

# Semester 1 Examinations 2023-2024

Course Instance 4BCT, 4BS, 1EM, 1MBM

Code(s)

**Exam(s)** B.Sc. (CS&IT), B.Sc., Erasmus, Biomedical

Engineering

Module Code(s) CT404, CT336

Module(s) Graphics and Image Processing

Paper No.

External Examiner(s) Dr. R. Trestian Internal Examiner(s) Prof. M. Madden

\* Dr. S. Redfern

#### **Instructions**:

• Answer three questions.

- Of which at least one must be Graphics (Q1, Q2, Q3).
- And at least one must be Image Processing (Q4, Q5).
- Your third question can come from either (Q1, Q2, Q3, Q4, Q5).
- All questions carry equal marks.

**Duration** 2 hours

No. of Pages 7

**Discipline(s)** Computer Science Course Co-ordinator(s) Dr. C. O'Riordan

Requirements:

Graphic material in colour Yes Release in Exam Venue Yes

End of requirements.

# Section A – Graphics

#### Q.1. (Graphics)

- (i) Provide short sections of code illustrating **translation**, **rotation**, and **scaling** in either Canvas2D or Threejs. Note that the final page of this exam paper lists some commonly used functions in Canvas2D and Threejs. [10]
- (ii) Using the code below as a starting point, write Javascript/Canvas2D code for use in the **draw()** function which will draw a line graph from the numbers contained in the **data[]** array. The graph should apply appropriate scales on the x and y axes, bearing in mind that the values in **data[]** may be changed, i.e. you should not hard-code the scales. There is no requirement to label the axes. [10]



#### Q.2. (Graphics)

(i) Using the Javascript/Threejs code provided below (and on the next page) as a starting point, add code in the **draw()** and **animate()** functions as indicated by // T0 D0.

The program should produce an animation similar to that depicted below (3 images, each of which is a frame from the animation), whereby Math.Sin(angle) is used to change the y component of the position of each mesh, with the value of *angle* changing over time.



(ii) Add code so that the camera rotates clockwise/anticlockwise around the world's y axis as long as the left/right arrow keys are held, while continuing to have it look at the world's origin (x=0, y=0, z=0). Hint: the keyCode values for the left/right arrow keys, as received by the onkeydown event in Javascript are 37 and 39. [10]

```
<html>
 <head>
  <script src="three.js"></script>
  <script>
    var scene, camera, renderer;
    var meshes = [];
    var angle = 0;
    function draw() {
      // create renderer attached to HTML Canvas object
      var c = document.getElementById("canvas");
      renderer = new THREE.WebGLRenderer({ canvas: c });
      // create the scenegraph
      scene = new THREE.Scene();
      // create a camera and a light
      camera = new THREE.PerspectiveCamera(75, 1, 0.1, 1000);
      camera position z = 100;
      var light = new THREE.PointLight(0xfffffff);
      light.position.set(10, 0, 25);
      scene.add(light);
      // define a material and geometry shared by each Mesh
      var material = new THREE.MeshLambertMaterial({color: 0xf
ffffff);
      var geometry = new THREE.OctahedronBufferGeometry(2);
```

PTO
[CODE LISTING CONTINUES ON NEXT PAGE]

```
// add a set of Meshes to the scene
      for (var xpos=-60; xpos<=60; xpos+=5) {</pre>
           // TO DO (1 of 2): create a THREE Mesh using the
geometry and material defined above
           // Position this Mesh at x=xpos, y=0, z=0
          // And also add each mesh to the meshes[] array
      }
      animate();
    function animate() {
       setTimeout(animate, 1000/60);
       angle += 0.1;
/* TO DO (2 of 2): change the y component of the position of each object in the meshes[] array,
using Math.Sin(angle) which takes a number (angle) and
      returns a value from -1 to +1 */
        renderer.render(scene, camera);
    }
  </script>
 </head>
 <body onload="draw();">
   <canvas id="canvas" width="600" height="600"></canvas>
 </body>
</html>
```

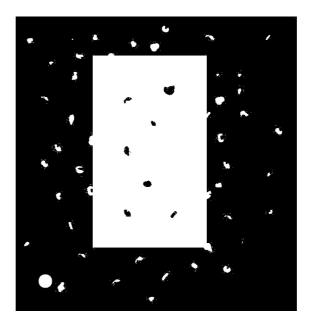
#### Q.3. (Graphics)

- (i) Many of the techniques used in real-time 3D graphics programming attempt to maximise the realism of the rendered scene while processing a minimal number of polygons. With specific reference to the so-called 'polygon budget', and using diagrams where appropriate, discuss each of the following five techniques: [15]
  - a) Frustum Culling
  - b) Bump Mapping
  - c) Back Face Culling
  - d) Billboards
  - e) Levels-of-Detail (LODs)
- (ii) Discuss the Flat Shading, Gourard Shading and Phong Shading algorithms, illustrating each with a diagram. [5]

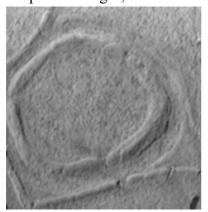
# Section B – Digital Image Processing

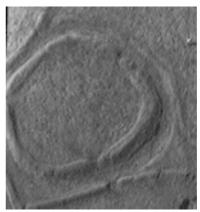
### Q.4. (Image Processing)

- (i) Describe the *mathematical morphology* approach to image processing. Outline some typical circumstances in which this approach is useful. [4]
- (ii) The image below contains a large white rectangle and a number of patches of noise. Outline and defend a morphology-based algorithm for automatic isolation of the rectangle. Use sketches to indicate approximately how the image would appear following each step of your solution. [7]



(iii) Outline, at a high level, a suitable algorithm for extracting 3D information from a stereo pair of images, such as the image pair illustrated below. [9]

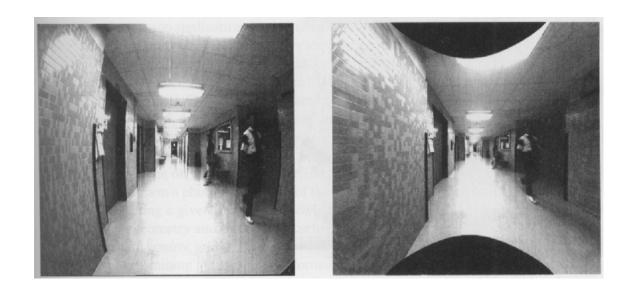




### Q.5. (Image Processing)

- (i) <u>Camera decalibration</u> is a technique for geometric correction of images which is often employed when sources of geometric error are poorly understood. With regard to camera decalibration:
  - Outline the use of reference images such as grids of dots to construct and apply geometric corrections to images captured with a wide-angle lens (e.g. the image below). Use the terms 'control points', 'pixel filling', and 'bilinear interpolation' in your answer.
  - Explain why you would expect a reference image to be constructed with black markings on a white background (or white markings on a black background)

[3]



- (ii) Convolution (also called 'filtering') is one of the most fundamental low-level image processing techniques.
  - Describe, with use of a diagram, the convolution algorithm. [3]
  - Present a convolution kernel suitable for <u>noise reduction</u>. Explain how this kernel produces the desired result, assuming a greyscale image with pixel values in the range 0 to 255.
  - Present a convolution kernel suitable for <u>edge detection</u>. Explain how this kernel produces the desired result, assuming a greyscale image with pixel values in the range 0 to 255.

# Some useful methods/properties of the Canvas 2D Context object:

Method/Property	Arguments/Values	Notes
fillRect	(Left, Top, Width,	Draw a filled rectangle
	Height)	
beginPath	None	Start a stroked path
moveTo	(X, Y)	Move the graphics cursor
lineTo	(X, Y)	Draw a line from graphics
		cursor
stroke	None	End a stroked path
fillStyle	="rgb(R,G,B)"	Set fill colour
strokeStyle	="rgb(R,G,B)"	Set line colour
save	None	Save the current coordinate
		system
restore	None	Restore the last saved coord
		system
translate	(X, Y)	Translate the coordinate
		system
rotate	(angle)	Rotate the coordinate system
		clockwise, with angle in
		radians
scale	(X, Y)	Scale the coordinate system
		independently on the X and Y
		axes

# Some useful objects/methods from the Threejs library:

Object/Method	Notes
<pre>new THREE.WebGLRenderer({canvas:c})</pre>	Constructs a renderer, attached
	to the Canvas object c
<pre>new THREE.PerspectiveCamera(fov,aspect,n</pre>	Constructs a camera, with the
ear, far)	specified field-of-view, aspect
cui , i ui ,	ratio, near clipping distance,
TUDEE Coope ()	far clipping distance
new THREE.Scene();	Constructs a scene
<pre>new THREE.PointLight(0xffffff);</pre>	Constructs a white point light
object.position.set(x,y,z)	Sets an object's x,y,z position
	relative to its parent
object.rotation.set(x,y,z)	Sets an object's x,y,z rotation
	(using Euler angles) relative to its parent
object retateOnAvis/new TUDEE Vector2/0 1	Rotates object by 0.1 radians
<pre>object.rotateOnAxis(new THREE.Vector3(0,1    ,0), 0.1)</pre>	on the y axis
,0), 0.1)	On the y axis
object1.add(object2)	Sets object2 as a child of
	object1
object.parent	Obtains a reference to the
	parent of object
<pre>camera.lookAt(new THREE.Vector3(0,0,0));</pre>	Turns a camera object to face
	the world coordinate 0,0,0
new THREE.BoxGeometry(20, 20, 20)	Constructs Box geometry, with
, , , , , , , , , , , , , , , , ,	specified width, height, depth
<pre>new THREE.MeshLambertMaterial({color: 0xf</pre>	Constructs a Lambert (Phong)
d59d7})	material of the specified
0.5907 } }	colour
<pre>new THREE.Mesh(geometry, material)</pre>	Constructs a mesh using the
	specified geometry and material
renderer.render(scene, camera)	Uses a renderer to draw a scene
	as seen by a camera, onto the
	renderer's Canvas

**END**