

## Appendix D. Covariance matrices

Although the concepts presented below apply identically to vector fields, for brevity present discussion is limited to simple vectors.

Consider a two-component force vector response  $\mathbf{F}$ :

$$\mathbf{F}_j = \begin{bmatrix} F_{xj} & F_{yj} \end{bmatrix}^\top \quad (\text{D.1})$$

where  $j$  indexes the responses, and there are a total of  $J$  responses. After computing the mean force vector  $\bar{\mathbf{F}}$  as:

$$\bar{\mathbf{F}} = \begin{bmatrix} \bar{F}_x \\ \bar{F}_y \end{bmatrix} = \frac{1}{J} \sum_{j=1}^J \mathbf{F}_j \quad (\text{D.2})$$

the covariance matrix  $\mathbf{W}$  can be assembled as follows:

$$\mathbf{W} = \begin{bmatrix} W_{xx} & W_{xy} \\ W_{yx} & W_{yy} \end{bmatrix} \quad (\text{D.3})$$

where the elements of  $\mathbf{W}$  are:

$$W_{xx} = \frac{1}{J-1} \sum_{j=1}^J (F_{xj} - \bar{F}_x)^2 \quad (\text{D.4})$$

$$W_{yy} = \frac{1}{J-1} \sum_{j=1}^J (F_{yj} - \bar{F}_y)^2 \quad (\text{D.5})$$

$$W_{xy} = W_{yx} = \frac{1}{J-1} \sum_{j=1}^J (F_{xj} - \bar{F}_x)(F_{yj} - \bar{F}_y) \quad (\text{D.6})$$

Thus the diagonal elements  $W_{xx}$  and  $W_{yy}$  are the intra-component variances (i.e. squared

standard deviations), and the off-diagonal elements  $W_{xy}$  and  $W_{yx}$  are the inter-component covariances between  $F_x$  and  $F_y$  over multiple responses. Importantly, changes in  $F_x$  and  $F_y$  are completely uncorrelated if and only if  $W_{xy}=0$ .

One contention of this paper is that separate (univariate) analysis of  $F_x$  and  $F_y$  is biased when testing non-directed hypotheses. The main reason is that  $F_x$  analysis considers only  $W_{xx}$  and  $F_y$  analysis considers only  $W_{yy}$ . This is equivalent to assuming  $W_{xy}=0$ , an assumption which may not be valid (Appendix B).

A geometric interpretation of  $\mathbf{W}$  is useful both for visualizing vector variance (Fig.S3) and for appreciating canonical correlation analysis (Appendix E). Consider that  $\mathbf{W}$  represents an ellipse whose geometry is defined by the solutions to the eigenvalue problem:

$$\mathbf{W}\mathbf{v} = \lambda\mathbf{v} \tag{D.7}$$

Here  $\mathbf{v}$  and  $\lambda$  are the eigenvectors and eigenvalues, respectively, and there are two unique eigensolutions unless both  $(W_{xx} = W_{yy})$  and  $(W_{xy} = 0)$ , in which case there is only one eigensolution and  $\mathbf{W}$  represents a circle. When there are two solutions the eigenvectors represent the ellipse axes (or equivalently: principal axes), and the eigenvalues represent the axes' lengths (or variance in the direction of the principal axes). An equivalent interpretation is that one eigenvector of  $\mathbf{W}$  represents the direction of maximum variance within the dataset. This means that we can rotate our original coordinate system  $xy$  to a new coordinate system  $x'y'$  so that variance along the new  $x'$  axis is the maximum possible variance obtainable for all possible  $x'$ .