Decision Rule Approach with Transformation Technique

Zhan Lin linzhan@mail.ustc.edu.cn

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Original Problems

$$\max_{\mathbf{x_{t}}} \quad \mathbb{E}_{\xi} \left(\sum_{t=1}^{T} \mathbf{v}^{T} \mathbf{x_{t}} \left(\xi^{t-1}, \xi_{t} \right) \right)$$

$$s.t. \quad \sum_{t=1}^{T} A \mathbf{x_{t}} \left(\xi^{t-1}, \xi_{t} \right) \leq \mathbf{c}$$

$$\mathbf{x_{t}} (\xi^{t-1}, \xi_{t}) \geq 0$$

$$\forall \xi \in \Xi, t = 1, \dots, T$$

$$(1)$$

- Capacity levels $\mathbf{c} = (c_1, \dots, c_m)^T$.
- ▶ Corresponding prices $\mathbf{v} = (v_1, \dots, v_n)^T$.
- ▶ Each products needs at most one unit of each resource. Let $A = (a_{ij})$ be the resource coefficient matrix.
- ξ_t is demands on period t and ξ^{t-1} is information of demands before period t.

Transformation

$$\max_{\mathcal{X}_{\mathbf{t}}} \quad \mathbb{E}_{\xi} \left(\sum_{t=1}^{T} \mathbf{v}^{T} \mathcal{X}_{\mathbf{t}} \left(\xi^{t-1}, \xi_{t} \right) \right)$$
s.t.
$$\mathcal{X}_{t}(\xi^{t-1}, \xi_{t}) \leq \xi_{t}$$

$$\left\{ \mathcal{X}_{\mathbf{t}}(\xi^{t-1}, \xi_{t}) = (\mathcal{X}_{t,1}(\xi^{t-1}, \xi_{t,1}), \mathcal{X}_{t,2}(\xi^{t-1}, \xi_{t,2}) \dots \right.$$

$$\left. \mathcal{X}_{t,j}(\xi^{t-1}, \xi_{t,j}) \right)^{T} \right\} \in \mathcal{F}$$

$$\forall \xi \in \Xi, t = 1, \dots, T$$
where
$$\mathcal{F} = \left\{ \left\{ f(\xi^{t-1}, \xi_{t}) \right\} : f(\xi^{t-1}, \xi_{t}) = \mathbf{u}_{t}(\xi^{t-1}) \wedge \xi_{t}, \mathbf{u}_{\mathbf{t}}(\xi^{t-1}) \in \mathbb{R}^{+}, \sum_{t=1}^{T} A\mathbf{u}_{\mathbf{t}}(\xi^{t-1}) \leq \mathbf{c} \right\}.$$

$$(2)$$

Functional Optimization

- ▶ How to optimize object with $\{\mathcal{X}_t(\xi^{t-1}, \xi_t)\} \in \mathcal{F}$?
- ▶ How to implement polices when we have no knowledge of ξ_t ?
- ► As lower time complexity as possible with acceptable numerical accuracy.

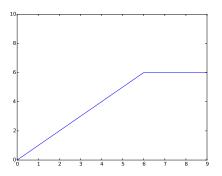
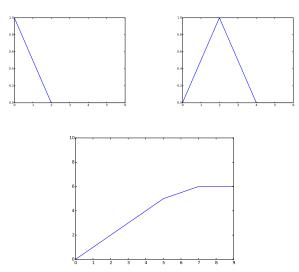


Figure: values of $\mathcal{X}_t(\xi^{t-1}, \xi_t)$ when ξ_t varies and keep ξ^{t-1}

Generalized Decision Rule Approach

Put decisions as a linear combination of historic information? No! Put it as a linear combination of basis functions!



Approach

Forget about historic information temporarily and use linear programming,

$$\max_{\mathcal{X}_{t}} \quad \mathbb{E}_{\xi} \left(\sum_{t=1}^{T} \sum_{j=1}^{J} v_{j} X_{t,j} L(\xi) \right)$$

$$s.t. \quad 0 \leq X_{t,j} L(\xi) \leq \xi_{t,j}$$

$$\sum_{t=1}^{T} \sum_{j=1}^{J} A X_{t,j} L(\xi) \leq 2\mathbf{c} - \mathbb{E} \left(\sum_{t=1}^{T} \sum_{j=1}^{J} A X_{t,j} L(\xi) \right)$$

$$\forall \xi \in \Xi, t = 1, \dots, T$$

$$(3)$$

where $L(\xi)$ lift ξ to values of basis functions,and $X_{t,j}$ is actually coefficient matrixes.

Details in above equation

- It's not hard to prove that shapes of $X_{t,j}L(\xi)$ will be something like we required. So we can get booking limits from maximum of $X_{t,j}L(\xi)$ and then implement polices.
- ▶ $\mathbf{c} \mathbb{E}(\sum_{t=1}^{T} \sum_{j=1}^{J} AX_{t,j} L(\xi))$ is added to ensure that we can make use of resources as much as possible. In fact, $\sum_{t=1}^{T} \sum_{j=1}^{J} AX_{t,j} L(\xi) \approx 2\mathbf{c} \mathbb{E}(\sum_{t=1}^{T} \sum_{j=1}^{J} AX_{t,j} L(\xi)).$ So expectations of used resources will be \mathbf{c} .

Now we turn to problems of making use of historic information.

Historic information

A usual way is using linear combinations of historic information,that is, $X(\xi^{t-1},\xi_t)=X_1(\xi_t)+X_2(\xi^{t-1})$. However,it couldn't give a good results,as we have constraints $X(\xi^{t-1},\xi_t)\leq \xi_t$ and $X_1(\xi_t)\leq \xi_t$. It suggests that we cannot use linear way to approach the multivariate function.

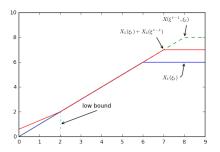


Figure: Cases of low bound of $\xi_t \geq 0$, we can see the limitation of the method

Historic information

- ▶ Remember that we didn't give $L(\cdot)$ a specific form.
- Now we are going to set elements of $L(\cdot)$ be functions of two variables and deal with problems in 2-dimension seems like in 1-dimension.
- ► Simple triangulations are required to approach with piecewise linear functions in 2-dimension.

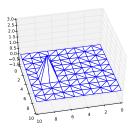


Figure: a basis function in 2-dimension

Solving Nonlinear Optimization in 2-d with Linear Programming

► What we are actually doing is solving a nonlinear optimization in 2-dimension with linear programming!

Computational Results

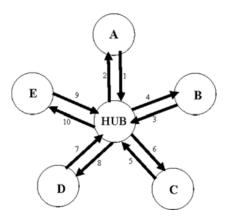


Figure: Network in Re-solving stochastic programming models for airline revenue management

Computational Results

- ▶ Number of variables is only $O(T \times J)$.
- Decision rule approach can give a fractional estimation of booking limits. After rounding, we can use Zhang's method to give a better solution in need of a higher accuracy.

Future Work

- As we can see, we can generalize original problems into higher dimension. In the meantime, we have to face curse of dimensionality.
- Not only $X(\sum_{\tau=1}^{t-1} \xi_{\tau}, \xi_{t})$ but also $X(\max_{\tau=1,\dots,t-1} \xi_{\tau}, \xi_{t})$ is available. It hints us that the methodology is suitable to approximate dynamic programs in other scenrios.