DSC 255 - MACHINE LEARNING FUNDAMENTALS

# FEEDFORWARD NEURAL NETS

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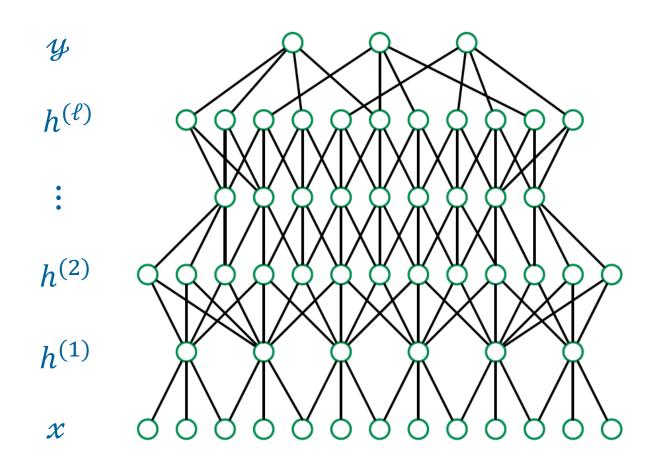


COMPUTER SCIENCE & ENGINEERING

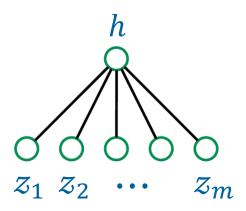
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## **Feedforward Neural Nets**

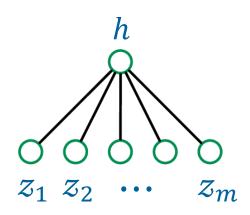


### The Value at a Hidden Unit



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- $h = \sigma(w_1 z_1 + w_2 z_2 + \dots + w_m z_m + b)$
- $\bullet \sigma(\cdot)$  is a nonlinear **activation function**, e.g., "rectified linear"

$$\sigma(u) = \begin{cases} u & \text{if } u \ge 0 \\ 0 & \text{otherwise} \end{cases}$$

#### **Common Activation Functions**

Threshold function or Heaviside step function

$$\sigma(z) = \begin{cases} 1 & \text{if } z > 0 \\ 0 & \text{otherwise} \end{cases}$$

Sigmoid

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

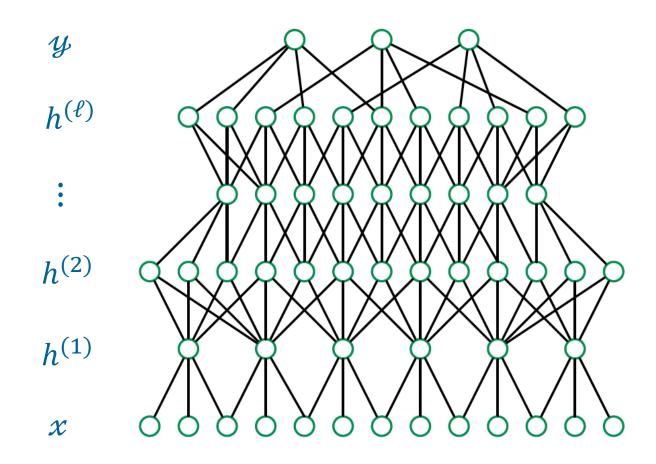
Hyperbolic tangent

$$\sigma(z) = \tanh(z)$$

ReLU (rectified linear unit)

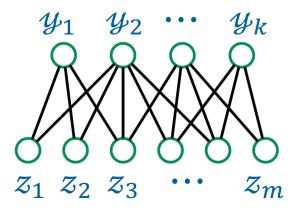
$$\sigma(z) = \max(0, z)$$

## Why do we Need Nonlinear Activation Functions?



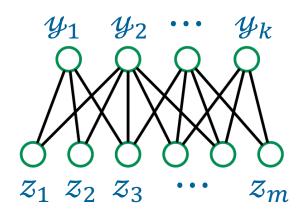
#### **The Output Layer**

Classification with k labels: want k probabilities summing to 1.



#### The Output Layer

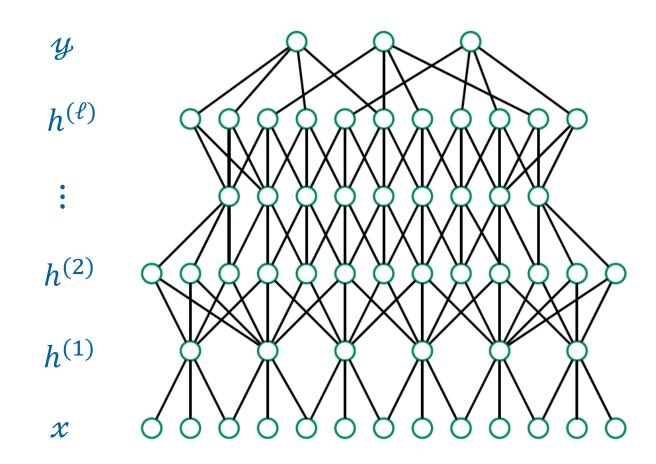
Classification with k labels: want k probabilities summing to 1.



- $y_1, ..., y_k$  are linear functions of the parent nodes  $z_i$ .
- Get probabilities using softmax:

$$\Pr(label j) = \frac{e^{y_j}}{e^{y_1} + \dots + e^{y_k}}$$

# The Complexity



#### **Approximation Capability**

Let  $f: \mathbb{R}^d \to \mathbb{R}$  be any continuous function. There is a neural net with one hidden layer that approximates f arbitrarily well.

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■ The hidden layer may need a lot of nodes.

- The benefit of depth: for certain classes of functions, you need:
  - > Either: one hidden layer of enormous size
  - > Or: multiple hidden layers of moderate size