

# DATA.ML.300 Computer Vision

## Exercise Round 5

For these exercises you will need Python or Matlab and a webcam. The second exercise can only be done with Python. Return your answers as a pdf along with your modified code to Moodle. Exercise points will be granted after a teaching assistant has checked your answers. Returns done before the solution session will result in maximum of 4 points, whereas returns after the session will result in maximum of 1 point. For pen & paper task(s), the submitted pdf should include a screenshot of hand written task, or text converted from Word or Latex format. For programming tasks, don't submit code as a screenshot, but rather as modified code files.

**If you are using Python, make sure you have *OpenCV* library for Python installed.**

```
pip install --user --upgrade opencv-python
```

**If you are using Matlab, make sure you have *Support Package for USB Webcams* installed. This can be done through the add-on explorer.**

**Task 1.** Similarity transformation from two point correspondences. (pen & paper) (1 point)

A similarity transformation consists of rotation, scaling and translation and is defined in two dimensions as follows:

$$\mathbf{x}' = s\mathbf{R}\mathbf{x} + \mathbf{t} \quad \Leftrightarrow \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = s \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \end{pmatrix} \quad (1)$$

Describe a method for solving the parameters  $s, \theta, t_x, t_y$  of a similarity transformation from two point correspondences  $\{\mathbf{x}_1 \rightarrow \mathbf{x}'_1\}, \{\mathbf{x}_2 \rightarrow \mathbf{x}'_2\}$  using the following stages. Remember to include the equations used and all provings, the end results are not enough.

- Compute the correspondence between vectors  $\mathbf{v}' = \mathbf{x}'_2 - \mathbf{x}'_1$  and  $\mathbf{v} = \mathbf{x}_2 - \mathbf{x}_1$  using the similarity transform above. Use corresponding unit vectors to solve the scale factor  $s$  from this correspondence. *Hint: There should be no scaling in a transformation between two unit vectors*
- Solve also the rotation angle  $\theta$  from this correspondence.

- c) After solving  $s$  and  $\theta$  compute  $\mathbf{t}$  using equation (1) and either one of the two point correspondences.
- d) Use the procedure to compute the transformation from the following point correspondences:  $\{(\frac{1}{2}, 0) \rightarrow (0, 0)\}, \{(0, \frac{1}{2}) \rightarrow (-1, -1)\}$ .  
(Hint: Drawing the point correspondences on a grid paper may help you to check your answer.)

**Task 2.** Homography using SIFT (Programming exercise) (1 point)

This exercise can only be done in Python. Look up the code in **homography.py** and complete the missing parts. Include the code and its outputs in your submission. Feel free to try your own images albeit not required.

**Task 3.** Real-time face point tracking (Programming exercise) (2 points)

We'll be using KLT-tracker to track points detected from a face. Open **face\_tracking** and follow the instructions written in the comments. Answer the following questions in your pdf. **You do not have to include an output image.**

- a) How does this program work, i.e. what are its main parts? List 4 separate steps in the tracking process.
- b) Do you notice any problems with the tracking? How do you think these could be avoided?