电子科技大学 2019 -2020 学年第 2 学期 期末(A) 试卷

考试科目: 信号与系统 考试形式: 一页纸开卷 考试日期: 2020 年 9 月 2 日

本试卷由 八 部分构成, 共 8 页。考试时长: 120 分钟

成绩构成比例: 平时成绩 50 %, 期末成绩 50 %

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一、计算题(10分)

Determine which of these properties hold and which do not hold for the

following discrete-time system:
$$y[n] = \begin{cases} 0, & x[n] < 0 \\ x[n] + x[n-3], & x[n] \ge 0 \end{cases}$$

where x[n] denotes the system input and y[n] is the system output.

(a) Memoryless (b) Time invariant (c) Linear (d) Causal (e) Stable

得分二、计算题(8分)

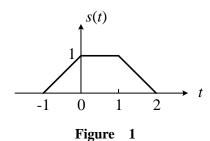
Let $x[n] = (2 + e^{j\pi n}) \cdot u[n]$

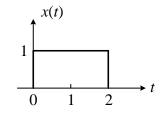
- (a) Is x[n] periodic? If it is, determine the fundamental period.
- **(b) Determine and sketch** $y[n] = \frac{1}{2} (1 e^{j\pi n}) x[n]$
- (c) Determine and sketch the even and odd parts of x[n]

得分 三、计算题(12分)

The unit step response s(t) is the output of an LTI system when the input is the unit step signal u(t). Suppose that the unit step response s(t) of an LTI system is as shown in Figure 1.

- (a) Determine and sketch unit impulse response h(t) of the system.
- (b) Determine whether the system is causal and/or stable.
- (c) If the input of the system is as shown in Figure 2, sketch the output y(t).





Given the following facts about a periodic signal x(t).

- (a) x(t) is real;
- (b) The period of x(t) is 4 and its Fourier coefficients are denoted as a_k ;
- (c) $a_k = 0$ for |k| > 1;
- (d) A real signal with Fourier coefficients $b_k = e^{-jk\frac{\pi}{2}}a_k$ is odd;
- (e) $\frac{1}{4} \int_{<T>} |x(t)|^2 dt = \frac{1}{2}$.

Determine all possible x(t).

五、计算题(14分)

The following figure shows a series connection of an amplitude modulation and the corresponding demodulation. The carrier is given by $p(t) = \cos(\omega_c t)$.

When the input is given by $x(t) = \sum_{k=-\infty}^{+\infty} \delta\left(t - k\frac{4\pi}{3\omega_c}\right)$,

- (a) Determine the output y(t).
- (b) Sketch the spectrum of $x_1(t)$ and the spectrum of $x_2(t)$

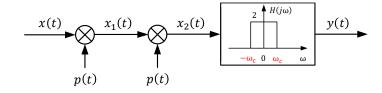


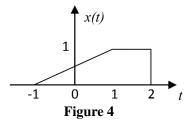
Figure 3

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六、计算题(12分)

Let $X(j\omega)$ denote the Fourier transform of the signal x(t) shown in Figure 4.

- (a) Find $X(j\omega)|_{\omega=0}$
- (b) Determine the expression of $\operatorname{Re}\left\{ X\left(j\omega\right)\right\}$
- (c) Find $\int_{-\infty}^{+\infty} \left| \operatorname{Re} \left\{ X \left(j \omega \right) \right\} \right|^2 d \omega$



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七、计算题(16分)

Consider the inverse of a causal LTI system H(s) is, $H^{-1}(s) = \frac{s^2 + 3s + 2}{2s^2 + 4s - 6}$

- (a) Determine the system H(s) and sketch the pole-zero pattern of H(s). Is this system H(s) stable?
- (b) Determine the differential equation relating the input x(t) and output y(t) for system H(s).
- (c) Draw the block diagram of the system H(s).
- (d) Find the impulse response h(t) of the system.

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八、计算题(16分)

Consider the digital filter structure shown in Figure 5.

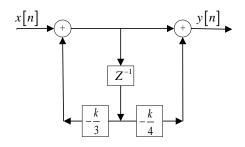


Figure 5

- (a) Find H[z] for this causal filter.
- (b) For what values of the k is the system stable?
- (c) If k=1, determine h[n].
- (d) If k=1 and $x[n]=(\frac{2}{3})^n$, determine y[n] for all n.