

Lec. 12

15/11

(LTI Systems) Properties

[I] Commutative: $y[n] = x[n] * h[n]$

$$y[n] \triangleq \sum_{k=-\infty}^{+\infty} x[k] h[n-k] \quad \text{--- (1)}$$

$$m = n - k \implies k = n - m$$

$$\text{at } k = -\infty \implies m = n - (-\infty) = n + \infty = +\infty$$

$$\text{at } k = +\infty \implies m = n - \infty = -\infty$$

$$\therefore y[n] = \sum_{m=-\infty}^{+\infty} x[n-m] h[m]$$

$$= \sum_{m=-\infty}^{+\infty} h[m] x[n-m]$$

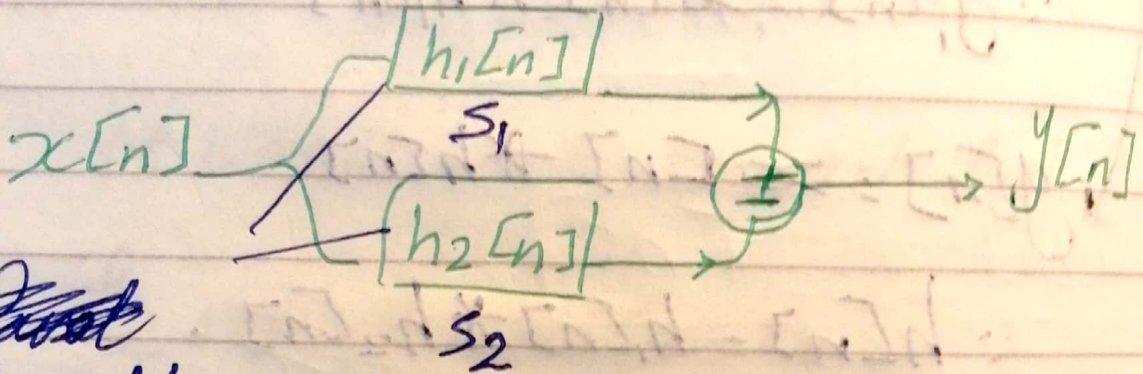
Rename: $y[n] = \sum_{k=-\infty}^{+\infty} h[k] x[n-k]$

$$= h[n] * x[n] \quad \text{--- (2)}$$

[2] Distributive:- لتوزيع

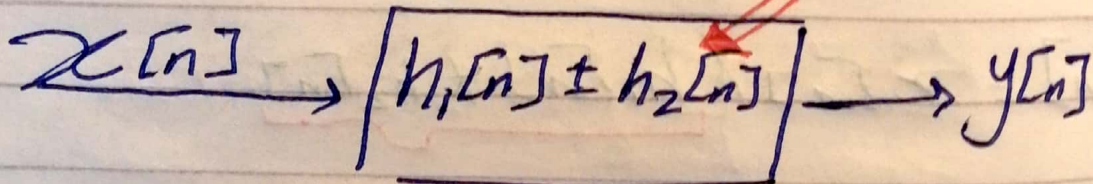
$$y[n] = x[n] * \{h_1[n] \pm h_2[n]\}$$

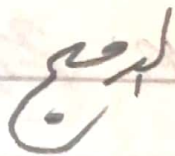
$$= \underbrace{x[n] * h_1[n]}_{s_1} \pm \underbrace{x[n] * h_2[n]}_{s_2}$$



~~Parallel~~
Parallel

$$h[n] = h_1[n] \pm h_2[n]$$



[3] Associative: 

$$y[n] = \underbrace{x[n] * h_1[n]} * h_2[n]$$

$$y[n] = y_1[n] * h_2[n]$$

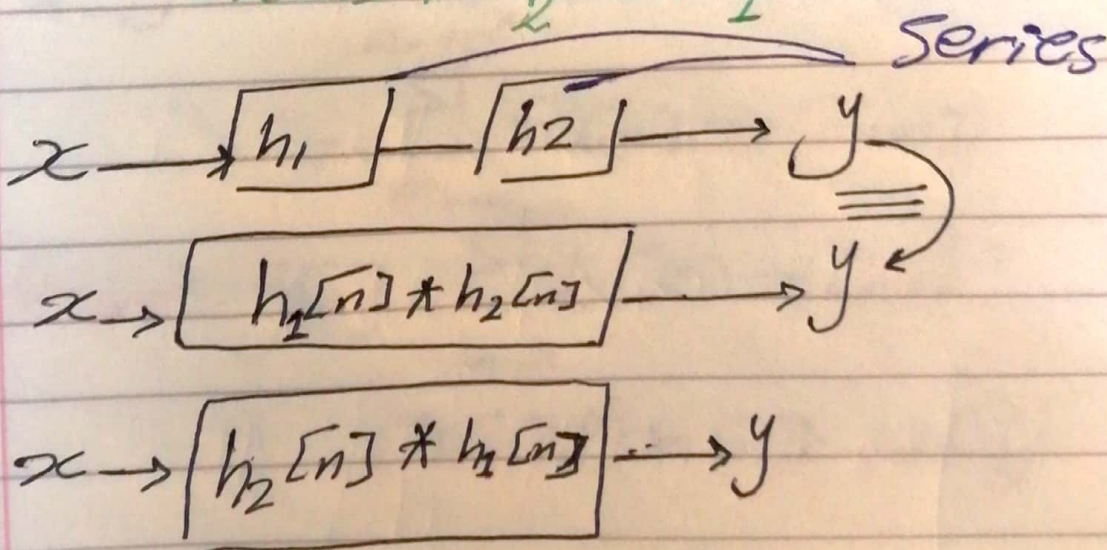
$$\therefore y_1[n] = x[n] * h_1[n]$$

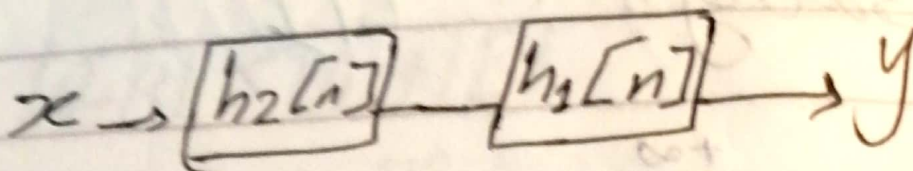
$$\rightarrow y[n] = x[n] * h[n]$$

$$\therefore h[n] = h_1[n] * h_2[n]$$

$$y[n] = x[n] * \underbrace{h_1[n] * h_2[n]}$$

$$= x[n] * h_1[n] * h_2[n]$$





[4] Memory less:- مترجم لانه

$$y[n] = \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

we need $h[n-k] = 0 \quad \forall n \neq k$

re-write it to be $n-k \neq 0$

∴ The required condition is

$$h[n-k] = 0 \quad \forall n-k \neq 0$$

$$h[n] = 0 \quad \forall n \neq 0$$

$$h[n] = 0 \quad \forall n \neq 0$$

[5] Causality: LTI

$$y[n] = \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

causal

$$h[n-k] = 0 \quad \forall \quad k > n$$

causal

$$n-k \leq 0$$

$$h[n] = 0 \quad \forall \quad n < 0$$

[6] Stability: LTI

$$y[n] = \sum_{k=-\infty}^{+\infty} h[k] x[n-k]$$

if $|x[n]| \leq K; K < \infty; \forall n$

$$\therefore |x[n-k]| \leq K$$

we need $|y[n]| < \infty$

$$\therefore |y[n]| = \left| \sum_{k=-\infty}^{+\infty} h[k] \cdot x[n-k] \right|$$

$$\therefore |A+B| \leq |A| + |B|$$

$$\therefore |y[n]| \leq \sum_{k=-\infty}^{+\infty} |h[k]x[n-k]|$$

$$\therefore |A \cdot B| = |A| \cdot |B|$$

$$\therefore |y[n]| \leq \sum_{k=-\infty}^{+\infty} |h[k]| |x[n-k]|$$

$$\leq \sum_{k=-\infty}^{+\infty} |h[k]| \cdot 1$$

$$\therefore |y[n]| \leq 1 \cdot \sum_{k=-\infty}^{+\infty} |h[k]|$$

\therefore the required Condition for LTI

sys. to be stable is

$$\sum_{n=-\infty}^{+\infty} |h[n]| < \infty$$

[7] Invertibility:

$$x \xrightarrow{h_1} y \xrightarrow{h_1^{-1}} x$$

$$x * [h_1 * h_1^{-1}] = x$$

$$\delta[n]$$

$$y[n] = x[n - n_0]$$

\uparrow \uparrow
 h δ

$$\therefore h_1[n] = \delta[n - n_0]$$

$$w[n] = y[n + n_0] = x[n + n_0 - n_0]$$

$$= x[n]$$

$$h_1^{-1} = \delta[n + n_0]$$

$$h_1[n] * h_1^{-1}[n]$$

$$\delta[n-n_0] \quad \delta[n+n_0]$$

$$= \sum_{k=-\infty}^{+\infty} h_1[k] h_1^{-1}[n-k]$$

$$= \sum_{k=-\infty}^{+\infty} \underbrace{\delta[k-n_0]}_{\boxed{k=n_0}} \delta[n-k+n_0]$$

$$= 0 + 0 + 0 + 0 + \delta[n] + 0 + 0 + \dots$$

$$\boxed{\therefore h_1[n] * h_1^{-1}[n] = \delta[n]}$$