

Machine learning: lecture 8

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Topics

- Support vector machines
 - training, prediction
 - other kernel methods
- Kernels
 - examples, properties, construction
 - feature vectors and sparsity

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SVM summary

ullet Training: We can find the optimal setting of the Lagrange multipliers α_i by maximizing

$$\sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{n} y_i y_j \alpha_i \alpha_j \frac{K(\mathbf{x}_i, \mathbf{x}_j)}{}$$

subject to $0 \le \alpha_i \le C$ and $\sum_i \alpha_i y_i = 0$.

- larger ${\cal C}$ means larger penalty for errors
- $\hat{\alpha}_i = 0$ except for "support vectors"
- all misclassified examples will be support vectors
- \hat{w}_0 can be found based on examples for which $\hat{\alpha}_i$ is between 0 and C (when classification constraints are satisfied with equality)





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subject to $0 \le \alpha_i \le C$ and $\sum_i \alpha_i y_i = 0$.

 Prediction: We make predictions according to the sign of the discriminant function

$$\hat{y} = \operatorname{sign}(\hat{w}_0 + \sum_{i \in SV} \hat{\alpha}_i y_i \underline{K}(\mathbf{x}, \mathbf{x}_i))$$

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Other kernel methods: linear regression

• A linear regression model with feature vectors:

$$f(\mathbf{x}; \mathbf{w}) = \phi(\mathbf{x})^T \mathbf{w}_1 + w_0,$$

where
$$\phi(\mathbf{x}) = [\phi_1(\mathbf{x}), \dots, \phi_m(\mathbf{x})]^T$$
.

We can train these models via regularized least squares

$$\min \frac{1}{2} \sum_{i=1} (y_i - f(\mathbf{x}; \mathbf{w}))^2 + \frac{\lambda}{2} ||\mathbf{w}_1||^2$$

• We'd like to turn these models into kernel methods where the examples (feature vectors) appear only in inner products $K(\mathbf{x}, \mathbf{x}') = \phi^T(\mathbf{x})\phi(\mathbf{x}')$.



Other kernel methods: linear regression

• Training: maximize

$$\sum_{i=1}^{n} (\alpha_i y_i - \lambda \alpha_i^2 / 2) - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j)$$

subject to $\alpha_i \in \mathcal{R}$ and $\sum_i \alpha_i = 0$.

The offset parameter \hat{w}_0 can be obtained directly from the solution:

$$\hat{w}_0 = \frac{1}{n} \sum_{i=1}^n \left(y_i - \sum_{j=1}^n \hat{\alpha}_j K(\mathbf{x}_i, \mathbf{x}_j) \right)$$

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 \bullet $\boldsymbol{Prediction}:$ the predicted output for a new point \boldsymbol{x} is

$$f(\mathbf{x}; \hat{\alpha}, \hat{w}_0) = \hat{w}_0 + \sum_{i=1}^n \hat{\alpha}_i K(\mathbf{x}, \mathbf{x}_i)$$

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Other kernel methods: logistic regression

• A logistic regression model with feature vectors

$$P(y = 1 | \mathbf{x}, \mathbf{w}) = g(\phi(\mathbf{x})^T \mathbf{w}_1 + w_0)$$

where
$$\phi(\mathbf{x}) = [\phi_1(\mathbf{x}), \dots, \phi_m(\mathbf{x})]^T$$

As before we can train these models by minimizing the following regularized empirical loss (maximizing penalized log-likelihood):

$$\min \sum_{i=1}^{n} -\log P(y_i|\mathbf{x}_i, \mathbf{w}) + \frac{\lambda}{2} ||\mathbf{w}_1||^2$$

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Other kernel methods: logistic regression

• Training: maximize

$$\sum_{i=1}^{n} H(\lambda \alpha_i) / \lambda - \frac{1}{2} \sum_{i,j=1}^{n} y_i y_j \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j)$$

subject to $0 \le \alpha_i \le 1/\lambda$ and $\sum_i \alpha_i y_i = 0$.

Here $H(p)=-p\log(p)-(1-p)\log(1-p)$ is the binary entropy function. \hat{w}_0 has to be solved iteratively after obtaining $\hat{\alpha}$.

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Here $H(p)=-p\log(p)-(1-p)\log(1-p)$ is the binary entropy function. \hat{w}_0 has to be solved iteratively after obtaining $\hat{\alpha}$.

• **Prediction:** the predicted probabilities over possible labels for a new point x are given by

$$P(y = 1 | \mathbf{x}, \hat{\alpha}, \hat{w}_0) = g(\hat{w}_0 + \sum_{i=1}^n \hat{\alpha}_i y_i K(\mathbf{x}, \mathbf{x}_i))$$

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Example kernels

Linear kernel

$$K(\mathbf{x}, \mathbf{x}') = (\mathbf{x}^T \mathbf{x}')$$

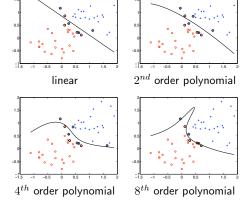
Polynomial kernel

$$K(\mathbf{x}, \mathbf{x}') = (1 + (\mathbf{x}^T \mathbf{x}'))^p$$

where $p=2,3,\ldots$ To get the feature vectors we concatenate all up to p^{th} order polynomial terms of the components of ${\bf x}$ (weighted appropriately)



Polynomial kernels with SVMs



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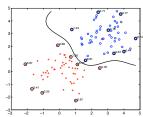


Example kernels

Radial basis kernel

$$K(\mathbf{x}, \mathbf{x}') = \exp\left(-\frac{1}{2}\|\mathbf{x} - \mathbf{x}'\|^2\right)$$

In this case the feature space is infinite dimensional function space (use of the kernel results in a *non-parametric* classifier).



 support vectors need not appear close to the boundary in the input space, only in the feature space

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Definition of kernels

- We can think of kernels in terms of explicit or implicit feature mappings
- Definition 1: $K(\mathbf{x}, \mathbf{x}')$ is a kernel if it can be written as an inner product $\phi(\mathbf{x})^T \phi(\mathbf{x}')$ for some feature mapping ϕ .
- Definition 2: $K(\mathbf{x}, \mathbf{x}')$ is a kernel if for any finite set of training examples, $\mathbf{x}_1, \ldots, \mathbf{x}_n$, the $n \times n$ matrix $K_{ij} = K(\mathbf{x}_i, \mathbf{x}_j)$ is positive semi-definite.

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Kernels and construction

- We can build kernels from simpler ones. For example:
 - If $K_1(\mathbf{x}, \mathbf{x}')$ and $K_2(\mathbf{x}, \mathbf{x}')$ are valid kernels then

$$\begin{split} f(\mathbf{x})K_1(\mathbf{x},\mathbf{x}')f(\mathbf{x}') & \text{(scaling)} \\ K_1(\mathbf{x},\mathbf{x}') + K_2(\mathbf{x},\mathbf{x}') & \text{(sum)} \\ K_1(\mathbf{x},\mathbf{x}')K_2(\mathbf{x},\mathbf{x}') & \text{(product)} \end{split}$$

are valid kernels.

– If $\mathbf{x}=[x_1,\dots,x_d]^T\in\mathcal{R}^d$ and $K_i(x_i,x_i')$ are valid 1-dimensional kernels, then

$$K(\mathbf{x}, \mathbf{x}') = \prod_{i=1}^{d} K_i(x_i, x_i')$$

is a valid kernel in \mathbb{R}^d .

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Kernels and sequences

 We can also derive kernels for variable length sequences. For example:

$$x = \dots$$
 my first day this term was \dots $x' = \dots$ Last year the midterm had \dots

Gap-weighted subsequence kernel:

$$K(\mathbf{x},\mathbf{x}') = \sum_{u \in \Sigma^d} \sum_{\vec{i}: u = \mathbf{x}[\vec{i}]} \sum_{\vec{j}: u = \mathbf{x}[\vec{j}]} \lambda^{(i_d - i_1)} \lambda^{(j_d - j_1)}$$

where $\lambda \in (0,1)$ and Σ^d is the set of all sequences of length d. The kernel reflects the degree to which the sequences have common subsequences penalizing noncontiguous subsequences.

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Dimensionality and complexity

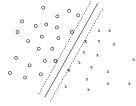
- Many of these kernels correspond to very high dimensional feature spaces
 - polynomial kernel for large p or $dim(\mathbf{x})$
 - radial basis kernel (infinite)
- subsequence kernel (combinatorial) etc.
- The dimensionality of the feature space determines the number of parameters in the primal formulation

min
$$\|\mathbf{w}_1\|^2$$
 subject to $y_i[w_0 + \phi(\mathbf{x}_i)^T \mathbf{w}_1] - 1 \ge 0$, $\forall i$

Can these methods generalize?



Cross-validation



 For SVMs the leave-one-out cross-validation error does not depend on the dimensionality of the feature space but only on the # of support vectors

(similar results exist for kernel logistic regression)

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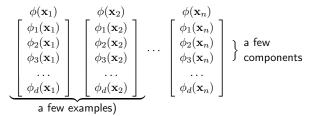
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Kernels, examples, sparsity

 High dimensional feature vectors (many basis functions) can still permit a sparse solution in terms of the number of training examples



 Alternatively, we could try to find a few basis functions (components) that solve the classification/regression task

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