

robo\_init

pid\_init

steering::set\_PID\_constants

```
graph LR; A[robo_init] --> B[pid_init]; B --> C[steering::set_PID_constants];
```

The diagram illustrates a three-step initialization process. It begins with a box labeled 'robo\_init', which points via a dark blue arrow to a box labeled 'pid\_init'. This second box then points via another dark blue arrow to a final box labeled 'steering::set\_PID\_constants'. The final box is shaded gray, indicating it is the last step in the sequence.