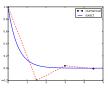
## On Schemes for Exponential Decay

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## Goal

The primary goal of this demo talk is to demonstrate how to write talks with DocOnce and get them rendered in numerous HTML formats.

## Layout

This version utilizes beamer slides with the theme red\_plain.

Problem setting and methods

Result

# Problem setting and methods



# We aim to solve the (almost) simplest possible differential equation problem

$$u'(t) = -au(t) \tag{1}$$

$$u(0) = I \tag{2}$$

#### Here,

- $t \in (0, T]$
- a, I, and T are prescribed parameters
- $\triangleright$  u(t) is the unknown function
- ► The ODE (1) has the initial condition (2)



- ▶ Mesh in time:  $0 = t_0 < t_1 \cdots < t_N = T$
- Assume constant  $\Delta t = t_n t_{n-1}$
- $\triangleright$   $u^n$ : numerical approx to the exact solution at  $t_n$

The  $\theta$  rule.

$$u^{n+1} = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t}u^n, \quad n = 0, 1, \dots, N - 1$$

contains the Forward Euler ( $\theta=0$ ), the Backward Euler ( $\theta=1$ ), and the Crank-Nicolson ( $\theta=0.5$ ) schemes.

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## The Forward Euler scheme explained

http://youtube.com/PtJrPEIHNJw

## Implementation

## Implementation in a Python function:

## How to use the solver function

## A complete main program

```
# Set problem parameters
I = 1.2
a = 0.2
T = 8
dt = 0.25
theta = 0.5
\pause
from solver import solver, exact_solution
u, t = solver(I, a, T, dt, theta)
\pause
import matplotlib.pyplot as plt
plt.plot(t, u, t, exact_solution)
plt.legend(['numerical', 'exact'])
plt.show()
```

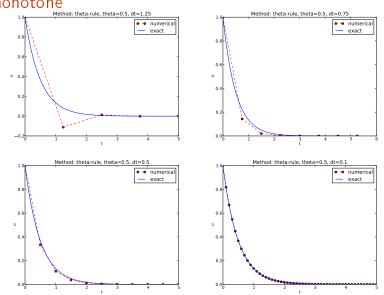
Problem setting and methods

Results

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The Crank-Nicolson method shows oscillatory behavior for not sufficiently small time steps, while the solution should be monotone



Exact solution of the scheme:

$$u^n = A^n$$
,  $A = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t}$ .

## Key results:

- Stability: |A| < 1
- No oscillations: A > 0
- $ightharpoonup \Delta t < 1/a$  for Forward Euler (heta = 0)
- lacksquare  $\Delta t < 2/a$  for Crank-Nicolson ( heta=1/2)

## Concluding remarks:

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