motor_config

+ max_omega
+ tolerance
+ in1_port
+ in1_pin
+ in2_port
+ in2_pin
+ htim
+ channel

-motor_

motor

+ motor()
+ motor()
+ motor()
+ motor()
+ operator=()
+ operator=()
+ ~motor()
+ set_config()
+ get_max_omega()
+ set_direction()
+ set_omega()