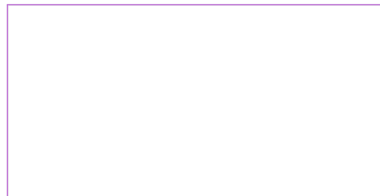


## Power



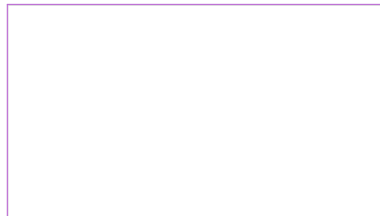
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## Sensors

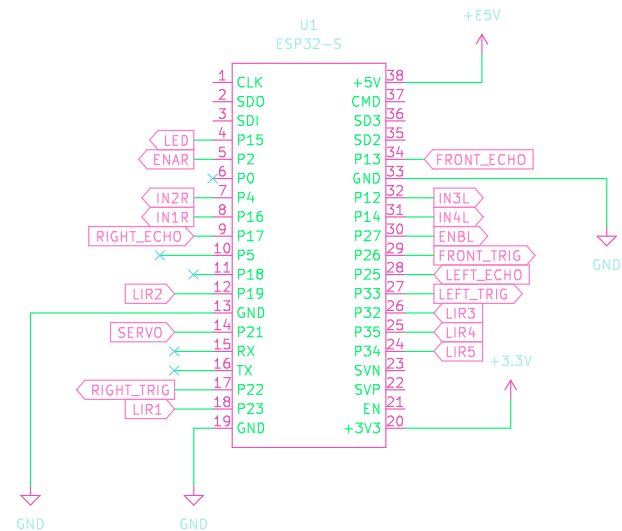
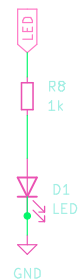


File: sensors.kicad\_sch

## Actuators



File: actuators.kicad\_sch



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File: DOJO\_PCB.kicad\_sch

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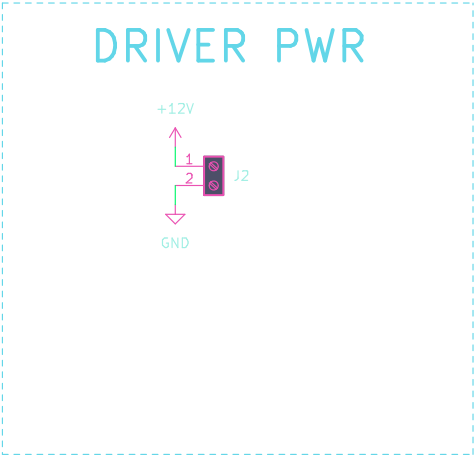
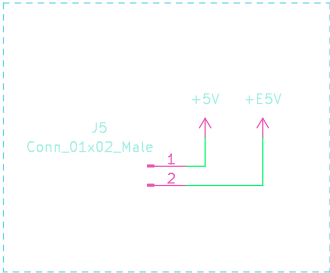
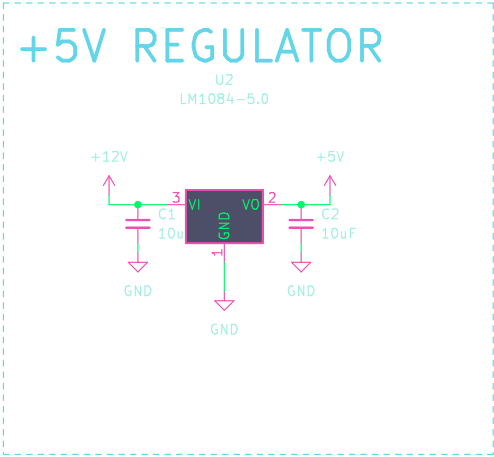
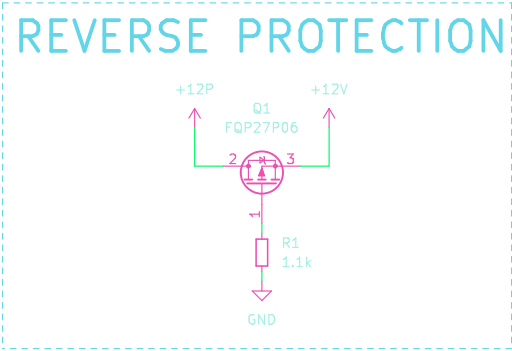
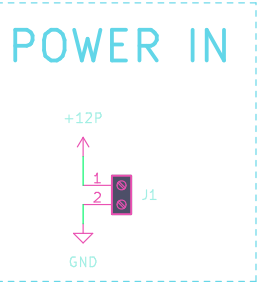
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KiCad E.D.A. kicad 6.0.7-f9a2dced07-116-ubuntu20.04.1

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Id: 1/4



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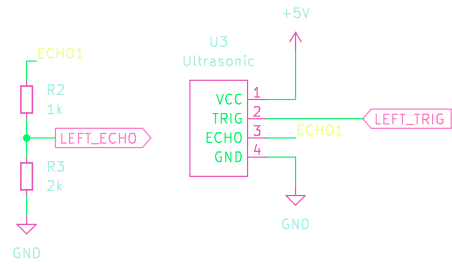
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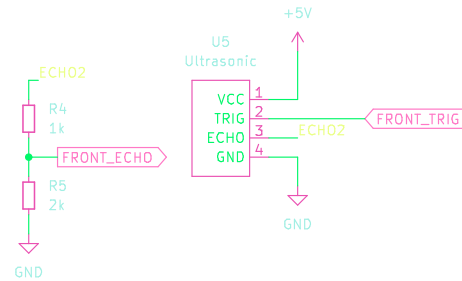
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Rev: 1  
Id: 2/4

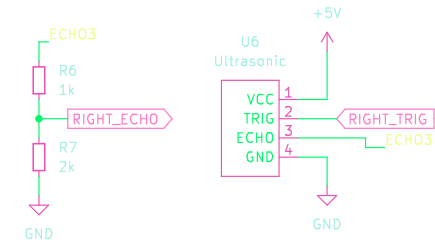
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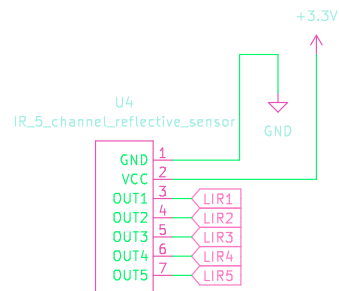
## ULTRASONIC 2



## ULTRASONIC 3



## IR\_SENSOR



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Sheet: /Sensors/

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**Title: DOJO\_ROBOT**

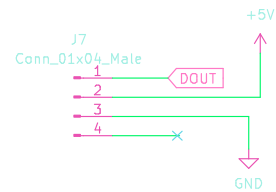
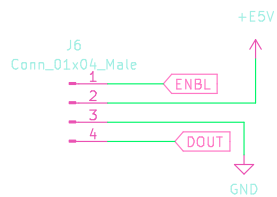
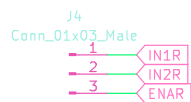
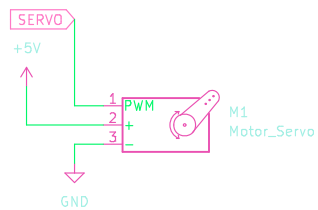
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**Rev: 1**

Id: 3/4



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Sheet: /Actuators/  
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**Rev: 1**  
Id: 4/4