Benchmark glider model with JuMP and OptimalControl

Model	Discretization	Iterations	Total Time	Ipopt Time	Objective Value	Flag
JuMP	100	223	3.17928	3.172	1254.61	LOCALLY_SOLVED
JuMP	500	734	17.2466	17.195	1247.98	LOCALLY_SOLVED
OptimalControl	100	126	1.44618	0.657	1254.78	Solve_Succeeded
OptimalControl	500	322	663.723	659.039	1247.98	Solve_Succeeded