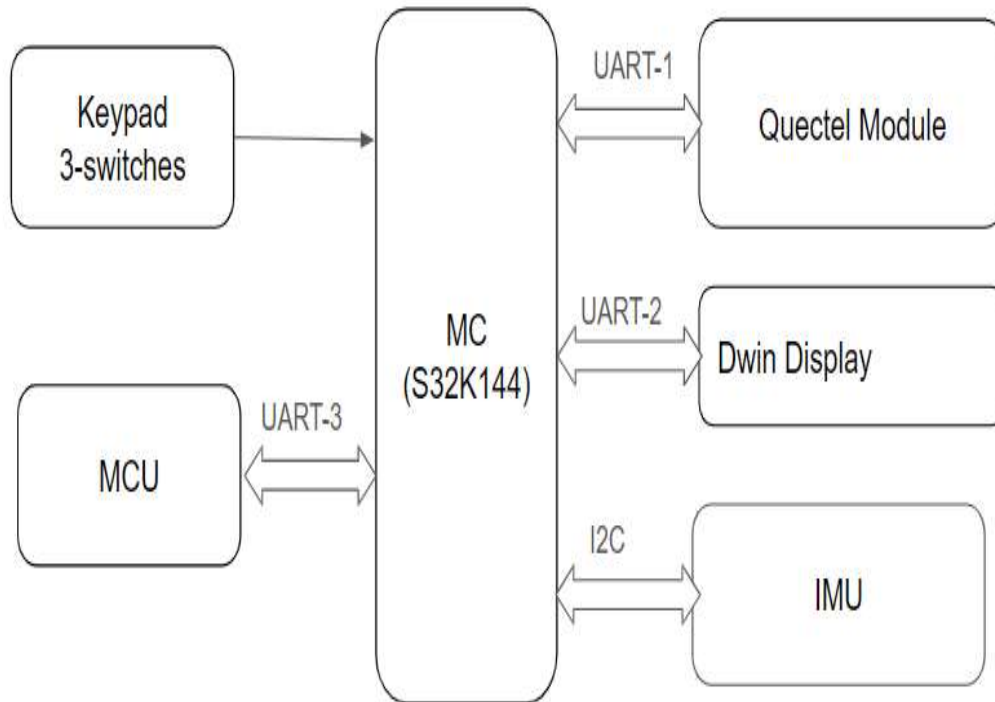


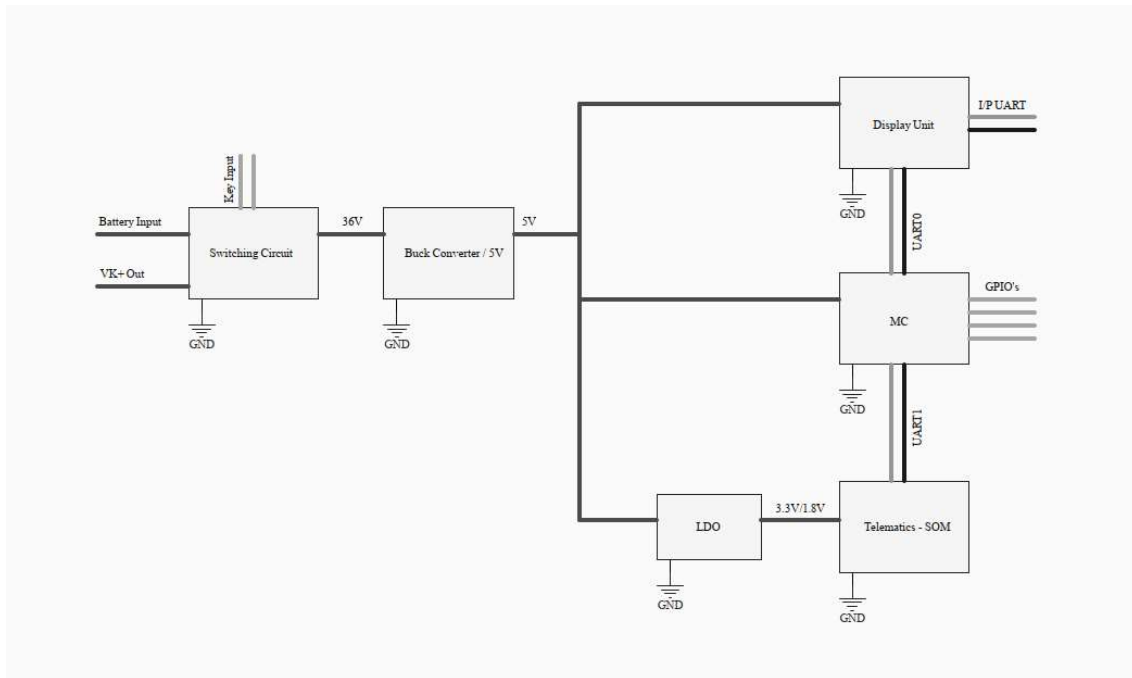
## Amigo Scope of work

Date : 8/05/2024

**Scope :** Developing the display which communicates with the Emotorad MCU unit.

Hardware Block:





### Software Implementation requirements :

#### **1) Keypad :**

- a) Powering ON the system using the power key
- b) Using up and down selecting the menu and other features (Walkmode, Cruisemode, Headlamp ON/OFF and other controls)

#### **2) Dwin Display :**

- a) Showing the speed, Battery voltage and current.
- b) Cruise and walk status
- c) Headlamp status
- d) Parameter settings
- e) PAS settings
- f) ODO display
- g) Trip distance
- h) Trip duration
- i) Navigation ( Left/right turn)
- j) UART communication with the S32k144

Note : Above Dwin display work with GUI based software build module ( Dgus software).

For more information please refer to : <https://www.dwin-global.com/dgus/>

### 3) **Quectel Module (SOM)**

- a) UART communication with the S32k144
- b) Communicate with the cloud using the **AT commands**
- c) Get the latitude and longitude and send it to cloud in format (Format needs to be discussed with the backend team)
- d) Receive the date from the cloud.

### 4) **MCU**

- a) UART communication with the S32k144 ( Baud rate -9600bps)
- b) Get the speed time and display it
- c) Send the PAS, walk mode, cruise and headlamp setting to MCU in a format ( As per M5 display format)
- d) Send ignition control related data to MCU

### 5) **IMU**

- a) I2c implementation to communicate with the S32k144.
- b) Read the IMU data and process as per the data ( if any unwanted data, send information to cloud)