

COT 5615 Math for Intelligent Systems Fall 2021 Homework #5

UFID: 96703101

Name: *Vyom Pathak*

Instructor: Professor Kejun Huang

Due Date: November 01, 2021

Problem A12.1**Solving least squares problems in Julia****Solution**

- a The following code shows the comparison for different methods to find the least square solution:

```
1 using LinearAlgebra
2 A = rand(20,10);
3 b = rand(20);
4 #a.1
5 x_cap_1 = A\b;
6 println(x_cap_1, "\n");
7 #a.2
8 x_cap_2 = inv(A'A)A'b;
9 println(x_cap_2, "\n");
10 #a.3
11 x_cap_3 = pinv(A)b;
12 println(x_cap_3, "\n");
13
14 println("Checking if the vectors are equal or not by printing it. One can see
15 that the vectors are similar upto 13 to 14 decimal places. Thus, they are equivalent.");
```

- b The following Julia code checks the inequality for the least squared problem:

```
1 function verify(A, b, x_cap, delta)
2     return norm(A*(x_cap+delta)-b).^2 > norm(A*x_cap-b).^2
3 end
4 delta1 = rand(10);
5 println(verify(A, b, x_cap, delta1));
6 delta2 = rand(10);
7 println(verify(A, b, x_cap, delta2));
8 delta3 = rand(10);
9 println(verify(A, b, x_cap, delta3));
10 delta4 = rand(10);
11 scaled_delta4 = (delta4.-minimum(delta4))./(maximum(delta4)-minimum(delta4));
12 println(verify(A, b, x_cap, scaled_delta4));
```

Problem A12.2**Julia timing test for least squares****Solution**

The following code finds the time for calculating the least squared solution:

```
1  A = rand(100000,100);
2  b = rand(100000);
3  @time x_cap = A\b;
4  @time x_cap = A\b;
5  @time x_cap = A\b;
6  @time x_cap = A\b;
7  @time x_cap = A\b;
8  @time x_cap = A\b;
9  @time x_cap = A\b;
10 #=
11 2.766416 seconds (2.49 M allocations: 216.166 MiB, 1.83% gc time, 17.91% compilation time)
12 2.273690 seconds (633 allocations: 77.364 MiB, 1.37% gc time)
13 2.187377 seconds (633 allocations: 77.364 MiB, 0.11% gc time)
14 2.186633 seconds (633 allocations: 77.364 MiB, 0.07% gc time)
15 2.208185 seconds (633 allocations: 77.364 MiB, 0.07% gc time)
16 2.199118 seconds (633 allocations: 77.364 MiB, 0.04% gc time)
17 2.195885 seconds (633 allocations: 77.364 MiB, 0.03% gc time)
18 =#
```

Here, we can see that on average 2.1 seconds are taken to solve the least squared solution. [M1 Macbook Air]

Problem A12.4

Transit system tomography

Solution

Here the c vector corresponds to the total trip time for each link which can be shown as below:

$$c = (f_1 - s_1, f_2 - s_2, \dots, f_n - s_n) \text{ where } n \text{ is the number of links}$$

For the vector R , it can be denoted as follows:

$$R = \begin{cases} 1, & \text{if passenger } i \text{ with link } j \text{ where } i \text{ is the row from } 1 \text{ to } m, j \text{ is the column from } 1 \text{ to } n. \\ 0, & \text{otherwise.} \end{cases}$$

The dimension of c vector is thus $n \times 1$ where n is the number of links, while the dimension of R vector is $m \times n$ where m is the number of passengers.

Problem A12.7

Constructing a portfolio of bonds to approximate a sequence of liabilities

Solution

From the equation $\|l - p\|$, we get the equation as follows:

$$\begin{aligned} \|l - p\|^2 &= \|p - l\|^2 \\ \|l - p\|^2 &= \|C * q - l\|^2 \quad [\because p = q_1 c_1 + q_2 c_2 + \dots + q_{20} c_{20}] \end{aligned}$$

Thus, for the original equation $\|Aq - b\|^2$, $A = C$, $q = q$, and $b = l$. Thus, the dimension of A is 120×20 [As it is given that there are 20 c values where each c value is having 120-vectors], and that of b is 120×1 .

Problem A13.3

Auto-regressive time series prediction

Solution

- a The matrix A , and vector b can be shown as follows:

$$A = (x_M, x_{M+1}, x_{M+2}, \dots, x_{N-1}; x_{M-1}, x_M, x_{M+1}, \dots, x_{N-2}; \\ x_{M-2}, x_{M-1}, x_M, \dots, x_{N-3}; \dots, \dots, \dots; x_1, x_2, x_3, \dots, x_{N-M})$$

$$b = (x_{M+1}, x_{M+2}, \dots, x_N)$$

The dimension of the matrix A and vector b are $((N - M)XM)$ and $(N - MX1)$ respectively.

- b The below Julia code shows all the train and test data Loss values and also how find the minimum value of J [0.01891584139384952] and the corresponding value of M [12]. It also shows the calculations for the sample predictors 1&2 [Sample 1 J: 2.6318895838567373 Sample 2 J: 13.116905507420244].

Train Losses:

[0.030494624025126198, 0.030292696561256324, 0.02449655127211178, 0.02439490352714129, 0.022996314298873437, 0.019842912056501263, 0.019137191183089056, 0.019081546282888485, 0.01899948835215664, 0.01920081297889598, 0.01891584139384952]

Test Losses:

[3.384808634417929, 3.380245845279127, 3.367326758735222, 3.3617479695771517, 3.3564118647685057, 3.293567803934302, 3.3375738507437154, 3.319862796736469, 3.3710871022554083, 3.3827366034025976, 3.4236529933573667]

```
1 include("time_series_data.jl")
2 J_train = zeros(11);
3 J_test = zeros(11);
4 for M in 2:12
5     N = size(x_train)[1];
6     A = toeplitz(x_train,M)[M:N-1,1:M];
7     b = x_train[M+1:N];
8     beta = A\b;
9     J_train[M-1] = (norm(A*beta-b).^2)./(N-M);
10
11     N_test = size(x_test)[1];
12     A = toeplitz(x_test,M)[M:N_test-1,1:M];
13     J_test[M-1] = (norm(A*beta-b).^2)./(N_test-M);
14 end
15 println("Train Losses");
16 println(J_train);
17 println("\nTest Losses: ");
18 println(J_test);
19 mJ = minimum(J_train);
20 print("The minimum value of J [", mJ, "] is at M = ", findall(x->x==mJ,J_train)[1]+1);
21
22 # 2 Sample predictors
23 M = 2;
24 N = size(x_train)[1];
25 A_sam1 = rand(N-M);
26 A_sam1 .= x_train[M:N-1]; #Previous value
```

```
27     J_sam1 = (norm(A_sam1-x_train[M+1:N]).^2)./(N-M);
28     println("\nSample 1: ", J_sam1);
29     A_sam2 = rand(N-M); #Extrapolating line
30     for i in M:N-2
31         A_sam2[i] = x_train[i]+(x_train[i]-x_train[i-1]);
32     end
33     J_sam2 = (norm(A_sam2-x_train[M+1:N]).^2)./(N-M);
34     println("\nSample 2: ", J_sam2);
```

Problem A13.5

Nonlinear auto-regressive model

Solution

The matrix A and vector b can be expressed as follows:

$$\begin{aligned} A &= (z_2, z_3, \dots, z_{T-1}; z_1, z_2, \dots, z_{T-2}; z_2 \cdot z_1, z_3 \cdot z_2, \dots, z_{T-1} z_{T-2}) \\ b &= (z_2, z_3, \dots, z_{T-1}) \\ \theta &= (\theta_1, \theta_2, \theta_3) \end{aligned}$$