.103	150.826	151.325	152.915	153.454	153.326	146.383
ShapesAll	21.230	15.139	12.812	12.824	14.086	14.084	12.408
SmallKitchenAppliances	176.407	173.053	175.462	171.829	178.142	173.198	181.316
SonyAIBORobotSurface	8.647	9.489	9.221	10.841	7.459	7.430	7.882
SonyAIBORobotSurfaceII StarLightCurves	16.137	17.066	16.947	17.336	14.439 7.457	15.585	15.215
StarLightCurves Strawberry	17.915 2.706	10.925 1.921	7.939 2.757	7.484 2.635	1.609	7.376 1.656	7.316 1.599
SwedishLeaf	2.700	2.442	2.483	2.688	2.087	2.073	2.395
Symbols	6.280	5.245	3.973	3.930	5.395	4.862	4.498
ToeSegmentation1	43.606	36.174	34.410	35.602	35.703	36.982	34.158
ToeSegmentation2	72.831	58.728	47.650	51.515	54.558	57.188	53.725
Trace	2.879	1.720	1.374	1.448	0.818	0.963	1.048
Two LeadECG	1.619	1.275	1.441	1.708	1.185	1.238	1.383
Two_Patterns UWaveGestureLibraryAll	12.546 78.820	9.490 51.054	8.107 46.568	8.012 47.568	9.502 45.660	8.415 47.290	8.943 41.052
Wine	0.807	0.549	2.339	1.202	0.103	0.101	0.765
WordsSynonyms	25.751	18.486	17.173	16.387	20.113	19.359	16.247
Worms	169.897	111.593	99.132	97.843	123.028	111.755	94.781
WormsTwoClass	172.790	119.187	110.483	105.179	114.444	113.869	105.696
synthetic_control	17.031	9.794	9.631	9.806	9.620	9.692	9.126
uWaveGestureLibrary_X	34.245	21.273	19.248	19.091	20.334	20.586	18.738
uWaveGestureLibrary_Y	37.343	20.565	19.212	18.875	19.129	19.481	17.015
uWaveGestureLibrary_Z wafer	35.221 30.642	22.716 23.935	20.444 27.221	20.108 24.758	20.072 30.820	21.296 32.328	18.303 24.577
yoga	24.982	14.573	15.286	11.849	11.681	11.887	11.120
yoga	24.702	14.3/3	13.200	11.049	11.001	11.00/	11.120