

Arm® SBSA Architecture Compliance

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User Guide

arm

Arm® SBSA Architecture Compliance

User Guide

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Release Information

Document History

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Preface

This preface introduces the *Arm® SBSA Architecture Compliance User Guide*.

It contains the following:

- *About this book* on page 6.
- *Feedback* on page 8.

About this book

This book describes the Architecture Compliance user guide for Arm® SBSA Architecture Compliance.

Product revision status

The *rmprn* identifier indicates the revision status of the product described in this book, for example, r1p2, where:

rm Identifies the major revision of the product, for example, r1.

prn Identifies the minor revision or modification status of the product, for example, p2.

Intended audience

This book is written for engineers who are specifying, designing, or verifying an implementation of the Arm® Server Base Systems Architecture.

Using this book

This book is organized into the following chapters:

Chapter 1 *UEFI shell application*

Read this chapter for information about executing the tests from UEFI Shell application.

Chapter 2 *Linux application*

Read this chapter for information about executing the tests from Linux application.

Appendix A *Revisions*

This appendix describes the technical changes between released issues of this book.

Glossary

The Arm Glossary is a list of terms used in Arm documentation, together with definitions for those terms. The Arm Glossary does not contain terms that are industry standard unless the Arm meaning differs from the generally accepted meaning.

See the *Arm® Glossary* for more information.

Typographic conventions

italic

Introduces special terminology, denotes cross-references, and citations.

bold

Highlights interface elements, such as menu names. Denotes signal names. Also used for terms in descriptive lists, where appropriate.

`monospace`

Denotes text that you can enter at the keyboard, such as commands, file and program names, and source code.

monospace

Denotes a permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.

`monospace italic`

Denotes arguments to monospace text where the argument is to be replaced by a specific value.

`monospace bold`

Denotes language keywords when used outside example code.

<and>

Encloses replaceable terms for assembler syntax where they appear in code or code fragments. For example:

```
MRC p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>
```

SMALL CAPITALS

Used in body text for a few terms that have specific technical meanings, that are defined in the *Arm® Glossary*. For example, IMPLEMENTATION DEFINED, IMPLEMENTATION SPECIFIC, UNKNOWN, and UNPREDICTABLE.

Timing diagrams

The following figure explains the components used in timing diagrams. Variations, when they occur, have clear labels. You must not assume any timing information that is not explicit in the diagrams.

Shaded bus and signal areas are undefined, so the bus or signal can assume any value within the shaded area at that time. The actual level is unimportant and does not affect normal operation.

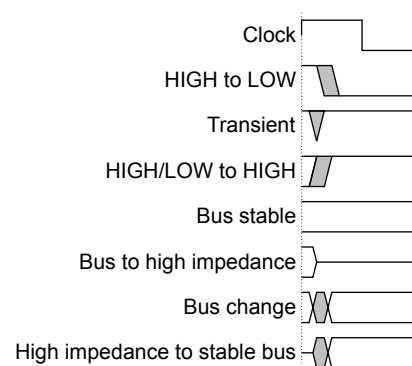


Figure 1 Key to timing diagram conventions

Signals

The signal conventions are:

Signal level

The level of an asserted signal depends on whether the signal is active-HIGH or active-LOW. Asserted means:

- HIGH for active-HIGH signals.
- LOW for active-LOW signals.

Lowercase n

At the start or end of a signal name denotes an active-LOW signal.

Additional reading

This book contains information that is specific to this product. See the following documents for other relevant information.

Arm publications

- *Arm® Server Base System Architecture Specification* (ARM-DEN-0029 Version 3.0).
- *Arm® Server Base Boot Requirements* (ARM-DEN-0044B).
- *Arm® Architecture Reference Manual ARMv8, for Armv8-A architecture profile* (ARM DDI 0487).

Other publications

None.

Feedback

Feedback on this product

If you have any comments or suggestions about this product, contact your supplier and give:

- The product name.
- The product revision or version.
- An explanation with as much information as you can provide. Include symptoms and diagnostic procedures if appropriate.

Feedback on content

If you have comments on content then send an e-mail to errata@arm.com. Give:

- The title *Arm SBSA Architecture Compliance User Guide*.
- The number 101547_0200_01_en.
- If applicable, the page number(s) to which your comments refer.
- A concise explanation of your comments.

Arm also welcomes general suggestions for additions and improvements.

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Chapter 1

UEFI shell application

Read this chapter for information about executing the tests from UEFI Shell application.

It contains the following sections:

- *1.1 Overview of tests* on page 1-10.
- *1.2 UEFI application arguments* on page 1-11.
- *1.3 Test IDs* on page 1-12.
- *1.4 UEFI implementation of PAL APIs* on page 1-13.

1.1 Overview of tests

The general division of tests between UEFI Shell application and Linux application is illustrated in the following table.

Table 1-1 Test environment and modules

Test environment	Modules
UEFI Shell	PE, GIC, Timers, Watchdog, Wakeup, Secure devices
Linux command line	PCIe, SMMU, Exerciser

1.2 UEFI application arguments

Run this application with the following set of arguments:

```
uefi shell> sbsa.efi [-v <n>] [-l <n>] [-skip <x,y,z>] [-f <file name>] [-s]
```

The parameter descriptions are available in the following table.

Table 1-2 Descriptions of UEFI application parameters

Parameter	Description
v	Print level 1 INFO and above. 2 DEBUG and above. 3 TEST and above. 4 WARN and ERROR. 5 ERROR.
l	Level of compliance to be tested for (0-5).
skip	Overrides the suite to skip the execution of a particular test. It allows a maximum of three values (comma-separated). For example, 300 skips test case with ID = 300. 500 skips all tests in module with ID = 500. For details on module IDs, see 1.3 Test IDs on page 1-12 .
f	File name to which the output log is written.
s	Runs Secure tests before executing Non-secure tests. It requires Secure firmware code from SBSA ACS to be ported to EL3 FW. If this option is not given, only Non-secure tests are run.

Example

```
shell > sbsa.efi -v 2 -l 3 -f acs.txt -skip 20,36
```

The set of parameters shown in the above code block:

- Prints messages with verbosity of 2 and above.
- Tests for compliance against SBSA level 3.
- Skips execution of all tests belonging to GIC module and test number 36.
- Stores the log messages to the file `acs.txt`.

1.3 Test IDs

Test ID of each test is generated as an addition of Module ID and Unit Test ID.

For a given module, Unit Test ID begins from 1.

Module IDs are as follows.

Table 1-3 Module Name and Module ID

Module name	Module ID
PE	0
GIC	100
Timer	200
Watchdog	300
PCIe	400
Power and Wakeup	500
Peripheral	600
SMMU	700
Exerciser	800
Secure	900

1.4 UEFI implementation of PAL APIs

The following table lists the UEFI interfaces used for the implementation of the *Platform Abstraction Layer* (PAL) APIs mentioned in the *Arm SBSA Validation Methodology* document. PAL APIs are classified into infrastructure and module-specific APIs.

Infrastructure APIs

Table 1-4 PAL APIs and UEFI interfaces

PAL API	UEFI interfaces
pal_print	AsciiPrint
mem_alloc	gBS->AllocatePool
mem_free	gBS->FreePool
mem_alloc_shared	gBS->AllocatePool
mem_free_shared	gBS->FreePool
mem_get_shared_addr	None
mmio_read	None
mmio_write	None

Module-specific APIs

Table 1-5 PAL APIs, UEFI interfaces, and ACPI tables consumed

PAL API	UEFI interfaces consumed	ACPI table consumed
pe_create_info_table	<ul style="list-style-type: none"> gST->ConfigurationTable CompareGuid IndustryStandard/Acpi61.h 	MADT Table
call_smc	None	-
pe_execute_payload	None	-
pe_install_esr	<ul style="list-style-type: none"> gEfiCpuArchProtocolGuid Cpu->RegisterInterruptHandler 	-
gic_create_info_table	<ul style="list-style-type: none"> gST->ConfigurationTable CompareGuid IndustryStandard/Acpi61.h 	MADT table
gic_install_isr	<ul style="list-style-type: none"> gHardwareInterruptProtocolGuid RegisterInterruptSource EnableInterruptSource 	-
timer_create_info_table	<ul style="list-style-type: none"> gST->ConfigurationTable CompareGuid IndustryStandard/Acpi61.h 	GTDT table
wd_create_info_table	<ul style="list-style-type: none"> gST->ConfigurationTable CompareGuid IndustryStandard/Acpi61.h 	GTDT table
pcie_create_info_table	<ul style="list-style-type: none"> gST->ConfigurationTable CompareGuid IndustryStandard/Acpi61.h 	MCFG table
pcie_get_mcfg_ecam	<ul style="list-style-type: none"> gST->ConfigurationTable CompareGuid, IndustryStandard/Acpi61.h IndustryStandard/MemoryMappedConfigurationSpaceAccessTable.h 	MCFG table
iovirt_create_info_table	<ul style="list-style-type: none"> gST->ConfigurationTable CompareGuid IndustryStandard/Acpi61.h 	IORT table
peripheral_create_info_table	<ul style="list-style-type: none"> gEfiPciIoProtocolGuid Pci->GetLocation Pci->Pci.Read 	-
memory_create_info_table	gBS->GetMemoryMap	-

Chapter 2

Linux application

Read this chapter for information about executing the tests from Linux application.

It contains the following sections:

- [2.1 Linux application arguments](#) on page 2-16.
- [2.2 Build steps and environment setup](#) on page 2-17.

2.1 Linux application arguments

Run the Linux application with the following set of arguments:

```
shell> sbsa [--v <n>] [--l <n>] [--e <n>] [--skip <x,y,z>]
```

Table 2-1 Description of Linux application parameters

Parameter	Description
v	Print level 1 INFO and above 2 DEBUG and above 3 TEST and above 4 WARN and ERROR 5 ERROR
l	Level of compliance to be tested for. (0 to 5)
e	1 Run exerciser tests. 0 Do not run exerciser tests.
skip	Overrides the suite to skip the execution of a particular test. For example, 53 skips test case with ID 53.

Example

```
shell> sbsa --v 3 --l 3 --e 1 --skip 57
```

This set of parameters tests for compliance against SBSA level 3 with print verbosity set to 3, runs the exerciser tests, and skips test number 57.

Loading the kernel module

Before the SBSA ACS Linux application can be run, load the SBSA ACS kernel module using the `insmod` command.

```
shell> insmod sbsa_acs.ko
```


2.2 Build steps and environment setup

This section lists the porting and build steps for the kernel module.

The patch for the kernel tree and the Linux Platform Abstraction Layer are hosted separately on linux-arm.org.

Building the kernel module

Prerequisites

- Linux kernel source version 4.14.
- Linaro GCC tool chain 5.3 or above.
- Build environment for AArch64 Linux kernel.

Porting steps for Linux kernel

1. `git clone git://linux-arm.org/linux-acsc.git <local_dir>/sbsa-acsc-drv`
2. `git clone https://github.com/ARM-software/sbsa-acsc.git <local_dir>/sbsa-acsc`
3. Apply the `<local_dir>/kernel/src/0001-Enterprise-acsc-linux-v4.13.patch` patch to your kernel source tree.
4. Build the kernel.

Build steps for SBSA kernel module

1. `cd <local_dir>/sbsa-acsc-drv/files`
2. Set `CROSS_COMPILE` to the ARM64 toolchain path.
3. `export KERNEL_SRC=<linux kernel path>`
4. `./setup.sh <local_dir>/sbsa-acsc`
5. `./linux_sbsa_acsc.sh`

`sbsa_acsc.ko` file is generated.

SBSA Linux application build

1. `cd <sbsa-acsc path>/linux_app/sbsa-acsc-app`
2. Set `CROSS_COMPILE` to the ARM64 toolchain path.
`export CROSS_COMPILE=<local_dir>/gcc-linaro-5.3-2016.02/bin/aarch64-linux-gnu-`
3. `make`

The executable file `sbsa` is generated.

This section contains the following subsections:

- [2.2.1 Target environment setup on page 2-17](#).
- [2.2.2 Runtime environment on page 2-18](#).

2.2.1 Target environment setup

The set of tests assumes that at least one SATA controller is behind a PCIe root complex. The SATA controller may or may not be behind an IOMMU.

Before running these tests, at least one SATA hard disk must be connected to the SATA controller. The test performs read and write operations to the SATA hard disk. Therefore, the data on the HDD is overwritten. The SATA drive must not be the boot device for the OS.

2.2.2 Runtime environment

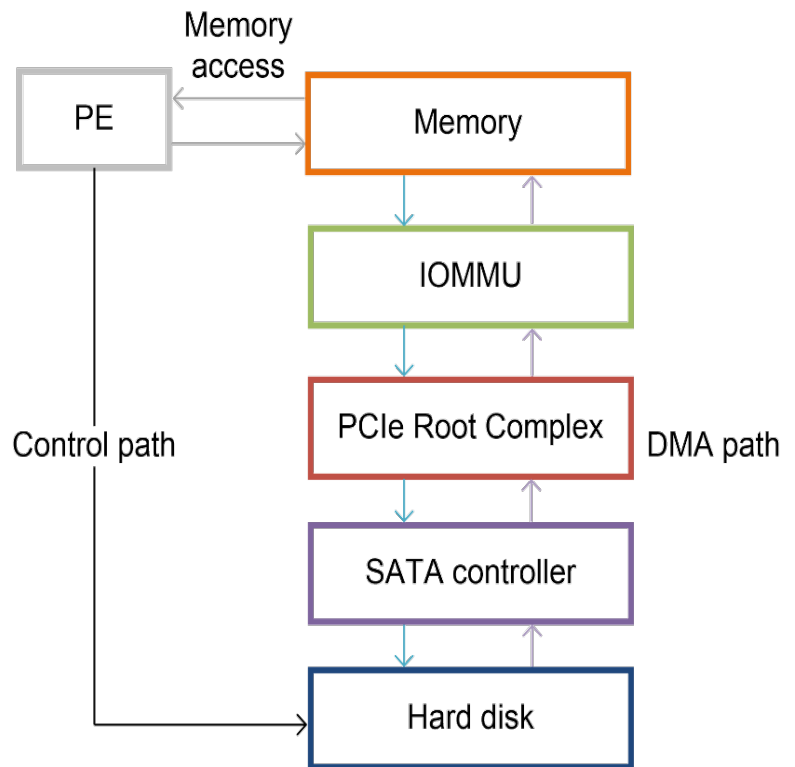


Figure 2-1 Hardware functional blocks

The PCIe-DMA tests initiate data transfers from a DMA master. By default, the test searches for a SATA controller which is part of the PCIe subsystem.

1. The test writes known data from the PE to main memory.
2. The test programs the DMA master to transfer this known data to its end-point device.
3. The test asks the DMA master to transfer the data back to a different location in the main memory.
4. The test compares the data at both the locations.

If the SATA controller is not behind an IOMMU, during this data transfer, the address that is used by the SATA controller is retrieved and compared with the DMA address that is seen by the PE.

If the DMA master is behind an IOMMU, then the address that is used by the SATA AHCI controller is compared with the address that is seen by the IOMMU. Both these addresses must match.

To enable the export of the addresses that are seen by the SATA AHCI controller and IOMMU, the kernel drivers for these two modules must be patched.

Appendix A

Revisions

This appendix describes the technical changes between released issues of this book.

It contains the following section:

- [A.1 Revisions on page Appx-A-20.](#)

A.1 Revisions

Table A-1 Issue101547-01

Change	Location	Affects
Added information about exerciser.	See 1.3 Test IDs on page 1-12	All revisions
Added a new parameter [- - e] to the Linux application arguments.	See 2.1 Linux application arguments on page 2-16 .	All revisions