**Interprocess Communication in Distributed Wireless Sensor Network**

Luhan Cheng

Faculty of Information Technology

Monash University

lche0021@student.monash.edu

*Abstract*—Wireless Sensor Network (WSN) has been deployed in a wide range of mission critical task from bushfire detection to water quality monitoring. Such system can be abstracted by representing each sensor with one process in computer system. In this report, I conducted an experiment which utilize MPI to simulate the communication pattern in a 4 by 5 grid network whereas all communications in network are encrypted. Threads level parallelization is applied to cryptographic operations with OpenMP. The experiment shows that (1) minimized communication in WSN can be achieved by MPI (2) the speedup of encryption/decryption algorithm may not be observed by simply adding more shared-memory threads.

Keywords-component; Inter-process Communication, shared memory parallel, Message Passing Interface, Wireless Sensor Network, OpenMP

# Introduction

Inter-process Communication (IPC) defines a set of mechanism that support data sharing and communication among processes[1]. It is commonly used in wireless sensor network (WSN) as communication management method. There are various methods have been developed to satisfy the requirements for different applications. For example, TCP/UDP protocol is developed to facilitate web browsing service, message passing serves concurrency model and shared memory scheme is built in all POSIX systems.

This report aims to simulate the communication in a wireless sensor network to discover most efficient communication pattern. In addition to the simulation in distributed environment, shared memory parallelization is to be discussed to explore the potentiality of accelerating cryptographic operation. The potential of speedup is based on the hypothesis that OpenMP will improve the performance of both encryption and decryption.

Target network is assumed to be a 2-dimensional cartesian grid, where each coordinate represents a sensor (process). An extra process is introduced to simulate base station in the network. The simulation consists of multiple iterations, and for each iteration each sensor sends an encrypted random number to its neighbor. An encrypted event is to be reported to base station if any sensor receives at least 3 identical numbers from its neighbors.

There are three objectives being identified in this scenario. (1) Minimize the message passing between sensor and base station. (2) Minimize the communication among sensors. (3) Speedup the encryption of message with thread level parallelization.

In term of event number being generated. Random seed on each process is computed as the addition of current timestamp and rank number. This setup ensures different random seeds on different processes. Due to limited amount of resources, high probability of event is necessary to generate meaningful outcomes of the simulation. It is achieved by taking first bits of random number, which means the random number has possible outcomes. The probability of one particular event is uniformly distributed across all events.

# Design Scheme for IPC

## Justify Chosen IPC

Message Passing Interface (MPI) is a library specification for message-passing in distributed system [2], which is one of the most popular message passing standard in industry[3]. MPI provides rich features of both point-to-point and collective communication. Compare to other standards, MPI provides several advantages. (1) MPI offers more portable libraries compare to older message passing standards (e.g. parallel virtual machine) [4]. (2) MPI is capable of delivering high performance on HPC system, and it is optimized on the hardware [4][5]. The implementation of MPI standard is vendor specific. One of the most popular open source implementations is OpenMPI [6]. Therefore OpenMPI is applied in experiment to simulate sensor-sensor and sensor-base communication.

OpenMP stands for Open Multi-Processing. It is an application programming interface that support shared memory parallelization. Its behaviors are defined by a set compiler directives and runtime environment variables [7]. OpenMP follows fork-join model whereas at the start of program, there is only one master thread. A set of slave threads can be dynamically forked, and workload is distributed across slave processes. In the experiment, OpenMP is applied in order to speedup encryption and decryption.

## Overall Topology

The network is designed as following. 20 Sensors is repartitioned into 4 by 5 cartesian grid, which forms the communicator local to sensors whereas the sensor-base communications will go through global communicator. The event detection criteria specify that an event is to be reported to base station if any sensor has at least 3 of its neighbors generate the same random number. Such criteria indicate strong local connectivity as for each sensor, it need to exchange a message from its neighbors. For the grid with size (|X|, |Y|), the number of message passing is ( for each iteration.

MPI provides build-in cartesian constructor in any dimension. The communicator among sensors is constructed from excluding the rank of base station from global communicator.

## local message exchange

In order to construct a single message, paddings need to be appended to random number. The messages are to be exchanged by each pair of neighbors. Nearest neighbor communication can be observed in this case. This type of communication pattern has been discussed in multiple literatures. In particular, Torsten and Jesper suggested that the scheduled sparse neighbor all-to-all can outperform naïve neighbor all-to-all operation by replace non-bloking message passing with bidirectional blocking MPI\_Sendrecv[8]. It has been shown that 10% speedup can be observed by applying scheduled all-to-all operation[8]. This optimization is achieved by reducing communication contention on cartesian mesh grid and utilize bidirectional communication link [8]. The application of such operation is limited to case where global knowledge of problem is known, otherwise deadlock could be generated. In the case of WSN, scheduled all-to-all operation is applied in the local message exchange as line 13 in figure 1.

## global event report

After local message passing stage, each node will need to iterate over all possible event values to determine if an event is triggered. If event is activated, the node will report the event to base station by blocking send in global communicator as line 20 in figure 1. Other event related information is also reported along with event number, such as iteration number, timestamp and aggregated encryption/decryption time. When simulation completes, each sensor will send a summary (line 22 figure 1), which includes its basic information, to base station. This message also signals the completion of simulation.

At base station side, at the start of simulation, assume there are N-1 sensors. Base station spawn MPI\_Irecv simultaneously along with a receiver array filled with corresponding request. The first half of the array is used for buffering event message, the second half of the array is used for receiving completion signal. The position in request array corresponds to the rank of base station is filled with null handler. During the simulation, for event received, the message is decrypted and stored in memory, and the same MPI\_Irecv will be respawned as line 32 figure 1. If any completion signal is received, then both events receiver and completion signal receiver will be set to null. Those two types of message are distinguished by using different tags.

Local message exchange and global event report together forms an iteration. A single simulation consists of multiple iterations. All event reports are stored in local memory of base station until being written to storage at the end of simulation. This implementation could potential cause high memory consumption on base station in large scale simulation, but it also comes with the advantage of more available analysis on event reports. The pseudo-code for algorithm is presented in figure 1.

# Encryption and Decryption

Advanced Encryption Standard (AES) is one of the most widely adopted symmetric encryption algorithms. It offers great security with little computational resource required [9]. In order to parallelize both encryption and decryption operation, counter mode AES is selected as encryption/decryption algorithm. Note that the most computational costly operation in counter mode is the cipher block initialization instead of the XOR operation between plaintext and cipher block [9]. Therefore, the speedup of parallelization may not be observed when message length is insufficient.

In realistic, the keys need to be distributed at initialization stage for security. IV need to be randomly generated in order to preserve the confidentially of message. In the experiment, a few assumptions are made for simplicity, I assume that all the parties involved in communication share the same 16 bytes key and the same 8 bytes initialization vector (IV, or nonce). The implementation of algorithm is taken from WjCryptLib [10]. Its counter mode implementation offers build-in OpenMP parallelization for both encryption and decryption. A sample message before and after encryption is presented in figure 2.

# Reseult

The experiment is conducted on high performance cluster MonARCH[11]. The simulation consists of 1000 iterations with 10 milliseconds interval between each iteration. Each message carries 1-byte random number at the start with tailing zeros. 2 CPUs are allocated to each task. The simulations consist of 4 runs with 1,2,4,8 maximum OpenMP threads. The configuration is written to logfile as shown in figure 3. A sample summary of events activation is shown in figure 4. First few events records are shown in figure 5. The experiment is profiled with MPIP[12], which stand for lightweight, scalable MPI profiler. The results are shown in figure 9.

Figure 7 shows MPI time for each rank, we can conclude that good load balance is achieve with presented algorithm.

For each event, there is only one message being passed from reference node to base station. The total amount of message is event number plus number of nodes as shown in figure 9. This communication pattern demonstrated near optimized message passing in WSN.

However, increasing the amount of OpenMP threads does not result in performance improvement. Instead, it leads to severe performance decay as shown in figure 10. There may be several causes for the issue. The problem is mostly likely caused by the limited resources being allocated (2 CPUs per task) to the submission. In addition, the processors use shared resources with other jobs on the cluster, which may indicate interference between simulation and other tasks running on the same node.

Figure 8 presented the time spent on each MPI function. We can conclude that 81.76% (sum of two Sendrecv) aggregated time is spent on sensor-sensor communication while 16.77% (Waitany) aggregated time are spent on sensor-sensor communication. Except message passing, MPI\_Cart\_Create and MPI\_Cart\_shift cost more than any other MPI function. This is because both operations require communications involves all processes.

# Conclusion

This report presented that IPC method, especially MPI, can provide optimized communication scheme for wireless sensor network. But shared memory parallelization does not demonstrate performance improvement in this experiment. The experiment provides some future guidance towards designing more optimized WSN. There are a few possible works left for future. The algorithm can potentially be extended to adapt multi-dimension grid of sensor network. More secure encryption algorithm may be applied. Additionally, we could develop more flexible event detection criteria or adding the feature that regularly save batch of events to storage for less memory overhead on base station. Overall, the experiment shows great potentiality of applying parallelization on wireless distributed network.

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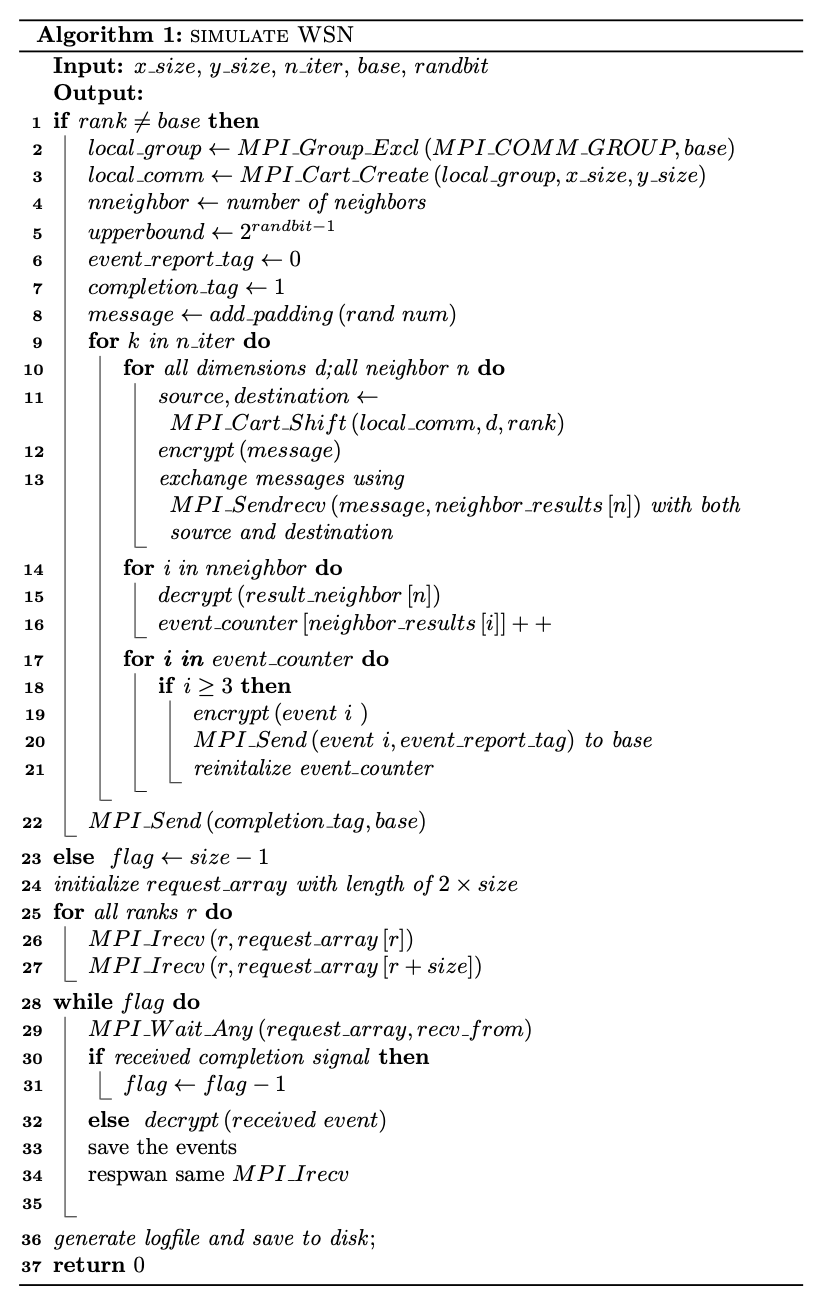
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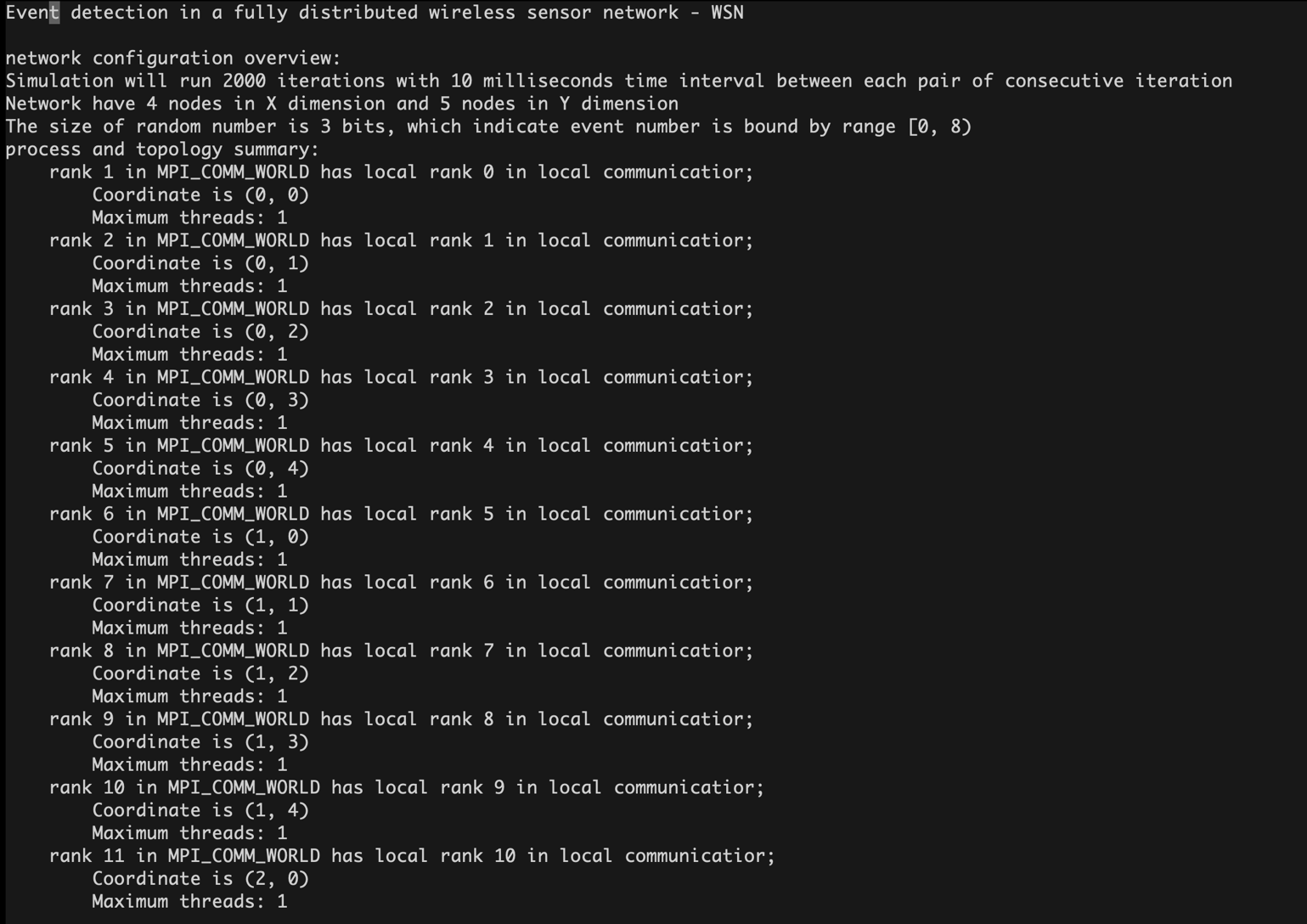
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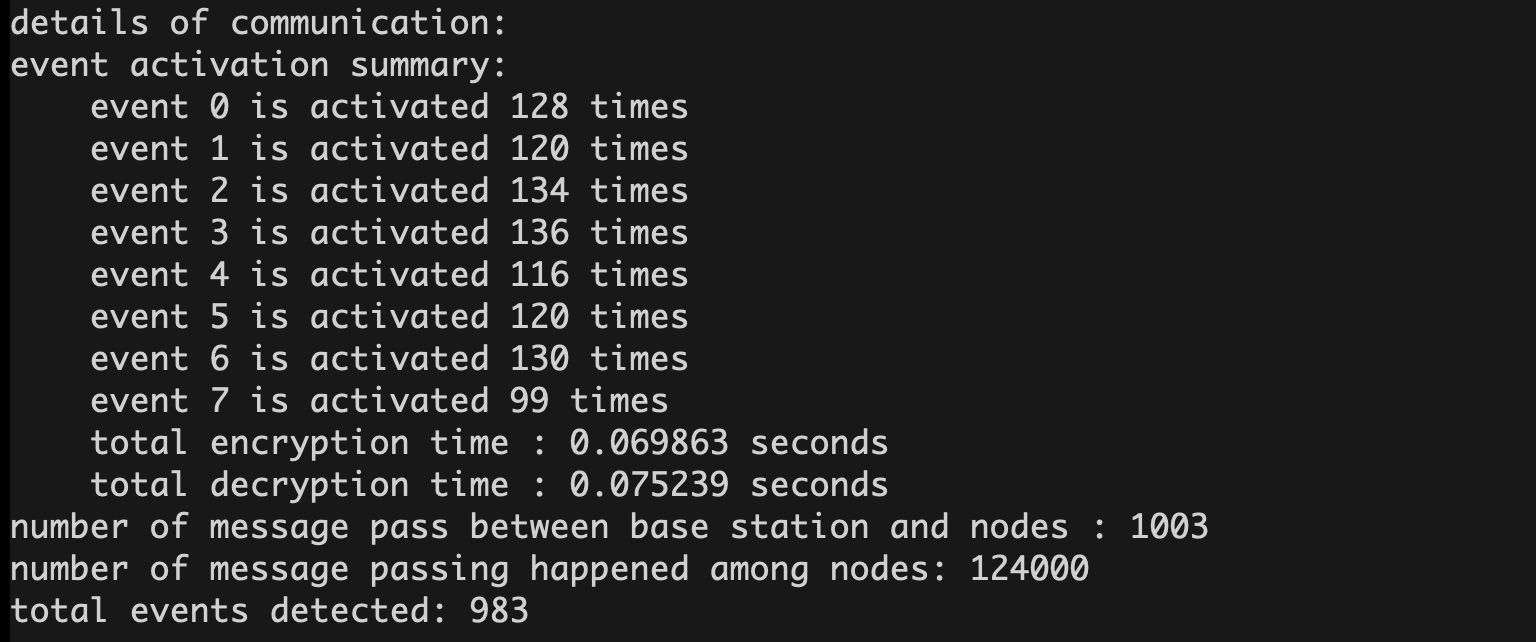
1. WSN simulation algorithm



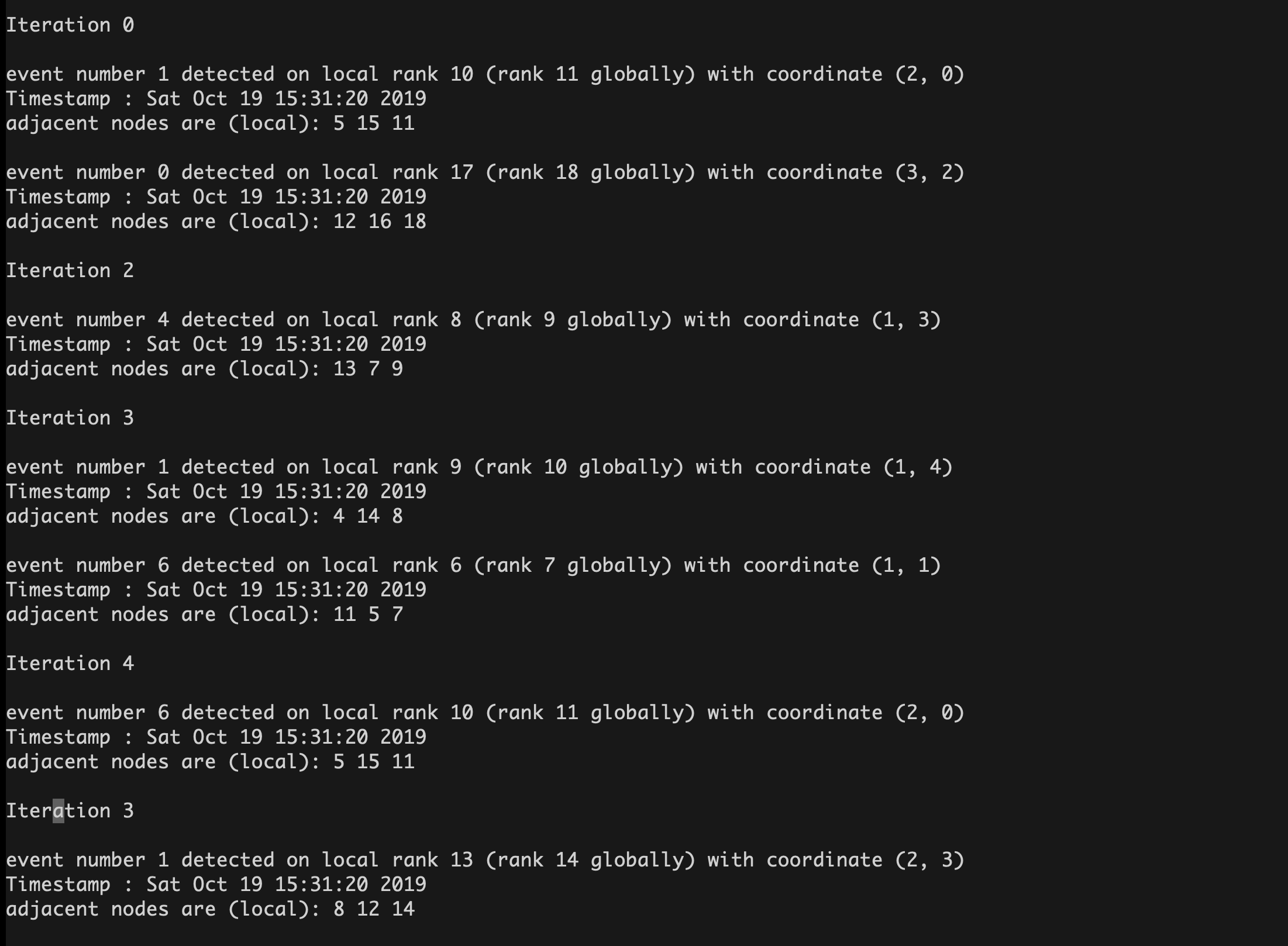
1. Sample message before and after encryption



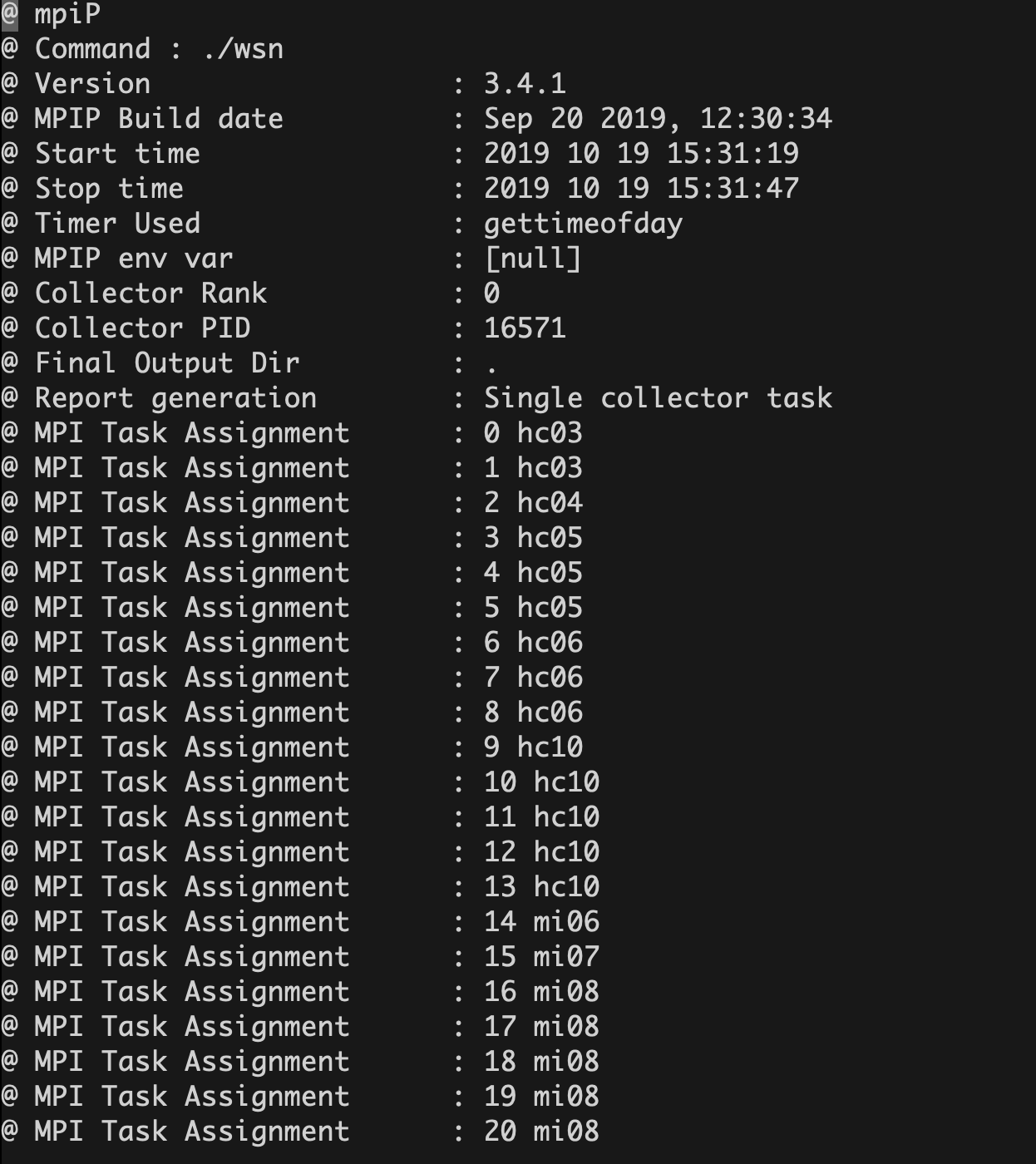
1. network configuration for single thread, process summary displayed for first 12 processes



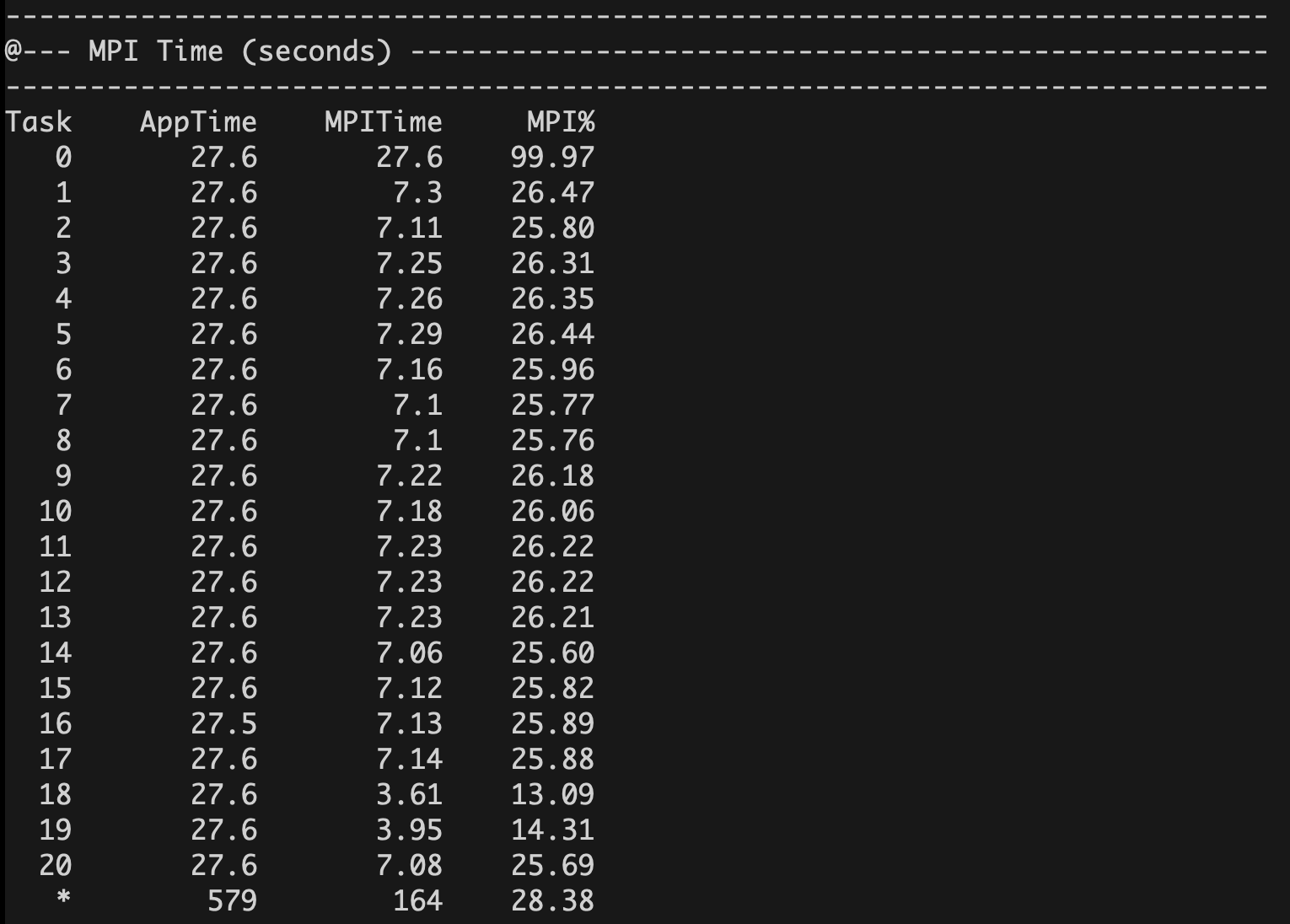
1. event activation summary



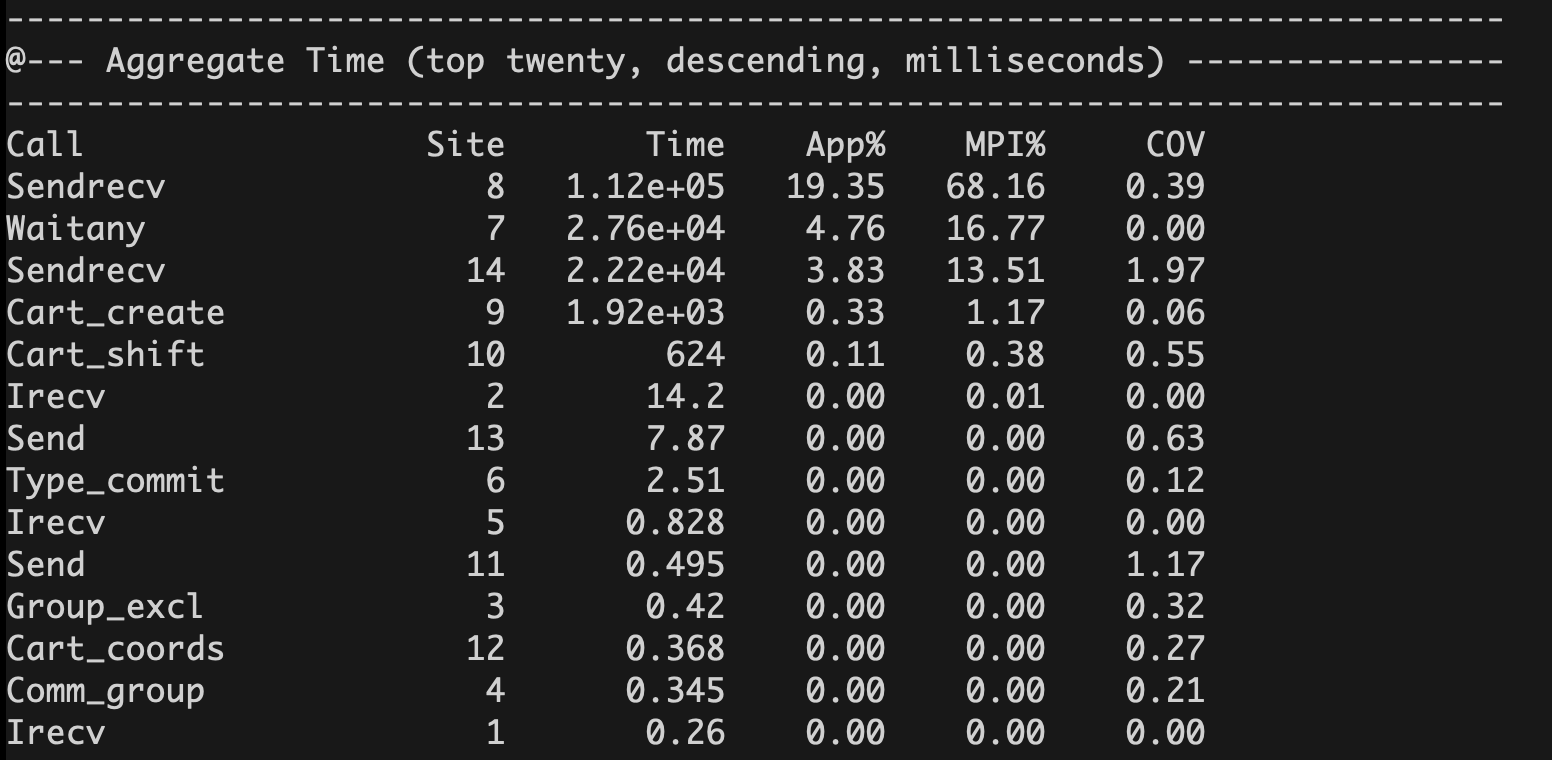
1. Sample details for each event



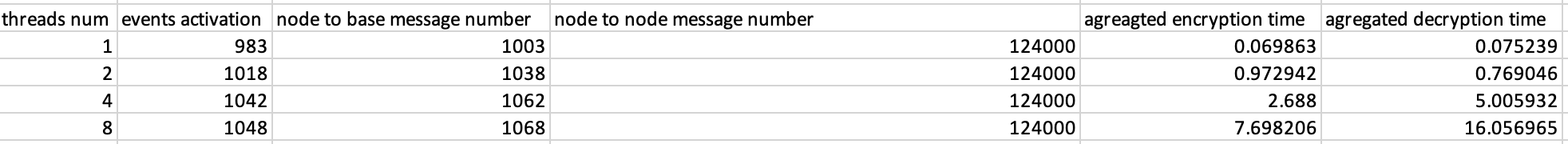
1. host list for running process



1. MPI time on each rank



1. Time spent on each function



1. Experiment result
2. agregated encryption and decryption time with respect to number of threads