

Mathematics

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1 Calculus

1.1 Differentiation

- 2 Series**
- 3 Multivariable Calculus**
- 4 Linear Algebra**
- 5 Differential Equations**
- 6 Partial Differential Equations**

7 Vector Calculus

7.1 Operators

7.1.1 Grad

7.1.2 Div

7.1.3 Curl

7.1.4 Laplacian

7.2 Integral Theorems

7.2.1 Divergence Theorem

7.2.2 Stokes's Theorem

8 Fluid Mechanics

8.1 Kinematics

8.1.1 Coordinates

Lagrangian $\underline{x}(\underline{a}, t)$: The *motion of individual particles* is studied; the position \underline{x} of a particle at time t is related to its position at a reference point in time \underline{a} (typically at $t = 0$).

Eulerian (\underline{x}, t) : The *'flow field' is considered as a whole* and the state of a fluid is described in terms of the values at a fixed location \underline{x} and at a fixed time t .

8.1.2 Velocity

In Cartesian coordinates the velocity of a fluid particle at position $\underline{x}(x, y, z)$ is given by:

$$\underline{u}(x, y, z) = u(x, y, z)\hat{i} + v(x, y, z)\hat{j} + w(x, y, z)\hat{k}$$

8.1.3 Stagnation Points

Stagnation points occur when the velocity vector \underline{u} is equal to $\underline{0}$

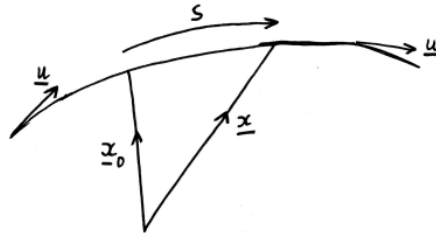
$$u = 0$$

$$v = 0$$

$$w = 0$$

8.1.4 Streamlines

A streamline is a curve C drawn at one point in time such that the fluid velocity vector \underline{u} is tangent to C at every point along C .



$$\frac{d\underline{x}}{ds} = \underline{u}$$

$$\frac{dx}{ds} = u, \frac{dy}{ds} = v, \frac{dz}{ds} = w$$

$$\boxed{\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w} (= ds)}$$

8.1.5 Particle Paths

Particle path is obtained by solving the initial value problem:

$$\frac{d\underline{x}}{dt} = \underline{u}(\underline{x}, t), \quad \underline{x} = x_0 \text{ at } t = 0$$

$$\frac{dx}{dt} = u, \quad x(0) = x_0$$

$$\frac{dy}{dt} = v, \quad y(0) = y_0$$

$$\frac{dz}{dt} = w, \quad z(0) = z_0$$

8.1.6 Steady Flow

Steady Flow: The flow velocity vector \underline{u} is independent of time t

Unsteady Flow: \underline{u} depends on t ; the pattern of streamlines changes with t

8.1.7 Convective Derivative

The convective derivative tells us how a property changes *as it moves with a flow*.

General

$$\boxed{\frac{D*}{Dt} = \frac{\partial*}{\partial t} + (\underline{u} \cdot \nabla)* = \frac{\partial*}{\partial t} + u \frac{\partial*}{\partial x} + v \frac{\partial*}{\partial y} + w \frac{\partial*}{\partial z}}$$

Scalar

$$\boxed{\frac{D\rho}{Dt} = \frac{\partial\rho}{\partial t} + (\underline{u} \cdot \nabla)\rho = \frac{\partial\rho}{\partial t} + u \frac{\partial\rho}{\partial x} + v \frac{\partial\rho}{\partial y} + w \frac{\partial\rho}{\partial z}}$$

Vector

$$\boxed{\frac{D\underline{u}}{Dt} = \frac{\partial\underline{u}}{\partial t} + (\underline{u} \cdot \nabla)\underline{u} = \frac{\partial\underline{u}}{\partial t} + u \frac{\partial\underline{u}}{\partial x} + v \frac{\partial\underline{u}}{\partial y} + w \frac{\partial\underline{u}}{\partial z}}$$

8.1.8 Vorticity

Vorticity $\underline{\omega}$ is a measure of the local rotation of fluid particles in flow.

$$\underline{\omega} = \nabla \times \underline{u}$$

$$\nabla \times \underline{u} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u & v & w \end{vmatrix}$$

Irrotational Flow:

$$\underline{\omega} = \underline{0}$$

8.1.9 Incompressible Flow

$$\nabla \cdot \underline{u} = 0$$

When this is true the convective derivative of the fluid density is zero:

$$\frac{D\rho}{Dt} = 0$$

8.1.10 Velocity Potential

For an irrotational flow the velocity can be described as the gradient of a scalar field known as the *Velocity Potential*.

$$\nabla \times \underline{u} = 0$$

The curl of the gradient of a scalar field is zero:

$$\nabla \times (\nabla \phi) = 0$$

$$\underline{u} = \nabla \phi$$

If the flow is also incompressible

$$\nabla \cdot \underline{u} = 0$$

$$\nabla \cdot (\nabla \phi) = 0$$

Therefore the velocity potential of an irrotational, incompressible flow satisfies

Laplace's Equation:

$$\nabla^2 \phi = 0$$

8.1.11 Equipotential Surfaces

Lines/surfaces of constant ϕ are *equipotentials*.

The velocity potential can be considered a surface:

$$\phi(x, y, z) = c$$

Let \underline{a} be tangent to the surface, the derivative of ϕ in the direction of \underline{a} :

$$\underline{a} \cdot \nabla \phi = 0$$

Because the derivative of a constant c is zero: $\nabla \phi$ is normal to the surface.

$$\underline{\hat{n}} = \frac{\nabla \phi}{|\nabla \phi|}$$

8.1.12 The Stream Function

Considering incompressible two dimensional flow:

$$\begin{aligned}\nabla \cdot \underline{u} &= 0 \\ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} &= 0\end{aligned}$$

We can introduce the stream function $\psi(x, y, t)$ such that:

$$u = \frac{\partial \psi}{\partial y}, v = -\frac{\partial \psi}{\partial x}$$

This satisfies the previous equations:

$$\frac{\partial^2 \psi}{\partial x \partial y} - \frac{\partial^2 \psi}{\partial y \partial x} = 0$$

Vorticity of an incompressible two dimensional flow:

$$\begin{aligned}\underline{\omega} &= \nabla \times \underline{u} \\ \underline{\omega} &= \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \\ \underline{\omega} &= -\frac{\partial^2 \psi}{\partial^2 x} - \frac{\partial^2 \psi}{\partial^2 y} \\ \underline{\omega} &= -\nabla^2 \psi\end{aligned}$$

8.2 Pressure in a Fluid

8.2.1 Pressure

The force exerted by the surrounding fluid on a body can be calculated:

8.3 Flow Dynamics

8.4 Two-dimensional Flow

8.5 Vorticity Dynamics

8.6 Free Surface Waves

9 Numerical Methods