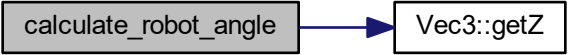


calculate_robot_angle



```
graph LR; A[calculate_robot_angle] --> B[Vec3::getZ]
```

A diagram showing a horizontal flow from left to right. On the left is a gray rectangular box with a black border containing the text 'calculate_robot_angle'. A dark blue arrow points from the right side of this box to the left side of a white rectangular box with a black border on the right. This second box contains the text 'Vec3::getZ'.

Vec3::getZ