Introduction to Clustering

Philip D. Waggoner

MACS 40800: Unsupervised Machine Learning

October 15, 2019

Lecture Outline

- Clustering Basics
- 2 Diagnosing Clusterability
- 3 Conceptualizing and Calculating Distance
- 4 Clustering Applications
- 5 Problem Set 2

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 - Classification: the group labels are known for a trained sample (we won't get into this iteration given the scope of the class)
- Thus, the typical goal in clustering is to discover the "natural groupings" present in the data

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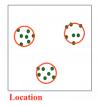
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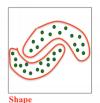
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 - Soft (model-based) partitioning, can be probabilistic or fractional (focus on the EM algorithm and Gaussian mixture models, with a few cousins)

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 - Mathematically (sparse sampling)

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- This is a limitation of UML acorss the board; yet simultaneously the reason it is so important to combine UML with other data reduction and modeling processes

Diagnosing Clusterability: Informally

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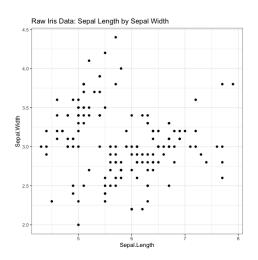
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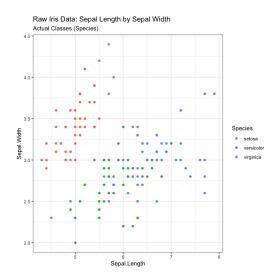
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 - ▶ 150 observations (50 of each)

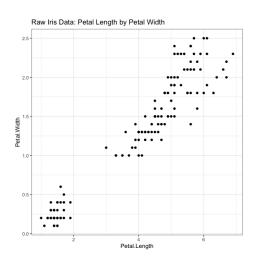
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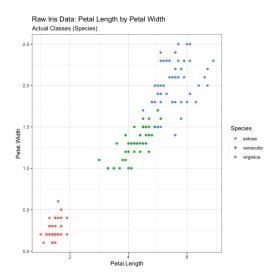
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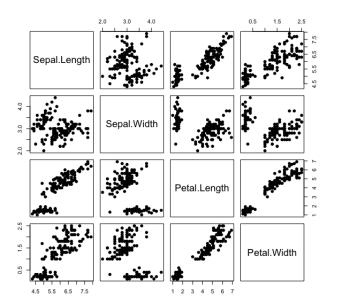
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Diagnosing Clusterability: Informally (All Features)



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- The visual result becomes darker blocks along the diagonal reflect greater spatial similarity, compared to lighter shaded blocks, which inversely suggest greater dissimilarity

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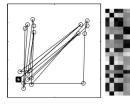






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VAT (ODI): Iris Data

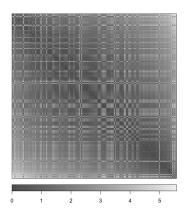


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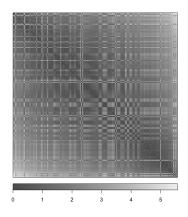


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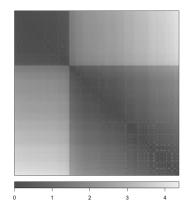


Figure: ODI: Petal

A Quick Comparison

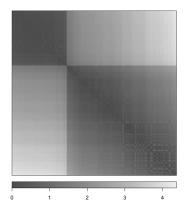


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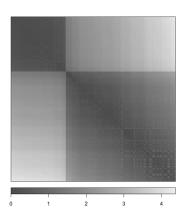


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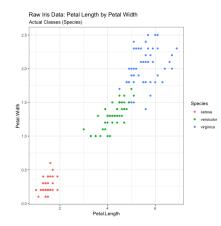


Figure: Raw Data: Petal

In R

Jump to ${\tt R}$ for a quick demo

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- This general procedure is called **sparse sampling**, of which *H* is one iteration

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 some random distribution (usually uniform) with the same standard
 deviation as the original data
- In other words, we are creating a random, synthetic version of the original data set (the sampling "window"), and we are comparing to see whether these produce similar distributions (i.e., is the actual data random, compared to the synthetic data set, which we know is random?)

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ullet In general, H>0.5 leads to rejection of H_0 , suggesting the data are non-random, and are "clusterable"

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- By contrast, *features* are usually grouped on the basis of correlations (but also for observations)

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- The result is effectly "unit-less" inputs

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 - \rightarrow $d(p,q) \leq d(p,g) + d(g,q)$

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Canberra Distance (weighted version of Manhattan):

$$d_{canberra}(p,q) = \sum_{i=1}^{n} \frac{|p_i - q_i|}{|p_i| + |q_i|}$$

Spatial Measures

$$d_m(p,q) = \left(\sum_{i=1}^n |p_i - q_i|^m\right)^{\frac{1}{m}} \tag{3}$$

where, setting $m \ge 1$ defines some true distance

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- The problem: need a distance measure to transform both types of data, without information loss or meaningless values

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(4)

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 Gower's measure essentially captures the weighted average of the distances on the different features

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 And numeric features are scaled by dividing the absolute difference by the range of the feature,

$$s_{pqk} = \frac{|p_k - q_k|}{\max(k) - \min(k)} \tag{6}$$

Lecture Outline

- Clustering Basics
- Diagnosing Clusterability
- 3 Conceptualizing and Calculating Distance
- 4 Clustering Applications
- 5 Problem Set 2

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 - And a lot more...

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Problem Set #2: Clustering (part 1)

• Due Saturday, 10/19, by 12 noon