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max iter = 1000, tol = 1.0e-8, constr viol tol = 1.0e-6, solver = ma57
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Model	Discretization	Variables	Constraints	Iterations	Total Time	Ipopt Time	Objective Value	Flag
cart_pendulum	100	507	405	230	1.83	1.8	1.74437	Solve Succeeded
cart_pendulum	500	2507	2005	477	17.39	17.37	1.74397	Solve Succeeded
robot	100	910	612	75	1.13	1.1	9.14269	Solve Succeeded
robot	500	4510	3012	656	43.11	43.09	9.14099	Solve Succeeded
insurance	100	910	809	65	1.12	1.1	-2.05778	Solve Succeeded
insurance	500	4510	4009	85	4.53	4.5	-2.05921	Solve Succeeded
robbins	100	505	407	19	0.26	0.24	20.2042	Solve Succeeded
robbins	500	2505	2007	34	0.84	0.81	19.4666	Solve Succeeded
electrical_vehicle	100	404	305	16	0.45	0.43	1.22905e6	Solve Succeeded
electrical_vehicle	500	2004	1505	1000	21.05	21.03	1.09722e5	Iterations Exceeded
double_oscillator	100	606	503	5	0.16	0.15	0.000908244	Solve Succeeded
double_oscillator	500	3006	2503	5	0.25	0.22	0.000910921	Solve Succeeded
ducted_fan	100	910	713	112	1.03	1.01	1832.94	Solve Succeeded
ducted_fan	500	4510	3513	82	161.61	161.59	0.0109369	Infeasible Problem
steering	100	506	408	11	0.08	0.06	0.554595	Solve Succeeded
steering	500	2506	2008	17	0.24	0.22	0.554572	Solve Succeeded
rocket	100	405	304	21	0.12	0.1	-1.01283	Solve Succeeded
rocket	500	2005	1504	77	8.09	8.07	-1.01284	Solve Succeeded
chain	100	404	305	7	0.07	0.05	5.06978	Solve Succeeded
chain	500	2004	1505	14	0.17	0.15	5.06858	Solve Succeeded
beam	100	404	305	24	0.07	0.06	8.8986	Solve Succeeded
beam	500	2004	1505	21	0.19	0.17	8.88928	Solve Succeeded
dielectrophoretic_particle	100	304	203	38	0.12	0.1	-9.97699e-9	Infeasible Problem
dielectrophoretic_particle	500	1504	1003	38	0.48	0.46	-9.99545e-9	Infeasible Problem
jackson	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN
vanderpol	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN
quadrotor	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN
moonlander	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN
glider	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN
truck_trailer	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN
bioreactor	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN
space_shuttle	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN