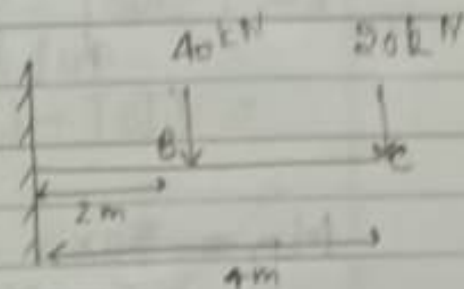
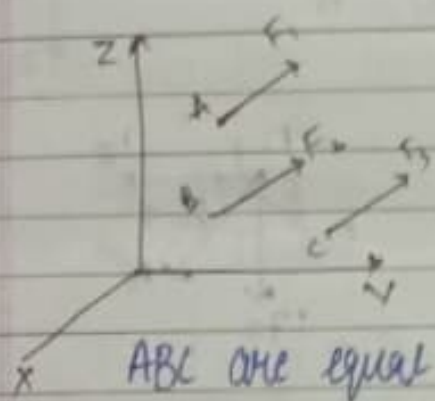


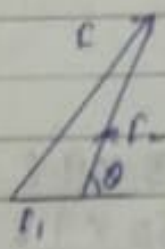
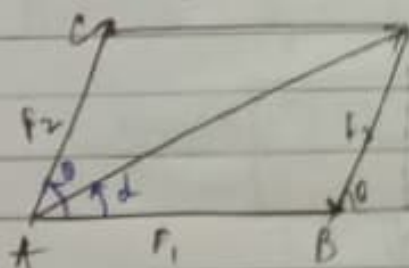
Unit - 1

Fundamentals of Engineering Mechanics



40 & 20 kN are equivalent

• Parallelogram law of forces



(Triangle law of forces)

$$F = \sqrt{(F_1 + F_2 \cos \theta)^2 + (F_2 \sin \theta)^2}$$

$$= \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$$

$$\tan \alpha = \frac{F_2 \sin \theta}{F_1 + F_2 \cos \theta}$$

* Several // forces acting

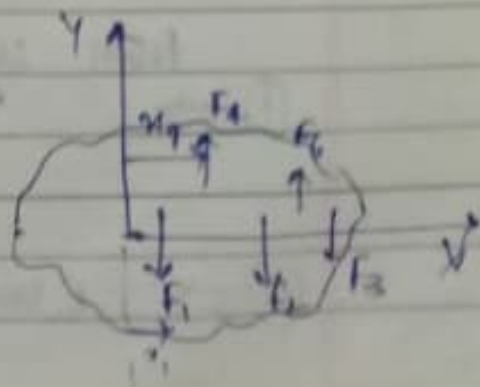
for eq^m

$$\sum F_i = 0$$

$$F_1 + F_2 + F_3 + \dots = 0$$

$$\sum F_i x_i = 0$$

$$F_1 x_1 + F_2 x_2 + \dots + F_n x_n = 0$$



Example

$$F_A = -100\hat{j}$$

$$F_C = -70\hat{j}$$

$$F_B = 50\hat{i}$$

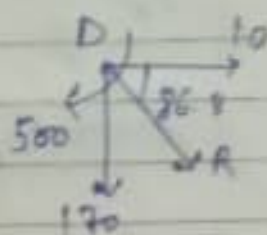
$$F_D = -40\hat{i}$$

$$R = (-100\hat{j} - 70\hat{j} + 50\hat{i} - 40\hat{i}) \text{ N}$$

$$= (10\hat{i} - 170\hat{j}) \text{ N}$$

$$M_D = 50 \times 3 + 70 \times 5$$

$$= 500 \text{ N m}$$



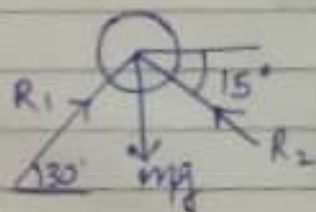
example



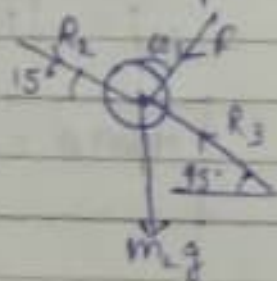
$$m_1 = 75 \times 9.8 = 735 \text{ N}$$

$$m_2 = 50 \times 9.8 = 490 \text{ N}$$

F.B.D. of cylinder A



F.B.D. of B



From cylinder A F.B.D

(1) \Rightarrow

$$R_1 \cos 30^\circ = R_2 \cos 15^\circ$$

$$R_1 = 1.1154 R_2 \quad \text{--- (1)}$$

(2) \Rightarrow

$$R_1 \sin 30^\circ + R_2 \sin 15^\circ = 735$$

$$R_2 = 900.9 \text{ N}$$

From FBD of B

$$R_2 \cos 15 = F \sin 60 + R_2 \cos 45$$

$$R_2 \sin 15 + F \cos 60 + m \cdot g = R_2 \sin 45$$

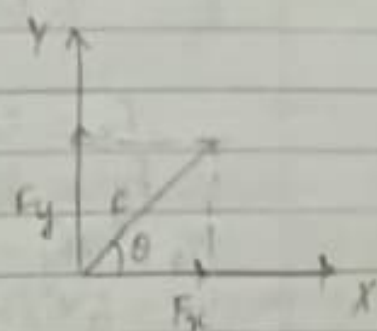
$$A = \underline{107.2 \text{ N}}$$

* Rectangular components

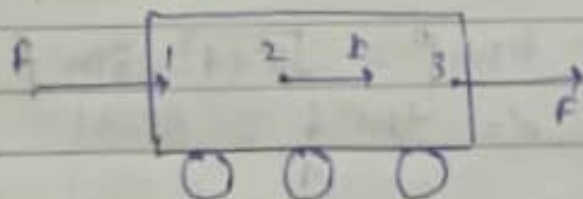
$$F_x = F \cos \theta$$

$$F_y = F \sin \theta$$

$$\vec{F} = F_x \hat{i} + F_y \hat{j}$$



* Principle of transmissibility for force



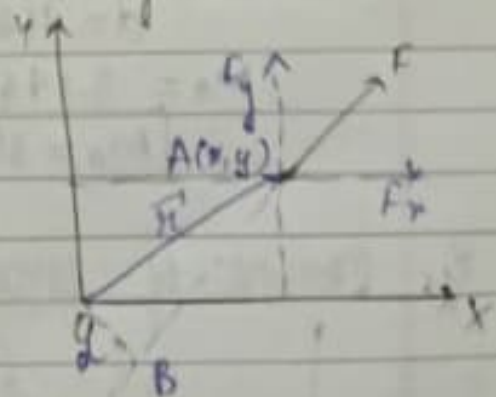
* Moment of a force about origin

$$\vec{r} = x\hat{i} + y\hat{j}$$

$$M_o = \vec{r} \times \vec{F} \quad (\text{cross product})$$

$$= (x\hat{i} + y\hat{j}) \times (F_x\hat{i} + F_y\hat{j})$$

$$= (x F_y - y F_x) \hat{k}$$



Also scalar method

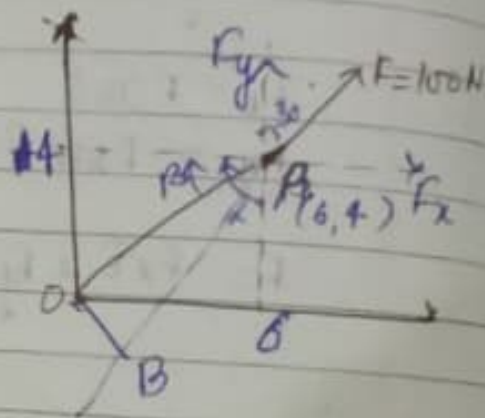
$$M_o = OB \times F = d \times F$$

(+ve CCW, -ve CW)

Ex -

A force of magnitude 100 N is passing through a point A (6, 4) m on a body as shown in figure. Force 100 N is inclined at angle 30° with the vertical. Determine the moment of force about 'O' of coordinate system.

$$\begin{aligned} F_x &= 50 \text{ N} \\ F_y &= 86.6 \text{ N} \\ M_o &= x F_y - y F_x \quad \text{by direct} \\ &= 6 \times 86.6 + 4 \times 50 \\ \boxed{M_o &= 314.6 \text{ CCW (N-m)}} \end{aligned}$$



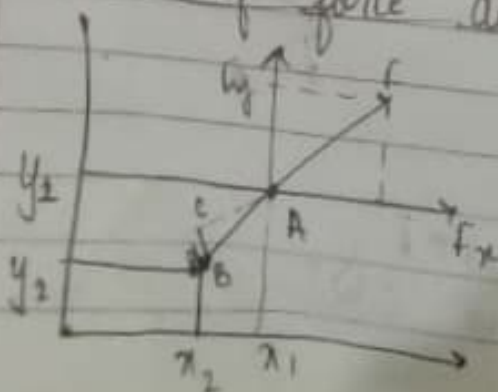
2nd approach

Scalar Method

$$\begin{aligned} OB &= 4 \sin \beta = \sqrt{6^2 + 4^2} \sin \beta \\ \angle OAC &= \alpha = \tan^{-1} \frac{6}{4} = 56.31^\circ \\ \angle OAB &= \beta = 56.31 - 30 = 26.31^\circ \end{aligned}$$

$$\begin{aligned} d &= 42.21 \times \sin 26.31 = 3.146 \\ M_o &= 3.146 \times 100 \\ \boxed{M_o &= 314.6 \text{ N-m}} \end{aligned}$$

* Moment of force about a point in space -



$$M_B = \vec{r}_{BA} \times \vec{F}$$

$$\vec{r}_{BA} = \vec{r}_A - \vec{r}_B$$

$$= (x_1 - x_2) \hat{i} + (y_1 - y_2) \hat{j}$$

$$M_B = (x_1 - x_2) F_y - (y_1 - y_2) F_x \quad \hat{k}$$

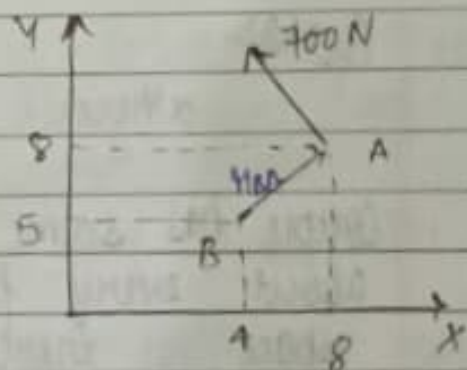
Scalar Method

$$M_B = BC \times F \\ = d \times F$$

ex- A force $F, 700 \text{ N}$ is applied at a point A on a body as shown. Force is inclined with x -axis at angle 30° as shown. Coordinates of point A are $(8, 8)$ what is the moment of this force about $B(4, 5)$ in the space.

$$F_x = -F \cos 30^\circ \\ = -606.2 \text{ N}$$

$$F_y = F \sin 30^\circ \\ = 350 \text{ N}$$



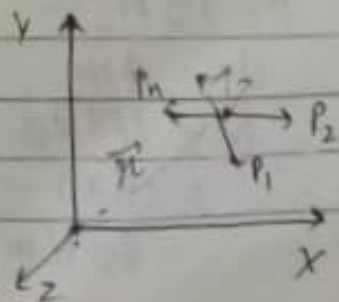
$$r_{BA} = (8-4) \hat{i} + (8-5) \hat{j}$$

$$M_B = (x_A - x_B) F_y - (y_A - y_B) F_x \\ = 4 \times 350 - 3(606.2) \\ = 3918.6 \text{ N}\cdot\text{m} \quad \text{(CW)}$$

* Varignon's Theorem

$$M_O = \vec{r} \times \vec{P}_1 + \vec{r} \times \vec{P}_2 + \dots + \vec{r} \times \vec{P}_n$$

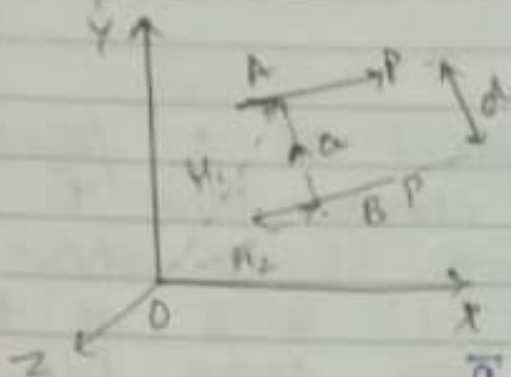
Distributed property of cross product



$$M_O = \vec{r} \times (\vec{P}_1 + \vec{P}_2 + \dots + \vec{P}_n)$$

$$= \vec{r} \times \vec{P}_R \quad (\text{where } \vec{P}_R \text{ is resultant forces})$$

* Couple and its Moments



$$M = \vec{r}_1 \times \vec{P} + \vec{r}_2 \times (-\vec{P})$$

$$= (\vec{r}_1 - \vec{r}_2) \times \vec{P}$$

$$(\vec{r}_1 - \vec{r}_2) = \vec{a}$$

$$= \vec{a} \times \vec{P}$$

\vec{a} = displacement vector between

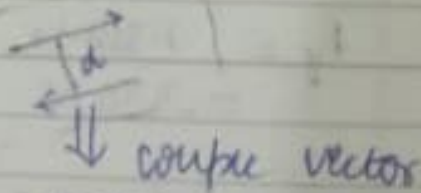
Scalars,

$$M = |\vec{P}| \times d$$

where d is per distance

Couple has same moment about every point in space, therefore

couple moment is free vector



Ex

Find couple moment

i) about origin

ii) about $(2, 3, -2)$

i)

$$P = 15 \text{ N}$$

$$d = 4 \text{ m}$$

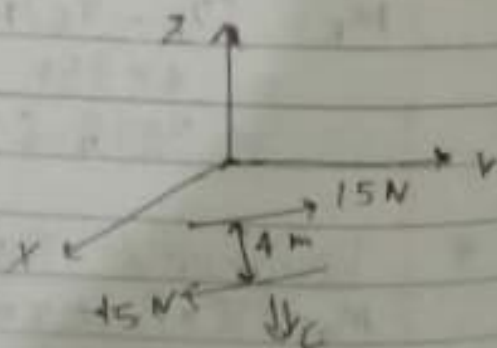
$$M = |\vec{P}| \times d$$

$$= 15 \times 4$$

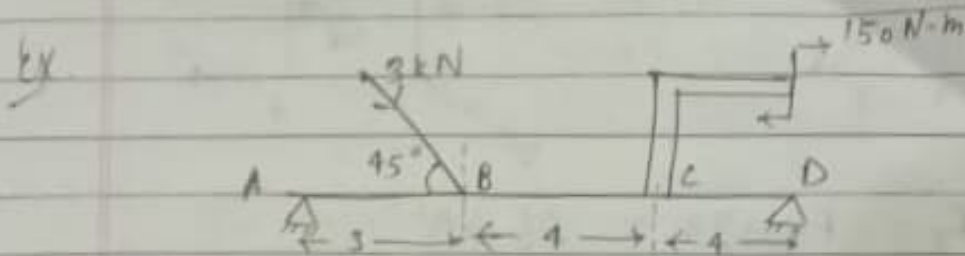
$$= 60 \text{ N}\cdot\text{m}$$

(Right-hand screw rule)

$$M = -60 \text{ N}\cdot\text{m}$$



ii) Since C is force vector. So, moment about $(2, 3, -2)$ will be same.



$$M_A = 3 \sin 45^\circ \times 3 \times 1000 + 150 \text{ N-m}$$

$$= 6513 \text{ N-m (CW)}$$

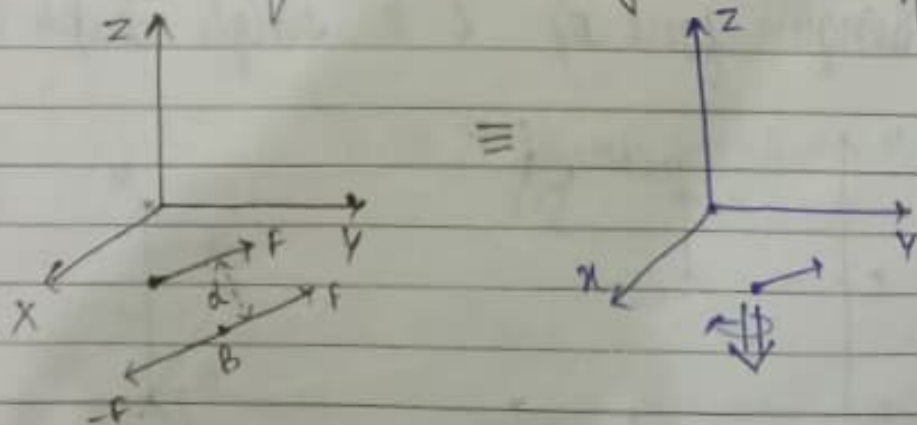
$$M_C = 3 \sin 45^\circ \times 8 \times 1000 - 150 \text{ N-m}$$

$$= 16818 \text{ N-m (CCW)}$$

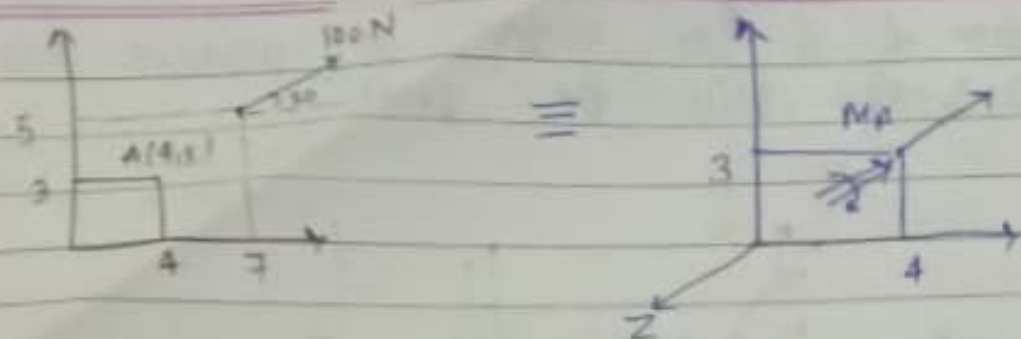
* Resultant Force System

- Sum of concurrent forces is a single force
- Force may be moved along line of action.
- Effect of a couple is only a couple.

* Replacement of a force by equivalent couple and a force at any other point:



Ex.



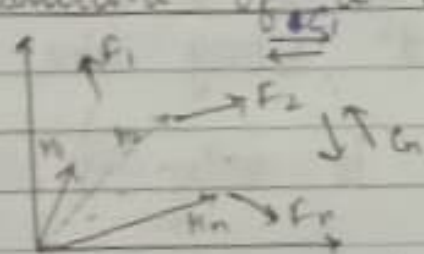
$$F_x = F \cos 30 = 86.6\text{ N}$$

$$F_y = F \sin 30 = 50\text{ N}$$

$$F_A = 86.6\text{ i} + 50\text{ j}\text{ N}$$

$$\begin{aligned} M_A &= (y-4)F_x - (x-3)F_y \\ &= 150 - 133.8 \\ &= -16.2\text{ Nm} \end{aligned}$$

* Resultant of a force system

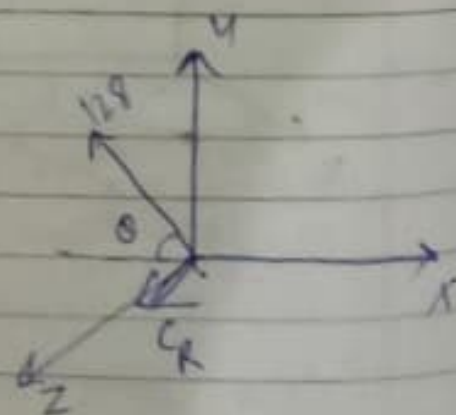
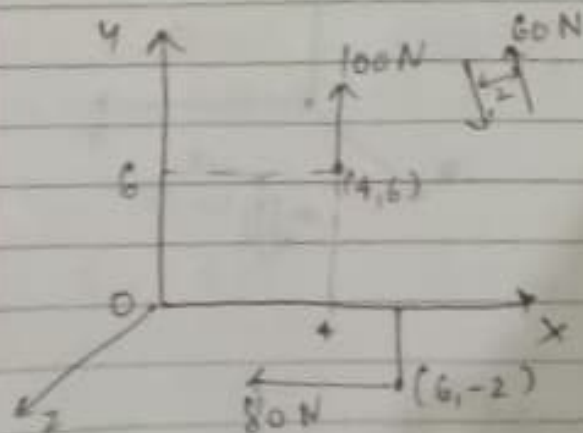


$$\begin{aligned} F_R &= F_1 + F_2 + \dots + F_n \\ &= \sum_{i=1}^n F_{xi} \text{ i} + \sum_{i=1}^n F_{yi} \text{ j} \end{aligned}$$

$$\begin{aligned} C_R &= x_1 F_{y1} + x_2 F_{y2} + \dots + x_n F_{yn} \\ &\quad + y_1 F_{x1} + y_2 F_{x2} + \dots + y_n F_{xn} \end{aligned}$$

Single force F_R & 2 single couple C_R

Ex



$$F_R = \sqrt{(80)^2 + (100)^2} = 128 \text{ N}$$

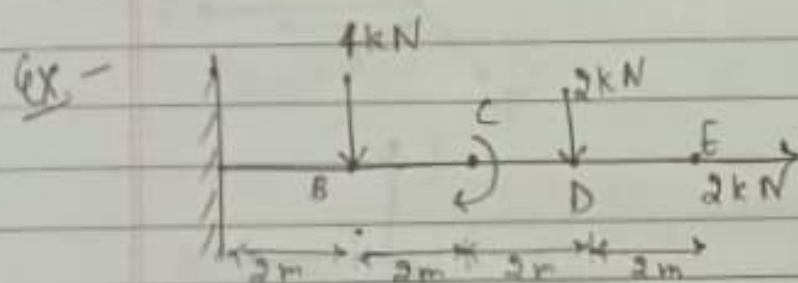
Resultant Couple at O

$$M_O = -80 \times 2 + 100 \times 4 + 60 \times 2$$

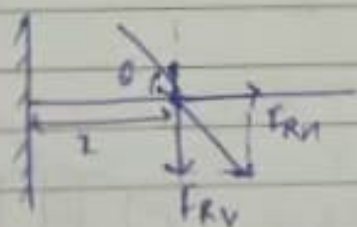
$$= 360 \text{ Nm ccw along z}$$

$$\theta = \tan^{-1} \frac{100}{80} = 51.34^\circ$$

• Whence Resultant



Find the Resultant
of single force
& its line of action



$$F_{RV} = 4 + 2$$

$$= 6 \text{ kN} \downarrow$$

$$F_{RH} = 2 \text{ kN} \rightarrow$$

$$F_{RV} \times x + F_{RH} \times 0 = 4 \times 2 + 2 \times 6 + 5 \text{ kNm}$$

$$= 25 \text{ kNm}$$

$$x = \frac{25}{6} = 4.16 \text{ m}$$

$$F_R = \sqrt{6^2 + 2^2} = 6.39$$

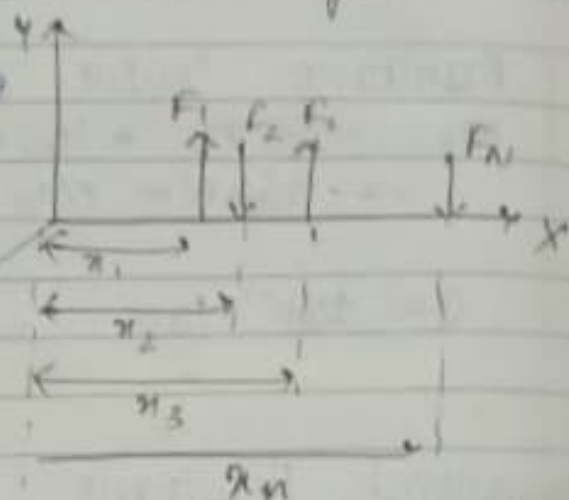
$$\theta = \tan^{-1} \frac{F_{RV}}{F_{RH}}$$

* Resultant of Parallel Force System -

$$F_R = F_1 - F_2 + F_3 + \dots - F_n$$

Line of action
Taking moment about
O

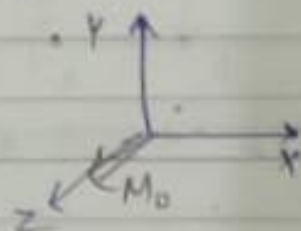
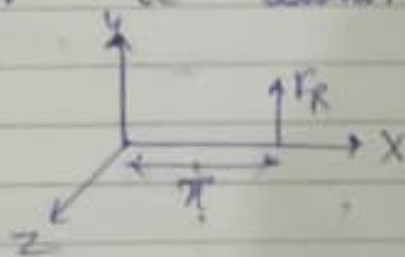
$$M_O = F_1 x_1 - F_2 x_2 + F_3 x_3 - \dots - F_n x_n$$



Say resultant act at a distance \bar{x} from O

$$F_R \bar{x} = M_O$$

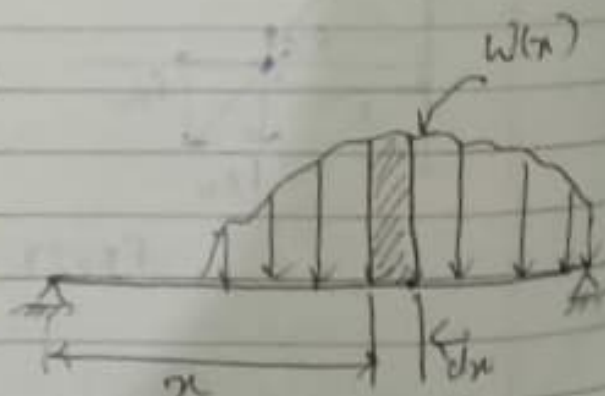
$$\bar{x} = \frac{M_O}{F_R}$$



* Distributed Force System

$$dF = w(x) dx$$

where $w(x)$ is intensity
of loading



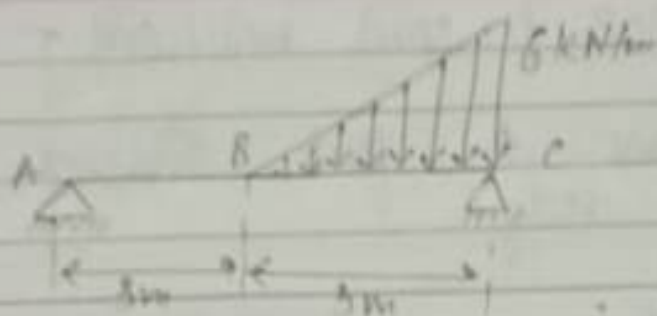
Resultant load on the beam

$$F_R = - \int w(x) dx$$

Position,

$$\bar{x} = \frac{- \int x w(x) dx}{- \int w(x) dx}$$

Ex -



Say $w(x) = ax + b$

$w(x) = 0$ at $x = 3$

$w(x) = 6$ at $x = 6$

$\Rightarrow 0 = 3a + b$

$6 = 6a + b$

$a = 2, b = -6$

$w(x) = 2x - 6$

Resultant force $= F_R = \int_3^6 w(x) dx$
 $= 9 \text{ kN}$

Moment of distributed load about A

$\bar{x} F_R = \int_3^6 x w(x) dx$

$= \int_3^6 x (2x - 6) dx$

$= 45$

$\bar{x} = 5 \text{ m}$

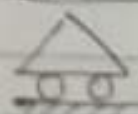
* Free Body Diagram (F.B.D) -

A sketch of the object showing all the actions & reactions at proper places is called F.B.D of the object.

→ Common Supports & their reactions -

a) Pulley Rope Support: A force directed away from the body

b) Roller Support:

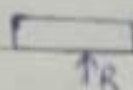
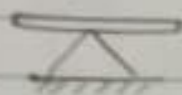


FBD of
Roller



Reacⁿ of
Roller

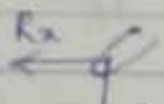
c) Knife edge Support:



R

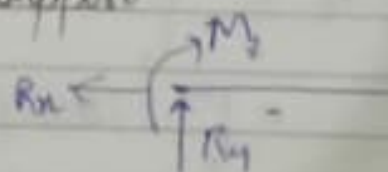
FBD

d) Pin or Hinged Joint:



R_x
 R_y (FBD)

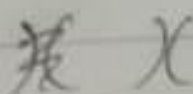
e) Fixed or Rigid Support:



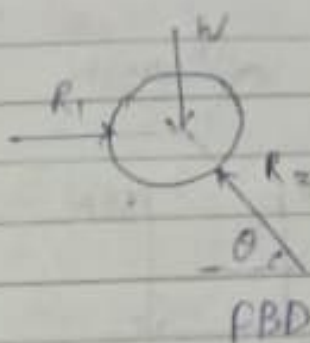
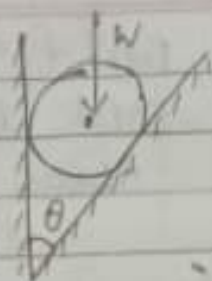
f) Smooth Surface:



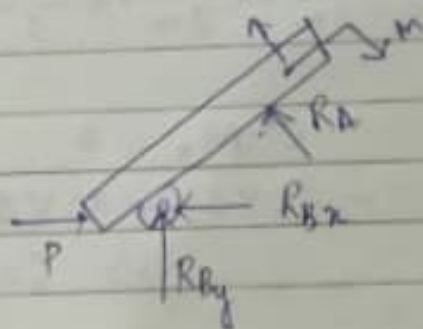
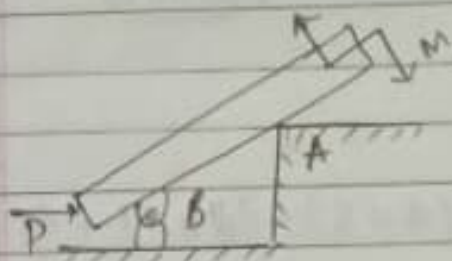
g) Friction Surface:



Ex -



Ex.



* Equilibrium of Rigid Bodies -

When the resultant forces or couple become zero the body is said to be in eq^m.
for eq^m $F_R = 0$, $C_R = 0$

for 3D

$$\sum F_x = 0 \text{ --- (1)}$$

$$\sum F_y = 0 \text{ --- (2)}$$

$$\sum F_z = 0 \text{ --- (3)}$$

$$\sum M_x = 0 \text{ --- (4)}$$

$$\sum M_y = 0 \text{ --- (5)}$$

$$\sum M_z = 0 \text{ --- (6)}$$

for 2D coplanar

$$\sum F_x = 0 \text{ --- (1)}$$

$$\sum F_y = 0 \text{ --- (2)}$$

$$\sum F_x, \sum F_y, \sum M_z = 0 \text{ --- (3)}$$

} Eqⁿ of
Equilibrium

for concurrent forces

$$\sum F_x = 0 \text{ --- (1)}$$

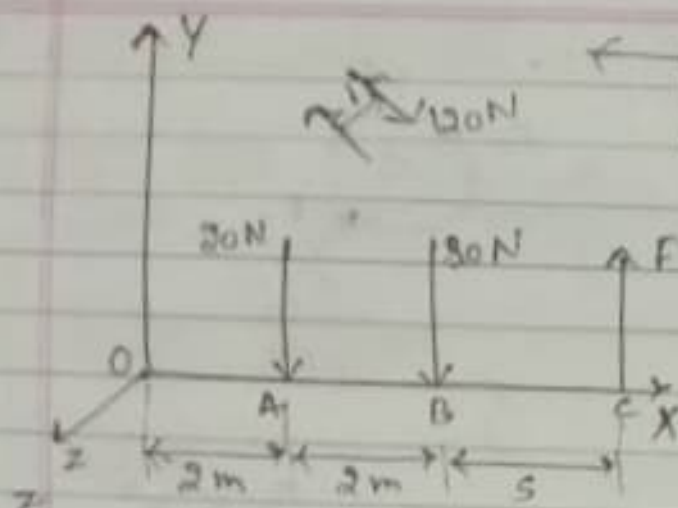
$$\sum F_y = 0 \text{ --- (2)}$$

for II force system

$$\sum F_x = 0 \text{ --- (1)}$$

$$\sum M_z = 0 \text{ --- (2)}$$

Ex



find F & s
check equilibrium
about B

$$\sum F_y = 0$$

$$-20 - 30 + F = 0$$

$$F = 50 \text{ N}$$

$$\sum M_z = 0$$

$$-20 \times 2 - 30 \times 4 + F(4+s) - 120 \times 1 + 40 = 0$$

$$\Rightarrow s = 0.8 \text{ m}$$

Check about B :-

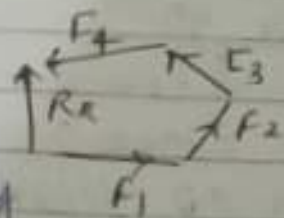
$$R_B = 20 \times 2 + 50 \times 0.8 - 120 + 40$$

$$R_B = 0$$

Equilibrium

* Law Of Polygon

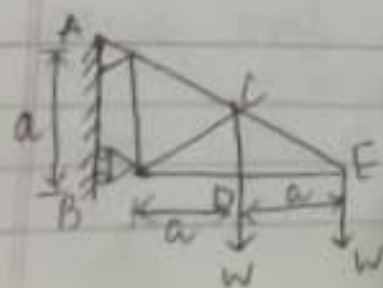
con
Non-coplanar forces
 $F_1 + F_2 + \dots + F_N = 0$ vectorially

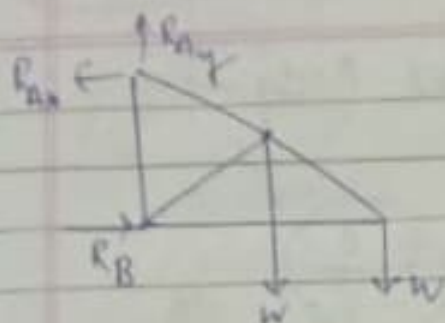


$$(\gamma_1 \times F_1 + \gamma_2 \times F_2 + \dots + \gamma_n \times F_n)$$

$$+ C_1 + C_2 + \dots + C_N = 0$$

Ex





$$R_{Ay} = W + W \\ = 2W \uparrow$$

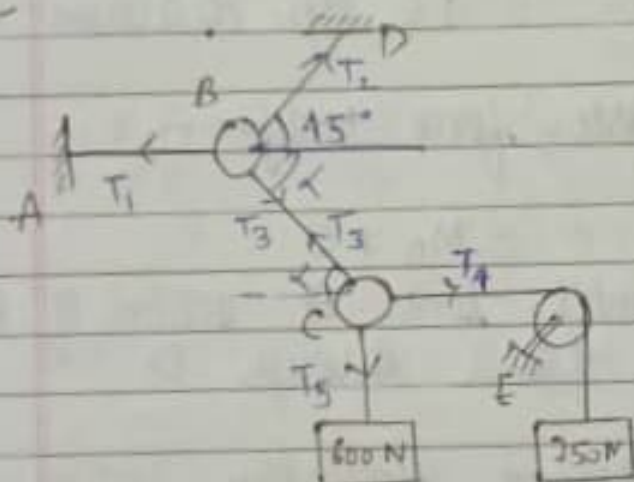
$$\sum M_B = 0$$

$$W \times a + W \times 2a = R_{Ay} \times a$$

$$R_{Ay} = 3W$$

$$R_B = 3W$$

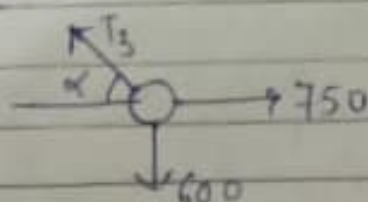
Ex -



$$T_4 = 750 \text{ N}$$

$$T_5 = 600 \text{ N}$$

FBD of C



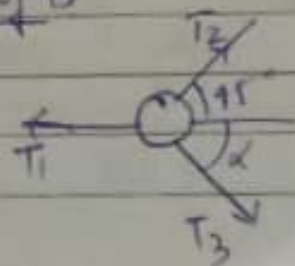
$$T_3 \cos \alpha = T_4 = 750$$

$$T_3 \sin \alpha = T_5 = 600$$

$$\alpha = 38.66^\circ$$

$$T_3 = 961.5 \text{ N}$$

FBD of B

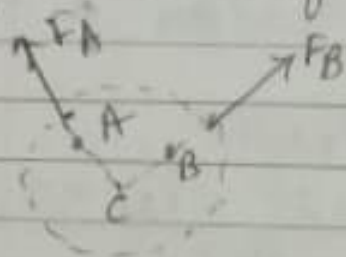


$$T_1 = T_2 \cos 45 + T_3 \cos \alpha$$

$$T_2 \sin 45 = T_3 \sin \alpha$$

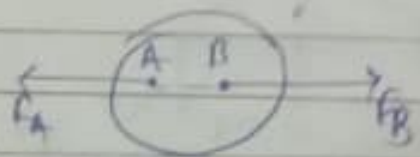
$$T_2 = 849.6 \text{ N}$$

* Equilibrium of a Two force Body -



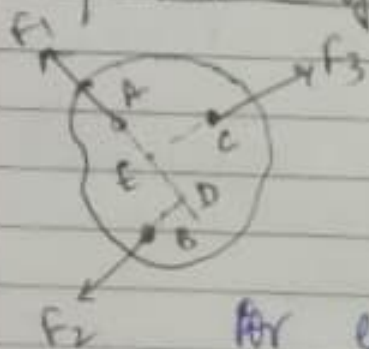
$$\sum M_C = 0$$

But $\sum F_x \neq 0$
 $\sum F_y \neq 0$



Line of action
 should be same
 Same magnitude
 & opp. direction

* Equilibrium of three force body -

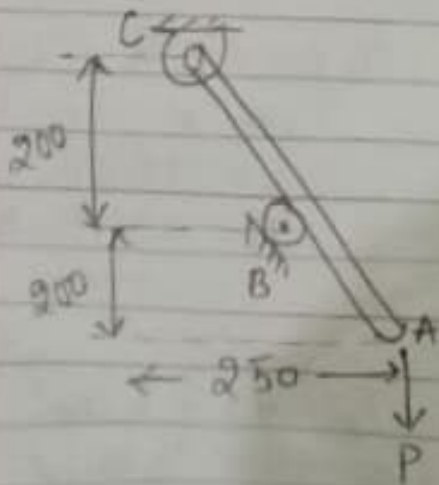


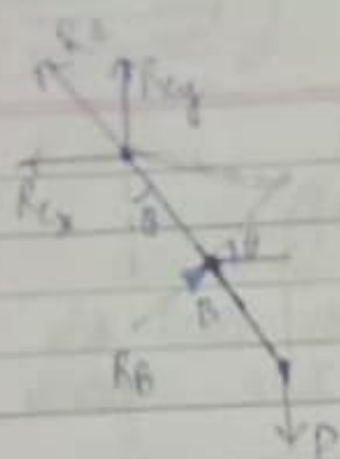
$$\sum M_D \neq 0$$

Until line of action of F_3
 passes through D

For equilibrium the line of action
 of three forces must be concurrent
 (Only for non // forces)

Ex -





$$CB = \sqrt{(400)^2 + (250)^2} = 235.8 \text{ mm}$$

$$\sum M_C = 0$$

$$\Rightarrow R_B \times CB - 200 \times 250 = 0$$

$$R_B = 212 \text{ N}$$

FBD

$$\tan \theta = \frac{250}{400} \Rightarrow \theta = 39^\circ$$

$$\sum F_x = 0 \Rightarrow R_B \cos \theta = R_C$$

$$\sum F_y = 0 \Rightarrow R_B \sin \theta - 200 + R_{Cy} = 0$$

$$R_{Cy} = 87.6 \text{ N}$$

$$R_C = 179.8 \text{ N}$$

$$R_C = 200 \text{ N}$$

* Lami's Theorem

$$\sum F_x = 0 \quad \text{--- (1)}$$

$$\sum F_y = 0 \quad \text{--- (2)}$$

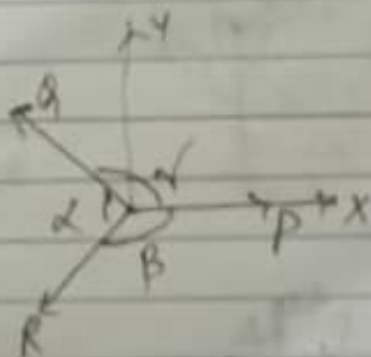
$$(2) \Rightarrow$$

$$Q \sin \gamma = R \sin \beta$$

$$\frac{Q}{\sin \beta} = \frac{R}{\sin \gamma}$$

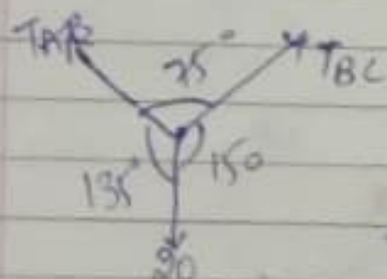
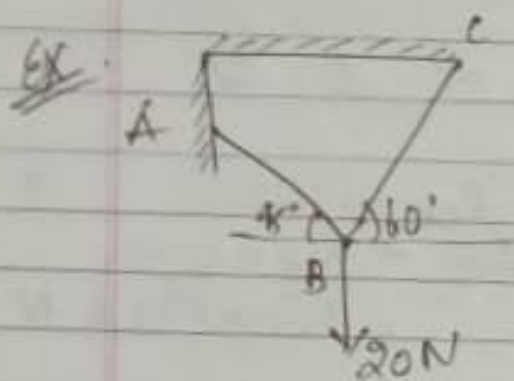
Similarly had we selected the x-axis coinciding with θ , the result would have been

$$\frac{P}{\sin \alpha} = \frac{R}{\sin \gamma}$$



$$\Rightarrow \frac{P}{\sin \alpha} = \frac{R}{\sin \gamma} = \frac{Q}{\sin \beta}$$

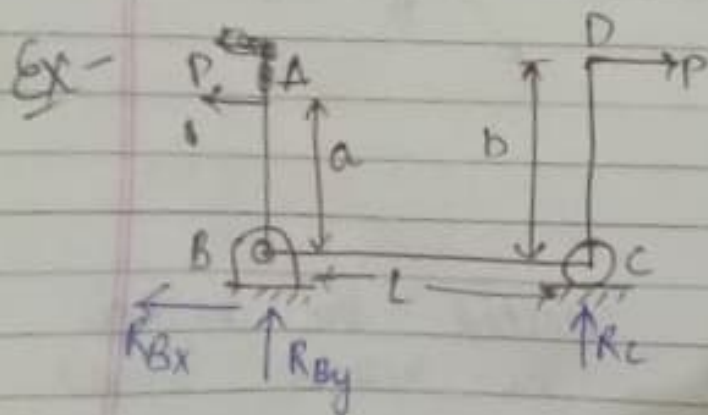
The ratio of a force and sin of angle between offer two forces is constant.



$$\frac{T_{AB}}{\sin 150} = \frac{T_{BC}}{\sin 135} = \frac{20}{\sin 75}$$

$$T_{AB} = 10.35 \text{ N}$$

$$T_{BC} = 14.64 \text{ N}$$



$$\sum M_B = 0 \Rightarrow P \times b - P(a) - R_C \times L = 0$$

$$R_C = \frac{P(b-a)}{L}$$

$$\sum F_y = 0$$

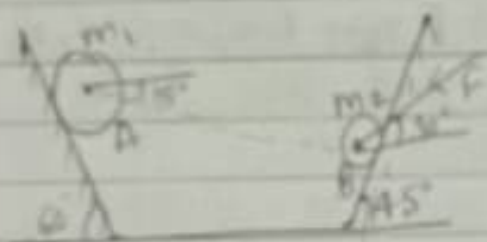
$$R_{Ay} + R_C = 0$$

$$R_{Ay} = - \frac{P(b-a)}{L}$$

$$\sum F_x = 0$$

$$R_{Ax} = 0$$

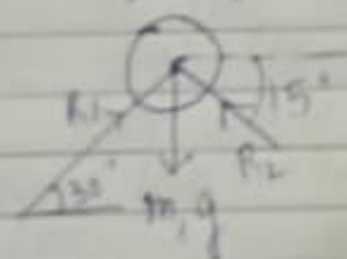
Ex



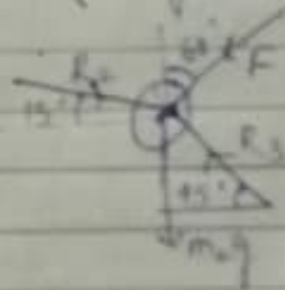
$$m_1 = 75 \times 9.8 = 735 \text{ N}$$

$$m_2 = 50 \times 9.8 = 490 \text{ N}$$

FBD of Cylinder A



FBD of Cylinder B



From cylinder A FBD

$$\textcircled{1} \Rightarrow R_1 \cos 30^\circ = R_2 \cos 15^\circ$$

$$R_1 = 1.1154 R_2 \text{ --- } \textcircled{1}$$

$$\textcircled{2} \Rightarrow R_1 \sin 30^\circ + R_2 \sin 15^\circ = 735 \text{ --- } \textcircled{2}$$

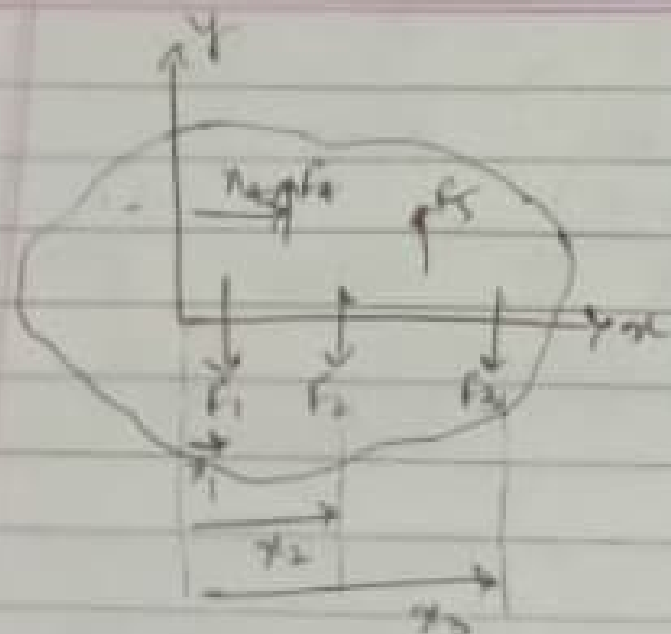
$$\Rightarrow R_2 = 900.2 \text{ N}$$

From FBD of B,

$$R_2 \cos 15^\circ = F \cos 60^\circ + R_3 \cos 45^\circ$$

$$R_2 \sin 15^\circ + F \sin 60^\circ + m_2 g = R_3 \sin 45^\circ$$

$$F = 107.2 \text{ N}$$



For equilibrium

$$\sum F_i = 0$$

$$\Rightarrow F_1 + F_2 + \dots + F_n = 0$$

$$\sum F_i x_i = 0$$

$$F_1 x_1 + F_2 x_2 + \dots + F_n x_n = 0$$