



Autumn Examinations 2010

Exam Code(s)	4IF, 4BP, 3BA, 1SD
Exam(s)	4th Year B.Sc. (Information Technology) 4th Year B.E. (Electronic & Computer Engineering) 3rd Year B.A. (Information Technology) Higher Diploma in Applied Science (Software Design & Development)
Module Code(s)	CT404, CT336
Module(s)	GRAPHICS AND IMAGE PROCESSING
Paper No.	I
Repeat Paper	Yes
External Examiner(s)	Prof. M. O'Boyle
Internal Examiner(s)	Prof. G. Lyons Dr. J. Duggan * Dr. S. Redfern

Instructions: Answer any three questions.
All questions carry equal marks.

<i>Duration</i>	2 hours
No. of Pages	5
Department(s)	Information Technology
Course Co-ordinator(s)	

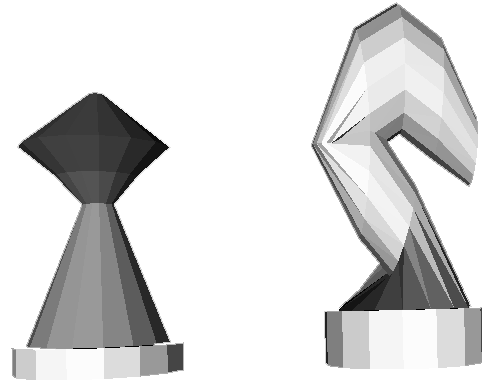
Requirements:

MCQ	Release to Library: Yes <input type="checkbox"/>	No <input type="checkbox"/>
Handout		
Statistical/ Log Tables		
Cambridge Tables		
Graph Paper	Required	
Log Graph Paper		
Other Materials		

Q.1.

- (i) Describe the use of extrusion in VRML, referring to each of the seven fields used by the Extrusion node. Note that extrusion and other useful nodes from the VRML language are summarised on the final page of this exam paper. **(5 marks)**

- (ii) The two models of chess-pieces pictured on the right were created by extruding circular cross sections. Write Virtual Reality Modelling Language (VRML) code to create objects similar to these. Note that the most useful VRML nodes are summarised on the final page of this exam paper. **(15 Marks).**



Q.2.

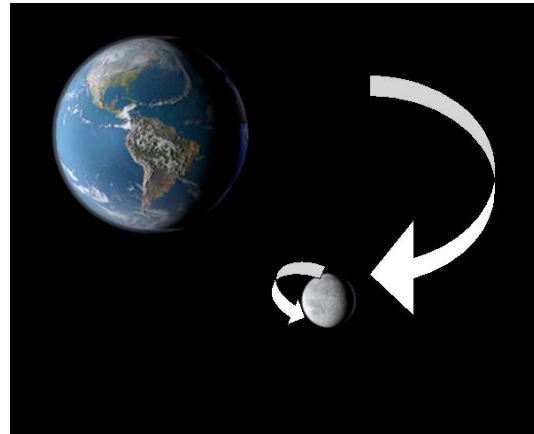
- (i) *“GLUT is an additional library that is often used in conjunction with OpenGL in order to provide platform-independent development of graphics applications for windowed operating systems.”*
Discuss this statement. **(8 marks).**
- (ii) Why are nested co-ordinate systems useful for 3D graphics/animation programming? In your answer, explain and provide code samples illustrating the use of nested co-ordinate systems in both OpenGL and VRML. **(8 marks).**
- (iii) What are back buffers used for in computer animation? In your answer, explain how to use back buffers in OpenGL. **(4 marks).**

Q.3.

- (i) Many of the techniques used in real-time 3D graphics programming attempt to maximise the realism of the rendered scene while processing a minimal number of polygons. With specific reference to this ‘polygon budget’, and using diagrams where appropriate, discuss each of the following five techniques **(5 x 3 = 15 marks)**.
- a) Sky Boxes (also called World Boxes)
 - b) Texture Mapping
 - c) Binary Space Partitioning
 - d) Fog
 - e) Levels-of-Detail (LODs)
- (ii) Discuss the Lambert, Gourard and Phong Shading algorithms, illustrating your answer with diagrams **(5 marks)**.
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Q.4.

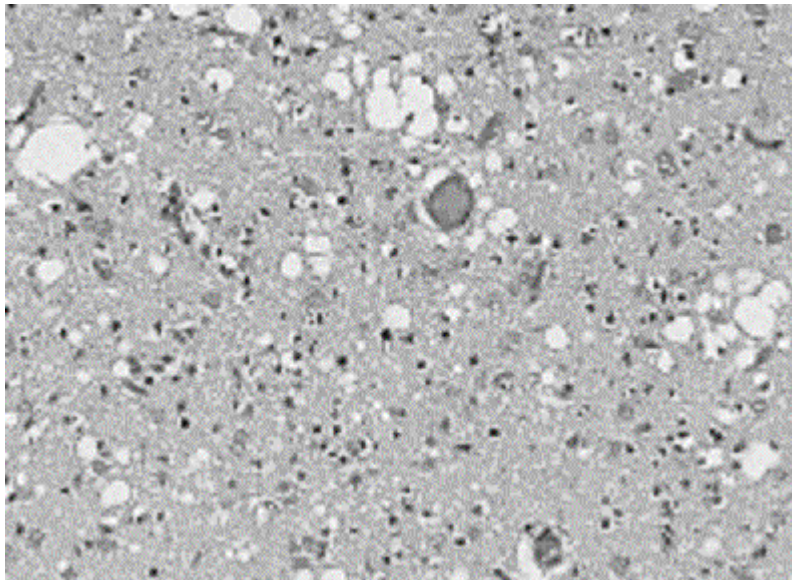
- (i) Write VRML code to produce an animation of a moon moving around a static earth. You should assume that two jpeg files “earth.jpg” and “moon.jpg” have been provided for you to texture map onto two spheres. The moon should rotate on its own axis as well as around the earth. Note that the most useful VRML nodes are summarised on the final page of this exam paper. **(8 marks)**.



- (ii) Explain the *keyframe* approach to animation in computer graphics, and explain its use in VRML, referring to the *TimeSensor*, *Transform*, *OrientationInterpolator* and *PositionInterpolator* nodes in your answer. **(6 marks)**
- (iii) A more powerful approach to producing animations in VRML is to use *JavaScript* nodes to dynamically calculate positions or orientations. Write VRML code for a *JavaScript* node which produces a bouncing motion (for an object representing a ball), and which is suitable for use with a *TimeSensor* and a *Transform* node **(6 marks)**.

Q.5.

- (i) Many automatic image analysis algorithms begin by smoothing an image, and then applying an edge extraction filter in order to ascertain the evidence for the edges of objects in the image. Discuss the use of smoothing and edge detection for these purposes. **(6 marks)**
- (ii) Describe the *mathematical morphology* approach to image processing. Outline some typical circumstances in which this approach is useful **(6 marks)**.
- (iii) The image below is taken from tissue sample of a human brain affected by neurological damage. Of interest are white areas that are at least 5 pixels in diameter. Outline and discuss an algorithm for automatic isolation of areas matching this specification. **(8 marks)**.



Some useful VRML node information:

```
Shape
{
    geometry
    appearance
}
```

```
Transform
{
    children [ ]
    translation 0.0 0.0 0.0
    rotation 0.0 0.0 1.0 0.0
    scale 1.0 1.0 1.0
    center 0.0 0.0 0.0
}
```

```
TimeSensor
{
    enabled TRUE
    startTime 0.0
    stopTime 0.0
    cycleInterval 1.0
    loop FALSE
    isActive # eventOut
    time # eventOut
    cycleTime # eventOut
    fraction_changed # eventOut
}
```

```
PositionInterpolator
{
    key [ ]
    keyValue [ ]
    set_fraction # eventIn
    value_changed # eventOut
}
```

```
OrientationInterpolator
{
    key [ ]
    keyValue [ ]
    set_fraction # eventIn
    value_changed # eventOut
}
```

```
Extrusion
{
    crossSection [ ]
    spine [ ]
    scale [ ]
    orientation [ ]
    beginCap
    endCap
    creaseAngle
}
```

```
Box
{
    size 2.0 2.0 2.0
}
```

```
Sphere
{
    radius 1.0
}
```

```
Cylinder
{
    radius 1.0
    height 2.0
    side TRUE
    top TRUE
    bottom TRUE
}
```

```
Appearance
{
    material
}
```

```
Material
{
    diffuseColor
    specularColor
    ambientIntensity
    emissiveColor
    transparency
    shininess
    texture
}
```

```
ImageTexture
{
    url
}
```

Co-ordinates for a circle-shaped cross section, suitable for extrusion:

```
1.00 0.00, 0.92 -0.38,
0.71 -0.71, 0.38 -0.92,
0.00 -1.00, -0.38 -0.92,
-0.71 -0.71, -0.92 -0.38,
-1.00 0.00, -0.92 0.38,
-0.71 0.71, -0.38 0.92,
0.00 1.00, 0.38 0.92,
0.71 0.71, 0.92 0.38,
1.00 0
```