```
testing if this is done right (asd) {
  asdkjasdf
}

kms; ╭
```

7d8b50a ⟩ :: ⟨ 2017—08—04, by Robert ⟩ :: ⟨ Initial commit ⟩K
05944d2 ⟩ :: ⟨ 2017—08—04, by Rob A ⟩ :: ⟨ Updated FTC App to 3.2 Beta ⟩K
d922861 ⟩ :: ⟨ 2017—08—04, by Rob A ⟩ :: ⟨ fixing submodule issue. Removed toTC.sh ⟩K
0bf0f57 ⟩ :: ⟨ 2017—08—04, by Rob A ⟩ :: ⟨ Fixed submodule issue ⟩K
a10c785 ⟩ :: ⟨ 2017—08—05, by Rob A ⟩ :: ⟨ lol notes ⟩K
a426297 ⟩ :: ⟨ 2017—08—06, by Rob A ⟩ :: ⟨ Added enum for bot actions and the bot class to be filled in. ⟩K
c16594f ⟩ :: ⟨ 2017—08—06, by Rob A ⟩ :: ⟨ testing for slack integration ⟩K
ab6379d ⟩ :: ⟨ 2017—08—07, by Rob A ⟩ :: ⟨ removed slack test file ⟩K
bdfb595 ⟩ :: ⟨ 2017—08—07, by Rob A ⟩ :: ⟨ slight improvements to bot class ⟩K
e77f0d9 ⟩ :: ⟨ 2017—08—07, by Wen P ⟩ :: ⟨ Added some basic enums; we should add more as we figure out the bot's hardware ⟩K
51efa9d ⟩ :: ⟨ 2017—08—07, by Rob A ⟩ :: ⟨ minor updates to bot actions for future us to fill in (actions enum). ⟩K
255bb0e ⟩ :: ⟨ 2017—08—07, by Rob A ⟩ :: ⟨ updates to bot class ⟩K
775db69 ⟩ :: ⟨ 2017—08—18, by Rob A ⟩ :: ⟨ update to bot ⟩K
17319a8 ⟩ :: ⟨ 2017—08—29, by Rob A ⟩ :: ⟨ updated gitignore ⟩K
12ad864 ⟩ :: ⟨ 2017—09—09, by Wen P ⟩ :: ⟨ Updated sdk? ⟩K
a3c0292 ⟩ :: ⟨ 2017—09—09, by Wen P ⟩ :: ⟨ Updated sdk ⟩K
c2e111a ⟩ :: ⟨ 2017—09—09, by Wen P ⟩ :: ⟨ Finish updating ⟩K
94f2f8b ⟩ :: ⟨ 2017—09—09, by Wen P ⟩ :: ⟨ Created standalone package for enums ⟩K
c2165f3 ⟩ :: ⟨ 2017—09—10, by Rob A ⟩ :: ⟨ added telebop class and 2 auton classes — unfilled ⟩K
13b7c9e ⟩ :: ⟨ 2017—09—11, by Rob A ⟩ :: ⟨ Added PDFs ⟩K
d1bcac3 ⟩ :: ⟨ 2017—09—14, by Rob A ⟩ :: ⟨ Learning rev stuff and making robot do things for activities fair ⟩K
4c17073 ⟩ :: ⟨ 2017—09—15, by Rob A ⟩ :: ⟨ Finished tester bot ⟩K
75f169e ⟩ :: ⟨ 2017—09—16, by Rob A ⟩ :: ⟨ moved test bot stuff into a seperate folder and made some minor adjustments to the bot class. ⟩K
2f7d080 ⟩ :: ⟨ 2017—09—18, by Rob A ⟩ :: ⟨ Some changes to telebop — started wrok on field centric drive ⟩K
b8f69d2 ⟩ :: ⟨ 2017—09—20, by Rob A ⟩ :: ⟨ Split field centric drive work into a seperate class ⟩K
f707fe1 ⟩ :: ⟨ 2017—09—22, by Rob A ⟩ :: ⟨ lol field centric drive in 2017 ⟩K
0d28392 ⟩ :: ⟨ 2017—09—22, by Wen P ⟩ :: ⟨ bzzt bzzt ⟩K
35327ec ⟩ :: ⟨ 2017—09—22, by Wen P ⟩ :: ⟨ Made better readme for teamcode ⟩K
be64251 ⟩ :: ⟨ 2017—09—22, by Wen P ⟩ :: ⟨ added motor related stuff to Bot class, made init function have arguments ⟩K
110b66e ⟩ :: ⟨ 2017—09—22, by Wen P ⟩ :: ⟨ hyperlul fixed that interesting drive orientation ⟩⊢|K

  7f16776 ⟩ :: ⟨ 2017—09—22, by Wen P ⟩ :: ⟨ Worked on enums. Migrated movement enum to ADT to allow for Angle and easier drive function maker ⟩|K
  97ebcb4 ⟩ :: ⟨ 2017—09—22, by Wen P ⟩ :: ⟨ removed impo from Bot.java ⟩⊢|<
  9ca949b ⟩ :: ⟨ 2017—09—22, by Rob A ⟩ :: ⟨ Worked on Field Centric Driving, NOTE: problem with setting negative powers on wheels ⟩⊢K

fb7d18d ⟩ :: ⟨ 2017—09—22, by Rob A ⟩ :: ⟨ Merge branch 'master' of https://github.com/0207—Critical—Mass/0207—Relic—Recovery ⟩K
a91f55b ⟩ :: ⟨ 2017—09—22, by Rob A ⟩ :: ⟨ fixed the field centric drive (I think) ⟩K
ebfe628 ⟩ :: ⟨ 2017—09—22, by Rob A ⟩ :: ⟨ commented the field centric drive code — requires testing still. ⟩K
9dc5483 ⟩ :: ⟨ 2017—09—22, by Rob A ⟩ :: ⟨ Moved around old testbot opmodes ⟩K
686665b ⟩ :: ⟨ 2017—09—22, by Rob A ⟩ :: ⟨ Minor changes to the field centric drive opmode ⟩K
6a16c6b ⟩ :: ⟨ 2017—09—22, by Robert ⟩ :: ⟨ Update README.md ⟩K
bfedca0 ⟩ :: ⟨ 2017—09—23, by Rob A ⟩ :: ⟨ minor change to bot class and bug fixes in Field Centric ⟩K
0fd860a ⟩ :: ⟨ 2017—09—25, by Wen P ⟩ :: ⟨ made it lowercase folder ⟩K
7c3b8c8 ⟩ :: ⟨ 2017—09—25, by Wen P ⟩ :: ⟨ Added some comments ⟩⊢|K

033b1f4 ⟩ :: ⟨ 2017—09—26, by Rob A ⟩ :: ⟨ Added OpMode for calibration of the gyro. ⟩|K

8dac403 ⟩ :: ⟨ 2017—09—26, by Rob A ⟩ :: ⟨ Minor changes to Field Centric so that we can effectively test the new CalibrateGyro opmode ⟩H⟨

990d96c ⟩ :: ⟨ 2017—09—29, by Wen P ⟩ :: ⟨ Worked on bot clas, added imu related code, added simple example drive function ⟩⊢K

c0f39f7 ⟩ :: ⟨ 2017—09—29, by Wen P ⟩ :: ⟨ Merge branch 'master' of https://github.com/0207—Critical—Mass/0207—Relic—Recovery ⟩K

322df22 ⟩ :: ⟨ 2017—09—29, by Wen P ⟩ :: ⟨ created the teleopautobalance teleop ⟩K

9d6d133 ⟩ :: ⟨ 2017—09—29, by Wen P ⟩ :: ⟨ removed extra created by comment ⟩K

a8bc827 ⟩ :: ⟨ 2017—09—29, by Wen P ⟩ :: ⟨ added a comment, but finishing yp for the day so logging it even though its small ⟩K

7a8e6f5 ⟩ :: ⟨ 2017—10—08, by Rob A ⟩ :: ⟨ field centric thing ⟩K

72abd86 ⟩ :: ⟨ 2017—10—08, by Rob A ⟩ :: ⟨ stuff for workshop ⟩K

d97f8be ⟩ :: ⟨ 2017—10—08, by Wen P ⟩ :: ⟨ Added basic tank drive teleop for 10/8/17 ⟩K

bdae268 ⟩ :: ⟨ 2017—10—08, by Rob A ⟩ :: ⟨ Rob stuff, pushing so wen can fix natural log ⟩K

531dfd7 ⟩ :: ⟨ 2017—10—20, by Rob A ⟩ :: ⟨ updates from work session 10/20/17 ⟩K

ac631b8 ⟩ :: ⟨ 2017—10—20, by Rob A ⟩ :: ⟨ updates from work session 10/20/17 ⟩K

feb2bf9 ⟩ :: ⟨ 2017—10—23, by Rob A ⟩ :: ⟨ Bot class updates ⟩K

95786bf ⟩ :: ⟨ 2017—10—23, by Rob A ⟩ :: ⟨ bot changes + vuforia test ⟩K

d3a3a12 ⟩ :: ⟨ 2017—10—23, by Rob A ⟩ :: ⟨ updates to autons and bot class ⟩K

34ea701 ⟩ :: ⟨ 2017—10—23, by Rob A ⟩ :: ⟨ Added subclass autonbot and teleopbot ⟩K

d4c1fcc ⟩ :: ⟨ 2017—10—23, by Rob A ⟩ :: ⟨ removed constructor from bot class ⟩K

55404b0 ⟩ :: ⟨ 2017—10—23, by Rob A ⟩ :: ⟨ removed the autonbot and telebopbot classes to make room for wen's new system ⟩K

101441f ⟩ :: ⟨ 2017—10—27, by Rob A ⟩ :: ⟨ updated to 3.0—⟶ gradles etx change ⟩K

e0ac1bd ⟩ :: ⟨ 2017—10—27, by Rob A ⟩ :: ⟨ PUSH ⟩K

a7e7e08 ⟩ :: ⟨ 2017—10—30, by Rob A ⟩ :: ⟨ edits to bot class and telebop ⟩K

cab994f ⟩ :: ⟨ 2017—10—30, by Rob A ⟩ :: ⟨ removed field centric drive opmode ⟩K

8897bf7 ⟩ :: ⟨ 2017—10—31, by Rob A ⟩ :: ⟨ Added more functions and motors to bot class, cleaned autons up using improved class. ⟩K

8e9a547 ⟩ :: ⟨ 2017—11—01, by Wen P ⟩ :: ⟨ updated sdk to 3.5 ⟩K

501e3f7 ⟩ :: ⟨ 2017—11—01, by Wen P ⟩ :: ⟨ added arm servo stuff to bot, hopefully it works ⟩K

5f64187 ⟩ :: ⟨ 2017—11—01, by Wen P ⟩ :: ⟨ idk possibly added arm stuff ⟩⊢|K

b5daab5 ⟩ :: ⟨ 2017—11—02, by Wen P ⟩ :: ⟨ added comments for burto ⟩|⊣⊢|⟨

c7f5bf3 ⟩ :: ⟨ 2017—11—02, by Rob A ⟩ :: ⟨ telebop update ⟩⊢|⊢|⟨

3e66963 ⟩ :: ⟨ 2017—11—02, by Rob A ⟩ :: ⟨ Merge branch 'master' of https://github.com/Dwight—Englewood—Robotics/0207—Relic—Recovery ⟩|K

24d0854 ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ added more comment: ⟩|K

844d263 ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ added OneButtonMan Teleop for testing motor and configuration ⟩|K

93b6c0a ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ chagned some stuff in bot and teleop to make other stuff work ⟩|K

52c710f ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ added start of system for the ASM based robot/subsystem design: ⟩|⊢|⊢|⟨

fc1f16e ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ fixed a type making the armBottomExtendyServo not work properly ⟩H|⟨

8de32d8 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ rob bot stuff ⟩⊢□⊣⊢|⟨

3a80428 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ Merge branch 'master' of https://github.com/Dwight—Englewood—Robotics/0207—Relic—Recovery ⟩⊢||⊣|K

1c4c1a9 ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ Merge branch 'master' of https://github.com/Dwight—Englewood—Robotics/0207—Relic—Recovery ⟩H⟨

788023e ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ Random crap ⟩⊢H⟨

3aee82b ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ Merge branch 'master' of https://github.com/Dwight—Englewood—Robotics/0207—Relic—Recovery ⟩⊢|K

749bdff ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ changed onebuttonman so it doesnt have the bad releaseTheKraken ⟩|⊣⊢|⟨

607df86 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ changed to range clip ⟩⊢|⊢|⟨

3a01764 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ Merge branch 'master' of https://github.com/Dwight—Englewood—Robotics/0207—Relic—Recovery ⟩ⱵⅠⅠⅠⱵ

79f92dd ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ releaseTheGiantQuid ⟩ⅠⱵⅠⱵ

8c73387 ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ Merge branch 'master' of https://github.com/Dwight—Englewood—Robotics/0207—Relic—Recovery ⟩ⱵⱵ⟨
ce687d2 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ idk ⟩ⱵⱵ

ff04520 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ asd ⟩Ⱶ
8922528 ⟩ :: ⟨ 2017—11—03, by Wen P ⟩ :: ⟨ chjanged arm extendy values to make them work ⟩Ⱶ
4347415 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ k ⟩Ⱶ
fc14508 ⟩ :: ⟨ 2017—11—03, by Rob A ⟩ :: ⟨ Minor fix to gyro turns ⟩Ⱶ
95a13fd ⟩ :: ⟨ 2017—11—05, by Rob A ⟩ :: ⟨ pre match pushes ⟩Ⱶ
12b75b4 ⟩ :: ⟨ 2017—11—05, by Wen P ⟩ :: ⟨ lots of natural log from today from rob/wen ⟩Ⱶ
a06109d ⟩ :: ⟨ 2017—11—06, by Wen P ⟩ :: ⟨ renamed ServoTest teleops made in competition, made them more readable ⟩Ⱶ
65994f9 ⟩ :: ⟨ 2017—11—06, by Wen P ⟩ :: ⟨ added intellij templates — must be manually added to intellij, allows for super easy new teleop/auton creation ⟩Ⱶ
e6dbe58 ⟩ :: ⟨ 2017—11—08, by Wen P ⟩ :: ⟨ Removed Useless comment and added a newline to readme ⟩Ⱶ
32c3e3c ⟩ :: ⟨ 2017—11—09, by Rob A ⟩ :: ⟨ Finished the test bench code. Began adding new servos to the bot class for the flipper and two release servos (now te
6c68edf ⟩ :: ⟨ 2017—11—09, by Rob A ⟩ :: ⟨ Commented out end game servos from bot class and teleop. ⟩Ⱶ
4e0d78f ⟩ :: ⟨ 2017—11—09, by Rob A ⟩ :: ⟨ Cleaned up different opmodes into respective packages (Auton, Teleop, Testing, etc.) for cleanliness ⟩Ⱶ
69b994a ⟩ :: ⟨ 2017—11—09, by Rob A ⟩ :: ⟨ cleaned the bot class by removing unnecessary comments and adding functions for things that could be automated. ⟩Ⱶ
977d79d ⟩ :: ⟨ 2017—11—09, by Rob A ⟩ :: ⟨ Moved hardware mapping to the bot class constructor to make loading times faster when pressing init on the drivers st
905902e ⟩ :: ⟨ 2017—11—09, by Rob A ⟩ :: ⟨ Changed the inputs to the constructor of the bot class to take over the role of setting hardwaremap references to mot
23819de ⟩ :: ⟨ 2017—11—10, by Rob A ⟩ :: ⟨ Added an invert drive mode to the bot class' tank drive function. ⟩Ⱶ
b6265f9 ⟩ :: ⟨ 2017—11—10, by Rob A ⟩ :: ⟨ Minor change to ordering of declarations in bot class to make more sense. ⟩Ⱶ
7ab27f4 ⟩ :: ⟨ 2017—11—13, by Rob A ⟩ :: ⟨ Renamed wen's wip bot class for confusion reasons. Also added the Enderbot's closable vuforia localizer so that we ca
9b77560 ⟩ :: ⟨ 2017—11—13, by Rob A ⟩ :: ⟨ added enderbot's default exception handler for if the bot randomly crashes while on the field. Will auto restart the
[HEAD—][master—][remotes/origin/HEAD—][remotes/origin/master—⟨] fa11a29 ⟩ :: ⟨ 2017—11—13, by Wen P ⟩ :: ⟨ Added script which pretty prints our git history ⟩