

## Lab 5

Register maps:

### 10.2.3 SYSCFG external interrupt configuration register 1 (SYSCFG\_EXTICR1)

Address offset: 0x08

Reset value: 0x0000 0000

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Res	Res	Res	Res	Res	Res	Res	Res	Res	Res	Res	Res	Res	Res	Res	Res
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Res	EXTI3[2:0]			Res	EXTI2[2:0]			Res	EXTI1[2:0]			Res	EXTI0[2:0]		
	rw	rw	rw		rw	rw	rw		rw	rw	rw		rw	rw	rw

Bits 31:15 Reserved, must be kept at reset value.

Bits 14:12 **EXTI3[2:0]**: EXTI 3 configuration bits

These bits are written by software to select the source input for the EXTI3 external interrupt.

000: PA[3] pin

001: PB[3] pin

010: PC[3] pin

011: PD[3] pin

100: PE[3] pin

101: PF[3] pin

110: PG[3] pin

111: Reserved

Bit 11 Reserved, must be kept at reset value.

### Problem 1:

#### Main:

```

INCLUDE core_cm4_constants.s           ; Load Constant Definitions
INCLUDE stm32l476xx_constants.s
INCLUDE jstick.h
INCLUDE leds.h

```

```

AREA main, CODE, READONLY
EXPORT __main
ENTRY

```

```

__mainPROC
    ldr    r0,=RCC_AHB2ENR_GPIOBEN
    bl     portclock_en
    ldr    r0,=RCC_AHB2ENR_GPIOEEN
    bl     portclock_en

```

```

        ldr        r0,=GPIOB_BASE
        ldr        r1,=GPIO_MODER_MODER2_0
        bl        port_bit_pushpull
        ldr        r0,=GPIOE_BASE
        ldr        r1,=GPIO_MODER_MODER8_0
        bl        port_bit_pushpull

        bl        porta_init
        bl        exti3_init
        bl        exti0_init

endlessb        endless
        ENDP

```

#### EXTI3\_IRQHandler PROC

```

        EXPORT     EXTI3_IRQHandler
        push    {lr}
        bl      red_tog
        pop     {lr}
        ldr     r2,=(EXTI_BASE+EXTI_PR1)
        mov     r1,#EXTI_PR1_PIF3
        str     r1,[r2]
        dsb
        bx      lr
        ENDP

```

#### EXTI0\_IRQHandler PROC

```

        EXPORT     EXTI0_IRQHandler
        push    {lr}
        bl      green_tog
        pop     {lr}
        ldr     r2,=(EXTI_BASE+EXTI_PR1)
        mov     r1,#EXTI_PR1_PIF0
        str     r1,[r2]
        dsb
        bx      lr
        ENDP

```

```
ALIGN
AREA myData, DATA, READWRITE

ALIGN
```

```
END
```

### **Jstick.s**

```
exti0_init PROC
EXPORT      exti0_init
ldr         r2,=(RCC_BASE+RCC_APB2ENR)
ldr         r1,[r2]
orr         r1,#RCC_APB2ENR_SYSCFGEN
str         r1,[r2]
ldr         r2,=(SYSCFG_BASE+SYSCFG_EXTICR0)
ldr         r1,[r2]
bic         r1,#0x00000007
str         r1,[r2]
ldr         r2,=(EXTI_BASE+EXTI_RTSTR1)
ldr         r1,[r2]
orr         r1,#EXTI_RTSTR1_RT0
str         r1,[r2]
ldr         r2,=(EXTI_BASE+EXTI_FTSR1)
ldr         r1,[r2]
bic         r1,#EXTI_FTSR1_FT0
str         r1,[r2]
ldr         r2,=(EXTI_BASE+EXTI_IMR1)
```

```

ldr        r1,[r2]
orr        r1,#EXTI_IMR1_IM0
str        r1,[r2]
ldr        r2,=(NVIC_BASE+NVIC_ISER0)
ldr        r1,=(1<<6)
str        r1,[r2]
bx         lr
ENDP

```

```

ALIGN
END

```

### Jstick.h

```

IMPORT porta_init
IMPORT read_jstick
IMPORT exti3_init
IMPORT exti0_init

END

```

### Problem 2:

#### Main:

```

INCLUDE core_cm4_constants.s
INCLUDE stm32l476xx_constants.s
INCLUDE jstick.h
INCLUDE leds.h

```

```

AREA main, CODE, READONLY
EXPORT __main
ENTRY

```

#### \_\_mainPROC

```

ldr        r0,=RCC_AHB2ENR_GPIOBEN
bl         portclock_en
ldr        r0,=RCC_AHB2ENR_GPIOEEN
bl         portclock_en

ldr        r0,=GPIOB_BASE
ldr        r1,=GPIO_MODER_MODER2_0
bl         port_bit_pushpull

```

```

        ldr        r0,=GPIOE_BASE
        ldr        r1,=GPIO_MODER_MODER8_0
        bl         port_bit_pushpull

        bl         porta_init
        bl         exti3_init
        bl         exti5_init

endlessb        endless
        ENDP

```

#### EXTI3\_IRQHandler PROC

```

        EXPORT     EXTI3_IRQHandler
        push    {lr}
        bl         red_tog
        pop     {lr}
        ldr        r2,=(EXTI_BASE+EXTI_PR1)
        mov        r1,#EXTI_PR1_PIF3
        str        r1,[r2]
        dsb
        bx         lr
        ENDP

```

#### EXTI9\_5\_IRQHandler PROC

```

        EXPORT     EXTI9_5_IRQHandler
        ldr        r3,=(EXTI_BASE+EXTI_PR1)
        ldr        r4,[r3]
        tst        r4,#EXTI_PR1_PIF5
        beq        return
        push    {lr}
        bl         green_tog
        pop     {lr}
        ldr        r2,=(EXTI_BASE+EXTI_PR1)
        mov        r1,#EXTI_PR1_PIF5
        str        r1,[r2]
        dsb
return bx         lr
        ENDP

```

ALIGN

```

        AREA    myData, DATA, READWRITE

        ALIGN

END

```

### **Jstick.s:**

```

exti5_init    PROC
EXPORT      exti5_init
ldr          r2,=(RCC_BASE+RCC_APB2ENR)
ldr          r1,[r2]
orr          r1,#RCC_APB2ENR_SYSCFGEN
str          r1,[r2]
ldr          r2,=(SYSCFG_BASE+SYSCFG_EXTICR0)
ldr          r1,[r2]
bic          r1,#0x00000070
str          r1,[r2]
ldr          r2,=(EXTI_BASE+EXTI_RTSTR1)
ldr          r1,[r2]
orr          r1,#EXTI_RTSTR1_RT5
str          r1,[r2]
ldr          r2,=(EXTI_BASE+EXTI_FTSR1)
ldr          r1,[r2]
bic          r1,#EXTI_FTSR1_FT5
str          r1,[r2]
ldr          r2,=(EXTI_BASE+EXTI_IMR1)

```

```

ldr        r1,[r2]
orr        r1,#EXTI_IMR1_IM5
str        r1,[r2]
ldr        r2,=(NVIC_BASE+NVIC_ISER0)
ldr        r1,=(1<<23)
str        r1,[r2]
bx         lr
ENDP

```

### Jstick.h:

```

IMPORT porta_init
IMPORT read_jstick
IMPORT exti3_init
IMPORT exti5_init

END

```

### Problem 3:

```

tim2_init  PROC      ;initialize Timer 2 for this program and setup its interrupt
EXPORT     tim2_init
ldr        r2,=(RCC_BASE+RCC_APB1ENR1)          ;enable timer 2

clock

ldr        r1,[r2]
orr        r1,#RCC_APB1ENR1_TIM2EN
str        r1,[r2]

ldr        r2,=(TIM2_BASE+TIM_PSC)              ;Setup the prescaler.
Assuming a 4MHz clock, this gives 1ms timer ticks
ldr        r1,=39
str        r1,[r2]

ldr        r2,=(TIM2_BASE+TIM_ARR)              ;Setup the reload.
Assuming a 1ms tick, this gives 1s overflows
ldr        r1,=49
str        r1,[r2]

```

```

        ldr        r2,=(TIM2_BASE+TIM_CR1)           ;enable the counter in
control register 1
        ldr        r1,[r2]
        orr        r1,#TIM_CR1_CEN
        str        r1,[r2]

        ldr        r2,=(TIM2_BASE+TIM_DIER)           ;enable the timer
update interrupt
        ldr        r1,[r2]
        orr        r1,#TIM_DIER_UIE
        str        r1,[r2]

        ldr        r2,=(NVIC_BASE+NVIC_ISER0)        ;enable the TIM2 interrupt in
NVIC_ISER0
        ldr        r1,=(1<<28)
        str        r1,[r2]
        bx        lr

        ENDP
        ALIGN

        END

```



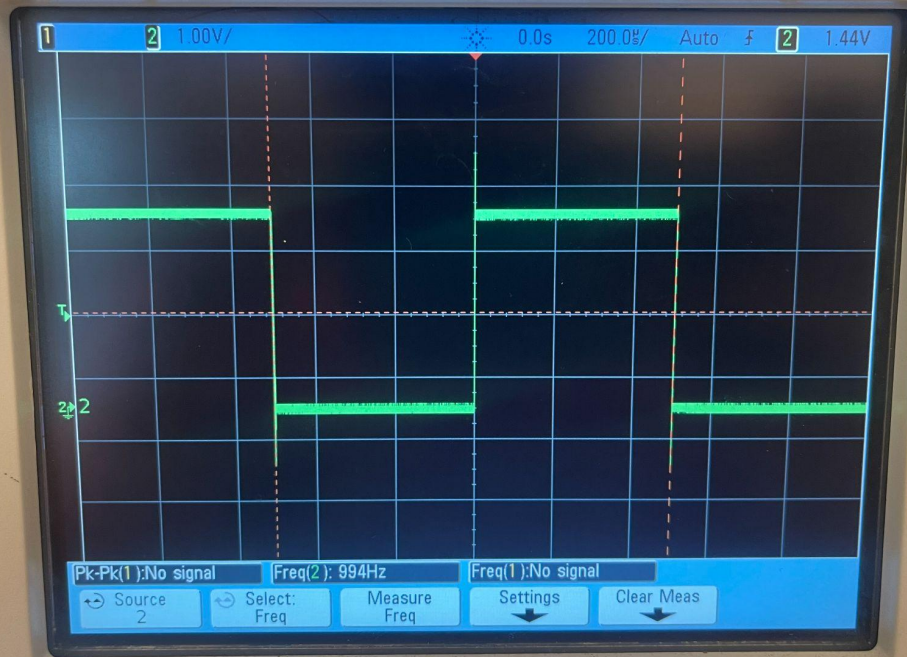


Agilent Technologies

MSO6012A  
Mixed Signal Oscilloscope

MEGA Zoom

100 MHz  
2 GSa/s



Digital

Select

D15  
Thru  
D0

Position