heap

- complete binary tree (review)
- heap and priority queues (Chapter 9)
- binary heap and min-heap
- max-heap demo
- max-heap coding
- heap sort (Chapter 7)

heap coding: heap.h

Heap ADT: A **one - based** and **one dimensional array** is used to simplify parent and child calculations.

```
struct Heap {
 int *nodes; // an array of nodes
 int capacity; // array size of node or key, item
 int N; // the number of nodes in the heap
 bool (*comp) (Heap*, int, int);
 Heap(int capa = 2) {
   capacity = capa;
   nodes = new int[capacity];
   N = 0;
   comp = nullptr;
 };
 ~Heap() {};
};
using heap = Heap*;
```

heap coding: heap.h

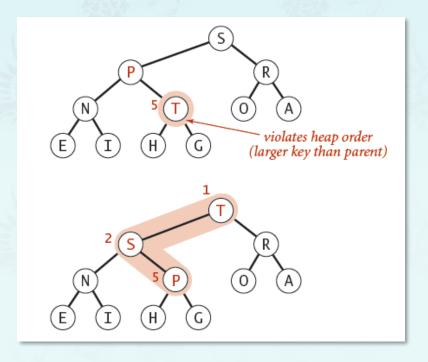
```
void clear(heap hp);
                             // deallocate heap
int size (heap hp);
                          // return nodes in heap currently
int level(int n);
                            // return level based on num of nodes
int capacity (heap hp);
                          // return its capacity (array size)
int reserve (heap hp, int capa); // reserve the array size (= capacity)
                  // return true/false
int full (heap hp);
int empty(heap hp);
                           // return true/false
                       // add a new key
void grow(heap hp, int key);
                          // delete a queue
void trim(heap hp);
int heapify (heap hp);
                             // convert a complete BT into a heap
// helper functions to support grow/trim functions
int less(heap hp, int i, int j); // used in max heap
int more (heap hp, int i, int j); // used in min heap
// helper functions to check heap invariant
```

Promotion in a heap: swim

- To eliminate the violation:
 - Swap key in child with key in parent.
 - Repeat until heap order restored.

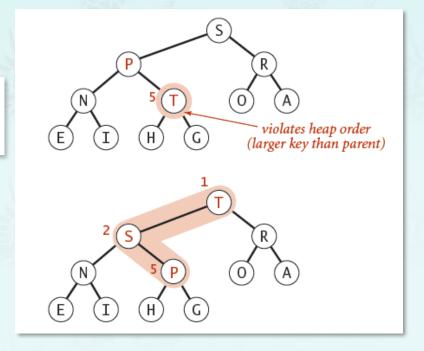
swim up or sink down

This is a maxheap example.

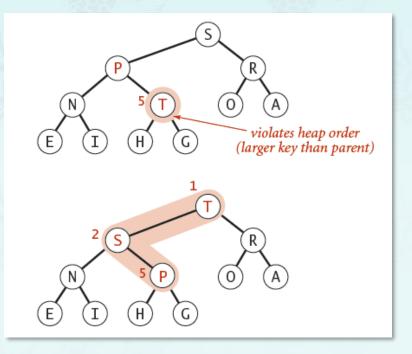


- To eliminate the violation:
 - Swap key in child with key in parent.
 - Repeat until heap order restored.

```
bool (heap h, int p, int c) {
   return h->nodes[p] < h->nodes[c];
}
```



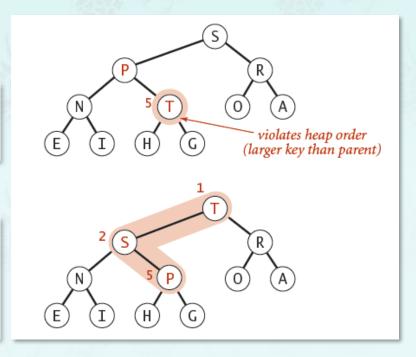
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- To eliminate the violation:
 - Swap key in child with key in parent.
 - Repeat until heap order restored.

```
bool less(heap h, int p, int c) {
    return h->nodes[p] < h->nodes[c];
}
```

```
void swap(heap h, int p, int c) {
   int item = h->nodes[p];
   h->nodes[p] = h->nodes[c];
   h->nodes[c] = item;
}
```



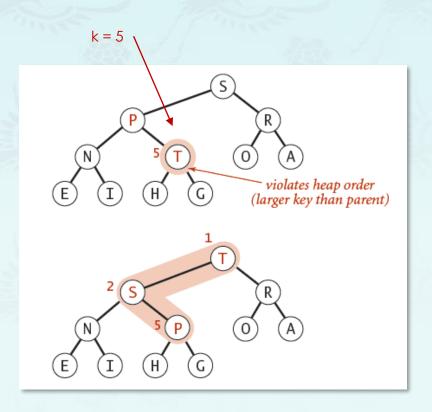
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 - Swap key in child with key in parent.
 - Repeat until heap order restored.

```
not reached at root

void swim(h p h, int k)

{
while (
{
}
}
}
```



- To eliminate the violation:
 - Swap key in child with key in parent.
 - Repeat until heap order restored.

```
not reached at root

void swim(h p h, int k)

while (k > 1 &&

{

while (k > 1 &&

{

parent(k/2) is less its child(k)

| the continuous parent(k/2) is less its child(k)

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```



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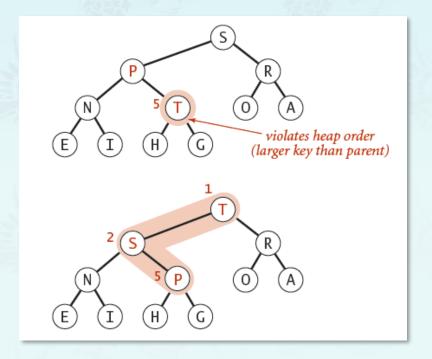
```
not reached at root

void swim(h p h, int k)

while (k > 1 && less(h, k / 2, k))

swap parent(k/2) and its child(k)

swap parent(k/2) and its child(k)
```



- To eliminate the violation:
 - Swap key in child with key in parent.
 - Repeat until heap order restored.

```
not reached at root

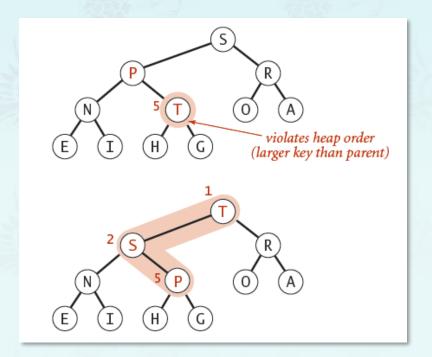
void swim(h p h, int k)

while (k > 1 && less(h, k / 2, k))

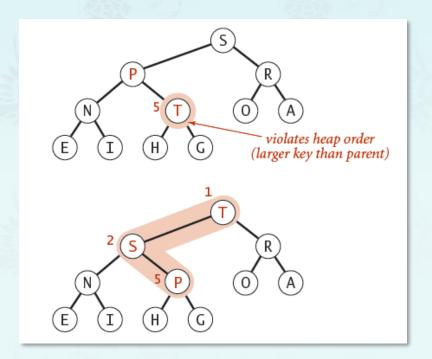
swap(h, k / 2, k);

swap parent(k/2)
and its child(k)

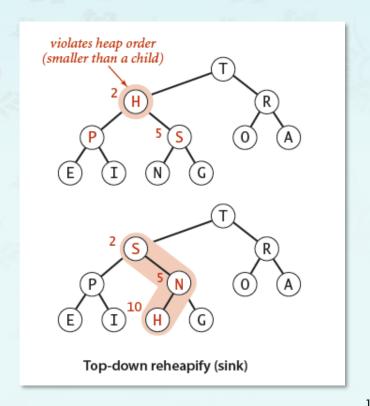
move up
one level
```



- To eliminate the violation:
 - Swap key in child with key in parent.
 - Repeat until heap order restored.



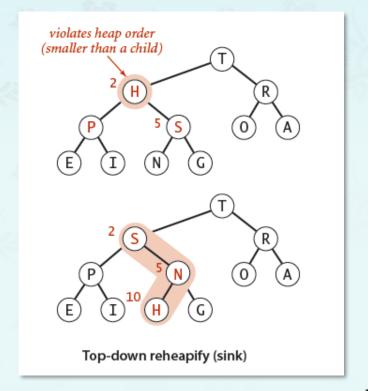
swim up or sink down



Demotion in a heap: sink

- Parent's key becomes smaller than one (or both) of its children's.
- To eliminate the violation:
 - Swap key in parent with key in larger child (of two)
 - Repeat until heap order restored.

This is a maxheap example.

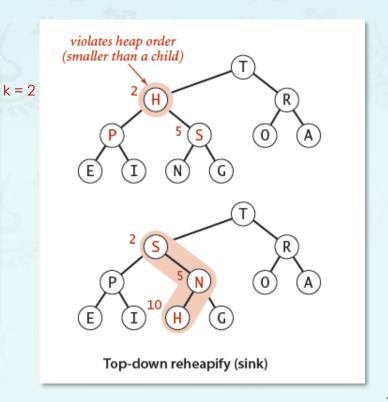


Demotion in a heap: sink

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- To eliminate the violation:
 - Swap key in parent with key in larger child (of two)
 - Repeat until heap order restored.

```
void sink(heap h, int k)
{
  while (k's child not reached the last)
  {
    find the larger child of k, let it be j. (j = 5)

    if k's key is not less than j's key, break;
    swap k and j since k's key > j's key
    set k to the next node w
}
}
```

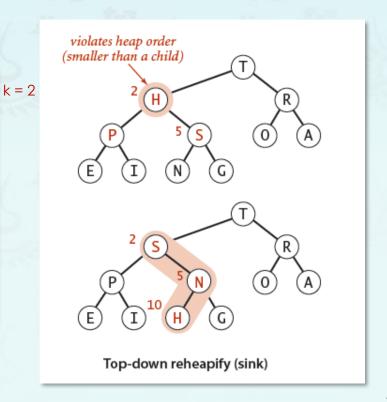


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  while (k's child not reached the last)
  {
    find the larger child of k, let it be j. (j = 5)

    if k's key is not less than j's key, break;
    swap k and j since k's key > j's key
    set k to the next node which is j.
  }
}
```



Demotion in a heap: sink

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 - Swap key in parent with key in larger child
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}
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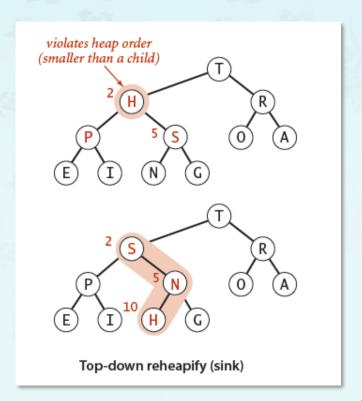
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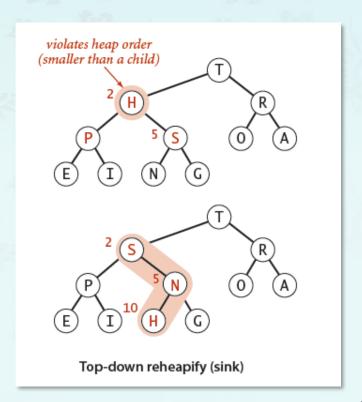
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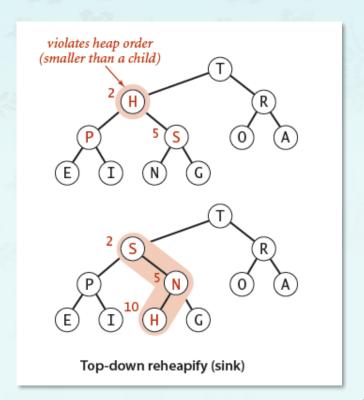
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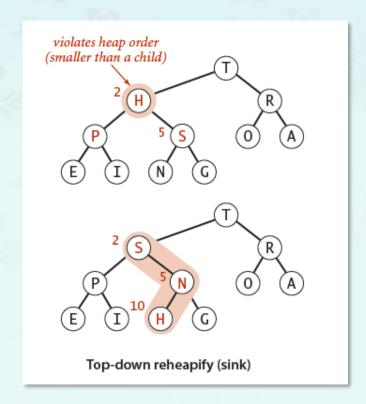
Demotion in a heap: sink

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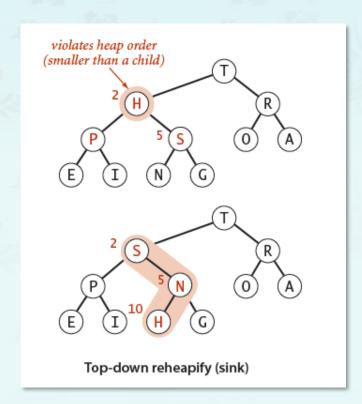
Demotion in a heap: sink

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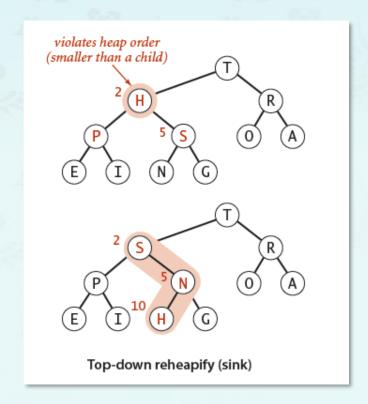


Demotion in a heap: sink

- Parent's key becomes smaller than one (or both) of its children's.
- To eliminate the violation:
 - Swap key in parent with key in larger child
 - Repeat until heap order restored.

```
void sink(heap h, int k)
{
    while (2 * k <= h->N)
    {
        int j = 2 * k;

        if (j < h->N && less(h, j, j + 1)) j++;
        if (!less(h, k, j)) break;
        swap(h, k, j);
        k = j;
    }
}
```



Insert: Add node at end, then swim it up.

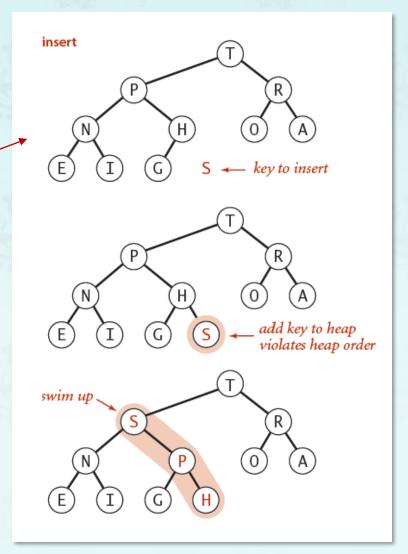
Cost: At most 1 + log N compares.

What is N now?

Insert

Step 1

Step 2



Insertion in a heap: insert Insert: Add node at end, then swim it up. Cost: At most 1 + log N compares. What is N now? (E)void insert(heap h, int key) add key to heap violates heap order struct Heap { // an array of nodes int *nodes; swim up // array size of node or key, item int capacity; // the number of nodes in the heap int N; using heap = *Heap;

Insertion in a heap:

- Insert: Add node at end, then swim it up.
 - Cost: At most 1 + log N compares.

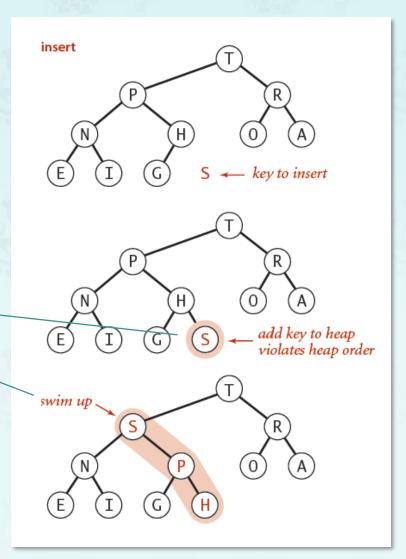
```
void insert(heap h, int key)
{
    h->nodes[++h->N] = key;
}

struct Heap {
    int *nodes;
    int capacity;
    int N;
    int N;
    // the number of nodes in the heap

//
};
using heap = *Heap;

void swim(heap h, int k)
```

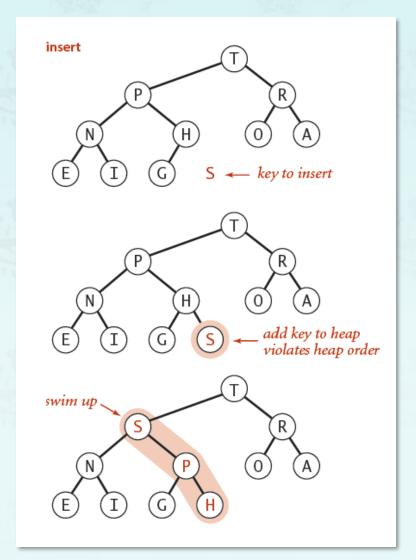
void sink(heap h, int k)



Insertion in a heap:

- Insert: Add node at end, then swim it up.
 - Cost: At most 1 + log N compares.

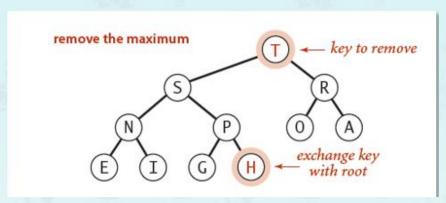
```
void insert(heap h, int key)
{
  h->nodes[++h->N] = key;
  swim(h, h->N);
}
```







- (1) Delete the root (max or min) in a heap:
- (2) How many times do comparisons occur for n nodes ? (select one): n, 2n, n^2, 2 log n, n log n, log n



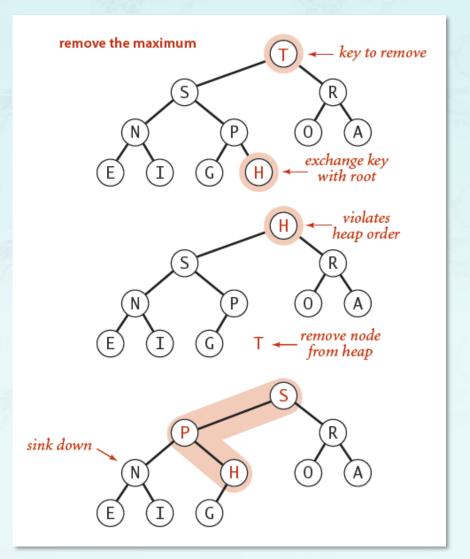
```
void swim(heap h, int k)
void sink(heap h, int k)
bool less(heap h, int p, int c)
void swap(heap h, int p, int c)
```

- Delete root: Swap root with node at end, then sink it down.
- Cost: At most 2 log N compares.

```
void delete(heap h) {

    swap(h, ..., ...);
    sink(h, ...);
}
```

```
void swim(heap h, int k)
void sink(heap h, int k)
bool less(heap h, int p, int c)
void swap(heap h, int p, int c)
```



- Delete root: Swap root with node at end, then sink it down.
- Cost: At most 2 log N compares.

```
void delete(heap h) {
}
```

```
void swim(heap h, int k)
void sink(heap h, int k)
bool less(heap h, int p, int c)
void swap(heap h, int p, int c)
```



- Delete root: Swap root with node at end, then sink it down.
- Cost: At most 2 log N compares.

```
void delete(heap h) {
    swap(h, 1, h->N--);
}
```

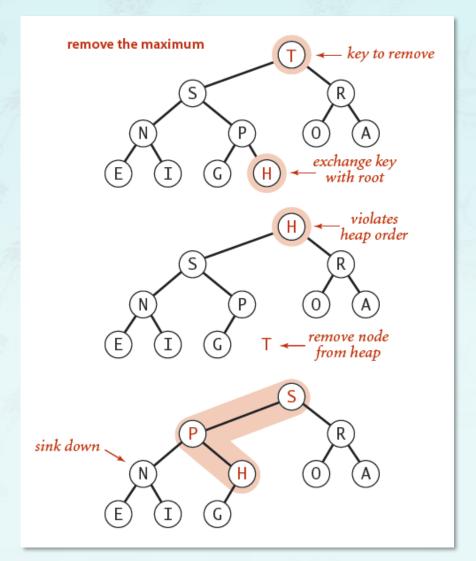
```
void swim(heap h, int k)
void sink(heap h, int k)
bool less(heap h, int p, int c)
void swap(heap h, int p, int c)
```



- Delete root: Swap root with node at end, then sink it down.
- Cost: At most 2 log N compares.

```
void delete(heap h) {
    swap(h, 1, h->N--);
    sink(h, 1);
}
```

```
void swim(heap h, int k)
void sink(heap h, int k)
bool less(heap h, int p, int c)
void swap(heap h, int p, int c)
```



heap coding: heap.h

```
void clear(heap hp);
                         // deallocate heap
int size (heap hp);
                       // return nodes in heap currently
int level(int n);
                       // return level based on num of nodes
                // return its capacity (array size)
int capacity (heap hp);
int reserve (heap hp, int capa); // reserve the array size (= capacity)
              // return true/false
int full (heap hp);
               // return true/false
int empty(heap hp);
void trim(heap hp);
               // delete a queue
int heapify (heap hp);
              // convert a complete BT into a heap
// helper functions to support grow/trim functions
int less(heap hp, int i, int j);  // used in max heap
int more (heap hp, int i, int j); // used in min heap
// helper functions to check heap invariant
```

```
// return the number of items in heap
int size(heap hp) {
   return heap->N;
// Is this heap empty?
int empty(heap hp) {
   return (heap->N == 0) ? true : false;
// Is this heap full?
int full(heap hp) {
   return (heap->N == heap->capacity - 1) ? true : false;
```

```
int less(heap hp, int i, int j) {
   return heap->nodes[i] < heap->nodes[j];
}
```

```
void swap(heap hp, int i, int j) {
   int t = heap->nodes[i];
   heap->nodes[i] = heap->nodes[j];
   heap->nodes[j] = t;
}
```

```
void swim(heap hp, int k) {
}
```

```
void sink(heap hp, int k) {
}
```

```
void grow(heap hp, int key) {
    cout << "YOUR CODE HERE\n";
    // add key @ ++heap->N
    // swim up @ heap->N
}
```

```
void trim(heap hp) {
   if (empty(heap)) return;

cout << "YOUR CODE HERE\n";
}</pre>
```

newCBT()	with a given array, instantiate a new complete binary tree its result is neither maxheap nor minheap.
heapify() heapsort()	make a complete binary tree into a (max) heap use max/min-heap to sort elements in heap

```
// instantiates a CBT with given data and its size.
heap newCBT(int *a, int n) {
    int capa = ?
   heap p = new Heap{ capa };
    p->N = n;
    for (int i = 0; i < n; i++)
       p->nodes[i + 1] = a[i];
    return p;
```

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