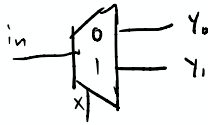


D-MULTIPLEXER

1:2



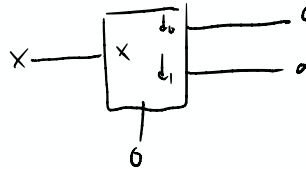
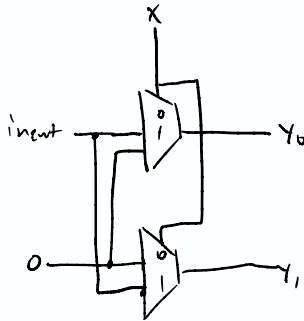
if $x=0$
 $y_0 = \text{input}$
 $y_1 = 0$

else

$y_0 = 0$
 $y_1 = \text{input}$

• comparing TVs, either one or other.

• if input = 0, output always 0



ENCODERS

2:1 encoder

d_0	d_1	x
1	0	0
0	1	1

4:2 encoder

d_0	d_1	d_2	d_3	x_0	x_1
1	0	0	0	0	0
0	1	0	0	0	1
0	0	1	0	1	0
0	0	0	1	1	1
0	0	0	0	0	0

PRIORITY ENCODER

d_0	d_1	d_2	d_3	x_0	x_1
1	0	0	0	0	0
x	1	0	0	0	1
x	x	1	0	1	0
x	x	x	1	1	1
0	0	0	0	0	0

↳ overriding factor is rightmost 1.

What if multiple inputs are on?

• robot w/ sensors

- scout → #4 priority (d_0)
- sand → #3 priority (d_1)
- bone → #2 priority (d_2)
- fire → #1 priority (d_3)

