



**Cairo University**  
**Faculty of Computers and Information**  
**Information Technology Department**  
**Course: Computer Graphics (IT322)**  
**Spring 2015**



**ATTEMPT ALL QUESTIONS**

**Question 1**

**(15 points)**

- Derive the parametric circle drawing algorithm in its most efficient form.
- Describe the parametric cubic Bezier curves. Show how their parameters are computed from the control points.
- Trace the mid-point line drawing algorithm for drawing the line with end points (12, 9), (2, 15). Summarize your traces by supplying the following information:

<b>Initial decision:</b> $d_{initial} =$		
<b>Change in decision when <math>d &lt; 0</math>:</b> $d_1 =$		
<b>Change in decision when <math>d &gt; 0</math>:</b> $d_2 =$		
Traces		
X	Y	Decision variables

**Question 2**

**(15 points)**

- What is clipping in 2D? Write an algorithm to clip a line against a rectangular window.
- Write the convex polygon raster scan filling algorithm? Show why it cannot be used to draw non-convex polygons? What are the modifications needed to overcome the problems of convex polygons.
- Trace the general polygon filling algorithm while filling the polygon: (30, 10) – (15, 15) – (30, 20) – (10, 10) by supplying the following information:

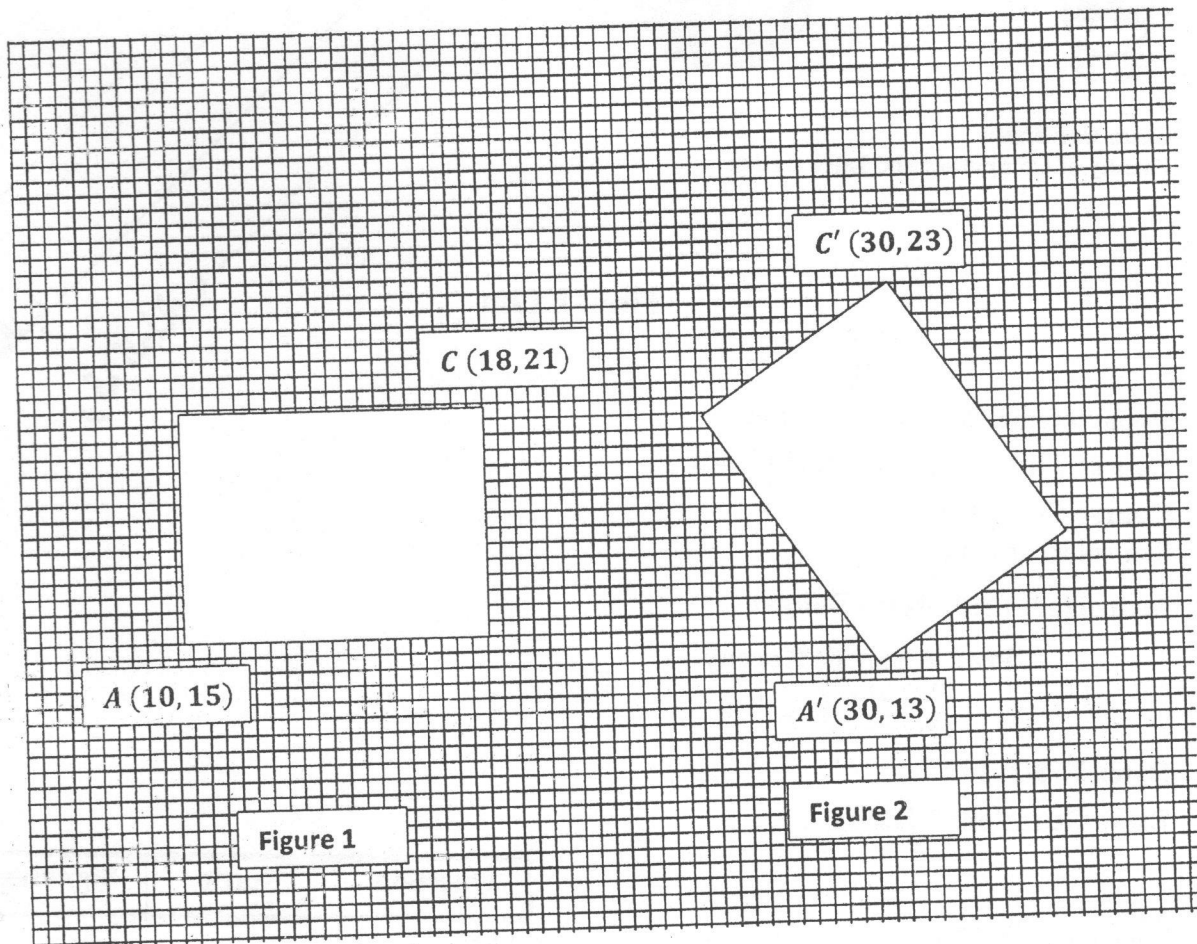
Y	Active List	Filling Line Coordinates
10		
11		
12		
13		
14		
15		

**Question 3**

**(15 points)**

Write a homogeneous transformation matrix (or product of matrices) to:

- Translate an object a distance of 10 steps in the direction (3, 0, 4).
- Rotate an object about the y axis with a rotation angle of  $30^\circ$  in the anti clock wise direction.
- Transform the rectangle in Figure 1 to the rectangle in Figure 2 as shown below.



- Scale a 3D object around the fixed point  $(5, 7, 2)$  uniformly with a scaling factor of 0.5.
- Shear a 2D object in the direction  $(5, 12)$  with a shearing factor 3.
- Compute the representation of a given world point in a coordinate system located at  $(4, 2, 10)$  with principle axes  $(0.6, 0.8, 0)$ ,  $(-0.8, 0.6, 0)$ ,  $(0, 0, 1)$ . All the given vectors are measured in the world coordinate system.

(15 points)

#### Question 4

- Show how the OpenGL Frustum matrix is computed. Write an algorithm that computes the frustum matrix derived from the six clipping point parameters: (left, right, bottom, top, near, far).
- Given the following camera view parameters:  $COP = (-1, -1, -1)$ ,  $TP = (0, 0, 0)$ ,  $VUP = (1, 0, 1)$ . The clipping volume parameters are: (left=-10, right=10, bottom=-20, top=20, near=10, far=30). The viewport parameters are (left=5, right=5, width=200, height=300)
  - Compute the camera view matrix.
  - Compute the frustum matrix.
  - Compute the viewport matrix
  - Compute the coordinates of the world points:  $(15, 15, 15)$ ,  $(15, 15, 20)$  and  $(20, 20, 25)$  in the viewport.

*Best wishes*