

## Final (2012):

Q1: Any point  $(x, y)$  has one of three cases depending  
 a) on the function  $f(x, y)$  provided that  $x$  is positive:

$$f(x, y) = \begin{cases} > 0 & (x, y) \text{ on the line} \\ < 0 & (x, y) \text{ under the line} \\ > 0 & (x, y) \text{ above the line} \end{cases}$$

Initial value of  $d$ : at  $(x=0, y=R)$

$$\begin{aligned} d_{\text{initial}} &= d(x, y) = f(x+1, y - \frac{1}{2}) = (x+1)^2 + (y - \frac{1}{2})^2 - R^2 \\ &= (0+1)^2 + (R - \frac{1}{2})^2 - R^2 \\ &= 1 + R^2 - R + \frac{1}{4} - R^2 \\ &= \frac{5}{4} - R \approx 1 - R \end{aligned}$$

Change in  $d$ :

① if  $d < 0$  then:  $x + t$

$$\begin{aligned} \Delta d &= d(x+2, y - \frac{1}{2}) - d(x, y) \\ &= [(x+2)^2 + (y - \frac{1}{2})^2 - R^2] - [(x+1)^2 + (y - \frac{1}{2})^2 - R^2] \\ &= (x^2 + 4x + 4) - (x^2 + 2x + 1) = 2x + 3 \end{aligned}$$

② if  $d > 0$  then:  $x + t \quad y -$

$$\begin{aligned} \Delta d &= d(x+2, y - \frac{3}{2}) - d(x, y) \\ &= [(x+2)^2 + (y - \frac{3}{2})^2 - R^2] - [(x+1)^2 + (y - \frac{1}{2})^2 - R^2] \\ &= [(x^2 + 4x + 4) + (y^2 - 3y + \frac{9}{4})] + [(x^2 + 2x + 1) + (y^2 - y + 1)] \\ &= (2x + 3) + (-2y + \frac{5}{4}) \end{aligned}$$

$$\approx 2(x-y) + 5$$

## Algorithm:

DrawCircle( $x_c, y_c, R$ ) :

1.  $x = 0$

2.  $y = R$

3.  $d = 1 - R$

4. Draw points  $(x_c, y_c, x, y)$ .

5. if ( $d < 0$ )  $\rightarrow$  while ( $x < y$ ):

$d += 2x + 3;$

$x += 1;$

    else

$d += 2(x - y) + 5;$

$x += 1;$

$y += 1;$

6. Draw point  $(x_c, y_c, x, y)$ .

b) Slope =  $\frac{15-9}{12-2} = 0.6 \quad ; \text{ slope} < 1$

Initial value (d<sub>initial</sub>) =  $\Delta x - 2\Delta y = 10 - (2+6) = -2$

Change in decision when  $d < 0$ :  $d_1 = 2\Delta x - 2\Delta y = 20 - 12 = 8$

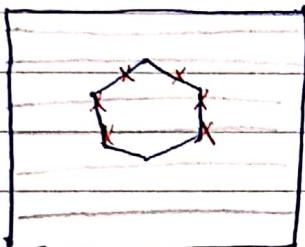
Change in decision when  $d > 0$ :  $d_2 = -2\Delta y = -2 + 6 = 4$

Traces

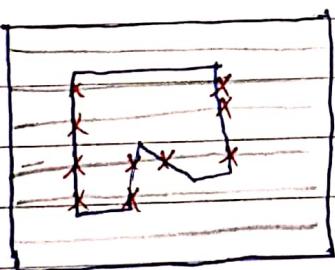
X	Y	Decision Variable
2	9	$ d_{<0}  d = d + d_1 = -2 + 8 = 6$
3	10	$ d > 0  d = d + d_2 = 6 + 4 = 10$
4	10	$ d < 0  d = d + d_1 = -6 + 8 = 2$
5	11	$ d > 0  d = d + d_2 = 2 + 4 = 6$
6	11	$ d < 0  d = d + d_1 = -10 + 8 = -2$
7	12	$ d > 0  d = d + d_2 = -2 + 4 = 2$
8	13	$ d < 0  d = d + d_1 = 6 + 4 = 10$
9	13	$ d > 0  d = d + d_2 = 10 + 4 = 14$

Q2:

- a Convex shape: is a shape that has at most 2 intersection with scan line.



Non-convex shape: is a shape that has more than 2 intersection with scan line.



Algorithm:

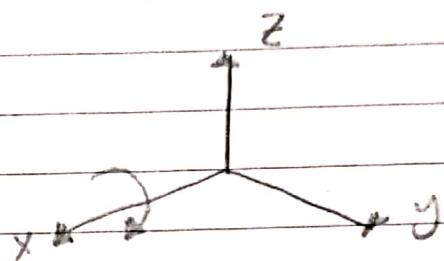
1. Initialize the edge list array 'table' with the edge information.
2. Start with  $y =$  the first index in table with non-empty edge list.
3. Let Active List =  $\text{table}[y]$
4. while Active list is not empty
  - 4.1 Sort Active List node in an ascending order with X.
  - 4.2 Draw horizontal lines between points represented by successive pairs of node in Active List.
  - 4.3 Increment  $y$  by 1
  - 4.4 Delete from ActiveList those node with  $Y_{max} = y$ .
  - 4.5 Append to ActiveList the new node at  $\text{table}[y]$  if not null
- end while
- 4.5 Update  $x$  where  $x += \Delta h v$

Q4:

+ Rotate an object about x axis with a rotation angle of  $30^\circ$  clockwise.

∴ Rotation  $\rightarrow$  from z to y

$$R_x = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(30) & \sin(30) & 0 \\ 0 & -\sin(30) & \cos(30) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



+ Scale 3D object with respect to a fixed point (3,2,8) where the scaling factors in x,y and z directions are (2, 0.5, 3).

1. Translate object to origin:

$$T = \begin{bmatrix} 1 & 0 & 0 & -3 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & -8 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

2. Scale object on origin:

$$S = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 0.5 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

3. Undo step 1:

3. Undo Step 1:

$$T^{-1} = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 8 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Composite Scaling Matrix:

$$T^{-1} \cdot ST = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 8 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 0.5 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -3 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & -8 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

so matrix structure remains after multiplying

Transform Figure 1 into Figure 2:

A

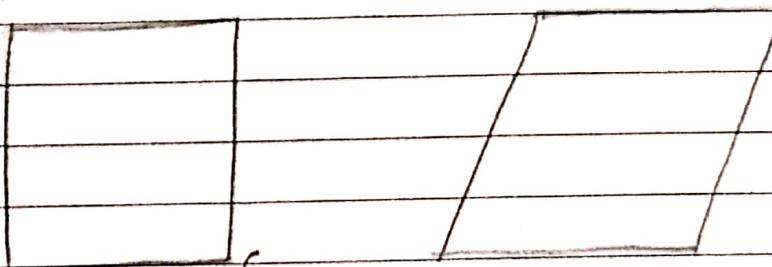


figure 1

figure 2

$$T = \begin{bmatrix} 1 & \alpha & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ w \end{bmatrix}$$

$$x' = x + \alpha y$$

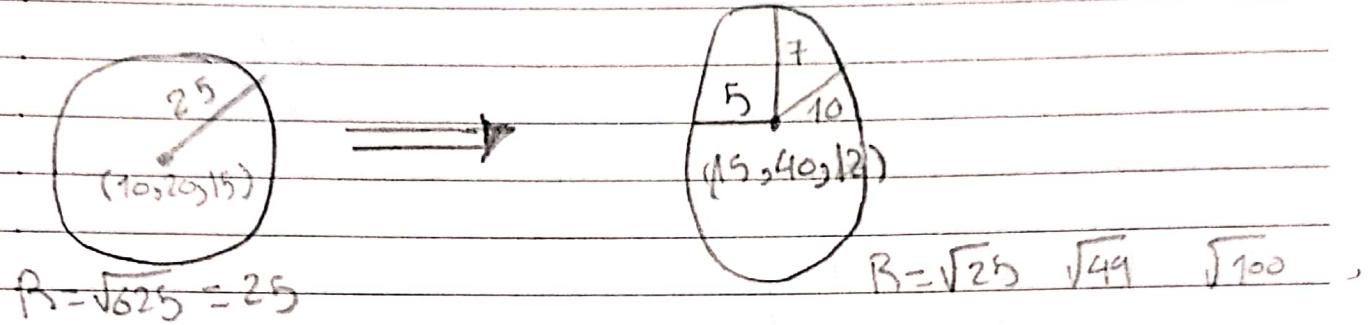
$$y' = y + Bx$$

$$x = x + \alpha y$$

$$y = y$$

Map the sphere  $(x-10)^2 + (y-20)^2 + (z-15)^2 = 625$  to the ellipsoid

$$\frac{(x-15)^2}{25} + \frac{(y-40)^2}{49} + \frac{(z-12)^2}{100} = 1$$



If we want to map shape into another there is 2 difference:

- ① center of ellipsoid
- ② R in sphere is 25 but ellipsoid has 3 different values (5, 7, 10)

① Translate sphere to origin:

$$T_1 = \begin{vmatrix} 1 & 0 & 0 & -10 \\ 0 & 1 & 0 & -20 \\ 0 & 0 & 1 & -15 \\ 0 & 0 & 0 & 1 \end{vmatrix}$$

② We need to convert R which (25) to (A, B, C) which are (5, 7, 10) so we need to apply two scaling one to convert (25) to 1 and other to Rescale 1 to (5, 7, 10):

$$S_1 = \begin{vmatrix} \frac{1}{25} & 0 & 0 & 0 \\ 0 & \frac{1}{49} & 0 & 0 \\ 0 & 0 & \frac{1}{100} & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix}$$

$$S_2 = \begin{vmatrix} 5 & 0 & 0 & 0 \\ 0 & 7 & 0 & 0 \\ 0 & 0 & 10 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix}$$

③ Translate from origin to ellipsoid center:

$$T_2 = \begin{vmatrix} 1 & 0 & 0 & 15 \\ 0 & 1 & 0 & 40 \\ 0 & 0 & 1 & 12 \\ 0 & 0 & 0 & 1 \end{vmatrix}$$

Final Matrix =  $T_2 S_2 S_1 T_1 x_{\text{input}}$

$$= \begin{vmatrix} 1 & 0 & 0 & 15 \\ 0 & 1 & 0 & 40 \\ 0 & 0 & 1 & 12 \\ 0 & 0 & 0 & 1 \end{vmatrix} \begin{vmatrix} 5 & 0 & 0 & 0 \\ 0 & 7 & 0 & 0 \\ 0 & 0 & 10 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} \begin{vmatrix} \frac{1}{5} & 0 & 0 & 0 \\ 0 & \frac{1}{7} & 0 & 0 \\ 0 & 0 & \frac{1}{10} & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} \begin{vmatrix} 1 & 0 & 0 & -10 \\ 0 & 1 & 0 & -20 \\ 0 & 0 & 1 & -15 \\ 0 & 0 & 0 & 1 \end{vmatrix}$$

# Final (2017) :

Q:

b) (12, 10), (6, 14)

$$1. \Delta y = 14 - 10 = 4 \quad \Delta x = 6 - 12 = -6$$

$$|5| \leq |-6|$$

slope < 1

↓  
left

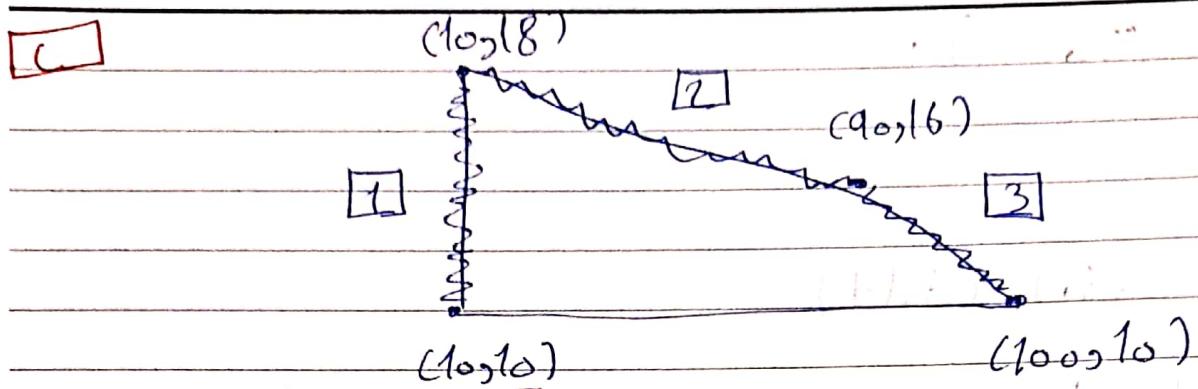
negative

$$d = -\Delta x - 2\Delta y = -(6) - 2(4) = -14$$

$$ch_1 = -\Delta x - \Delta y = 6 - 4 = 2$$

$$ch_2 = -2\Delta y = -2(4) = -8$$

X	Y	decision
6	14	-2 $\because d \leq 0 \therefore d = ch_1$
7	13	0 $\because d \leq 0 \therefore d = ch_1$
8	12	2 $\because d > 0 \therefore d = ch_2$
9	11	-6 $\because d \leq 0 \therefore d = ch_1$
10	10	-4 $\because d \leq 0 \therefore d = ch_1$
11	9	-2 $\because d \leq 0 \therefore d = ch_1$
12	8	0



Activelist

0	N	
1	N	1
2	N	
3	N	
10	$x_{\min}, y_{\max}$	$x_{\min}, y_{\max}$
10	10   0   18	100   $-\frac{5}{3}$   16
11	N	
12	N	2
13	N	
16	$x_{\min}, y_{\max}$	$y$
16	10   -40   18	

start with  $y = 0$

- ① while ( $tbl[y] == \text{null}$ )  $y++;$
- ② Active =  $tbl[y]$  "Active =  $tbl[10]$ "
- ③ while (Active != null)

- ::  $y = 10$
- ① Sort x ascending ::  $10 | 0 | 18 \rightarrow 100 | -\frac{5}{3} | 16$
- ② Draw Line between  $(10, 10)$   $(100, 10)$
- ③ Increase  $y$  by one. ::  $y = 11$
- ④ delete will not occur cause  $y \neq y_{\max}$
- ⑤ Update x of each node in ActiveList

$x_{\min}, y_{\max}$	$x_{\min}, y_{\max}$
10   0   18	$\frac{295}{3}   -\frac{5}{3}   16$

⑥ Append if  $t.b.[y]$  not Null

$\because$  Append will not occur cause  $t.b[11]$  Null

$\therefore y = 11$

Active  $\rightarrow [10 | 0 | 18] \rightarrow [\frac{29}{3} | -\frac{5}{3} | 16]$

① Sort x ascending

② Draw line between  $(10, 11)$   $(\frac{29}{3}, 11)$

③ Increase y by one  $\therefore y = 12$

④ delete will not occur cause  $y \neq y_{max}$

⑤ update x of each node in ActiveList

$[10 | 0 | 18] \rightarrow [\frac{29}{3} | -\frac{5}{3} | 16]$

⑥ Append if  $t.b[y]$  not Null

$\because$  Append will not occur cause  $t.b[12]$  Null

Q2

a: The line will accepted if

1 both outcode not empty

2 both outcode not have common side

Condition of 1:

$\text{if } (\text{outCode}_1.\text{All} \neq 0 \text{ \& } \text{outCode}_2.\text{All} \neq 0)$

Condition of 2:

$\text{if } (\text{outCode}_1.\text{All} \neq \text{outCode}_2.\text{All}) != 0$

Q2:

b)  $P(t_1, t_2) = t_1 P_1 + t_2 P_2 + (1-t_1-t_2) P_3$

$$0 \leq t_1, t_2 \leq 1$$
$$t_1 + t_2 \leq 1$$

\* Every time  $(t_1, t_2)$  change we can calculate new point inside the triangle.

1] for ① iterate on  $t_1$  values  
② iterate on  $t_2$  values  
③ check if  $t_1+t_2 \leq 1$   
④ generate  $p$  values.  
⑤ set pixel.

For  $(t_1=0, t_1 \leq 1, t_1 = 1/\max(P_1, P_2, P_3))$   
for  $(t_2=0, t_2 \leq 1, t_2 = 1/\max(P_1, P_2, P_3))$   
if  $(t_1+t_2 > 1)$   
else  
 $P(t_1, t_2) = t_1 P_1 + t_2 P_2 + (1-t_1-t_2) P_3$   
setpixel( $P$ ).

2] for ① iterate on  $t_1$  values  
② iterate on  $t_2$  values  
③ check if  $(t_1+t_2) \leq 1$   
④ check  $(x, y)$  values of  $P$  with  $(P_1, P_2, P_3)$  compare  
for  $(t_1=0, t_1 \leq 1, t_1 = 1/\max(P_1, P_2, P_3))$   
for  $(t_2=0, t_2 \leq 1, t_2 = 1/\max(P_1, P_2, P_3))$   
if  $(t_1+t_2 > 1)$   
else  
 $P(t_1, t_2) = t_1 P_1 + t_2 P_2 + (1-t_1-t_2) P_3$   
if  $(P.x \leq P_1.x \& P.x \geq P_2.x \& P.x \leq P_3.x)$   
 $\& P.y \leq P_1.y \& P.y \geq P_2.y \& P.y \leq P_3.y)$   
then Pixel is inside

Q3: Explain what is homogeneous coordinate system.

a) The homogeneous coordinate Systems;

Is related to the standard 2D System through the relation H and S with H mapping from standard to homogeneous and S from homogeneous to standard:

$$H: (x, y) \rightarrow (x, y, 1)$$

$$S: (x, y, w) \rightarrow (\frac{x}{w}, \frac{y}{w})$$

Importance of homogenous coordinate System:

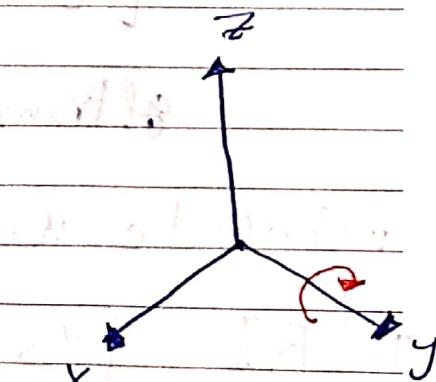
It used for representation of affine transformation and help full with operation of \* and + of matrices so it can simplify the operations

Affine transformation in homogeneous coordinate System:

$$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ 0 & 0 & 1 \end{pmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

b) rotate from x to z

$$R_y = \begin{bmatrix} \cos(\theta_0) & 0 & -\sin(\theta_0) & 0 \\ 0 & 1 & 0 & 0 \\ \sin(\theta_0) & 0 & \cos(\theta_0) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



of Rotate  $(-\theta_0, 0, 1, 0)$

C 1. Translate the object such that  $(10, 12)$  become the origin using the translation matrix:

$$T = \begin{bmatrix} 1 & 0 & -10 \\ 0 & 1 & -12 \\ 0 & 0 & 1 \end{bmatrix}$$

glTranslatef( $30, 0, 0, 1$ )

glTranslatef( $-10, -12, 1$ )

2. Rotate the object about the origin using the rotation matrix:

$$R = \begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

glRotatef( $30, 0, 0, 1$ )

3. Undo step 1: Translate the origin to  $(10, 12)$

$$T^{-1} = \begin{bmatrix} 1 & 0 & 10 \\ 0 & 1 & 12 \\ 0 & 0 & 1 \end{bmatrix}$$

gltranslate( $10, 12, 1$ )

Composite Matrix:

$$T^{-1} \cdot R \cdot T = \begin{bmatrix} 1 & 0 & 10 \\ 0 & 1 & 12 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -10 \\ 0 & 1 & -12 \\ 0 & 0 & 1 \end{bmatrix}$$

Shearing in x-direction:

$$\begin{bmatrix} x' \\ y' \\ w' \end{bmatrix} = \begin{bmatrix} 1 & \alpha & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$x = 5$   
 $y = 12$   
 $\alpha = 4$   
 $\beta = 9$

Shearing in y-direction:

$$\begin{bmatrix} x' \\ y' \\ w' \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \beta & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

2018

b

\* Recursive Algorithm:

Floodfill (x, y, Bc, Fc):

1. COLORREF c = Getpixel (x, y);
2. if (c == Bc || c == Fc) return;
3. Setpixel (x, y, Fc);
4. Floodfill (x+1, y, Bc, Fc);
5. Floodfill (x, y+1, Bc, Fc);
6. Floodfill (x-1, y, Bc, Fc);
7. Floodfill (x, y-1, Bc, Fc);

end

\* Non-Recursive Algorithm:

#include <queue>

Floodfill (x, y, Bc, Fc):

1. struct Point:

1.1 x, y;

1.2 Point (x=0, y=0) : x(x) Y(y) {};

2. queue <Point> qu;

3. qu.push (Point (x, y));

4. while (!qu.empty()):

4.1 Point p = qu.top();

4.2 qu.pop();

4.3 COLORREF c = Getpixel (p.x, p.y);

4.4 if (c == Bc || c == Fc) continue;

4.5 Setpixel (p.x, p.y, Fc);

4.6 qu.push (Point (x+1, y));

4.7 qu.push (Point (x, y+1));

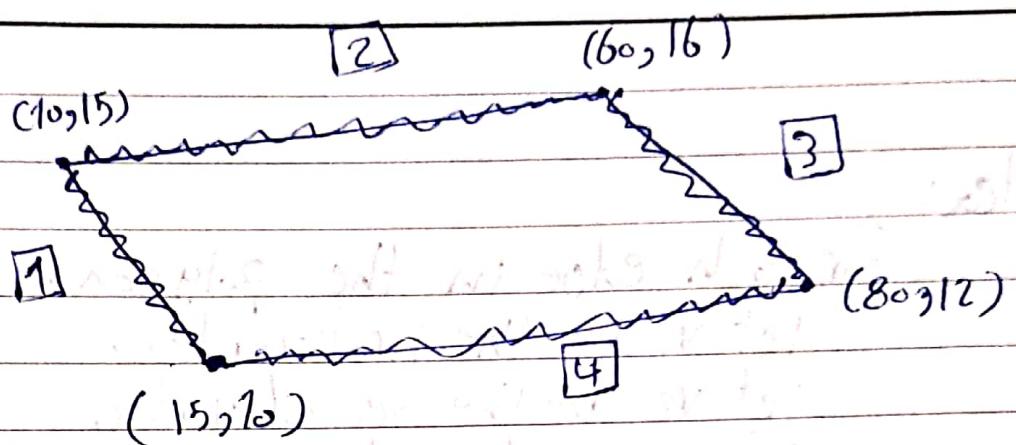
4.8 qu.push (Point (x-1, y));

4.9 qu.push (Point (x, y-1));

4. end while

end.

C



Active List (non-interfering nodes)

	N	X min	Y max		X min	Y max	
1	N						
2	N			1			
3	N						4
10	N	15	15		80	85	12
11	N	80	-5	16			3
12	N						
13	N						
14	N						
15	N	60	50	16			2

Q2:

a) Idea:

for each edge in the polygon:

let  $v_1$  be the first vertex.

let  $v_2$  be the second vertex.

if  $v_1$  is out and  $v_2$  is In then:

- compute intersection as inter

- Append inter to outlist,

- Append  $v_2$  to outlist

else if  $v_1$  is In and  $v_2$  is In then:

- Append  $v_2$  to outlist

else if  $v_1$  is In and  $v_2$  is out then:

- compute intersection as inter

- Append inter to outlist

b) DrawCircle ( $x_c, y_c, R$ ):

1.  $x = 0;$
2.  $y = R;$
3.  $d_1 = 1 - R;$
4.  $d_2 = 3;$
5.  $d_2 = 5 - 2 * R;$
6. DrawPoint ( $x_c, y_c, x, y, \text{color}$ );
7. while ( $x < y$ ):

    7.1 if ( $d_1 < 0$ ):

        7.1.1  $d_1 = d_1 + 1;$

        7.1.2  $d_2 = d_2 + 2;$

        7.1.3  $d_1 = d_1 + 2;$

    7.2 else:

        7.2.1  $d_1 = d_2;$

        7.2.2  $d_2 = d_2 + 4;$

        7.2.3  $d_1 = d_1 + 2;$

        7.2.4  $y = y - 1;$

    7.3 DrawPoint ( $x_c, y_c, x, y, \text{color}$ );

end while

end

DrawPoint ( $x_c, y_c, x, y$ ):

1. SetPixel ( $x_c + x, y_c + y, \text{color}$ );
2. DrawLine ( $x_c, y_c, x_c + x, y_c + y, \text{color}$ );
3. SetPixel ( $x_c + y, y_c + x, \text{color}$ );
4. DrawLine ( $x_c, y_c, x_c + y, y_c + x, \text{color}$ );
5. SetPixel ( $x_c - x, y_c + y, \text{color}$ );
6. DrawLine ( $x_c, y_c, x_c - x, y_c + y, \text{color}$ );
7. SetPixel ( $x_c - x, y_c - y, \text{color}$ );
8. DrawLine ( $x_c, y_c, x_c - x, y_c - y, \text{color}$ );
9. SetPixel ( $x_c + x, y_c - y, \text{color}$ );

10. DrawLine ( $x_c, y_c, x_c+y, y_c+x$ , color);

11. SetPixel ( $x_c-y, y_c+x$ , color);

12. DrawLine ( $x_c, y_c, x_c-y, y_c+x$ , color);

13. SetPixel ( $x_c+y, y_c-x$ , color);

14. DrawLine ( $x_c, y_c, x_c+y, y_c-x$ , color);

15. SetPixel ( $x_c-y, y_c-x$ , color);

16. DrawLine ( $x_c, y_c, x_c-y, y_c+x$ , color);

17. ~~SetPixel~~

End.

Q3:

a) General form of Affine transformation in homogenous space:

$$T \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

b) Translate (10, 12) to origin:

$$T = \begin{bmatrix} 1 & 0 & -10 \\ 0 & 1 & -12 \\ 0 & 0 & 1 \end{bmatrix}$$

glTranslatef (-10, -12, 1);

\* Rotate about origin with angle  $30^\circ$  anti-clock:

$$R = \begin{bmatrix} \cos 30 & -\sin 30 & 0 \\ \sin 30 & \cos 30 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

glRotatef (30, 0, 0, 1);

undo step 1:

$$T^{-1} = \begin{bmatrix} 1 & 0 & 10 \\ 0 & 1 & 12 \\ 0 & 0 & 1 \end{bmatrix}$$

gltranslate(10, 12, 1);

; overall Matrix =

$$T^{-1} \cdot B \cdot T = \begin{bmatrix} 1 & 0 & 10 \\ 0 & 1 & 12 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & -10 \\ 0 & 1 & -12 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} & 10 \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & 12 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -10 \\ 0 & 1 & -12 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} & 16 - 5\sqrt{3} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & 7 - 6\sqrt{3} \\ 0 & 0 & 1 \end{bmatrix}$$

b) Shearing in x-direction:

$$\begin{bmatrix} x' \\ y' \\ w' \end{bmatrix} = \begin{bmatrix} 1 & x_0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Shearing in y-direction:

$$\begin{bmatrix} x' \\ y' \\ w' \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \beta & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

where:  $x=5$   $y=12$   $\alpha=\beta=4$ .

Final (2019):

Q1 Line Generation

a) Bresenham Algorithm ( $x_1, y_1, x_2, y_2$ ):

$$1. x = x_1$$

$$2. y = y_1$$

$$3. dx = x_2 - x_1$$

$$4. dy = y_2 - y_1$$

5. setPixel( $x, y$ )

$$6. d = dx - 2 * dy$$

$$7. d_1 = -2 * dy$$

$$8. d_2 = 2 * dx - 2 * dy$$

9. while ( $x < x_2$ ):

9.1 if ( $d > 0$ ):

$$x++ \quad y++$$

$$d = d + d_2$$

9.2 else:

$$x++$$

~~else~~

$$d = d + d_1$$

9.3 setPixel( $x, y$ ))

endwhile

end

for loop ends

## DDA Algorithm

- + less efficient
- + calculation speed less.
- + costlier
- + less accuracy
- + more complex
- + use multiplication and division

## Bresenham Algorithm

- + More efficient
- + Calculation speed faster.
- + cheaper
- + more accuracy
- + simple
- + use only subtraction and addition.

b)  $(6, 10) \rightarrow (12, 18)$  slope = 1.33

$$x_1 = 6 \quad x_2 = 12 \quad y_1 = 10 \quad y_2 = 18$$

$$\Delta x = 6$$

$$\Delta y = 8$$

$$d_{initial} = 2\Delta x - \Delta y = 12 - 8 = 4$$

$$d_1 = 2\Delta x - 2\Delta y = 12 - 16 = -4$$

$$d_2 = 2\Delta x = 12$$

### Traces

x	y	decision
6	10	$d > 0$ $d = d_1$ $d = 0$
7	11	$d > 0$ $d = d_1$ $d = 4$
8	12	$d < 0$ $d = d_2$ $d = 8$
8	13	$d > 0$ $d = d_1$ $d = 4$
9	14	$d > 0$ $d = d_1$ $d = 0$
10	15	$d > 0$ $d = d_1$ $d = 4$
11	16	$d < 0$ $d = d_2$ $d = 8$
11	17	$d > 0$ $d = d_1$ $d = 4$
12	18	

d

(10, 16)

(60, 15)

(15, 10)

(80, 12)

Edge2Table ( point<sub>1</sub>(15, 10), point<sub>2</sub>(10, 16) ) :

Initial Table :

$x_{left}$	$x_{right}$
$\infty$	$-\infty$
$\infty$	$-\infty$
$\infty$	$-\infty$

$$\therefore y_1 = 10 \quad x = 15 \quad \min v = -\frac{5}{6}$$

$$y=10 \quad \begin{bmatrix} x_{left} & x_{right} \\ 15 & 15 \end{bmatrix} \rightarrow y++ \quad x+=\min v$$

$$\therefore y=11 \quad x = \frac{85}{6}$$

$$y=11 \quad \begin{bmatrix} \frac{85}{6} & \frac{85}{6} \end{bmatrix} \rightarrow y++ \quad x+=\min v$$

$$\therefore y=12 \quad x = \frac{40}{3}$$

$$y=12 \quad \begin{bmatrix} \frac{40}{3} & \frac{40}{3} \end{bmatrix} \rightarrow y++ \quad x+=\min v$$

$$\therefore y=13 \quad x = \frac{25}{2}$$

$$y=13 \quad \begin{bmatrix} \frac{25}{2} & \frac{25}{2} \end{bmatrix} \rightarrow y++ \quad x+=\min v$$

$$\therefore y=14 \quad x = \frac{35}{3}$$

$$y=14 \quad \begin{bmatrix} \frac{35}{3} & \frac{35}{3} \end{bmatrix} \rightarrow y++ \quad x+=\min v$$

Edg2Table (Point<sub>2</sub>(10,16), Point<sub>3</sub>(60,15)):

$$y = 15 \quad x = \frac{65}{3} \quad \text{minv} = 50$$

$$y = 15 \quad [80 \quad 60] \rightarrow y++ \quad x+ = \text{minv}$$

Edg2Table (Point<sub>3</sub>(60,15), Point<sub>4</sub>(80,12)):

$$y = 12 \quad x = 80 \quad \text{minv} = -\frac{20}{3}$$

$$y = 12 \quad \left[ \frac{40}{3} \quad 80 \right]$$

$$y++ \quad x+ = \text{minv} \rightarrow y = 13 \quad x = \frac{220}{3}$$

$$y = 13 \quad \left[ \frac{25}{2} \quad \frac{220}{3} \right]$$

$$y++ \quad x+ = \text{minv} \rightarrow y = 14 \quad x = \frac{200}{3}$$

$$y = 14 \quad \left[ \frac{35}{3} \quad \frac{200}{3} \right]$$

$$y++ \quad x+ = \text{minv} \rightarrow y = 15 \quad x = 60$$

Edg2Table (point<sub>0</sub>(80, 12), point<sub>1</sub>(15, 10)):

$$y = 10$$

$$x = 15$$

$$\text{minv} = \frac{65}{2}$$

$$y = 10 \quad [15, \quad 32.5] \rightarrow y++ \quad x = \frac{95}{2}$$

$$y = 11 \quad \left[ \frac{85}{8}, \quad \frac{95}{2} \right] \rightarrow y++ \quad x = 80$$

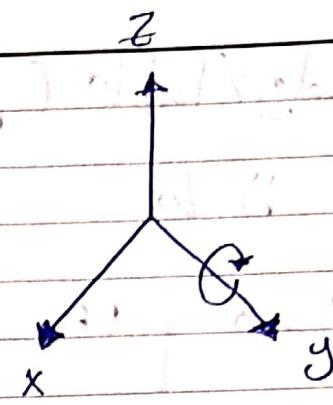
$\therefore$  EdgTable =

y	10	11	12	13	14	15
	15	$\frac{85}{8}$	$\frac{45}{2}$	$\frac{25}{2}$	$\frac{35}{3}$	60
	32.5	$\frac{95}{2}$	80	$\frac{225}{3}$	$\frac{205}{3}$	60

Writing all the values above.

Q2: Transformation with rotation, translation.

from x to z



$$B_y = \begin{bmatrix} \cos(60) & 0 & -\sin(60) & 0 \\ 0 & 1 & 0 & 0 \\ \sin(60) & 0 & \cos(60) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} & 0 & -\frac{\sqrt{3}}{2} & 0 \\ 0 & 1 & 0 & 0 \\ \frac{\sqrt{3}}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

1. Translate object to origin:

$$T = \begin{bmatrix} 1 & 0 & 0 & -3 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & -7 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

2. Scale object on the origin:

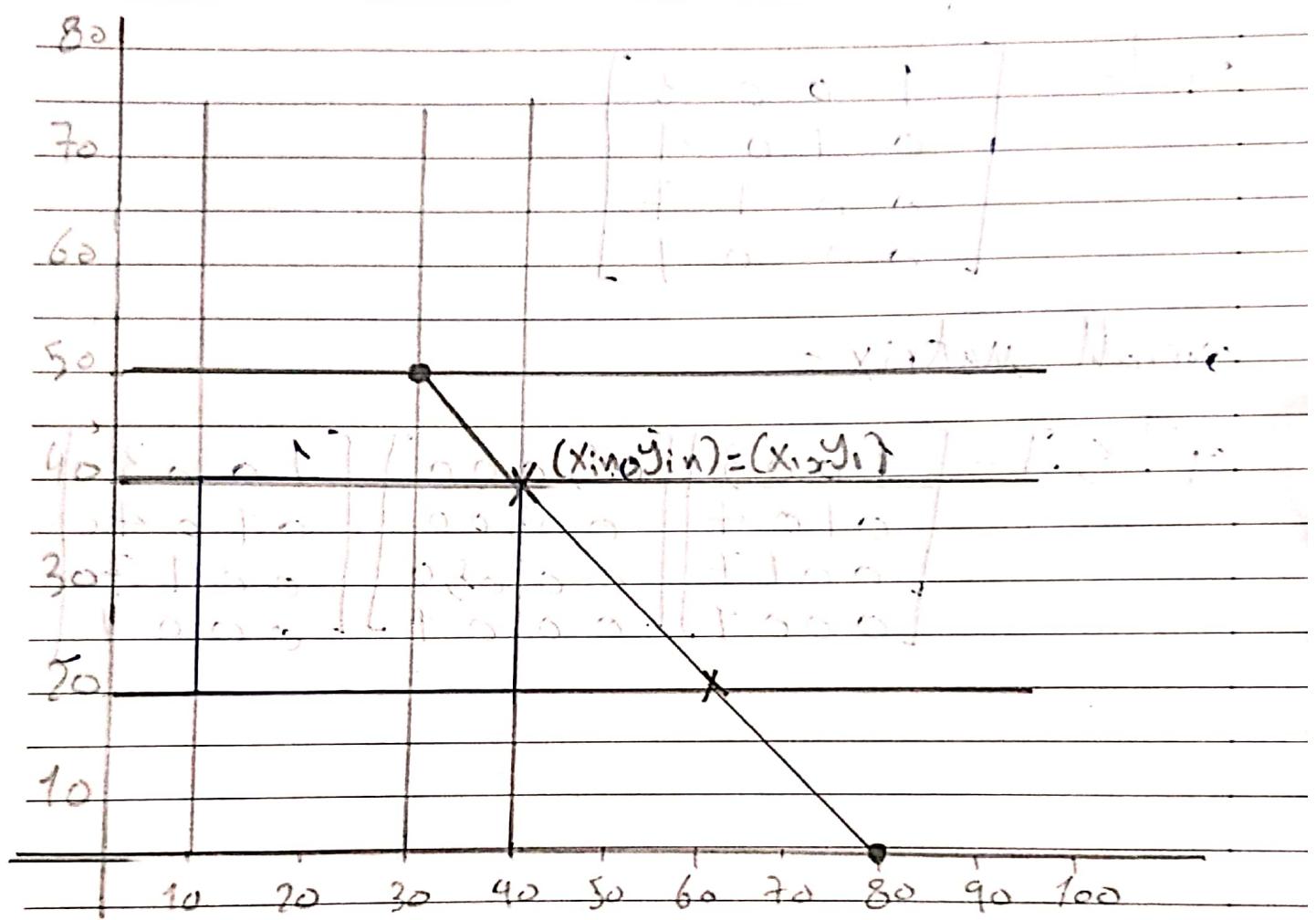
$$S = \begin{bmatrix} 0.5 & 0 & 0 & 0 \\ 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Undo step 1:

$$T^{-1} = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 7 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

overall matrix =

$$T^{-1} \cdot S \cdot T = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 7 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.5 & 0 & 0 & 0 \\ 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 7 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$\text{out}_1 = \{0010\} \quad \text{out}_2 = \{0101\}$$

1 out<sub>1</sub>.left = 0 out<sub>1</sub>.bottom = 0 out<sub>1</sub>.top = 1  $\rightarrow$  intersect with top side

$$\because y_{top} = 40 \quad \therefore y_{in} = y_{top} = 40 \quad \text{where } (x_1, y_1) = (30, 50) \\ (x_2, y_2) = (80, 0)$$

$$\therefore x_{in} = x_1 + (x_2 - x_1) + (y_{in} - y_1) / (y_2 - y_1)$$

$$= 30 + (80 - 30) + (40 - 50) / (0 - 50) = 40$$

$$\therefore (x_{in}, y_{in}) = (x_1, y_1) = (40, 40)$$

$$\therefore \text{out}_1 = \{0000\} \# \text{ trivial empty}$$

$$[2] \text{out}_2 = \{0101\}$$

$\text{out}_2.\text{left} = 0 \quad \text{out}_2.\text{bottom} = 1 \Rightarrow$  intersect with ybottom

$\because y_{\text{bottom}} = y_{\text{in}} = 20 \quad \text{where } (x_1, y_1) = (40, 40)$   
 $(x_2, y_2) = (80, 0)$

$$\begin{aligned}\therefore x_{\text{in}} &= x_1 + (x_2 - x_1) * (y_{\text{in}} - y_1) / (y_2 - y_1) \\ &= 40 + (80 - 40) * (20 - 40) / (0 - 40) = 60\end{aligned}$$

$$\therefore (x_{\text{in}}, y_{\text{in}}) = (x_2, y_2) = (60, 20)$$

$$\text{out}_2 = \{0001\}$$

$\text{out}_2.\text{left} = 0 \quad \text{out}_2.\text{bottom} = 0 \quad \text{out}_2.\text{top} = 0 \quad \text{out}_2.\text{right} = 1$

intersect with xright

$$\begin{aligned}\therefore x_{\text{right}} &= x_{\text{in}} = 40 \quad \text{where } (x_1, y_1) = (40, 40) \\ &\quad (x_2, y_2) = (60, 20)\end{aligned}$$

$$\begin{aligned}y_{\text{in}} &= y_1 + (x_{\text{in}} - x_1) * (y_2 - y_1) / (x_2 - x_1) \\ &= 40 + (40 - 40) * (20 - 40) / (60 - 40) = 40\end{aligned}$$

$$\therefore (x_{\text{in}}, y_{\text{in}}) = (x_2, y_2) = (40, 40)$$

$$\text{out}_2 = \{0000\}$$

$(\text{out}_1.\text{All} = 0 \text{ & } \text{out}_2.\text{All} = 0)$

1) raw point (40, 40).

(2017) :

write an efficient Algorithm to fill an ellipse with axes parallel to the x and y axes.

DrawEllipse(  $x_c, y_c, A, B, \text{color}$  ):

$x=0$     $y=B$

Draw4point(  $x_c, y_c, x, y, \text{color}$  )

while (  $xB^2 < yA^2$  ) :

$x++$

$y = \text{Round}(\sqrt{B^2 + A^2 - \frac{x^2}{A^2}})$

Draw4point(  $x_c, y_c, x, y, \text{color}$  )

endwhile

$y=0$     $x=A$

Draw4point(  $x_c, y_c, x, y, \text{color}$  )

while (  $xB^2 > yA^2$  ) :

$y++$

$x = \text{Round}(\sqrt{B^2 + A^2 - \frac{y^2}{B^2}})$

Draw4point(  $x_c, y_c, x, y, \text{color}$  )

endwhile

end

Draw4Point(  $x_c, y_c, x, y, \text{color}$  ):

setpixel(  $x+x_c, y+y_c, \text{color}$  )

setpixel(  $x-x_c, y-y_c, \text{color}$  )

drawline(  $x+x_c, y+y_c, x-x_c, y-y_c, \text{color}$  )

setpixel(  $x+x_c, y-y_c, \text{color}$  )

setpixel(  $x-x_c, y+y_c, \text{color}$  )

drawline(  $x+x_c, y-y_c, x-x_c, y+y_c, \text{color}$  )

write an efficient algorithm to fill an ellipse  
using the following parametric equations:

$$X = A \cos \theta$$

$$Y = B \sin \theta$$

DrawEllipse(  $x_c, y_c, R, r^2, \text{color}$  ):

$$\Delta\theta = 1.0/R$$

for ( theta=0.0, theta < 6.28, theta+=dtheta )

$$x = x_c + r * \cos(\theta)$$

$$y = y_c + R * \sin(\theta)$$

setpixel( Bound(x), Bound(y), color )  
Drawline(  $x_c, y_c, \text{Bound}(x), \text{Bound}(y), \text{color}$  )

endfor

end

2017:

The Barycentric equation of the triangle with vertices  $P_1, P_2, P_3$  is:

$$P(t_1, t_2) = t_1 P_1 + t_2 P_2 + (1-t_1-t_2) P_3$$
$$0 \leq t_1, t_2 \leq 1$$
$$t_1 + t_2 \leq 1$$

1 write an algorithm to fill-in a triangle based on this equation

```
t2 + t1 ≤ 1 => t2 ≤ 1 - t1
for (t1=0.0; t1≤ 1; t1+=max(P1, P2, P3)) {
    for (t2=0.0; t2≤ 1-t1; t2+=1/max(P1, P2, P3)) {
        Point p = t1*P1 + t2*P2 + (1-t1-t2)*P3
        Drawpixel(p.x, p.y, color)
    }
}
```

2 write an algorithm to determine whether a given point is inside the triangle.

$$\begin{bmatrix} x \\ y \end{bmatrix} = t_1 \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} + t_2 \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} + (1-t_1-t_2) \begin{bmatrix} x_3 \\ y_3 \end{bmatrix}$$

$$\bar{x} = t_1 x_1 + t_2 x_2 + (1-t_1-t_2) x_3$$

$$\bar{y} = t_1 y_1 + t_2 y_2 + (1-t_1-t_2) y_3$$

$$\bar{x} - x_3 = (x_1 - x_3) t_1 + (x_2 - x_3) t_2$$

$$\bar{y} - y_3 = (y_1 - y_3) t_1 + (y_2 - y_3) t_2$$

matrix form

$$\begin{bmatrix} \bar{x} - x_3 \\ \bar{y} - y_3 \end{bmatrix} = \begin{bmatrix} x_1 - x_3 & x_2 - x_3 \\ y_1 - y_3 & y_2 - y_3 \end{bmatrix} \begin{bmatrix} t_1 \\ t_2 \end{bmatrix}$$

$$\therefore \begin{bmatrix} t_1 \\ t_2 \end{bmatrix} = \frac{1}{(x_1 - x_3)(y_2 - y_3) - (x_2 - x_3)(y_1 - y_3)}$$

$$* \begin{bmatrix} y_2 - y_3 & -(x_2 - x_3) \\ -(y_1 - y_3) & x_1 - x_3 \end{bmatrix}$$

. if:  $0 \leq t_1, t_2 \leq 1 \Rightarrow$  inside

$> 1 \Rightarrow$  outside

Algorithm:

for( $t_1=0.0$ ,  $t_1 \leq 1$ ,  $t_1 += \frac{1}{\max(P_1, P_2, P_3)}$ )

    for( $t_2=0.0$ ,  $t_2 \leq 1-t_1$ ,  $t_2 += \frac{1}{\max(P_1, P_2, P_3)}$ )

        if( $t_1+t_2 > 1$ )

            continue

        else

            Point  $P = t_1 P_1 + t_2 P_2 + (1-t_1-t_2) P_3$

            if( $P.x \leq P_1.x \& P.x \leq P_2.x \& P.x \leq P_3.x$

$\& P.y \leq P_1.y \& P.y \leq P_2.y \&$

$P.y \leq P_3.y$ )

            the pixel is inside

Q12:

Find the orthogonal projection of an object  
the plane passing through the points  $(1, -3, 0)$   
 $(2, 4, 1)$ ,  $(0, 1, 0)$

$$\hat{u} = \frac{(1, -3, 0)}{\sqrt{1^2 + (-3)^2 + 0^2}} = \left( \frac{1}{\sqrt{10}}, \frac{-3}{\sqrt{10}}, 0 \right)$$

$$\hat{v} = \frac{(2, 4, 1)}{\sqrt{2^2 + 4^2 + 1^2}} = \left( \frac{2}{\sqrt{21}}, \frac{4}{\sqrt{21}}, \frac{1}{\sqrt{21}} \right)$$

$$\hat{w} = \frac{(0, 1, 0)}{\sqrt{0^2 + 1^2 + 0^2}} = (0, \frac{1}{\sqrt{1}}, 0)$$

convert to  $O(x, y, z)$ :

$$C = \begin{bmatrix} \hat{u} \\ \hat{v} \\ \hat{w} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{10}}, \frac{-3}{\sqrt{10}}, 0 \\ \frac{2}{\sqrt{21}}, \frac{4}{\sqrt{21}}, \frac{1}{\sqrt{21}} \\ 0, 1, 0 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad C^{-1} \quad \text{To convert from } O(x, y, z) \text{ to } O(u, v, w)$$

$$C^{-1} = \begin{bmatrix} \frac{1}{\sqrt{10}}, \frac{2}{\sqrt{21}}, 0 \\ \frac{-3}{\sqrt{10}}, \frac{4}{\sqrt{21}}, \frac{1}{\sqrt{21}} \\ 0, 1, 0 \end{bmatrix}$$

$$\text{Composite} = C^{-1} \cdot P \cdot C$$

- find orthogonal projection of point  $(6, 2, 3)$  on plane passing through points  $(1, 3, 5)$ ,  $(2, 4, 1)$  and  $(0, 1, 0)$

1- construct 3 vectors

$$\mathbf{u} \rightarrow (1, 3, 5)$$

$$\mathbf{v} \rightarrow (2, 4, 1)$$

$$\mathbf{w} \rightarrow (0, 1, 0)$$

2- Normalize vectors:

$$\hat{\mathbf{u}} = \left( \frac{1}{\sqrt{1^2+3^2+5^2}}, \frac{3}{\sqrt{1^2+3^2+5^2}}, \frac{5}{\sqrt{1^2+3^2+5^2}} \right)$$

$$\hat{\mathbf{v}} = \left( \frac{2}{\sqrt{2^2+4^2+1^2}}, \frac{4}{\sqrt{2^2+4^2+1^2}}, \frac{1}{\sqrt{2^2+4^2+1^2}} \right)$$

$$\hat{\mathbf{w}} = (0, 1, 0)$$

$$\therefore \hat{\mathbf{u}} = (0.16, -0.507, 0.84)$$

$$\hat{\mathbf{v}} = (0.436, 0.87, 0.218)$$

$$\hat{\mathbf{w}} = (0, 1, 0)$$

3- Convert to  $O(x, y, z)$

$$C = \begin{bmatrix} \hat{\mathbf{u}} \\ \hat{\mathbf{v}} \\ \hat{\mathbf{w}} \end{bmatrix} = \begin{bmatrix} 0.16 & -0.507 & 0.84 \\ 0.436 & 0.87 & 0.218 \\ 0 & 1 & 0 \end{bmatrix}$$

4- Return to  $x, y, z$  origin

$$\mathbf{P} = \begin{bmatrix} 6 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

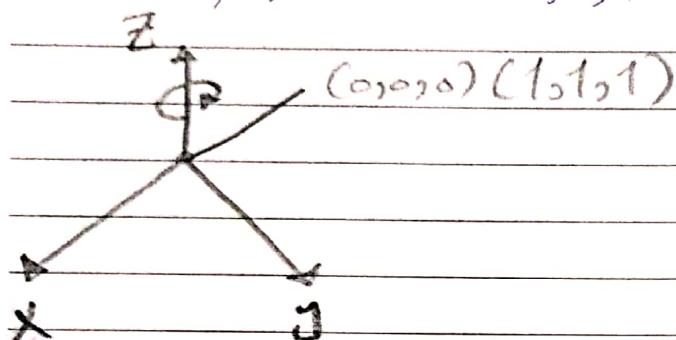
5- Convert to  $O(u, v, w)$ :

$$C^{-1} = \begin{bmatrix} u & v & w \end{bmatrix} = \begin{bmatrix} 0.16 & 0.436 & 0 \\ -0.507 & 0.87 & 1 \\ 0.84 & 1 & 0 \end{bmatrix}$$

$$\text{Composite} = C^{-1} \cdot P \cdot C$$

2018!

write the transformation matrix and opengl code needed to rotate some point 60 degree clockwise about the line connecting the points  $(0,0,0)$  and  $(1,1,1)$ .



1] Translate line to origin so the line will be parallel with z axes.

$$T = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ gltranslate } (-1, -1, 0)$$

2] clockwise  $\rightarrow$  from x to y and  $-\theta$   
Rotate the line about z clockwise.

$$R = \begin{bmatrix} \cos(60) & -\sin(60) & 0 & 0 \\ \sin(60) & \cos(60) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Undo step 1:

$$T^{-1} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

∴ Composite Matrix =

$$T^{-1} \cdot B \cdot T$$

2018:

Find the affine transformation needed to compute the position of some 2D world position in the coordinate system having basis vectors  $(0.6, 0.8)$  and origin  $(20, 25)$   
 $(-0.8, 0.6)$

1. Construct the vectors:

$$u \rightarrow (0.6, 0.8) \quad v \rightarrow (-0.8, 0.6)$$

2. Normalize the vectors:

$$\hat{u} = \left( \frac{0.6}{\sqrt{(0.6)^2 + (0.8)^2}}, \frac{0.8}{\sqrt{(0.6)^2 + (0.8)^2}} \right) = (0.6, 0.8)$$

$$\hat{v} = \left( \frac{-0.8}{\sqrt{(-0.8)^2 + (0.6)^2}}, \frac{0.6}{\sqrt{(-0.8)^2 + (0.6)^2}} \right) = (-0.8, 0.6)$$

3. Translate to origin:

$$T_1 = \begin{bmatrix} 1 & 0 & -20 \\ 0 & 1 & -25 \\ 0 & 0 & 1 \end{bmatrix}$$

4. Rotate  $(\hat{u}, \hat{v}) \rightarrow (x, y)$

$$B = \begin{bmatrix} 0.6 & 0.8 & 0 \\ -0.8 & 0.6 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

5. Undo step 3

$$T^{-1} = \begin{bmatrix} 1 & 0 & 20 \\ 0 & 1 & 25 \\ 0 & 0 & 1 \end{bmatrix}$$

composit Matrix

$$= T^{-1} \cdot B \cdot T$$

2015:

\* Trace the general polygon filling algorithm with:

$$(30, 10) - (15, 15) - (30, 20) - (10, 10)$$

$$(30, 10) \text{ } (15, 15) \rightarrow \frac{15-30}{15-10} = -3$$

$$(15, 15) \text{ } (30, 20) \rightarrow \frac{30-15}{20-15} = 3$$

$$(30, 20) \text{ } (10, 10) \rightarrow \frac{10-30}{10-20} = 2$$

(10, 10) (30, 10) X have same y

1	11	
2	N	
3	N	
4	N	X minus Ymax
5	30	X minus Ymax
6	-3	15
7		10
8		2
9		20

11		
12		
13		
14	X minus Ymax	
15	15	3
		20

$y = 10$

Sort  $\Rightarrow [10 | 2 | 20] \rightarrow [30 | -3 | 15]$

DrawLine (10, 10)  $\rightarrow$  (30, 10)

$y = 11$

update  $\Rightarrow [12 | 2 | 20] \rightarrow [27 | -3 | 15]$

DrawLine (12, 11)  $\rightarrow$  (27, 11)

$y = 12$

update  $\Rightarrow [14 | 2 | 20] \rightarrow [24 | -3 | 15]$

DrawLine (14, 12)  $\rightarrow$  (24, 12)

$y = 13$

update  $\Rightarrow [16 | 2 | 20] \rightarrow [21 | -3 | 15]$

DrawLine (16, 13)  $\rightarrow$  (21, 13)

$y = 14$

update  $\Rightarrow [18 | 2 | 20] \rightarrow [18 | -3 | 15]$

DrawLine (18, 14)  $\rightarrow$  (18, 14)

$y = 15$

delete  $\Rightarrow [18 | -3 | 15]$

update  $\Rightarrow [20 | 2 | 20]$

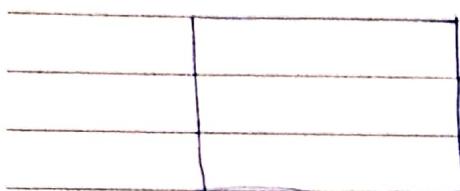
Active  $[15 | 3 | 20] \rightarrow [20 | 2 | 20]$

DrawLine (15, 15)  $\rightarrow$  (20, 15)

End \*

2015:

Rotate figure 1 to figure 2  $c(30, 23)$



A(10, 15)

Figure (1)



A'(30, 13)

Figure (2)

[1] Compute center of Figure (1):

$$\text{center} = \frac{10+18}{2} = 14 \quad \frac{21+15}{2} = 18$$

[2] Translate shape to origin:

$$T = \begin{bmatrix} 1 & 0 & -14 \\ 0 & 1 & -18 \\ 0 & 0 & 1 \end{bmatrix}$$

[3] Rotate Figure (2) at origin anti-clockwise:

$$R = \begin{bmatrix} \cos(45) & -\sin(45) & 0 \\ \sin(45) & \cos(45) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

[4] Compute center of figure (2)

$$\text{center} = \frac{30+30}{2} = 30 \quad \frac{23+13}{2} = 18$$

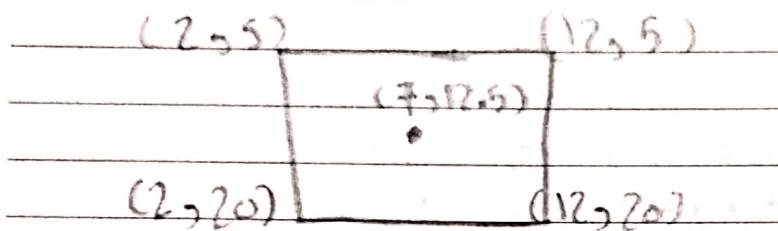
5 Translate figure (2) to (38, 18):

$$T^{-1} = \begin{bmatrix} 1 & 0 & 30 \\ 0 & 1 & 18 \\ 0 & 0 & 1 \end{bmatrix}$$

Composite Matrix =

$$T^{-1} \cdot B \cdot T$$

Map A rectangle left=2 top=5 width=10 height=15  
to square centered at (8,2) with length=1



① Calculate center of rectangle =

$$\text{center} = \frac{2+12}{2} = 7 \quad \frac{20+5}{2} = 12.5$$

② Translate Rectangle to origin:

$$T = \begin{bmatrix} 1 & 0 & -7 \\ 0 & 1 & -12.5 \\ 0 & 0 & 1 \end{bmatrix}$$

③ Scale width to 1 length to 1;

$$S_1 = \begin{bmatrix} \frac{1}{10} & 0 & 0 \\ 0 & \frac{1}{15} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

④ Translate from origin to square center

$$T_2 = \begin{bmatrix} 1 & 0 & 8 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{composite matrix} = T_2 \cdot S_1 \cdot T$$

2012:

write algorithm to draw spiral with parametric equations:

$$x = \theta \cos \theta$$

$$\theta \in [0, 20\pi]$$

$$y = \theta \sin \theta$$

for (int theta=0, theta< 62.8, theta+=  $\frac{1}{20 * 22}$ )

int x = theta + cos(cos(theta));

int y = theta + sin(sin(theta));

setpixel(Round(x), Round(y));

end for

Derive an algorithm to compute the intersection between line segment and the circle:

$$(x - x_c)^2 + (y - y_c)^2 = R^2$$

use parametric equation of line:

$$x(t) = x_1 + (x_2 - x_1)t$$

$$y(t) = y_1 + (y_2 - y_1)t$$

plug parametric equation into circle:

$$(x_1 + (x_2 - x_1)t)^2 + (y_1 + (y_2 - y_1)t)^2 = R^2$$

$$\begin{aligned} & [x_1^2 + 2x_1(x_2 - x_1)t + (x_2 - x_1)^2 t^2] \\ & + [y_1^2 + 2y_1(y_2 - y_1)t + (y_2 - y_1)^2 t^2] = R^2 \end{aligned}$$

using form of quadratic equation:

$$t^2[(x_2 - x_1)^2 + (y_2 - y_1)^2] + t[2x(x_2 - x_1) + 2y(y_2 - y_1)]$$

$$+ x_1^2 + y_1^2 - R^2 = 0$$

$$\Rightarrow At^2 + Bt - C = 0$$

$$t = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$$

$$\therefore d = B^2 - 4AC \Rightarrow \text{determinant}$$

if  $d < r$  then line cuts circle in two points

if  $d=r$  then line and circle are tangent

if  $d > r$  then line not cut circle in any point

Derive an algorithm to compute the intersection between line segment and the circle:

$$\frac{(x-x_c)^2}{a^2} + \frac{(y-y_c)^2}{b^2} = 1$$

Use parametric equation of line:

$$x(t) = x_1 + (x_2 - x_1)t$$

$$y(t) = y_1 + (y_2 - y_1)t$$

plug parametric equation into ellipse:

$$\frac{(x_1 + (x_2 - x_1)t)^2}{a^2} + \frac{(y_1 + (y_2 - y_1)t)^2}{b^2} = 1$$

$$\left[ \frac{1}{a^2} (x_1^2 + 2x_1(x_2 - x_1)t + (x_2 - x_1)^2 t^2) \right] + = 1$$

$$\left[ \frac{1}{b^2} (y_1^2 + 2y_1(y_2 - y_1)t + (y_2 - y_1)^2 t^2) \right]$$

using form of quadratic equation:

$$t^2 \left[ \frac{(x_2 - x_1)^2}{a^2} + \frac{(y_2 - y_1)^2}{b^2} \right] + t \left[ \frac{2x(x_2 - x_1)}{a^2} + \frac{2y(y_2 - y_1)}{b^2} \right]$$

$$+ \left[ \frac{x_1^2}{a^2} + \frac{y_1^2}{b^2} - 1 \right] = 0$$

$$\Rightarrow At^2 + Bt - C = 0$$

$$t = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$$

$$\therefore d = B^2 - 4AC \rightarrow \text{determinant}$$

if  $d < 0$  the line and ellipse does not intersect

if  $d = 0$  the line and ellipse tangent

if  $d > 0$  the line and ellipse intersect

Trace the convex polygon filling algorithm.

Compute the edge table values for a polygon  
of vertices  $(15, 10), (80, 12), (60, 15), (10, 16)$

	Xleft	Xright
1	$\infty$	$-\infty$
2	$\infty$	$-\infty$
3	$\infty$	$-\infty$

$\boxed{1} (10, 16) (15, 10) \text{ swap} \Rightarrow (15, 10) (10, 16)$

$$+ \because y=10 \quad x=15 \quad \text{minv} = -\frac{5}{3}$$

$$y=10 \quad [15 \quad 15] \rightarrow y++ \quad x+=\text{minv}$$

$$+ \because y=11 \quad x=\frac{85}{6} \quad \text{minv} = -\frac{5}{6}$$

$$y=11 \quad [\frac{85}{6} \quad \frac{85}{6}] \rightarrow y++ \quad x+=\text{minv}$$

$$+ \because y=12 \quad x=\frac{40}{3} \quad \text{minv} = -\frac{5}{6}$$

$$y=12 \quad [\frac{40}{3} \quad \frac{40}{3}] \rightarrow y++ \quad x+=\text{minv}$$

$$+ \because y=13 \quad x=2\frac{5}{2} \quad \text{minv} = -\frac{5}{8}$$

$$y=13 \quad [2\frac{5}{2} \quad 2\frac{5}{2}] \rightarrow y++ \quad x+=\text{minv}$$

$$+ \because y=14 \quad x=3\frac{5}{3} \quad \text{minv} = -\frac{5}{6}$$

$$y=14 \quad [3\frac{5}{3} \quad 3\frac{5}{3}] \rightarrow y++ \quad x+=\text{minv}$$

$$+ \because y=15 \quad x=\frac{65}{6} \quad \text{minv} = -\frac{5}{8}$$

$$y=15 \quad [\frac{65}{6} \quad \frac{65}{6}] \rightarrow y++ \quad x+=\text{minv}$$

+  $y=16$  end of  $\boxed{1}$

$$\boxed{2} (15, 10) (80, 12) \rightarrow \frac{80-15}{72-10} = \frac{65}{2}$$

$$+ y=10 \quad x=15 \quad \min v = \frac{65}{2}$$

$$y_{10} = [15 \quad 15] \rightarrow y++ \quad x+=\min v$$

$$+ y=11 \quad x=\frac{95}{2} \quad \min v = \frac{65}{2}$$

$$y_{11} = \left[ \frac{85}{6} \quad \frac{95}{2} \right] \rightarrow y++ \quad x+=\min v$$

$$+ y=12 \quad \text{end of } \boxed{2}$$

$$\boxed{3} (80, 12) (60, 15) \rightarrow \frac{60-80}{15-12} = -\frac{20}{3}$$

$$+ y=12 \quad x=80 \quad \min v = -\frac{20}{3}$$

$$y=12 \left[ \frac{40}{3} \quad 80 \right] \rightarrow y++ \quad x+=\min v$$

$$+ y=13 \quad x=\frac{220}{3} \quad \min v = -\frac{20}{3}$$

$$y=13 \left[ \frac{25}{2} \quad \frac{220}{3} \right] \rightarrow y++ \quad x+=\min v$$

$$+ y=14 \quad x=\frac{200}{3} \quad \min v = -\frac{20}{3}$$

$$y=14 \left[ \frac{35}{3} \quad \frac{200}{3} \right] \rightarrow y++ \quad x+=\min v$$

$$+ y=15 \quad \text{end of } \boxed{3}$$

Edge Table =

10	15	15
11	$\frac{85}{6}$	$\frac{95}{2}$
12	$\frac{40}{3}$	80
13	$\frac{75}{2}$	$\frac{200}{3}$
14	$\frac{35}{3}$	$\frac{200}{3}$
15	$\frac{65}{6}$	$\frac{65}{6}$