Benchmark Knitro Results									
Solver	Model	Discretization	Variables	Constraints	Iterations	Total Time	KNITRO Time	Objective Value	Flag
JuMP	rocket	50	205	154	missing	0.02	0.0	1.01282	Solve Succeeded
OptimalControl	$\operatorname{rocket}$	50	205	154	14	0.08	0.03	-1.01282	Solve Succeeded

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