

EN1060 Signals and Systems: Signals

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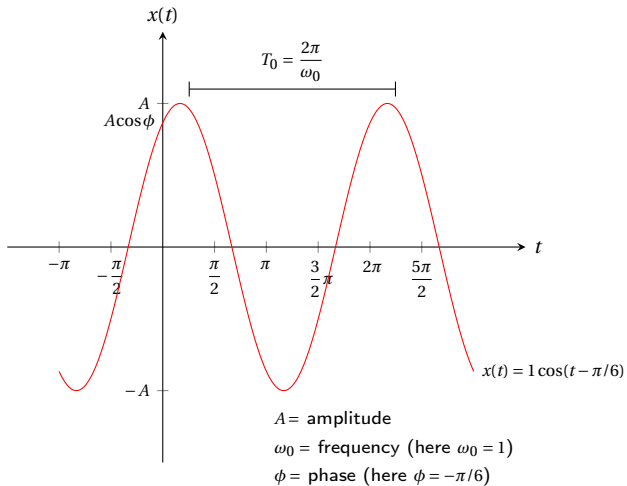
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Section 1

Signals

Continuous-Time Sinusoidal Signal

$$x(t) = A \cos(\omega_0 t + \phi). \quad (1)$$



Sinusoidal signal is **periodic**.

A periodic continuous-time signal $x(t)$ has the property that there is a positive value T for which

$$x(t) = x(t + T) \quad (2)$$

for all values of t . Under an appropriate time-shift the signal repeats itself. In this case we say that $x(t)$ is periodic with period T .

Fundamental period T_0 = smallest positive value of T for which 2 holds.

A signal that is not periodic is referred to as aperiodic.

E.g.: Consider $A\cos(\omega_0 t + \phi)$

$$\begin{aligned} A\cos(\omega_0 t + \phi) &= A\cos(\omega_0(t + T) + \phi) \quad \text{here } \omega_0 T = 2\pi m \quad \text{an integer multiple of } 2\pi \\ &= A\cos(\omega_0 t + \phi) \end{aligned}$$

$$T = \frac{2\pi m}{\omega_0} \Rightarrow \text{fundamental period } T_0 = \frac{2\pi}{\omega_0}.$$

A time-shift in a CT sinusoid is equivalent to a phase shift.

E.g.: Show that a time-shift of a sinusoid is equal to a phase shift.

A signal $x(t)$ or $x[n]$ is referred to as an *even* signal if it is identical to its time-reversed counterpart, i.e., with its reflection about the origin:

$$x(-t) = x(t)$$

$$x[-n] = x[n]$$

A is referred to as an *odd* if

$$x(-t) = -x(t)$$

$$x[-n] = -x[n]$$

An odd signal must be 0 at $t=0$ or $n=0$.

A signal can be broken into a sum of two signals, one of which is even and one for which is odd.

Even part of $x(t)$ is

$$\mathcal{E}\{x(t)\} = \frac{1}{2}[x(t) + x(-t)]$$

Odd part of $x(t)$ is

$$\mathcal{O}\{x(t)\} = \frac{1}{2}[x(t) - x(-t)]$$

Phase of a Sinusoidal: $\phi = 0$

Phase of a Sinusoidal: $\phi = -\pi/2$

$$x[n] = A\cos(\omega_0 n + \phi) \text{ with } \phi = 0$$

$$x[n] = A\cos(\omega_0 n + \phi) \text{ with } \phi = -\pi/2$$

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Does a phase change always correspond to a time shift in discrete-time signals?

All continuous-time sinusoids are periodic. However, discrete-time sinusoids are not necessarily so.

$$x[n] = x[n + N], \quad \text{smallest integer } N \text{ is the fundamental period.} \quad (3)$$

$$\begin{aligned}x(t) &= Ce^{a(t+t_0)}, \quad C \text{ and } a \text{ are real numbers} \\ &= Ce^{at_0} e^{at}.\end{aligned}$$

$$x[n] = Ce^{\beta n} = C\alpha^n, \quad C \text{ and } \alpha \text{ are real numbers}$$

$$x(t) = Ce^{at} \quad C \text{ and } a \text{ are complex numbers.}$$

$$C = |C|e^{j\theta}$$

$$a = r + j\omega_0$$

$$x(t) = |C|e^{j\theta} e^{(r+j\omega_0)t}$$

$$= |C|e^{rt} e^{j(\omega_0 t + \theta)}$$

$$= |C|e^{rt} [\cos(\omega_0 t + \theta) + j \sin(\omega_0 t + \theta)]$$

$$x[n] = C\alpha^n, \quad C \text{ and } \alpha \text{ are complex numbers.} \quad (4)$$

$$C = |C|e^{j\theta} \quad (5)$$

$$\alpha = |\alpha|e^{j\omega_0} \quad (6)$$

$$x[n] = |C|e^{j\theta} \left(|\alpha|e^{j\omega_0} \right)^n \quad (7)$$

$$= |C||\alpha|^n \cos(\omega_0 n + \theta) + j|C||\alpha|^n \sin(\omega_0 n + \theta) \quad (8)$$

$$(9)$$

Comments:

- When $|\alpha| = 1$: sinusoidal real and imaginary parts.
- $e^{j\omega_0 n}$ may or may not be periodic depending on the value of ω_0 .
- Sinusoidal, exponential, step, and impulse signal form the cornerstones for signals and systems analysis.

Periodicity Properties of Discrete-Time Complex Exponentials $e^{j\omega_0 n}$

- For the CT counterpart $e^{j\omega_0 t}$,
 - ① The larger the magnitude of ω_0 , the higher is the rate of oscillation in the signal.
 - ② $e^{j\omega_0 t}$ is periodic for any value of ω_0 .

- In DT, as

$$e^{j(\omega_0+2\pi)n} = e^{j2\pi n} e^{j\omega_0 n} = e^{j\omega_0 n}$$

the exponential at frequency $\omega_0 + 2\pi$ is the same as that at frequency ω_0 .

- Although in CT $e^{j\omega_0 t}$ are all distinct for distinct values of ω_0 . In DT, these signals are not distinct, as the signal with frequency ω_0 is identical to the signals with frequencies $\omega_0 + 2\pi$, $\omega_0 + 4\pi$, and so on. Therefore, in considering DT complex exponentials, we need only consider a frequency interval of length 2π in which to choose ω_0 .
- In DT, as we increase ω_0 from 0, we obtain signals that oscillate more and more rapidly until we reach $\omega_0 = \pi$. As we continue to increase ω_0 , we decrease the rate of oscillation until we reach $\omega_0 = 2\pi$. Note: $e^{j\pi n} = (e^{j\pi})^n = (-1)^n$.

$$u[n] = \begin{cases} 1, & n \geq 0, \\ 0, & n < 0. \end{cases} \quad (10)$$

Discrete-Time Unit Impulse (Unit Sample) $\delta[n]$

$$\delta[n] = \begin{cases} 1, & n = 0, \\ 0, & n \neq 0. \end{cases} \quad (11)$$

Unit impulse is the first backward difference of the unit step sequence.

$$\delta[n] = u[n] - u[n-1]. \quad (12)$$

The unit step sequence is the running sum of the unit impulse.

$$u[n] = \sum_{m=-\infty}^n \delta[m]. \quad (13)$$

The unit step sequence is a superposition of delayed unit impulses.

$$u[n] = \sum_{k=0}^{\infty} \delta[n-k]. \quad (14)$$

Continuous-Time Unit Step Function $u(t)$

$$u(t) = \begin{cases} 0, & t < 0, \\ 1, & t > 0. \end{cases} \quad (15)$$

Continuous-Time Unit Impulse Function $\delta(t)$

$$\delta(t) = \frac{du(t)}{dt}. \quad (16)$$

CT Unit Step Function and Unit Impulse Function

$$u(t) = \int_{-\infty}^t \delta(\tau) d\tau. \quad (17)$$

The total energy over a time interval $t_1 \leq t \leq t_2$ in a continuous-time signal $x(t)$ is

$$\int_{t_1}^{t_2} |x(t)|^2 dt$$

The total energy over a time interval $n_1 \leq n \leq n_2$ in a discrete-time signal $x[n]$ is

$$\sum_{n=n_1}^{n_2} |x[n]|^2$$

Total energy over an infinite interval in a CT signal:

$$E_{\infty} \triangleq \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt = \int_{-\infty}^{+\infty} |x(t)|^2 dt. \quad (18)$$

Total energy over an infinite interval in a DT signal:

$$E_{\infty} \triangleq \lim_{N \rightarrow \infty} \sum_{n=-N}^{+N} |x[n]|^2 = \sum_{n=-\infty}^{+\infty} |x[n]|^2. \quad (19)$$

Note that this integral and may not converge for some signals. Such signals have infinite energy, while signals with $E_\infty < \infty$ have finite energy.

Time-averaged power over an infinite interval in a CT signal:

$$P_{\infty} \triangleq \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt. \quad (20)$$

Total energy in a DT signal:

$$P_{\infty} \triangleq \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{+N} |x[n]|^2. \quad (21)$$

With these definitions, we can identify three important classes of signals:

- ① Energy signals: Signals with finite total energy $E_{\infty} < \infty$. These have zero average power.
- ② Power signals: Signals with finite average power $0 < P_{\infty} < \infty$. As $P_{\infty} > 0$, $E_{\infty} = \infty$.
- ③ Signals with neither E_{∞} nor P_{∞} are finite.