

Chapter1

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Continuous-time signals / discrete signals

CT 连续时间信号

t, τ, f

DT 离散时间信号

i, k, n, m, ℓ, q

Energy signals / power signals

• Energy E_x : (能量信号)

$$\begin{cases} E_x(T) \triangleq \int_{-T}^T |x(t)|^2 dt & -CT \\ E_x[N] \triangleq \sum_{n=-N}^N |x[n]|^2 & -DT \end{cases}$$

for $T > 0, N > 0$

$$\begin{cases} E_x \triangleq \lim_{T \rightarrow +\infty} E_x(T) = \int_{-\infty}^{+\infty} & -CT \\ E_x \triangleq \lim_{N \rightarrow +\infty} E_x[N] = \sum_{n=-\infty}^{+\infty} |x[n]|^2 & -DT \end{cases}$$

• Power P_x : (功率信号)

$$\begin{cases} P_x \triangleq \lim_{T \rightarrow +\infty} \frac{E_x(T)}{2T} & -CT \\ P_x \triangleq \lim_{N \rightarrow +\infty} \frac{E_x[N]}{2N+1} & -DT \end{cases}$$

$$\begin{cases} 0 < E_x < +\infty \Rightarrow \text{energy signal} \Rightarrow P_x = 0 \\ 0 < P_x < +\infty \Rightarrow \text{power signal} \Rightarrow E_x = +\infty \end{cases}$$

$$C = \text{Re}(C) + j \text{Im}(C) \quad C = P e^{j\theta}$$

$$|e^{j\theta}| = 1 \quad e^{j\theta} = \cos\theta + j \sin\theta$$

$$\begin{cases} \text{Re}(C) = P \cos\theta \\ \text{Im}(C) = P \sin\theta \end{cases} \quad \star \quad \begin{cases} \cos\theta = \frac{e^{j\theta} + e^{-j\theta}}{2} \\ \sin\theta = \frac{e^{j\theta} - e^{-j\theta}}{2j} \end{cases}$$

不可能同时是能量又是功率
但可以两个都不是

周期信号 $x(t) = x(t+T), \forall t \in \mathbb{R}$. $f_0 \triangleq \frac{1}{T_0}, \omega_0 = 2\pi f_0$
 $x[n] = x[n+N], \forall n \in \mathbb{Z}$. $F_0 \triangleq \frac{1}{N_0}, \Omega_0 = 2\pi F_0$

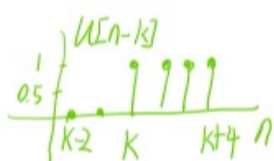
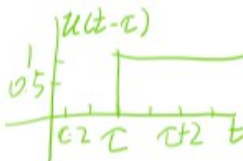
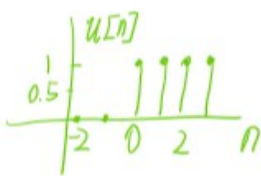
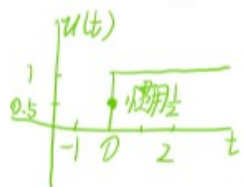
$$\sum_{k=0}^{N-1} \alpha^k = \begin{cases} N & , \alpha = 1 \\ \frac{1 - \alpha^N}{1 - \alpha} & , \alpha \neq 1 \end{cases}$$

Elementary signals (基本信号)

① Unit step signals (单位阶跃信号)

$$u(t) \triangleq \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$

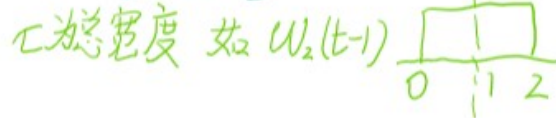
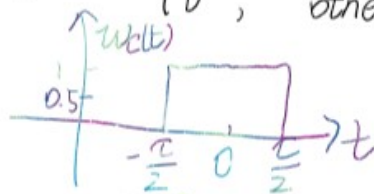
$$u[n] \triangleq \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$



② Window signals (窗信号)

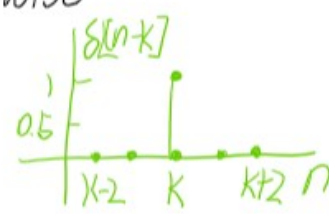
$$w[n] = u[n - N_1] - u[n - N_2 - 1]$$

$$w_\tau(t) \triangleq \begin{cases} 1 & -\frac{\tau}{2} < t < \frac{\tau}{2} \\ 0 & \text{otherwise} \end{cases}$$



③ Unit impulse signals (单位冲激信号)

$$\delta[n] \triangleq \begin{cases} 1 & n = 0 \\ 0 & \text{otherwise} \end{cases}$$



单位冲激

$$\delta(t) \triangleq \lim_{\tau \rightarrow 0} \frac{1}{\tau} w_\tau(t)$$

$$\int_{-\infty}^{+\infty} \delta(t) dt = \int_{-\sigma}^{\sigma} \delta(t) dt = 1, \forall \sigma > 0$$

$$\delta(\alpha t) = \frac{1}{|\alpha|} \delta(t)$$

$$\delta(t) = \delta(-t)$$

$$\chi(\xi) \delta(t - \xi) \equiv \chi(t) \delta(t - \xi) \Rightarrow \text{例 } (t-2) [\delta(t-2) - \delta(t-3)]$$

$$\int_{-\infty}^{+\infty} \chi(\xi) \delta(t - \xi) d\xi = \chi(t)$$

$$\chi(t) = \int_{-\infty}^t \delta(\tau) d\tau \Rightarrow \text{推导}$$

$$\delta(t) = \frac{d\chi(t)}{dt}$$

$$\chi(t) = \int_{-\infty}^{+\infty} \chi(\xi) \delta(\xi - t) d\xi$$

$$\xrightarrow{\tau = \xi - t} \int_{-\infty}^{+\infty} \chi(\tau + t) \delta(\tau) d\tau$$

$$\xrightarrow[\tau > -t]{\tau + t > 0} \int_{-t}^{+\infty} \delta(\tau) d\tau = \int_{-\infty}^t \delta(\tau) d\tau$$

$$\begin{aligned} &= (t-2) \delta(t-2) - (t-2) \delta(t-3) \\ &= (2-2) \delta(t-2) - (3-2) \delta(t-3) \\ &= 0 - \delta(t-3) = -\delta(t-3) \end{aligned}$$

Properties of systems

- ① Memoryless / with memory (记忆) 无记忆 \rightarrow 只与当前 t/n 有关. with memory
 $y(t) = x(t \pm t_0)$, $x(t^{n_0})$ 和 $x(t)$
- ② Causality (因果) $\begin{cases} y = x(t - t_0) \\ y = x(t + t_0) \end{cases} \begin{matrix} t_0 > 0 \text{ 因果} \\ t_0 < 0 \text{ 非因果} \end{matrix}$ 或用 ROC: $|s| > s_0$. 只与现在和过去时刻有关. 若任意时刻 $t < 0$ 或 $t > 0$.
- ③ Invertibility (可逆) 不同输入 (一定要不同) 得到不同的输出. 类似于单调函数.
- ④ Stability (稳定) 输入有界 \Rightarrow 输出有界. 或 ROC 包含 $j\omega$ 轴. 绝对可和 / 绝对可积.
- ⑤ Time-invariance (时不变)

例: $y[n] = n x[n] + \alpha$ (判断 $y[n]$ 与 $y[n-n_0]$)

则 $\hat{x}[n] = x[n-n_0]$ 时移

$$\hat{y}[n] = n \hat{x}[n] + \alpha \quad \text{又} \quad y[n-n_0] = (n-n_0)x[n-n_0] + \alpha$$

$$= n x[n-n_0] + \alpha$$

得 $\hat{y}[n] \neq y[n-n_0]$ Not TI.

$y(t) = x(at)$ $a \neq 1$ 时 时变.

$y(t) = f(t) \cdot x(t)$ $f(t)$ 为 t 的函数 时变.

$y(t) = x(t-t_0)$ 时移 为 时不变.

⑥ Linearity (线性)

例: $y[n] = n x[n] + \alpha$ (判断 $y[n]$ 与 $\alpha_1 y_1[n] + \alpha_2 y_2[n]$)

则 $\hat{x}[n] = \alpha_1 x_1[n] + \alpha_2 x_2[n]$ 线性组合.

$$\hat{y}[n] = n \hat{x}[n] + \alpha$$

$$= n \alpha_1 x_1[n] + n \alpha_2 x_2[n] + \alpha$$

$$\alpha_1 y_1[n] + \alpha_2 y_2[n] = n \alpha_1 x_1[n] + n \alpha_2 x_2[n] + \alpha (\alpha_1 + \alpha_2)$$

得 $\hat{y}[n] \neq \alpha_1 y_1[n] + \alpha_2 y_2[n]$ Not Linear