

Wen Wu

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Education Background

2013 – 2017	Ph.D. of Engineering (Mechanical Engineering) The University of Melbourne <i>Melbourne International Research Scholarship</i> <i>Melbourne International Fee Remission - 100%</i>
2008 – 2012	Bachelor of Engineering (Engineering Mechanics) GPA 3.8/4.0 Tianjin University (TJU) <i>Caterpillar Inc. Scholarship,</i> <i>Samsung Co., Ltd. Scholarship,</i> <i>National Scholarship</i>
2009 – 2012	Bachelor of Economics (Finance), TJU-Nankai dual degree Nankai University

Work Experience

Postdoctoral Research Fellow	2017 – Current
<i>Networked Society Institute,</i> <i>University of Melbourne, Australia</i>	9/2017 – 1/2018
<i>Joint Department of Biomedical Engineering,</i> <i>University of North Carolina at Chapel Hill & North Carolina State University, USA</i>	1/2018 – 11/2018
<i>Centre for Health, Exercise & Sports Medicine,</i> <i>University of Melbourne, Australia</i>	11/2018 – Current

Responsibilities:

- Undertook independent and collaborative research projects in the following areas:
 - *Machine learning (reinforcement learning, computer vision)*
 - *Computational biomechanics*
 - *Human-machine interaction (wearable robotics, sensors)*
- Supervised PhD/master students and delivered lectures/tutorial sessions in programming and computational modelling related topics.

Achievements:

- Acquired extensive programming experience through a wide variety of research projects.
- Greatly improved problem-solving and analytical skills.
- Gained ability to quickly grasp and apply technical knowledge.
- Published multiple research papers in top-tier journals and presented studies in conferences.

Research Data & Equipment Specialist	2018 – Current
<i>Centre for Health, Exercise & Sports Medicine, University of Melbourne, Australia</i>	

Responsibilities:

- Responsible for data extraction/cleaning/visualisation for scientific research projects conducted in the centre.
- Performed data mining from legacy data to discover valuable research questions.
- Developed automated data acquisition/processing pipelines for lab equipment.

Achievements:

- Known as the ‘data wizard’ in the centre.
- The ‘data-driven’ approaches opened-up multiple research opportunities.

Professional Projects

Run & Attack – An Online Multiplayer Mobile Game

2021

AWS (DynamoDB, Lambda, Cognito, GameLift, Polly), C#, Unity, JavaScript

- A self-motivated project.
- An online player-vs-player mobile game developed on Unity platform, which combines GPS-tracked running activity with board game, aiming to promote a healthier lifestyle through fun gaming.
- The backend was developed using AWS services, including DynamoDB, Lambda, Cognito, Amazon GameLift, and Amazon Polly.



Scan for demo video

https://youtu.be/pwyVY6_ytLA

3d Marker-less Motion Capturing System

2020 – 2021

Machine learning, Computer vision, Python, Matlab

- A marker-less multi-camera motion capturing system developed and validated using Python and Matlab, as an alternative to the conventional expensive and unportable system (e.g. marker-based Vicon system).
- The system is low-cost and portable, making it perfect for many applications in clinics, sports, ergonomics, etc.



Scan for demo video

<https://youtu.be/l8hfi-9soHY>

Musculoskeletal Modelling Research

2013 – 2021

Matlab, C++

- Developed and used a series of computational musculoskeletal models to accurately predict internal muscle and joint forces.
- Multiple research publications on this topic.

Applying Reinforcement Learning Technique to Biomechanical Modelling

2018 – 2019

Machine learning, Reinforcement learning, Python, C#, Unity,

- Developed an alternative reinforcement-learning-based technique to conventional modelling approaches to predict joint moments based on either measured kinematics or surface electromyography.
- Research paper published.

- Conducted multiple research that involved wearable robotics such as exoskeleton and robotic prosthesis.
- Developed an optimised robotic prosthesis controller.
- Investigated the influence of the exoskeleton on the human body.
- Research paper published.



Scan for demo video

<https://youtu.be/layHAtrlhRc>**Real-Time Virtual Reality System for Self-Directed Upper Limb Rehabilitation 2017***Matlab, C#, Unity, Sensors, VR*

- Built computational model for real-time arm dynamic simulation using Matlab and C#, and developed VR environment in Unity.
- Designed and prototyped the sensor kit (e.g. inertial measurement unit, electromyography, wireless data acquisition system).
- Proposed and wrote all the technical and budget sections, and secured a \$32,000 seed fund for the project

Research Achievements / Academic Journals

- Wu, W.,** Saul, K. R., & Huang, H. (2021). Using reinforcement learning to estimate human joint moments from electromyography or joint kinematics: An Alternative Solution to Musculoskeletal-Based Biomechanics. *Journal of Biomechanical Engineering*, 143(4), 44502.
- Wu, W.,** Fong, J., Crocher, V., Lee, P. V. S., Oetomo, D., Tan, Y., & Ackland, D. C. (2018). Modulation of shoulder muscle and joint function using a powered upper-limb exoskeleton. *Journal of Biomechanics*, 72, 7–16. <https://doi.org/10.1016/j.jbiomech.2018.02.019>
- Wu, W.,** Lee, P. V. S., & Ackland, D. C. (2017). The sensitivity of shoulder muscle and joint force predictions to changes in joint kinematics: A Monte-Carlo analysis. *Gait & Posture*, 54, 87–92.
- Wu, W.,** Lee, P. V. S., Bryant, A. L., Galea, M., & Ackland, D. C. (2016). Subject-specific musculoskeletal modeling in the evaluation of shoulder muscle and joint function. *Journal of Biomechanics*, 49(15), 3626–3634.
- Wu, W.,** Bryant, A. L., Hinman, R. S., Bennell, K. L., Metcalf, B. R., Hall M., Campbell, P. K., & Paterson, K., Walking-related knee contact forces and associations with knee pain across people with mild, moderate and severe radiographic knee osteoarthritis: a cross-sectional study. *Osteoarthritis and Cartilage* (**Under review**)
- Williams, C., Kolic, J., **Wu, W.,** & Paterson, K. (2021). Soft soled footwear has limited impact on toddler gait. *Plos One*, 16(5), e0251175.

- McManus, F., Pranata, A., Simpson, J. A., Farragher, J., Crofts, S., **Wu, W.**, & Bryant, A. (2021). Does pain self-efficacy influence initial bending following exercise in adults with chronic low back pain? *International Journal of Epidemiology* (Vol. 50, p. 152).
- Ackland, D. C., **Wu, W.**, Thomas, R., Patel, M., Page, R., Sangeux, M., & Richardson, M. (2019). Muscle and Joint Function After Anatomic and Reverse Total Shoulder Arthroplasty Using a Modular Shoulder Prosthesis. *Journal of Orthopaedic Research®*.
- Ackland, D. C., Robinson, D. L., Wilkosz, A., **Wu, W.**, Richardson, M., Lee, P., & Tse, K. M. (2018). The influence of rotator cuff tears on muscle and joint-contact loading after reverse total shoulder arthroplasty. *Journal of Orthopaedic Research®*, 37(1), 211–219.
- Ackland, D., Griggs, I., Hislop, P., **Wu, W.**, Patel, M., & Richardson, M. (2017). An intramedullary Echidna pin for fixation of comminuted clavicle fractures: a biomechanical study. *Journal of Orthopaedic Surgery and Research*, 12(1), 122.
- Hall, D. A., Snelling, S. R., Ackland, D. C., **Wu, W.**, & Morton, J. M. (2015). Bending Strength and Stiffness of Canine Cadaver Spines After Fixation of a Lumbar Spinal Fracture-Luxation Using a Novel Unilateral Stabilization Technique Compared to Traditional Dorsal Stabilization. *Veterinary Surgery*, 44(1), 94–102.
- Wu, W.**, Lee, P. V. S., Bryant, A. L., Ackland, D. C. (2016). The reliability of generic and scaled-generic musculotendon parameters in shoulder musculoskeletal modelling. Study presented at *Annual Australian & New Zealand Orthopaedic Research Society Conference (ANZORS)*, Melbourne, Australia.
- Wu, W.**, Lee, P. V. S., Ackland, D. C. (2016). The sensitivity of model predictions of muscle function to changes in shoulder girdle kinematics. Study presented at *ANZORS*, Melbourne, Australia.
- Wu, W.**, Fong, J., Oetomo, D., Lloyd, D., Besier, T., Halaki, M., Ginn, K., Lee, P.V.S. and Ackland, D.C., (2015). Muscle and joint contact loading during assisted upper-extremity movements performed with a robotic exoskeleton. Study presented at *25th International Society of Biomechanics Conference*, Glasgow, UK.
- Wu, W.**, Lee, P. V. S., Ackland, D. C. (2015). The influence of an assistive robotic exoskeleton on upper-limb muscle and joint function. Study presented at *ANZORS*, Auckland.
- Wu, W.**, Ginn, K., Halaki, M., Bryant, A. L., Lloyd, D., Besier, T., Lee, P. V. S, Ackland, D. C. (2014). A musculoskeletal model for the evaluation of shoulder muscle and joint function. Study presented at *ANZORS*, Adelaide, Australia.