

Question 1

Consider the two points

$$x = \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix}, x' = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

- (a) What is the L_2 distance between them
- (b) What is the L_1 distance between them
- (c) What is the L_∞ distance between them

Solution (a)

The L_2 distance is defined as:

$$L_2 = \sqrt{\sum_{i=1}^n (x_i - x'_i)^2}$$

Let, $n = 4$, $x_1 = -1$, $x_2 = 1$, $x_3 = -1$, $x_4 = 1$, $x'_1 = 1$, $x'_2 = 1$, $x'_3 = 1$, $x'_4 = 1$.

Use the L_2 equation and do the following:

- substitute n , expand the summation and substitute values for x_1, \dots, x'_4

$$L_2 = \sqrt{((-1 - 1)^2 + (1 - 1)^2 + (-1 - 1)^2 + (1 - 1)^2)}$$

$$L_2 = \sqrt{((-2)^2 + (0)^2 + (-2)^2 + (0)^2)}$$

$$L_2 = \sqrt{(4 + 4)}$$

$$L_2 = \sqrt{(8)}$$

\therefore the L_2 distance between x and x' is $\sqrt{8}$.

Solution (b)

The L_1 distance is defined as:

$$L_1 = \sum_{i=1}^n |x_i - x'_i|$$

Let, $n = 4$, $x_1 = -1$, $x_2 = 1$, $x_3 = -1$, $x_4 = 1$, $x'_1 = 1$, $x'_2 = 1$, $x'_3 = 1$, $x'_4 = 1$.

Use the L_1 equation and do the following:

- substitute n , expand the summation and substitute values for x_1, \dots, x'_4

$$L_1 = |(-1 - 1)| + |(1 - 1)| + |(-1 - 1)| + |(1 - 1)|$$

$$L_1 = |(-2)| + |(0)| + |(-2)| + |(0)|$$

$$L_1 = 2 + 0 + 2 + 0$$

$$L_1 = 4$$

\therefore the L_1 distance between x and x' is 4.

Solution (c)

The L_∞ distance is defined as:

$$L_\infty = \max_{i=1,2,\dots,n} |x_i - x'_i|$$

Let, $n = 4$, $x_1 = -1$, $x_2 = 1$, $x_3 = -1$, $x_4 = 1$, $x'_1 = 1$, $x'_2 = 1$, $x'_3 = 1$, $x'_4 = 1$.

Use the L_∞ equation and do the following:

- calculate the absolute differences for each component and find the maximum

$$L_\infty = \max\{|(-1 - 1)|, |(1 - 1)|, |(-1 - 1)|, |(1 - 1)|\}$$

$$L_\infty = \max\{|(-2)|, |(0)|, |(-2)|, |(0)|\}$$

$$L_\infty = \max\{2, 0, 2, 0\}$$

$$L_\infty = 2$$

\therefore the L_∞ distance between x and x' is 2.

Question 2

For the point $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \in \mathbb{R}^3$, compute the following

- (a) $\|x\|_1$
- (b) $\|x\|_2$
- (c) $\|x\|_\infty$

Solution (a)

The L_1 is defined as:

$$\|x\|_1 = \sum_{i=1}^n |x_i|$$

Let, $n = 3$, $x_1 = 1$, $x_2 = 2$, $x_3 = 3$

Use the L_1 equation and do the following:

- substitute n , expand the summation and substitute values for x_1 , x_2 , x_3

$$\|x\|_1 = \sum_{i=1}^3 |x_i|$$

$$\|x\|_1 = |1| + |2| + |3|$$

$$\|x\|_1 = 6$$

\therefore the L_1 norm of the vector x is 6.

Solution (b)

The L_2 is defined as:

$$\|x\|_2 = \sqrt{\sum_{i=1}^n x_i^2}$$

Let, $n = 3$, $x_1 = 1$, $x_2 = 2$, $x_3 = 3$

Use the L_2 equation and do the following:

- substitute n , expand the summation and substitute values for x_1 , x_2 , x_3

$$\|x\|_2 = \sqrt{\sum_{i=1}^3 x_i^2}$$

$$\|x\|_2 = \sqrt{1^2 + 2^2 + 3^2}$$

$$\|x\|_2 = \sqrt{1 + 4 + 9}$$

$$\|x\|_2 = \sqrt{14}$$

\therefore the L_2 norm of the vector x is $\sqrt{14}$.

Solution (c)

The L_∞ is defined as:

$$\|x\|_\infty = \max_{i=1,2,\dots,n} |x_i|$$

Let, $n = 3$, $x_1 = 1$, $x_2 = 2$, $x_3 = 3$

Use the L_∞ equation and do the following:

- substitute n , find the maximum absolute value among x_1 , x_2 , x_3

$$\|x\|_\infty = \max_{i=1,2,3} |x_i|$$

$$\|x\|_\infty = \max\{|1|, |2|, |3|\}$$

$$\|x\|_\infty = \max\{1, 2, 3\}$$

$$\|x\|_\infty = 3$$

\therefore the L_∞ norm of the vector x is 3.

Question 3

The following table specifies a distance on the space $\chi = \{A, B, C, D\}$. Is this a metric? Justify your answer.

	A	B	C	D
A	0	2	1	5
B	2	0	4	3
C	1	4	0	2
D	5	3	2	0

Table 1: Table that specifies a distance function for χ

Solution

To determine if the given distance function is a metric, it needs to satisfy the properties of a metric.

The four properties of a metric are:

1. **Non-negativity:** $d(x, y) \geq 0$ for all $x, y \in \chi$
2. **Identity of Indiscernibles:** $d(x, y) = 0$ if and only if $x = y$
3. **Symmetry:** $d(x, y) = d(y, x)$ for all $x, y \in \chi$
4. **Triangle Inequality:** $d(x, z) \leq d(x, y) + d(y, z)$ for all $x, y, z \in \chi$

Check the first property, Non-negativity.

$$0, 2, 1, 5, 2, 0, 4, 3, 1, 4, 0, 2, 5, 3, 2, 0 \geq 0$$

Hence, all values are all non-negative and the first property is satisfied.

Now, check the second property, Identity of Indiscernibles.

The diagonal elements are (A, A) , (B, B) , (C, C) , and (D, D) .

$$d(A, A) = 0, d(B, B) = 0, d(C, C) = 0, d(D, D) = 0$$

Hence, all diagonal elements are zero and the second property is satisfied.

Next, check the third property, Symmetry.

The symmetry elements are: (A, B) and (B, A) ; (A, C) and (C, A) ; (A, D) and (D, A) ; (B, C) and (C, B) ; (B, D) and (D, B) ; (C, D) and (D, C) .

$d(x, y)$	$d(y, x)$	Distance
$d(A, B)$	$d(B, A)$	2
$d(A, C)$	$d(C, A)$	1
$d(A, D)$	$d(D, A)$	5
$d(B, C)$	$d(C, B)$	4
$d(B, D)$	$d(D, B)$	3
$d(C, D)$	$d(D, C)$	2

Table 2: Table that compares distance for $d(x, y)$ and $d(y, x)$ for χ .

Hence, all symmetry elements are equal and the third property is satisfied

Lastly, check the fourth property, Triangle Inequality.

Check if $d(x, z) \leq d(x, y) + d(y, z)$ for all possible combinations of x , y , and z .

Let $x = A$, $y = B$ and $z = C$

Substitute, x , y , z into the triangle inequality and evaluate using *Table 2*:

$$d(A, C) \leq d(A, B) + d(B, C) \rightarrow 1 \leq 2 + 4 \rightarrow 1 \leq 6$$

Hence, the Triangle Inequality holds for $x = A$, $y = B$ and $z = C$

Let $x = A$, $y = C$ and $z = D$

Substitute, x , y , z into the triangle inequality and evaluate using *Table 2*:

$$d(A, D) \leq d(A, C) + d(C, D) \rightarrow 5 \leq 1 + 2 \rightarrow 5 \not\leq 3$$

Hence, for $x = A$, $y = C$ and $z = D$ the Triangle Inequality is not satisfied.

\therefore a distance on the space χ is not a metric

Question 4

The following vectors p and q specify probability distributions over a set of five outcomes. What is the KL divergence between them, $K(p, q)$

$$p = \left[\frac{1}{2}, \frac{1}{4}, \frac{1}{8}, \frac{1}{16}, \frac{1}{16}\right], q = \left[\frac{1}{4}, \frac{1}{4}, \frac{1}{6}, \frac{1}{6}, \frac{1}{6}\right]$$

Solution

The Kullback-Leibler (KL) divergence is defined as:

$$K(p, q) = \sum_{i=1}^n p_i \log \left(\frac{p_i}{q_i} \right)$$

Let $n = 5$,

$$p_1 = \frac{1}{2}, p_2 = \frac{1}{4}, p_3 = \frac{1}{8}, p_4 = \frac{1}{16}, p_5 = \frac{1}{16}$$

$$q_1 = \frac{1}{4}, q_2 = \frac{1}{4}, q_3 = \frac{1}{6}, q_4 = \frac{1}{6}, q_5 = \frac{1}{6}$$

- substitute n , expand the summation and substitute values for p_1, \dots, q_5 in the KL divergence equation

$$K(p, q) = \sum_{i=1}^5 p_i \log \left(\frac{p_i}{q_i} \right)$$

$$K(p, q) = p_1 \log \left(\frac{p_1}{q_1} \right) + p_2 \log \left(\frac{p_2}{q_2} \right) + p_3 \log \left(\frac{p_3}{q_3} \right) + p_4 \log \left(\frac{p_4}{q_4} \right) + p_5 \log \left(\frac{p_5}{q_5} \right)$$

$$K(p, q) = \frac{1}{2} \log \left(\frac{\frac{1}{2}}{\frac{1}{4}} \right) + \frac{1}{4} \log \left(\frac{\frac{1}{4}}{\frac{1}{4}} \right) + \frac{1}{8} \log \left(\frac{\frac{1}{8}}{\frac{1}{6}} \right) + \frac{1}{16} \log \left(\frac{\frac{1}{16}}{\frac{1}{6}} \right) + \frac{1}{16} \log \left(\frac{\frac{1}{16}}{\frac{1}{6}} \right)$$

$$K(p, q) = \frac{1}{2} \log(2) + \frac{1}{4} \log(1) + \frac{1}{8} \log \left(\frac{3}{4} \right) + \frac{1}{16} \log \left(\frac{3}{8} \right) + \frac{1}{16} \log \left(\frac{3}{8} \right)$$

$$K(p, q) \approx 0.082$$

\therefore the KL divergence between p and q is approximately 0.082

Question 5

For each of the following prediction tasks, state whether it is best thought of as a classification problem or a regression problem.

- (a) Based on sensors in a person's cell phone, predict whether they are walking, sitting, or running.
- (b) Based on sensors in a moving car, predict the speed of the car directly in front.
- (c) Based on a student's high-school SAT score, predict their GPA during freshman year of college.
- (d) Based on a student's high-school SAT score, predict whether or not they will complete college.

Solution (a)

We are attempting to predict a categorical variable (walking, sitting, or running).

∴ This is best thought as a classification problem.

Solution (b)

We are attempting to predict a continuous numerical variable (speed of a car).

∴ This is best thought as a regression problem.

Solution (c)

We are attempting to predict a continuous numerical variable (GPA).

∴ This is best thought as a regression problem.

Solution (d)

We are attempting to predict a categorical variable (pass or not pass).

∴ This is best thought as a classification problem.

Question 6

Variance examples. In each of the following cases, compute the variance.

- (a) X takes on values -1 and 1 with equal probability.
- (b) X always takes on same value.
- (c) $X \in \{0, 1\}$ and X is 1 with probability $\frac{1}{4}$.

Solution (a)

The variance of a random variable X is defined as:

$$\text{Var}(X) = E[(X - \mu)^2] = E[X^2] - (E[X])^2$$

- $E[X]$ is the expected value (mean) of X
- $\mu = E[X]$

Since the random variable X takes on values -1 or 1 with equal probability, the probability is 0.50 or $\frac{1}{2}$.

Let $n = 2$, $x_1 = -1$, $x_2 = 1$, $P(X = x_1) = \frac{1}{2}$, $P(X = x_2) = \frac{1}{2}$.

Calculate the expected value $E[X]$.

$$E[X] = \sum_{i=1}^n x_i P(X = x_i)$$

Substitute n , x_1 , x_2 , $P(X = x_1)$, $\frac{1}{2}$, $P(X = x_2)$ and expand summation.

$$E[X] = \sum_{i=1}^2 x_i \cdot P(X = x_i) = (-1) \cdot \frac{1}{2} + (1) \cdot \frac{1}{2} = -\frac{1}{2} + \frac{1}{2} = 0$$

Calculate $E[X^2]$.

Substitute n , x_1 , x_2 , $P(X = x_1)$, $\frac{1}{2}$, $P(X = x_2)$ and expand summation.

$$E[X^2] = \sum_{i=1}^2 x_i^2 \cdot P(X = x_i) = (-1)^2 \cdot \frac{1}{2} + (1)^2 \cdot \frac{1}{2} = \frac{1}{2} + \frac{1}{2} = 1$$

Calculate the variance.

Substitute $E[X^2]$ and $E[X]$ into the variance equation.

$$\text{Var}(X) = E[X^2] - (E[X])^2 = 1 - (0)^2 = 1 - 0 = 1$$

\therefore the variance of X is 1.

Solution (b)

The variance of a random variable X is defined as:

$$\text{Var}(X) = E[(X - \mu)^2] = E[X^2] - (E[X])^2$$

- $E[X]$ is the expected value (mean) of X
- $\mu = E[X]$

Since the random variable X always takes on the same value, $\exists x \in \mathbb{R}$ such that $P(X = x) = 1$. Calculate the expected value $E[X]$.

$$E[X] = \sum_{i=1}^n x_i P(X = x_i)$$

Substitute $n = 1$, $x_1 = x$, $P(X = x_1) = 1$ and expand summation.

$$E[X] = \sum_{i=1}^1 x_i \cdot P(X = x_i) = (x) \cdot 1 = x$$

Calculate $E[X^2]$.

Substitute $n = 1$, $x_1 = x$, $P(X = x_1) = 1$ and expand summation.

$$E[X^2] = \sum_{i=1}^1 x_i^2 \cdot P(X = x_i) = (x)^2 \cdot 1 = x^2$$

Calculate the variance.

Substitute $E[X^2]$ and $E[X]$ into the variance equation.

$$\text{Var}(X) = E[X^2] - (E[X])^2 = x^2 - x^2 = 0$$

\therefore the variance of X is 0.

Solution (c)

The variance of a random variable X is defined as:

$$\text{Var}(X) = E[(X - \mu)^2] = E[X^2] - (E[X])^2$$

- $E[X]$ is the expected value (mean) of X
- $\mu = E[X]$

Let $n = 2$, $x_1 = 1$, $x_2 = 0$, $P(X = x_1) = \frac{1}{4}$, $P(X = x_2) = \frac{3}{4}$.

Calculate the expected value $E[X]$.

$$E[X] = \sum_{i=1}^n x_i P(X = x_i)$$

Substitute n , x_1 , x_2 , $P(X = x_1)$, $P(X = x_2)$ and expand summation.

$$E[X] = \sum_{i=1}^2 x_i \cdot P(X = x_i) = (1) \cdot \frac{1}{4} + (0) \cdot \frac{3}{4} = \frac{1}{4}$$

Calculate $E[X^2]$.

Substitute n , x_1 , x_2 , $P(X = x_1)$, $P(X = x_2)$ and expand summation.

$$E[X^2] = \sum_{i=1}^2 x_i^2 \cdot P(X = x_i) = (1)^2 \cdot \frac{1}{4} + (0)^2 \cdot \frac{3}{4} = \frac{1}{4}$$

Calculate the variance.

Substitute $E[X^2]$ and $E[X]$ into the variance equation.

$$\text{Var}(X) = E[X^2] - (E[X])^2 = \frac{1}{4} - \left(\frac{1}{4}\right)^2 = \frac{1}{4} - \frac{1}{16} = \frac{3}{16}$$

\therefore the variance of X is $\frac{3}{16}$.

Question 7

Independence and uncorrelatedness. Random variables X ; Y take on values in the range $\{-1, 0, 1\}$ and have the following joint distribution.

$(X \downarrow, Y \rightarrow)$	-1	0	1
-1	0	0	1/3
0	0	1/3	0
1	1/3	0	0

Table 3: Joint distribution for random variables X and Y .

(a) What is the covariance between X and Y ?

(b) What is the correlation between X and Y ?

Solution (a)

Covariance for random variables A and B is defined as:

$$\text{Cov}(A, B) = E[AB] - E[A]E[B]$$

The expected value of a random variable A is defined as:

$$E[A] = \sum_{i=1}^n a_i P(A)$$

The expected value of AB where A and B are random variables is defined as:

$$E[AB] = \sum_{a \in \{-1, 0, 1\}} \sum_{b \in \{-1, 0, 1\}} ab \cdot P(A = a, B = b)$$

Calculate the expected value $E[X]$.

Let $x_1 = -1$, $x_2 = 0$, $x_3 = 1$, and $P(X = -1) = P(X = 0) = P(X = 1) = \frac{1}{3}$.

$$E[X] = (-1) \cdot P(X = -1) + (0) \cdot P(X = 0) + (1) \cdot P(X = 1)$$

$$E[X] = (-1) \cdot \frac{1}{3} + (0) \cdot \frac{1}{3} + (1) \cdot \frac{1}{3}$$

$$E[X] = -\frac{1}{3} + 0 + \frac{1}{3}$$

$$E[X] = 0$$

Calculate the expected value $E[Y]$.

Let $y_1 = -1$, $y_2 = 0$, $y_3 = 1$, and $P(Y = -1) = P(Y = 0) = P(Y = 1) = \frac{1}{3}$.

$$E[Y] = (-1) \cdot P(Y = -1) + (0) \cdot P(Y = 0) + (1) \cdot P(Y = 1)$$

$$E[Y] = (-1) \cdot \frac{1}{3} + (0) \cdot \frac{1}{3} + (1) \cdot \frac{1}{3}$$

$$E[Y] = -\frac{1}{3} + 0 + \frac{1}{3}$$

$$E[Y] = 0$$

Calculate the expected value $E[XY]$.

- Since we have a diagonal matrix our $E[XY]$ equation becomes the following:

$$E[XY] = x_1y_1 \cdot P(X = -1, Y = 1) + x_2y_2 \cdot P(X = 0, Y = 0) + x_3y_3 \cdot P(X = 1, Y = 1)$$

$$E[XY] = (-1)(1) \cdot \frac{1}{3} + (0)(0) \cdot \frac{1}{3} + (1)(-1) \cdot \frac{1}{3}$$

$$E[XY] = -\frac{1}{3} + 0 - \frac{1}{3}$$

$$E[XY] = -\frac{2}{3}$$

Calculate the covariance.

Substitute $E[XY]$, $E[X]$ and $E[Y]$ into the covariance equation.

$$Cov(X, Y) = E[XY] - E[X]E[Y] = -\frac{2}{3} - (0)(0) = -\frac{2}{3}$$

\therefore the covariance between X and Y is $-\frac{2}{3}$.

Solution (b)

Correlation for random variables A and B is defined as:

$$Corr(A, B) = \frac{Cov(A, B)}{\sqrt{Var(A) \cdot Var(B)}}$$

The variance of a random variable A is defined as:

$$Var(A) = E[A^2] - (E[A])^2$$

From part (a), we know that $Cov(X, Y) = -\frac{2}{3}$ and $E[X] = E[Y] = 0$.

Calculate the variance of X .

First, calculate $E[X^2]$.

$$E[X^2] = (-1)^2 \cdot P(X = -1) + (0)^2 \cdot P(X = 0) + (1)^2 \cdot P(X = 1)$$

$$E[X^2] = (1) \cdot \frac{1}{3} + (0) \cdot \frac{1}{3} + (1) \cdot \frac{1}{3}$$

$$E[X^2] = \frac{1}{3} + 0 + \frac{1}{3}$$

$$E[X^2] = \frac{2}{3}$$

Now, calculate $Var(X)$.

$$Var(X) = E[X^2] - (E[X])^2 = \frac{2}{3} - (0)^2 = \frac{2}{3}$$

Calculate the variance of Y .

First, calculate $E[Y^2]$.

$$E[Y^2] = (-1)^2 \cdot P(Y = -1) + (0)^2 \cdot P(Y = 0) + (1)^2 \cdot P(Y = 1)$$

$$E[Y^2] = (1) \cdot \frac{1}{3} + (0) \cdot \frac{1}{3} + (1) \cdot \frac{1}{3}$$

$$E[Y^2] = \frac{1}{3} + 0 + \frac{1}{3}$$

$$E[Y^2] = \frac{2}{3}$$

Now, calculate $Var(Y)$.

$$Var(Y) = E[Y^2] - (E[Y])^2 = \frac{2}{3} - (0)^2 = \frac{2}{3}$$

Calculate the correlation.

Substitute $Cov(X, Y)$, $Var(X)$, and $Var(Y)$ into the correlation equation.

$$Corr(X, Y) = \frac{Cov(X, Y)}{\sqrt{Var(X) \cdot Var(Y)}} = \frac{-\frac{2}{3}}{\sqrt{\frac{2}{3} \cdot \frac{2}{3}}} = \frac{-\frac{2}{3}}{\sqrt{\frac{4}{9}}} = \frac{-\frac{2}{3}}{\frac{2}{3}} = -1$$

\therefore the correlation between X and Y is -1 .

Question 8

Independence and uncorrelatedness. Random variables X ; Y take on values in the range $\{-1, 0, 1\}$ and have the following joint distribution.

$(X \downarrow, Y \rightarrow)$	-1	0	1
-1	1/6	0	1/6
0	0	1/3	0
1	1/6	0	1/6

Table 4: Joint distribution for random variables X and Y .

(a) Are X and Y independent?

(b) Are X and Y uncorrelated?

Solution (a)

Two random variables A and B are independent if:

$$P(A, B) = P(A) \cdot P(B)$$

Calculate probabilities $P(X = x)$ from Table 4.

$$P(X = -1) = P(X = -1, Y = -1) + P(X = -1, Y = 0) + P(X = -1, Y = 1)$$

$$P(X = -1) = \frac{1}{6} + 0 + \frac{1}{6}$$

$$P(X = -1) = \frac{1}{3}$$

$$P(X = 0) = P(X = 0, Y = -1) + P(X = 0, Y = 0) + P(X = 0, Y = 1)$$

$$P(X = 0) = 0 + \frac{1}{3} + 0$$

$$P(X = 0) = \frac{1}{3}$$

$$P(X = 1) = P(X = 1, Y = -1) + P(X = 1, Y = 0) + P(X = 1, Y = 1)$$

$$P(X = 1) = \frac{1}{6} + 0 + \frac{1}{6}$$

$$P(X = 1) = \frac{1}{3}$$

Calculate probabilities $P(Y = y)$ from Table 4.

$$P(Y = -1) = P(X = -1, Y = -1) + P(X = 0, Y = -1) + P(X = 1, Y = -1)$$

$$P(Y = -1) = \frac{1}{6} + 0 + \frac{1}{6}$$

$$P(Y = -1) = \frac{1}{3}$$

$$P(Y = 0) = P(X = -1, Y = 0) + P(X = 0, Y = 0) + P(X = 1, Y = 0)$$

$$P(Y = 0) = 0 + \frac{1}{3} + 0$$

$$P(Y = 0) = \frac{1}{3}$$

$$P(Y = 1) = P(X = -1, Y = 1) + P(X = 0, Y = 1) + P(X = 1, Y = 1)$$

$$P(Y = 1) = \frac{1}{6} + 0 + \frac{1}{6} = \frac{1}{3}$$

$$P(Y = 1) = \frac{1}{3}$$

Check if $P(X, Y) = P(X) \cdot P(Y)$ for all combinations:

For $(X = -1, Y = -1)$:

$$P(X = -1, Y = -1) = \frac{1}{6}$$

$$P(X = -1) \cdot P(Y = -1) = \frac{1}{3} \cdot \frac{1}{3} = \frac{1}{9}$$

$$\frac{1}{6} \neq \frac{1}{9} \rightarrow P(X = -1, Y = -1) \neq P(X = -1) \cdot P(Y = -1)$$

$\therefore X$ and Y are not independent.

Solution (b)

Two random variables A and B are uncorrelated if and only if their covariance is zero:

$$\text{Cov}(A, B) = 0$$

The covariance between A and B is defined as:

$$\text{Cov}(A, B) = E[AB] - E[A]E[B]$$

Calculate the expected value $E[X]$.

$$E[X] = \sum_{x \in P(X)} x \cdot P(X = x)$$

$$E[X] = (-1) \cdot \frac{1}{3} + (0) \cdot \frac{1}{3} + (1) \cdot \frac{1}{3}$$

$$E[X] = -\frac{1}{3} + 0 + \frac{1}{3}$$

$$E[X] = 0$$

Calculate the expected value $E[Y]$.

$$E[Y] = \sum_{y \in P(Y)} y \cdot P(Y = y)$$

$$E[Y] = (-1) \cdot \frac{1}{3} + (0) \cdot \frac{1}{3} + (1) \cdot \frac{1}{3}$$

$$E[Y] = -\frac{1}{3} + 0 + \frac{1}{3}$$

$$E[Y] = 0$$

Calculate the expected value $E[XY]$.

$$E[XY] = \sum_{x \in P(X)} \sum_{y \in P(Y)} xy \cdot P(X = x, Y = y)$$

$$E[XY] = (-1)(-1) \cdot \frac{1}{6} + (-1)(0) \cdot 0 + (-1)(1) \cdot \frac{1}{6} + (0)(-1) \cdot 0 + (0)(0) \cdot \frac{1}{3} + (0)(1) \cdot 0 + (1)(-1) \cdot \frac{1}{6} + (1)(0) \cdot 0 + (1)(1) \cdot \frac{1}{6}$$

$$E[XY] = \frac{1}{6} + 0 + (-\frac{1}{6}) + 0 + 0 + 0 + (-\frac{1}{6}) + 0 + \frac{1}{6}$$

$$E[XY] = \frac{1}{6} - \frac{1}{6} - \frac{1}{6} + \frac{1}{6}$$

$$E[XY] = 0$$

Calculate the covariance.

$$\text{Cov}(X, Y) = E[XY] - E[X]E[Y] = 0 - (0)(0) = 0$$

Since $\text{Cov}(X, Y) = 0$, the variables X and Y are uncorrelated.

$\therefore X$ and Y are uncorrelated.

Programming Exercises

Before starting on this section, download the archive **hw2.zip** from the course website.

- In these problems, you are asked to perform nearest neighbor classification with different distance functions and to calculate error using a hold-out set or by cross-validation. The code for these tasks is neither lengthy nor complex, so you should be able to write up your own routines. Alternatively, you may invoke modules from **sklearn**.

Question 9

Classifying back injuries. In this problem, you will use nearest neighbor to classify patients' back injuries based on measurements of the shape and orientation of their pelvis and spine. The data set `spine-data.txt` contains information from 310 patients. For each patient, there are: six numeric features (the x) and a label (the y): 'NO' (normal), 'DH' (herniated disk), or 'SL' (spondilololsthesis). We will divide this data into a training set with 250 points and a separate test set of 60 points.

- Make sure you have the data set `spine-data.txt`. You can load it into Python using the following.

```
import numpy as np
# Load data set and code labels as 0 = 'NO', 1 = 'DH', 2 = 'SL'
labels = [b'NO', b'DH', b'SL']
data = np.loadtxt('spine-data.txt', converters={6: lambda s: labels.index(s)})
```
- Split the data into a training set, consisting of the first 250 points, and a test set, consisting of the remaining 60 points.
- Code up a nearest neighbor classifier based on this training set. Try both ℓ_2 and ℓ_1 distance. Recall $x, x' \in \mathbb{R}^d$

$$\|x - x'\|_2 = \sqrt{\sum_{i=1}^d (x_i - x'_i)^2}$$

$$\|x - x'\|_1 = \sum_{i=1}^d |x_i - x'_i|$$

Now do the following exercises, to be turned in.

- What error rates do you get on the test set for each of the two distance functions?
- For each of the two distance functions, give the confusion matrix of the NN classifier. This is a 3×3 table of the form:

	NO	DH	SL
NO			
DH			
SL			

Table 5: he entry at row DH, column SL, for instance, contains the number of test points whose correct label was DH and got classified as SL.

Solution (a)

Python code for nearest neighbor classifier using ℓ_1 , ℓ_2 , and error rates:

```
1  ## import libraries
2  import numpy as np
3
4  ## initialize labels for data
5  data_labels = ['NO', 'DH', 'SL']
6
7  ## load data from spine-data.txt and relabel the 7th column (NO:1, DH:1, SL:2)
8  data = np.loadtxt('spine-data.txt', converters={6: lambda s: data_labels.index(s)})
9
10 ## split data into features and labels
11 features = data[:, :-1]
12 labels = data[:, -1]
13
14 ## split data into training and test sets
15 features_train = features[:250]
16 features_test = features[250:]
17 labels_train = labels[:250]
18 labels_test = labels[250:]
19
20 ## define l1 distance function
21 def l1_distance(x, x_prime):
22     l1_dist = np.sum(np.abs(x - x_prime))
23     return l1_dist
24
25 ## define l2 distance function
26 def l2_distance(x, x_prime):
27     l2_dist = np.sqrt(np.sum((x - x_prime) ** 2))
28     return l2_dist
29
30 ## define nn_classifier function
31 def nn_classifier(features_train, features_test, labels_train, distance_function):
32     """
33     1. loop through each test point in the features_test list
34     2. get the distance between the test point and each training point for every
35        training point
36     3. find the index of the training point with the smallest distance
37     4. use the index to get the label of the training point
38     5. append the label to the predictions list
39     6. return the predictions list
40     """
41     predictions = []
42     for test_point in features_test:
43         distances = [distance_function(test_point, train_point) for train_point in
44                     features_train]
45         nearest_neighbor_index = np.argmin(distances)
46         predictions.append(labels_train[nearest_neighbor_index])
47     predictions = np.array(predictions)
48     return predictions
49
50 ## define error rate function
51 def get_error_rate(predictions, labels):
52     correct = sum(p == l for p, l in zip(predictions, labels))
53     accuracy = correct / len(labels)
54     er = 1 - accuracy
55     return er
56
57 ## evaluate l1 distance classifier and get error rate
58 predictions_l1 = nn_classifier(features_train, features_test, labels_train, l1_distance)
59 error_rate_l1 = get_error_rate(predictions_l1, labels_test)
60
61 ## evaluate l2 distance classifier and get error rate
62 predictions_l2 = nn_classifier(features_train, features_test, labels_train, l2_distance)
63 error_rate_l2 = get_error_rate(predictions_l2, labels_test)
```

\therefore the error rates for the two distance functions are: $ER_{\ell_1} = 0.183$ and $ER_{\ell_2} = 0.117$

Solution (b)

Python code for confusion matrix for nearest neighbor using ℓ_1 , ℓ_2 , and confusion matrix visualization:

Note: Utilize functions and variables defined in **Solution (a)**

```
1  ## define confusion matrix function
2  def get_confusion_matrix(predictions, labels):
3      cm = confusion_matrix(predictions, labels)
4      return cm
5
6  ## visualize confusion matrix function
7  def plot_confusion_matrix(l1_er, cm1, l2_er, cm2, labels):
8      fig, ax = plt.subplots(1, 2, figsize=(10, 8), sharey=True)
9      ax = ax.flatten()
10     sns.heatmap(cm1, annot=True, fmt='d', cmap=sns.color_palette("rocket",
11         as_cmap=True), xticklabels=labels, yticklabels=labels, ax=ax[0])
12     ax[0].set_title(f'L1 Distance Confusion Matrix\nError Rate: {l1_er:.3f}')
13     sns.heatmap(cm2, annot=True, fmt='d', cmap=sns.color_palette("rocket",
14         as_cmap=True), xticklabels=labels, yticklabels=labels, ax=ax[1])
15     ax[1].set_title(f'L2 Distance Confusion Matrix\nError Rate: {l2_er:.3f}')
16     ax[0].set_xlabel('Predicted')
17     ax[1].set_xlabel('Predicted')
18     ax[0].set_ylabel('True')
19     plt.tight_layout()
20     plt.show()
21
22  ## get confusion matrix for l1 and l2 distance classifier
23  cm_l1 = get_confusion_matrix(predictions_l1, labels_test)
24  cm_l2 = get_confusion_matrix(predictions_l2, labels_test)
25
26  ## visualize confusion matrix for l1 and l2 distance classifier
27  plot_confusion_matrix(error_rate_l1, cm_l1, error_rate_l2, cm_l2, data_labels)
```

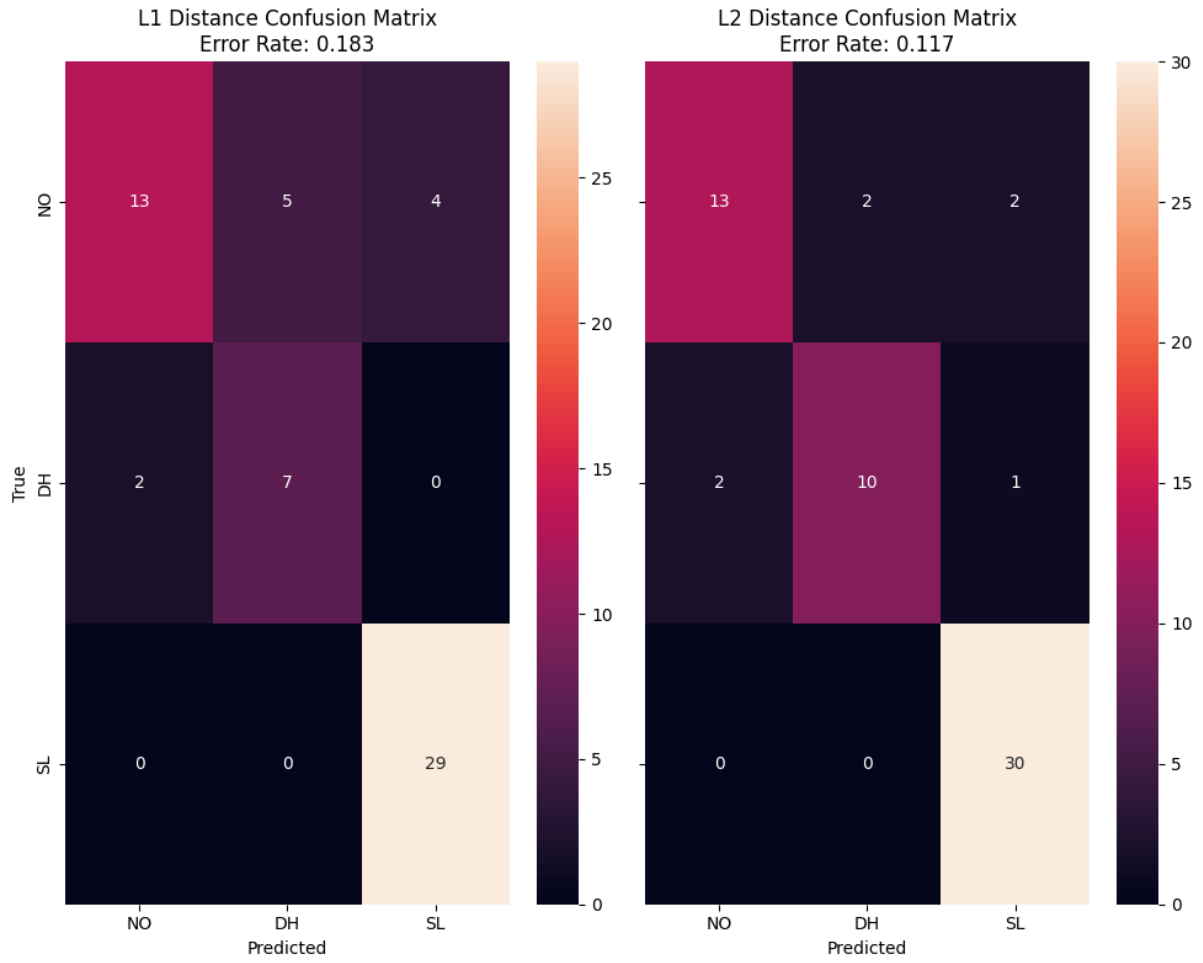


Figure 1: Confusion matrix for ℓ_1 and ℓ_2 nearest neighbor classifiers.

Question 10

Cross-validation for nearest neighbor classification. The wine.data data set is described in detail at:

<https://archive.ics.uci.edu/ml/datasets/wine>

This small data set has 178 observations. Each data point x consists of 13 features that capture visual and chemical properties of a bottle of wine. The label $y \in \{1, 2, 3\}$ indicates which of three wineries the bottle came from. The goal is to use the data to learn a classifier that can predict y from x .

Suppose we use the entire data set of 178 points as the training set for 1-NN classification with Euclidean distance. We would like to estimate the quality of this classifier.

- (a) Use leave-one-out cross-validation (LOOCV) to estimate the accuracy of the classifier and also to estimate the 3×3 confusion matrix.
- (b) Estimate the accuracy of the 1-NN classifier using k -fold cross-validation using 20 different choices of k that are fairly well spread out across the range 2 to 100. Plot these estimates: put k on the horizontal axis and accuracy estimate on the vertical axis.
- (c) The various features in this data set have different ranges. Perhaps it would be better to normalize them so as to equalize their contributions to the distance function. There are many ways to do this; one option is to linearly rescale each coordinate so that the values lie in $[0, 1]$ (i.e. the minimum value on that coordinate maps to 0 and the maximum value maps to 1). Do this, and then re-estimate the accuracy and confusion matrix using LOOCV. Did the normalization help performance?

Solution (a)

Python code for reading wine.DATA, and splitting data

```
1  ## import libraries
2  import numpy as np
3  import seaborn as sns
4  import matplotlib.pyplot as plt
5  import pandas as pd
6  import sklearn
7
8  ## read wine.DATA file
9  df = pd.read_csv('wine.data', header=None)
10
11  ## name columns
12  df.columns = ['Class', 'Alcohol', 'Malic Acid', 'Ash', 'Alcalinity of Ash',
13               'Magnesium', 'Total Phenols', 'Flavanoids', 'Nonflavanoid Phenols',
14               'Proanthocyanins', 'Color Intensity', 'Hue', 'OD280/OD315 of Diluted Wines',
15               'Proline']
16
17  ## define wine labels
18  wine_labels = ['Class 1', 'Class 2', 'Class 3']
19
20  ## split data into features and labels
21  features = df.iloc[:, 1:].values
22  labels = df.iloc[:, 0].values
```

Python code for estimating accuracy and confusion matrix for classifier

```
1  ## initialize 1-NN classifier
2  NN_1 = sklearn.neighbors.KNeighborsClassifier(n_neighbors=1, algorithm='brute',
3        metric='euclidean')
4
5  ## initialize LOOCV
```

```

6 | loocv = sklearn.model_selection.LeaveOneOut()
7 |
8 | ## get predictions from cross-validation
9 | predictions = sklearn.model_selection.cross_val_predict(NN_1, features, labels,
10 |               cv=loocv)
11 | ## estimate accuracy
12 | accuracy = sklearn.metrics.accuracy_score(labels, predictions)
13 | print(f'Accuracy: {accuracy:.3f}')
14 | ## get confusion matrix
15 | cm = sklearn.metrics.confusion_matrix(labels, predictions)
16 |
17 | ## visualize confusion matrix
18 | plt.figure(figsize=(10, 8))
19 | sns.heatmap(cm, annot=True, fmt='d', cmap=sns.color_palette("rocket", as_cmap=True),
20 |             xticklabels=wine_labels, yticklabels=wine_labels)
21 | plt.title(f'Wine Classification Confusion Matrix\n Accuracy: {accuracy:.3f}')
22 | plt.xlabel('Predicted')
23 | plt.ylabel('True')
24 | plt.tight_layout()
25 | plt.show()

```

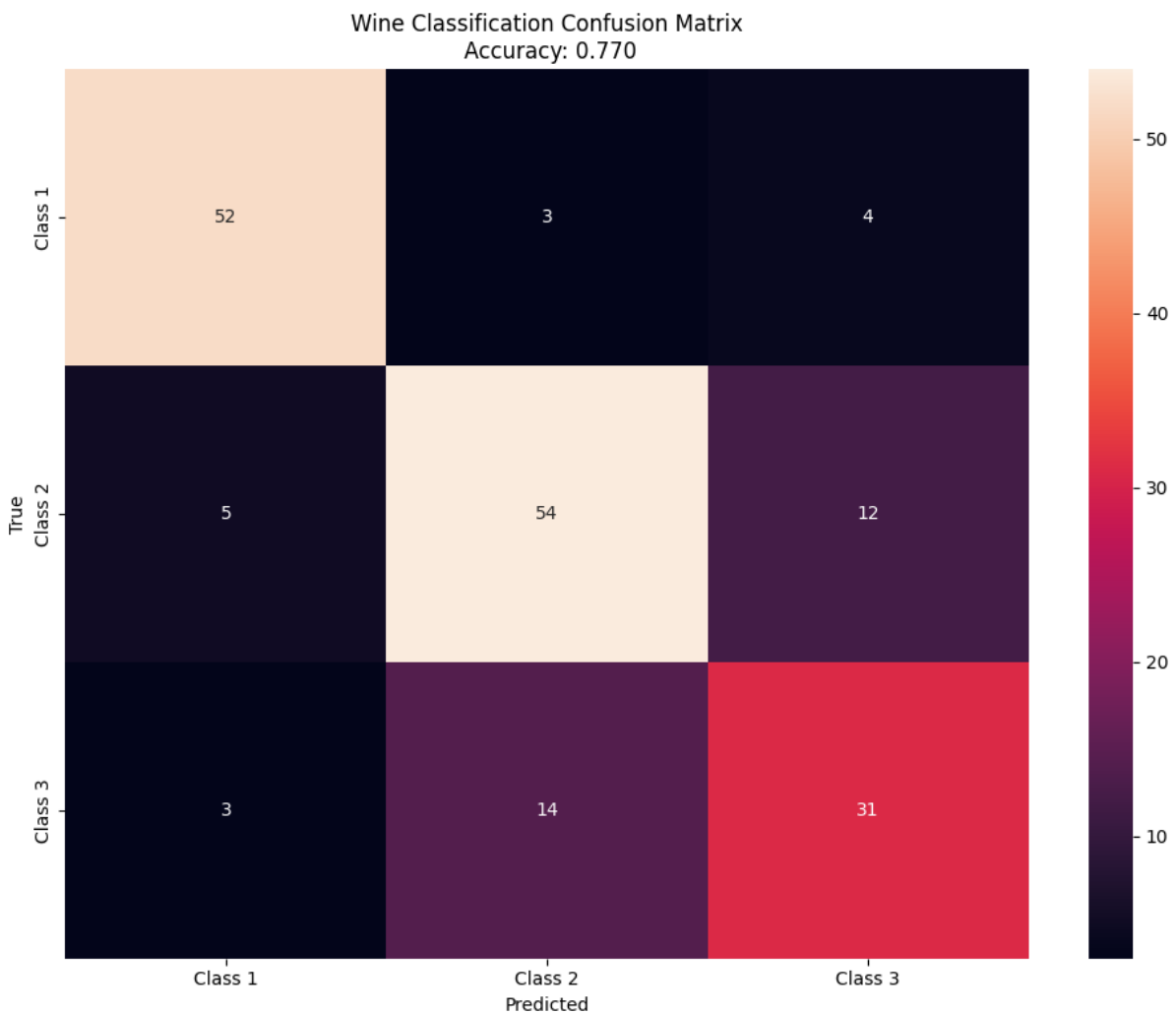


Figure 2: Estimate of confusion matrix using leave-one-out cross-validation (LOOCV) and 1-NN classification with Euclidean distance.

Solution (b)

Python code for estimating accuracy using k-fold cross-validation and visualization of the estimates

```
1  ## initialize k values such that we have 20 k's spread out across the range 2 to 100
2  k_values = np.linspace(2, 100, 20, dtype=int)
3
4  ## initialize accuracy list
5  accuracies = []
6
7  ## perform k-fold cross-validation for each k
8  for k in k_values:
9      cv = sklearn.model_selection.KFold(n_splits=k, shuffle=True, random_state=42)
10     scores = sklearn.model_selection.cross_val_score(NN_1, features, labels, cv=cv)
11     accuracies.append(np.mean(scores))
12
13 ## plot results
14 plt.figure(figsize=(10, 6))
15 plt.plot(k_values, accuracies, marker='o', linestyle='--')
16 plt.xlabel('Number of Folds (k)')
17 plt.ylabel('Accuracy Estimate')
18 plt.title('Accuracy Estimates for Different Values of k in k-Fold Cross-Validation')
19 plt.grid(True)
20 plt.show()
```

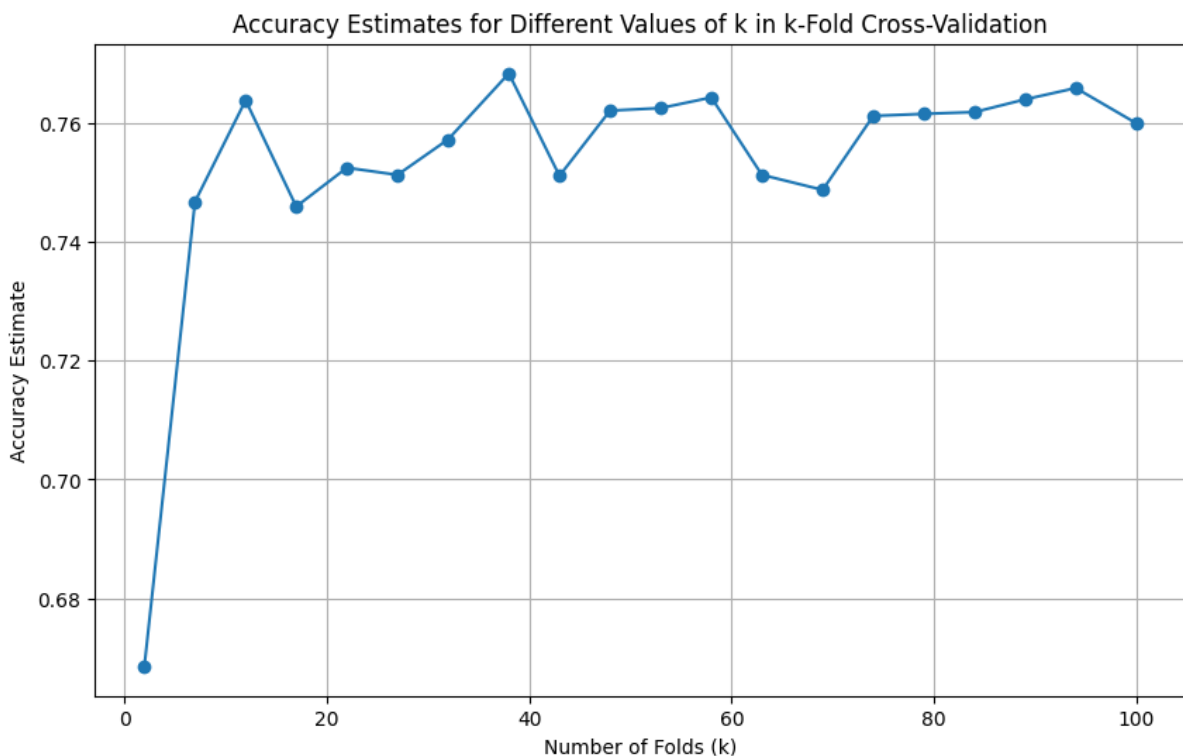


Figure 3: Estimates of k-fold cross validation accuracies.

Solution (c)

Python code for normalizing data and estimating accuracy and confusion matrix using LOOCV

```
1  ## normalize the features
2  norm_features = sklearn.preprocessing.normalize(features,norm='max')
3
4  ## initialize 1-NN classifier
5  NN_1_n = sklearn.neighbors.KNeighborsClassifier(n_neighbors=1, algorithm='brute',
6          metric='euclidean')
7
8  ## initialize LOOCV
9  loocv_n = sklearn.model_selection.LeaveOneOut()
10
11 ## get predictions from cross-validation
12 predictions_n = sklearn.model_selection.cross_val_predict(NN_1_n, norm_features,
13     labels, cv=loocv_n)
14
15 ## estimate accuracy
16 accuracy_n = sklearn.metrics.accuracy_score(labels, predictions_n)
17 print(f'Accuracy: {accuracy:.3f}')
18
19 ## get confusion matrix
20 cm_n = sklearn.metrics.confusion_matrix(labels, predictions_n)
21
22 ## compare confusion matrices
23 def compare_confusion_matrix(acc, cm, acc_norm, cm_n, labels):
24     fig, ax = plt.subplots(1,2,figsize=(10, 8),sharey=True)
25     ax = ax.flatten()
26     sns.heatmap(cm, annot=True, fmt='d', cmap=sns.color_palette("rocket",
27         as_cmap=True), xticklabels=labels, yticklabels=labels, ax=ax[0])
28     ax[0].set_title(f'Part (a) Confusion Matrix\nAccuracy: {acc:.3f}')
29     sns.heatmap(cm_n, annot=True, fmt='d', cmap=sns.color_palette("rocket",
30         as_cmap=True), xticklabels=labels, yticklabels=labels, ax=ax[1])
31     ax[1].set_title(f'Confusion Matrix for Normalized Features\nAccuracy:
32         {acc_norm:.3f}')
33     ax[0].set_xlabel('Predicted')
34     ax[1].set_xlabel('Predicted')
35     ax[0].set_ylabel('True')
36     plt.tight_layout()
37     plt.show()
38
39 compare_confusion_matrix(accuracy, cm, accuracy_n, cm_n, wine_labels)
```

∴ from *Figure 4* normalizing data improved the performance of the classifier.

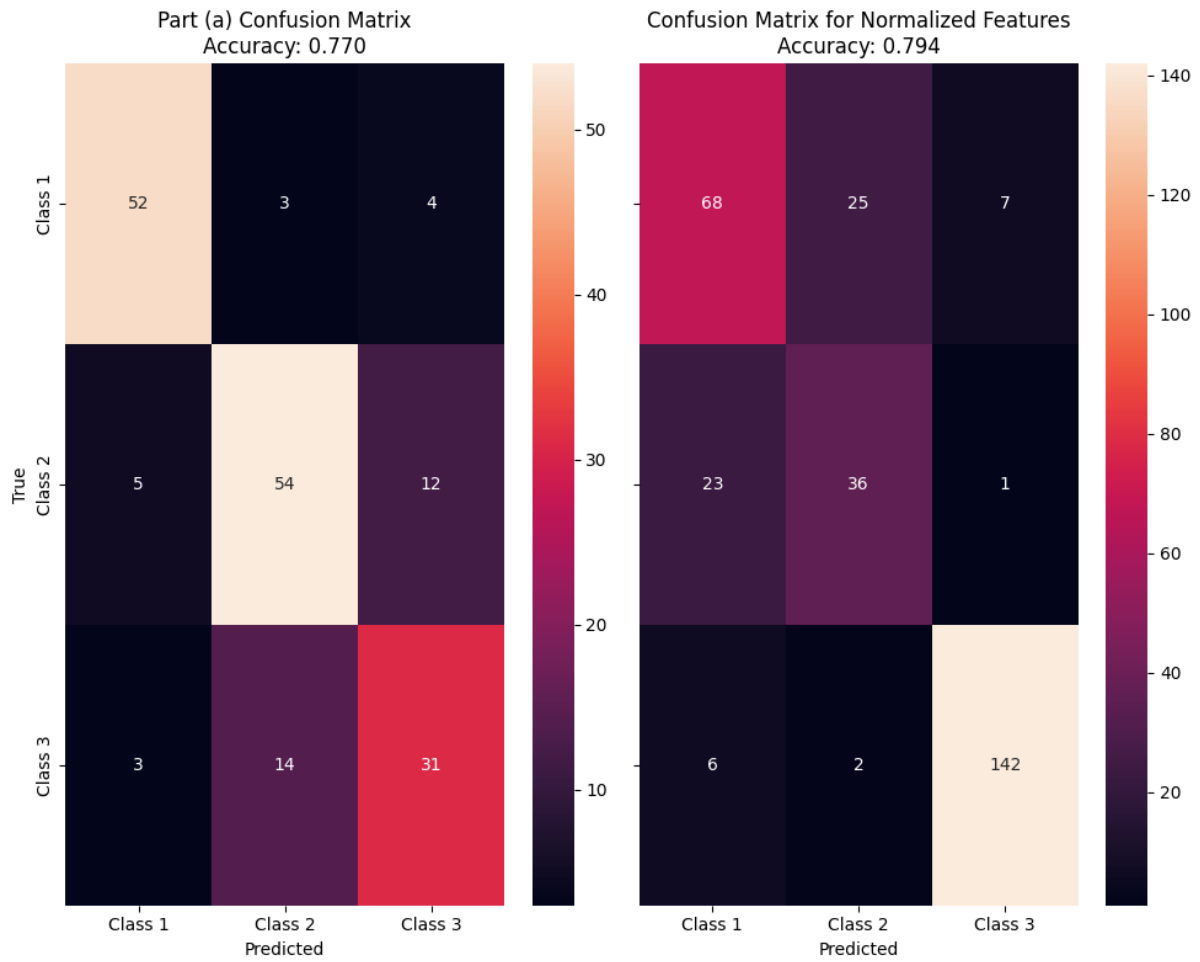


Figure 4: Estimate of confusion matrix for original data and normalized data using leave-one-out cross-validation (LOOCV) and 1-NN classification with Euclidean distance.