Benchmark Knitro Results									
Solver	Model	Discretization	Variables	Constraints	Iterations	Total Time	KNITRO Time	Objective Value	Flag
JuMP	rocket	50	205	154	missing	1.87	0.09	1.01282	Solve Succeeded
OptimalControl	$\operatorname{rocket}$	50	205	154	14	1.68	0.28	-1.01282	UNI ? $0$