

Project code explanation

```
clc;
clear all;
close all;
originalImage = imread('noisy_colorful_image.jpg'); % Load the original image
imshow(originalImage); % Display the original image
puzzleFolder = 'puzzleimages'; % Folder containing the puzzle pieces
numPieces = 16; % Total number of puzzle pieces
gridSize = 4; % The grid size (4x4 for 16 pieces)
```

- `clc`: Clears the command window, providing a fresh workspace.
- `clear all`: Clears all variables from the workspace to prevent interference with previous variables.
- `close all`: Closes all open figure windows, ensuring that any previous plots or images are removed.

This section prepares the MATLAB environment by clearing unnecessary variables and closing figures.

- `imread`: Loads the original image from the specified path ('noisy_colorful_image.jpg' in this case).
- `imshow`: Displays the loaded image on the screen.
- `puzzleFolder`: The folder where the 16 puzzle pieces are stored.
- `numPieces` and `gridSize`: Define the number of puzzle pieces (16) and the grid size (4x4), indicating that the original image will be split into 4x4 blocks.

```
grayOriginal = rgb2gray(originalImage);
[rows, cols] = size(grayOriginal); % Get the size of the grayscale image
blockRows = floor(rows / gridSize); % Number of rows per block
blockCols = floor(cols / gridSize); % Number of columns per block
```

`rgb2gray` : Converts the original color image (`originalImage`) into a grayscale image (`grayOriginal`). This simplifies the matching process, as grayscale images have only one channel, while color images have three channels (RGB).

`size` : Retrieves the dimensions of the grayscale image (`grayOriginal`), i.e., the number of rows and columns.

`blockRows` and `blockCols` : Calculate the number of rows and columns each block should have. This ensures that the original image is split into `gridSize` blocks. The `floor` function is used to ensure integer values when dividing.

```
originalBlocks = cell(gridSize, gridSize);
```

```
for i = 1:gridSize
    for j = 1:gridSize
        rowRange = (i-1)*blockRows + 1 : min(i*blockRows, rows); % Ensure rows stay within
        bounds
        colRange = (j-1)*blockCols + 1 : min(j*blockCols, cols); % Ensure columns stay within
        bounds

        originalBlocks{i, j} = grayOriginal(rowRange, colRange);
    end
end
```

`originalBlocks` : A cell array is initialized to store the blocks of the original image.

The nested `for` loops iterate over the grid size (4x4). For each block the `rowRange` and `colRange` define the pixel indices for each sub-image.

- `rowRange` and `colRange` : These ensure that each block extracts the correct part of the original image.
- `originalBlocks{i, j}` : Stores each 4x4 block of the grayscale image.

```

puzzlePieces = cell(numPieces, 1);
for k = 1:numPieces
    pieceFilename = fullfile(puzzleFolder, sprintf('piece%d.jpg', k));
    puzzlePieces{k} = imread(pieceFilename);
end
finalArrangement = zeros(gridSize, gridSize); % Store the arrangement of pieces
usedPieces = false(numPieces, 1); % Array to track which pieces have been used

```

`puzzlePieces` : A cell array to store the 16 puzzle pieces.

A `for` loop loads each puzzle piece from the specified folder (`puzzleFolder`).

- `fullfile` : Creates the full path to each puzzle piece by combining the folder name and the piece filename (`piece1.jpg`, `piece2.jpg`, etc.).
- `imread` : Reads each puzzle piece and stores it in the `puzzlePieces` cell array.

`finalArrangement` : A matrix to store the final placement of puzzle pieces, which will later be used to reconstruct the image.

`usedPieces` : A logical array to keep track of which puzzle pieces have been used. Each entry corresponds to a puzzle piece; `false` means unused, and `true` means used.

```

for i = 1:gridSize
    for j = 1:gridSize
        bestMatch = inf;
        bestPiece = 0;

        for k = 1:numPieces
            if ~usedPieces(k) % Only consider unused pieces
                piece = puzzlePieces{k};
                resizedPiece = imresize(piece, [blockRows, blockCols]); % Resize piece to match block
size

```

```

    % Convert puzzle piece to grayscale if RGB
    if size(resizedPiece, 3) == 3
        resizedPiece = rgb2gray(resizedPiece);
    end

    % Calculate similarity between block and piece
    diff = sum((double(originalBlocks{i, j}) - double(resizedPiece)).^2, 'all');

    if diff < bestMatch
        bestMatch = diff;
        bestPiece = k;
    end
end
end

% Assign the best matching piece to the current block
finalArrangement(i, j) = bestPiece;
usedPieces(bestPiece) = true; % Mark this piece as used
end
end

```

bestMatch and **bestPiece** : These variables store the smallest difference (**diff**) and the corresponding puzzle piece index.

Nested for loops:

- The outer loops iterate over each block in the original image.
- The inner loop compares each unused puzzle piece with the current block, resizing the puzzle piece and converting it to grayscale if necessary.
- **diff** : Calculates the difference between the block and the resized puzzle piece. The **sum** of squared differences is used as a similarity measure (the lower the **diff** , the better the match).
- **usedPieces** : Ensures that each piece is used only once by marking it as used once assigned.

```

disp('Final arrangement of puzzle pieces (as matrix):');
disp(finalArrangement);
reconstructedImage = uint8(zeros(rows, cols)); % Initialize an empty image

for i = 1:gridSize
    for j = 1:gridSize
        rowRange = (i-1)*blockRows + 1 : i*blockRows;
        colRange = (j-1)*blockCols + 1 : j*blockCols;

        piece = imresize(puzzlePieces{finalArrangement(i, j)}, [blockRows, blockCols]);

        % Convert puzzle piece to grayscale if RGB
        if size(piece, 3) == 3
            piece = rgb2gray(piece);
        end

        % Place the resized piece into the reconstructed image
        reconstructedImage(rowRange, colRange) = piece;
    end
end

```

Displays the final arrangement of puzzle pieces as a 4x4 matrix, showing which piece is assigned to each block.

reconstructedImage : An empty grayscale image is initialized to store the final reconstructed image.

Nested loops: These loops iterate over the grid, resizing the assigned puzzle piece and placing it in its corresponding location in **reconstructedImage**.

```

figure;
imshow(reconstructedImage);
title('Reconstructed Grayscale Image');

```

❓ **imshow**: Displays the reconstructed grayscale image.

❓ **title**: Adds a title to the image

The code performs the following tasks:

1. **Loads the original image** and the puzzle pieces.
2. **Converts the original image** to grayscale and divides it into 4x4 blocks.
3. **Resizes and compares each puzzle piece** with the blocks, selecting the best match using the sum of squared differences.

4. **Reconstructs the original image** by placing the puzzle pieces in the correct positions.

The final output is a grayscale reconstruction of the original image, using the correctly arranged puzzle pieces.