# COT 5615 Math for Intelligent Systems Fall 2021 Homework #5

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# Problem 10.11

## Trace of matrix-matrix product

#### Solution

a Trace represents diagonal entries, thus trace of  $A^TB$  can be shows as follows:

$$\sum_{i=1}^{m} (A^T B)_{ii} = \sum_{i=1}^{m} \sum_{j=1}^{n} (A^T)_{ij}(B)_{ji} = \sum_{i=1}^{m} \sum_{j=1}^{n} A_{ij} B_{ij}$$

The complexity of the algorithm is 2mn flops, as we only need mn multiplications and mn-1 additions.

- b The matrix  $B^TA$  is the transpose of  $A^TB$ , so it has the same diagonal entries and same trace. Hence,  $tr(B^TA) = tr(A^TB)$
- c From (a), we can derive  $A^T A$  as follows:

$$A^{T}A = \sum_{i=1}^{m} \sum_{j=1}^{n} A_{ij}^{2} = \|A\|^{2}$$

d Here the following derivations shows the proof:

$$tr(BA^T) = \sum_{i=1}^{m} (BA^T)_{ii} = \sum_{i=1}^{m} \sum_{j=1}^{n} (B)_{ij} (A^T)_{ji} = \sum_{i=1}^{m} \sum_{j=1}^{n} B_{ij} A_{ij}$$

## Problem 10.13

#### Laplacian matrix of a graph

### Solution

a The Dirichlet energy can be derived as follows:

$$v^T L v = v^T A A^T v = (A^T v)^T (A^T v) = \|A^T v\|^2 = D(v)$$

b Each entry of  $L_{ij}$  where i = j i.e.  $L_{ii}$  is the degree of node i and when  $i \neq j$  i.e.  $L_{ij}$  is the negative of the number of edges between nodes i and j.

## **Problem 10.31**

## Diameter of a graph

#### Solution

a From the figure, it is clear that number of paths from j to i of length n is shown as  $(A^k)_{ij}$ . Thus, total number of paths of length no more than k in-terms of A can be shown as follows:  $P = I + A + A^2 + A^3 + \ldots + A^k$ 

b Using equation from (a), we can find the diameter by calculating P for different values of k until all the desired entries are positive and thus get the final result.

## Problem 11.3

#### Matrix cancellation

#### Solution

- a  $A = (1,0)^T, X = (0,1), \text{ and } Y = (0,0)$
- b Let C be a left inverse of A, then by muliply AX = AY on the left side by C we get th following:  $CAX = CAY \implies X = Y \ [\because CA = I]$
- c As A is non-invertible, its columns are linearly dependent i.e. Ax = 0 where x is non-zero. Also, Ay = 0 where y = 0. Thus, Ax = Ay where  $x \neq y$ . Hence proved.

## Problem 11.11

## Interpolation of rational functions

#### Solution

The five interpolation equation can be written. as follows:

$$c_1 + c_2 + c_3 = 2(1 + d_1 + d_2)$$

$$c_1 + 2c_2 + 4c_3 = 5(1 + 2d_1 + 4d_2)$$

$$c_1 + 3c_2 + 9c_3 = 9(1 + 3d_1 + 9d_2)$$

$$c_1 + 4c_2 + 16c_3 = -1(1 + 4d_1 + 16d_2)$$

$$c_1 + 5c_2 + 25c_3 = -4(1 + 5d_1 + 25d_2)$$

These equations can be represented in matrix form as follows:

$$(1, 1, 1, 1, 1; 1, 2, 3, 4, 5; 1, 4, 9, 16, 25; -2, -10, -27, 4, 20; -2, -20, -81, 16, 100)(c_1, c_2, c_3, d_1, d_2) = (2, 5, 9, -1, -4)$$

The solution of the above equation is:

$$c_1 = 0.62962, c_2 = 0.60493, c_3 = -0.19753, d_1 = -0.56790, d_2 = 0.08641$$

The figure 1 shows the given rational function with the solution points.

```
using Plots
using LinearAlgebra
Plots.PlotlyBackend()

A = [1 1 1 1 1;1 2 3 4 5;1 4 9 16 25;-2 -10 -27 4 20;-2 -20 -81 16 100]';

C = [2 5 9 -1 -4]';

B = inv(A)C;
display(B);
f(t) = ((B[1])+(B[2]*t)+(B[3]*t*t))/(1+(B[4]*t)+(B[5]*t*t));
plot(f, 0, 6,label = "Rational Function",xlabel="t",ylabel="f(t)")
scatter!([1,2,3,4,5],[2,5,9,-1,-4],label="Interpolation Points")
```

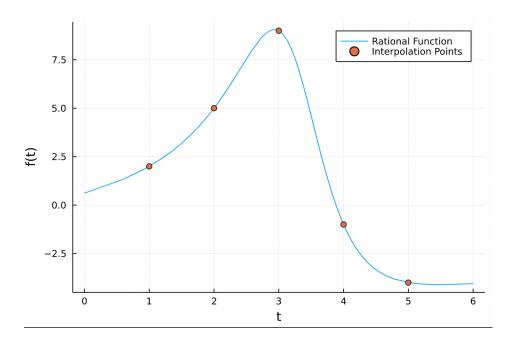


Figure 1: Interpolation of Rational Function

# Problem 11.21

# Quadrature weights.

Solution

$$(1,t_1,t_1^2,t_1^3;1,t_2,t_2^2,t_2^3;1,t_3,t_3^2,t_3^3;1,t_4,t_4^2,t_4^3)\ (w_1,w_2,w_3,w_4)=(b_1,b_2,b_3,b_4)$$

Here  $t_i$  where  $i = 1 \dots 4$  are the values of the vector t = (-0.6, -0.2, 0.2, 0.6), and

$$b_k = \int_{-1}^{1} t^{k-1} dt = \begin{cases} 2/k & k \text{ is odd} \\ 0k & k \text{ is even} \end{cases}$$

By solving it using left-inverse and matrix multiplication, we get the following values of w:

$$w_1 = 1.4375$$
,  $w_2 = -0.4375$ ,  $w_3 = -0.4375$ ,  $w_4 = 1.4375$ 

Furthermore, for solving  $f(t) = e^x$  we get the following values:

$$\alpha = 2.3504$$
 ,  $\hat{\alpha} = 2.5157$