

DESIGN ANALYSIS AND ALGORITHM

PRACTICAL NO 8

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Experiment No - 8

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Program :- Write a program to Implement Dijkstra's algorithm.

Algorithm

Dijkstra's Algorithm

1. Create cost matrix $C[][]$ from adjacency matrix $adj[][]$. $C[i][j]$ is the cost of going

from vertex i to vertex j . If there is no edge between vertices i and j then $C[i][j]$ is infinity.

2. Array $visited[]$ is initialized to zero.

for($i=0; i<n; i++$)

visited[i]=0;

3. If the vertex 0 is the source vertex then visited[0] is marked as 1.

4. Create the distance matrix, by storing the cost of vertices from vertex no. 0 to $n-1$

from the source vertex 0.

for($i=1; i<n; i++$)

distance[i]=cost[0][i];

Initially, distance of source vertex is taken as 0. i.e. distance[0]=0;

5. for($i=1; i<n; i++$)

- Choose a vertex w , such that distance[w] is minimum and visited[w] is 0. Mark visited[w] as 1.

- Recalculate the shortest distance of remaining vertices from the source.

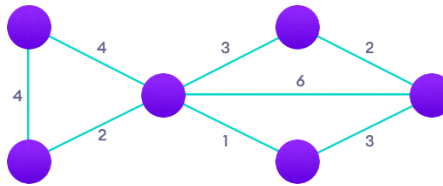
- Only, the vertices not marked as 1 in array visited[] should be considered for recalculation of distance. i.e. for each vertex v

if(visited[v]==0)

distance[v]=min(distance[v],

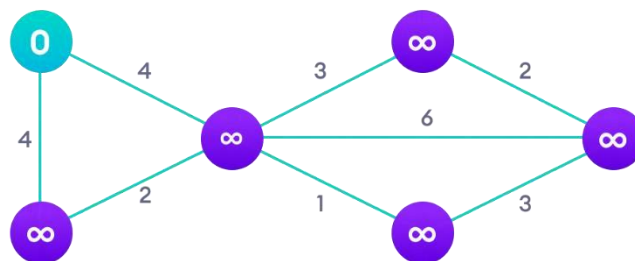
$$\text{distance}[w] + \text{cost}[w][v]$$

Fig:



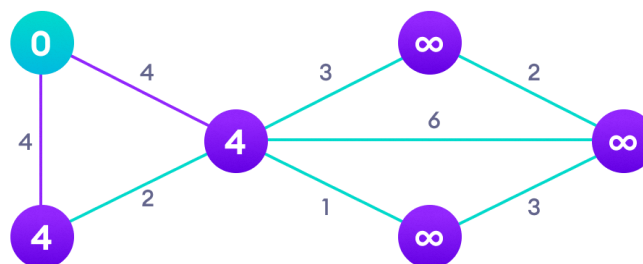
Step: 1

Start with a weighted graph



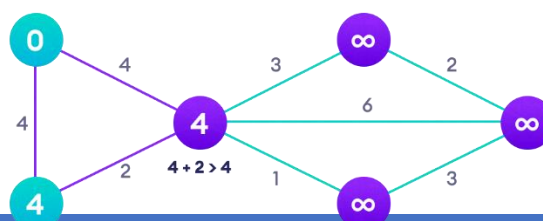
Step: 2

Choose a starting vertex and assign infinity path values to all other devices

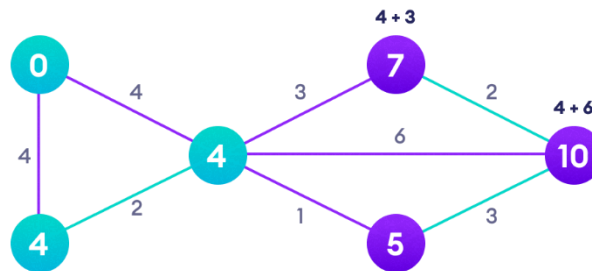


Step: 3

Go to each vertex and update its path length

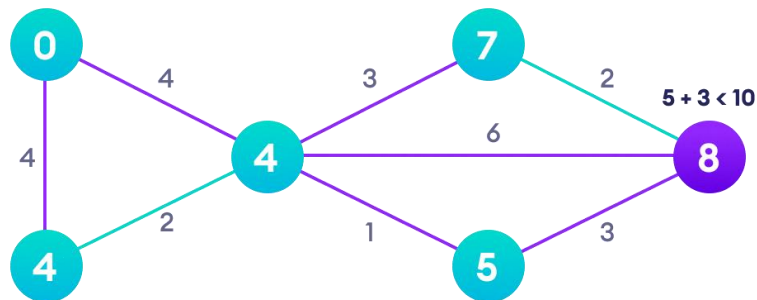


If the path length of the adjacent vertex is lesser than new path length, don't update it



Step: 5

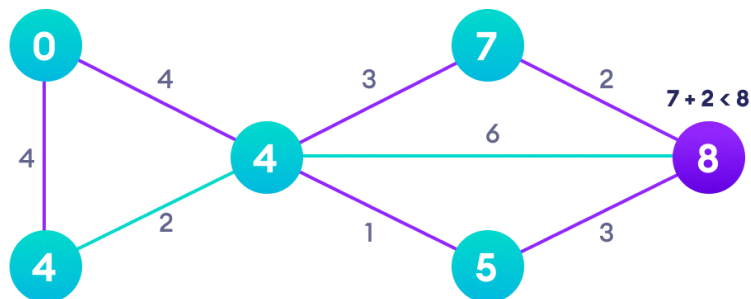
Avoid updating path lengths of already visited vertices



Step: 6

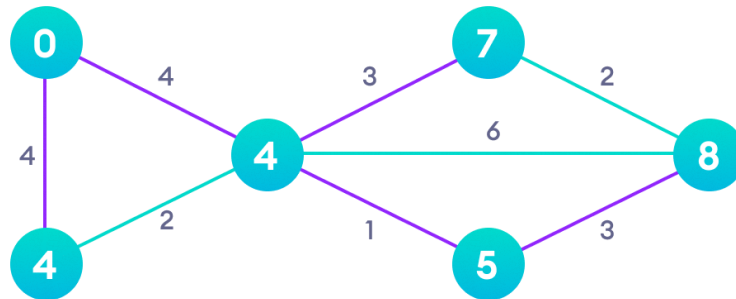
After each iteration, we pick the unvisited vertex with the least path length. So

we choose 5 before 7



Step: 7

Notice how the rightmost vertex has its path length updated twice



Step: 8

Repeat until all the vertices have been visited

Practical Implementation Djikstra's code algorithm

```
import sys

class Graph():

    def __init__(self, vertices):
        self.V = vertices
        self.graph = [[0 for column in range(vertices)]
                       for row in range(vertices)]

    def printSolution(self, dist):
        print "Vertex \tDistance from Source"
        for node in range(self.V):
            print node, "\t", dist[node]

    def minDistance(self, dist, sptSet):

        min = sys.maxint
        for u in range(self.V):
            if dist[u] < min and sptSet[u] == False:
                min = dist[u]
                min_index = u
```

```

    return min_index
def dijkstra(self, src):

    dist = [sys.maxint] * self.V
    dist[src] = 0
    sptSet = [False] * self.V

    for cout in range(self.V):

        x = self.minDistance(dist, sptSet)
        sptSet[x] = True
        for y in range(self.V):
            if self.graph[x][y] > 0 and sptSet[y] == False and \
                dist[y] > dist[x] + self.graph[x][y]:
                dist[y] = dist[x] + self.graph[x][y]

    self.printSolution(dist)

g = Graph(9)
g.graph = [[0, 4, 0, 0, 0, 0, 0, 8, 0],
            [4, 0, 8, 0, 0, 0, 0, 11, 0],
            [0, 8, 0, 7, 0, 4, 0, 0, 2],
            [0, 0, 7, 0, 9, 14, 0, 0, 0],
            [0, 0, 0, 9, 0, 10, 0, 0, 0],
            [0, 0, 4, 14, 10, 0, 2, 0, 0],
            [0, 0, 0, 0, 0, 2, 0, 1, 6],
            [8, 11, 0, 0, 0, 0, 1, 0, 7],
            [0, 0, 2, 0, 0, 0, 6, 7, 0]
            ];

g.dijkstra(0);

```

Output:

Vertex	Distance from Source
0	0
1	4
2	12

```
3      19
4      21
5      11
6       9
7       8
8      14
```

Time Complexity of the implementation is $O(V^2)$. If the input graph is represented using adjacency list, it can be reduced to $O(E \log V)$ with the help of a binary heap.

Conclusion: Successfully Implemented the Dijkstra's algorithm.