

数学分析第八次作业

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习题 6.7: (A) 2(2, 6), 4(3), 8, 10(2), 12(2, 4, 6, 7), 15, (B)2, 5, 6

习题 6.8: (A) 1, 2(3, 5), 3, 8(2), 10, 16(1, 3, 6)

6.7 (A)

2.

(2)

对于直线 $y = x$:

$$\int_{(C)} xy dx + (y - x) dy = \int_0^1 x^2 dx + \int_0^1 (x - x) dx = \frac{1}{3}$$

对于抛物线 $y^2 = x$:

$$\int_{(C)} xy dx + (y - x) dy = \int_0^1 y^3 dy^2 + \int_0^1 (y - y^2) dy = \frac{2}{5} + \frac{1}{6} = \frac{17}{30}$$

对于立方抛物线 $y = x^3$:

$$\int_{(C)} xy dx + (y - x) dy = \int_0^1 x^4 dx + \int_0^1 (x^3 - x) dx^3 = \frac{1}{5} - \frac{1}{4} = -\frac{1}{20}$$

(6)

$$\text{设 } \begin{cases} x = \cos \theta \\ y = \sin \theta \\ z = 2 - \cos \theta + \sin \theta \end{cases}$$

则有

$$\begin{aligned}
& \oint_{(C)} (z-y)dx + (x-z)dy + (x-y)dz \\
&= \int_0^{-2\pi} (2-\cos\theta)d\cos\theta + (2\cos\theta - \sin\theta - 2)d\sin\theta + (\cos\theta - \sin\theta)d(2-\cos\theta + \sin\theta) \\
&= \int_0^{-2\pi} (2-\cos\theta)(-\sin\theta)d\theta + (2\cos\theta - \sin\theta - 2)\cos\theta d\theta + (\cos\theta - \sin\theta)(\sin\theta + \cos\theta)d\theta \\
&= \int_0^{-2\pi} \left(-4\sin^2(\theta) - 2\sqrt{2}\sin\left(\theta + \frac{\pi}{4}\right) + 3\right)d\theta \\
&= -2\pi
\end{aligned}$$

4. (3)

对于 $(1, 0)$ 到 $(0, 1)$ 的下半圆周 $(x-1)^2 + (y-1)^2 = 1$

使用参数方程 $\begin{cases} x = 1 + \cos\theta \\ y = 1 + \sin\theta \end{cases}$, 则 $\vec{\tau} = \frac{\{x'(\theta), y'(\theta)\}}{\sqrt{x'(\theta)^2 + y'(\theta)^2}} = \{-\sin\theta, \cos\theta\}$, 其中 θ 由 $\theta = \frac{3}{2}\pi$ 到 $\theta = \pi$, 即 π 到 $\frac{3}{2}\pi$ 时取反.

$$\begin{aligned}
& \int_{(C)} P(x, y)dx + Q(x, y)dy = - \int_{(C)} \{P, Q\} \cdot \vec{\tau} ds = \\
& - \int_{(C)} [Q(1 + \cos\theta, 1 + \sin\theta)\cos\theta - P(1 + \cos\theta, 1 + \sin\theta)\sin\theta] ds
\end{aligned}$$

$$\text{而又有 } \sin\theta = -\sqrt{1 - \cos^2\theta} = -\sqrt{1 - (x-1)^2} = -\sqrt{2x - x^2}$$

$$\text{所以原式转化为 } \int_{(C)} \left[-\sqrt{2x - x^2} P(x, y) + (1-x)Q(x, y) \right] ds$$

8.

(1)

进行参数变换 $\begin{cases} x = \rho \cos\theta \\ y = \rho \sin\theta \\ z = \rho \end{cases}$, 则有

$$\frac{\partial(x, y)}{\partial(\rho, \theta)} = \begin{vmatrix} \cos\theta & -\rho \sin\theta \\ \sin\theta & \rho \cos\theta \end{vmatrix} = \rho \sin^2\theta + \rho \cos^2\theta = \rho$$

$$\iint_{(S)} \frac{e^z}{\sqrt{x^2 + y^2}} dx \wedge dy = - \iint_{D_{\theta\rho}} \frac{e^\rho}{\rho} \cdot \rho d\theta d\rho = - \int_0^{2\pi} d\theta \int_1^2 e^\rho d\rho$$

(2)

$$\text{对于 } I = \iiint_{\Sigma} (x+y+z)dx \wedge dy + (y-z)dy \wedge dz$$

其中 Σ 是正方体的表面, 即六个面, 边长为 a .

$$\begin{aligned}
 I &= \iint_{\Sigma_{\text{top}}} + \iint_{\Sigma_{\text{bottom}}} + \iint_{\Sigma_{\text{front}}} + \iint_{\Sigma_{\text{back}}} + \iint_{\Sigma_{\text{left}}} + \iint_{\Sigma_{\text{right}}} \\
 &= \iint_{D_{xy}} -(x+y+0)dx dy + \iint_{D_{xy}} (x+y+1)dx dy + 0 + 0 + 0 + 0 \\
 &= \int_0^1 dx \int_0^1 (x+y+1)dy - \int_0^1 dx \int_0^1 (x+y)dy
 \end{aligned}$$

10. (2)

$$\text{坐标变换} \begin{cases} x = \cos \theta \\ y = \sin \theta \\ z = 0 \end{cases}$$

则有

$$\begin{aligned}
 &\oint_{(C)} (3x^2 - 3yz + 2xz)dx + (3y^2 - 3xz + z^2)dy + (3z^2 - 3xy + x^2 + 2yz)dz \\
 &= \int_0^{2\pi} (3\cos^2 \theta)d\cos \theta + (3\sin^2 \theta)d\sin \theta \\
 &= \int_0^{2\pi} (-3\sin \theta \cos^2 \theta + 3\sin^2 \theta \cos \theta)d\theta \\
 &= 0
 \end{aligned}$$

12.

(2)

对于 $S_1 : x = 0, S_2 : y = 0, S_3 : z = 0, S_4 : x + y + z = 1$

$$\begin{aligned}
 &\oint_{(S)} xydy \wedge dz + yzdz \wedge dx + zx dx \wedge dy \\
 &= \iint_{S_1} + \iint_{S_2} + \iint_{S_3} + \iint_{S_4} \\
 &= 0 + 0 + 0 + \iint_{S_4} (1-y-z)ydydz + \iint_{S_4} (1-x-z)zdzdx + \iint_{S_4} (1-x-y)x dx dy \\
 &= \int_0^1 dy \int_0^{1-y} (1-y-z)ydz + \int_0^1 dz \int_0^{1-z} (1-x-z)zdx + \int_0^1 dx \int_0^{1-x} (1-x-y)x dy \\
 &= \int_0^1 \frac{y(y-1)^2}{2} dy + \int_0^1 \frac{z(z-1)^2}{2} dz + \int_0^1 \frac{x(x-1)^2}{2} dx \\
 &= 3 \int_0^1 \frac{y(y-1)^2}{2} dy \\
 &= \frac{1}{8}
 \end{aligned}$$

(4)

$$\begin{aligned}& \iint_{(S)} -ydz \wedge dx + (z+1)dx \wedge dy \\&= \iint_{S_1} (-\sqrt{4-x^2})dzdx - \iint_{S_1} (-\sqrt{4-x^2})dzdx + 0 \\&= -2 \int_{-2}^2 dx \int_0^{2-x} \sqrt{4-x^2} dz \\&= -2 \int_{-2}^2 (2-x) \sqrt{4-x^2} dx \\&= -2 \int_{-2}^2 (2-x) \sqrt{4-x^2} dx \\&= -2 \int_{-2}^2 2\sqrt{4-x^2} dx + 2 \int_{-2}^2 x\sqrt{4-x^2} dx \\&= -8\pi\end{aligned}$$

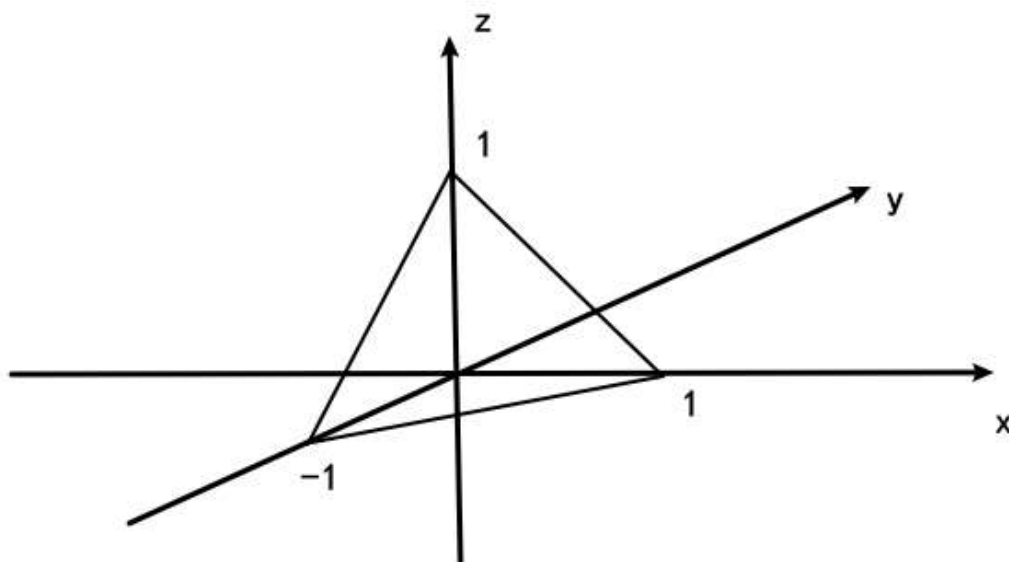
(6)

$$\text{令} \begin{cases} x = \sin \varphi \cos \theta \\ y = \sin \varphi \sin \theta \\ z = 1 + \cos \varphi \end{cases}$$

$$\text{则} \frac{\partial(x, y)}{\partial(\varphi, \theta)} = \begin{vmatrix} \cos \varphi \cos \theta & -\sin \varphi \sin \theta \\ \cos \varphi \sin \theta & \sin \varphi \cos \theta \end{vmatrix} = \frac{1}{2} \sin(2\varphi)$$

$$\begin{aligned}& \iint_{(S)} z^2 dx \wedge dy \\&= \iint_{D_{\varphi, \theta}} (1 + \cos \varphi)^2 \cdot \frac{1}{2} \sin(2\varphi) d\varphi d\theta \\&= \int_0^{2\pi} d\theta \int_0^{\pi} (1 + \cos \varphi)^2 \cdot \frac{1}{2} \sin(2\varphi) d\varphi \\&= \int_0^{2\pi} d\theta \int_0^{\pi} (\sin \varphi \cos \varphi + 2 \sin \varphi \cos^2 \varphi + \sin \varphi \cos^3 \varphi) d\varphi \\&= \int_0^{2\pi} d\theta \int_0^{\pi} (\sin \varphi \cos \varphi + 2 \sin \varphi \cos^2 \varphi + \sin \varphi \cos^3 \varphi) d\varphi \\&= \frac{8\pi}{3}\end{aligned}$$

(7)



$S : x - y + z = 1$ 的法向量 $\vec{n} = \{1, -1, 1\}$

$$\because \{f(x, y, z), 2f(x, y, z), f(x, y, z)\} \cdot \{1, -1, 1\} = 0$$

$$\begin{aligned} \therefore I &= \iint_{(S)} x dy \wedge dz + y dz \wedge dx + z dx \wedge dy \\ &= \iint_{D_{yz}} (y - z + 1) dy dz - \iint_{D_{zx}} (x + z - 1) dz dx + \iint_{D_{xy}} (y - x + 1) dx dy \\ &= \int_{-1}^0 dy \int_0^{y+1} (y - z + 1) dz - \int_0^1 dx \int_0^{1-x} (x + z - 1) dz + \int_{-1}^0 dy \int_0^{y+1} (y - x + 1) dx \\ &= 2 \int_{-1}^0 \frac{(y+1)^2}{2} dy + \int_0^1 \frac{(x-1)^2}{2} dx \\ &= \frac{1}{2} \end{aligned}$$

15.

(1)

$$\therefore y = 3 - \frac{3}{2}x - \sqrt{3}z$$

$$\therefore \frac{\partial(y, z)}{\partial(z, x)} = \begin{vmatrix} -\sqrt{3} & -\frac{3}{2} \\ 1 & 0 \end{vmatrix} = \frac{3}{2}, \frac{\partial(z, x)}{\partial(z, x)} = 1, \frac{\partial(x, y)}{\partial(z, x)} = \begin{vmatrix} 0 & 1 \\ -\sqrt{3} & -\frac{3}{2} \end{vmatrix} = \sqrt{3}$$

$$\text{且 } \sqrt{1 + y_z^2 + y_x^2} = \frac{5}{2}$$

$$\begin{aligned}
& \iint_{(S)} Pdy \wedge dz + Qdz \wedge dx + Rdx \wedge dy \\
&= \iint_{D_{zx}} \left(\frac{3}{2}P + Q + \sqrt{3}R \right) dzdx \\
&= \iint_{D_{zx}} \left(\frac{3}{5}P + \frac{2}{5}Q + \frac{2\sqrt{3}}{5}R \right) \sqrt{1+y_z^2+y_x^2} dzdx \\
&= \iint_{(S)} \left(\frac{3}{5}P + \frac{2}{5}Q + \frac{2\sqrt{3}}{5}R \right) dS
\end{aligned}$$

(2)

$$\text{令} \begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \\ z = 8 - \rho^2 \end{cases}$$

$$\therefore \frac{\partial(y, z)}{\partial(\rho, \theta)} = \begin{vmatrix} \sin \theta & \rho \cos \theta \\ -2\rho & 0 \end{vmatrix} = 2\rho^2 \cos \theta, \frac{\partial(z, x)}{\partial(\rho, \theta)} = \begin{vmatrix} -2\rho & 0 \\ \cos \theta & -\rho \sin \theta \end{vmatrix} = 2\rho^2 \sin \theta, \frac{\partial(x, y)}{\partial(\rho, \theta)} = \begin{vmatrix} \cos \theta & -\rho \sin \theta \\ \sin \theta & \rho \cos \theta \end{vmatrix} = \rho$$

$$\text{且 } |\vec{r}_\rho \times \vec{r}_\theta| = \sqrt{(2\rho^2 \cos \theta)^2 + (2\rho^2 \sin \theta)^2 + \rho^2} = \sqrt{4\rho^2 + 1}\rho$$

$$\begin{aligned}
& \iint_{(S)} Pdy \wedge dz + Qdz \wedge dx + Rdx \wedge dy \\
&= - \iint_{D_{\rho\theta}} (P \cdot 2\rho^2 \cos \theta + Q \cdot 2\rho^2 \sin \theta + R\rho) d\rho d\theta \\
&= - \iint_{D_{\rho\theta}} \frac{1}{\sqrt{4\rho^2 + 1}} (2P\rho \cos \theta + 2Q\rho \sin \theta + R) |\vec{r}_\rho \times \vec{r}_\theta| d\rho d\theta \\
&= - \iint_{D_{\rho\theta}} \frac{2xP + 2yQ + R}{\sqrt{4x^2 + 4y^2 + 1}} dS
\end{aligned}$$

6.7 (B)

2.

$$\text{令} \begin{cases} x = R \sin \varphi \cos \theta \\ y = R \sin \varphi \sin \theta, \text{则柱面转化为 } R^2 \sin^2 \varphi = R^2 \sin \varphi \cos \theta, 0 \leq \varphi \leq \frac{\pi}{2} \\ z = R \cos \varphi \end{cases}$$

$$\text{即 } \sin \varphi = \cos \theta, \text{原式化为} \begin{cases} x = R \cos^2 \theta \\ y = R \sin \theta \cos \theta \\ z = R |\sin \theta| \end{cases}$$

$$\begin{aligned}
& \oint_{(C)} y^2 dx + z^2 dy + x^2 dz \\
&= \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} R^2 \sin^2 \theta \cos^2 \theta dR \cos^2 \theta + R^2 \sin^2 \theta dR \sin \theta \cos \theta + R^2 \cos^4 \theta dR |\sin \theta| \\
&= \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} (-2R^3 \sin^3 \theta \cos^3 \theta + R^3 \sin^2 \theta \cos 2\theta) d\theta + 0 \\
&= -\frac{\pi}{4} R^3
\end{aligned}$$

5.

$$\text{令} \begin{cases} x = \rho \sin \varphi \cos \theta \\ y = \rho \sin \varphi \sin \theta, \text{则柱面转化为 } \rho^2 \sin^2 \varphi = R^2, \text{即 } \rho = \frac{R}{\sin \varphi} \\ z = \rho \cos \varphi \end{cases}$$

$$\text{则} \begin{cases} x = R \cos \theta \\ y = R \sin \theta \\ z = \frac{R}{\tan \varphi} \end{cases}, \frac{\partial(y, z)}{\partial(\varphi, \theta)} = \begin{vmatrix} 0 & R \cos \theta \\ -\frac{R}{\sin^2 \varphi} & 0 \end{vmatrix} = \frac{R^2 \cos \theta}{\sin^2 \varphi}$$

$$\text{其中 } -R \leq z = \frac{R}{\tan \varphi} \leq R, \text{即 } -\frac{\pi}{2} \leq \varphi \leq -\frac{\pi}{4} \text{ 或 } \frac{\pi}{4} \leq \varphi \leq \frac{\pi}{2}$$

$$\begin{aligned}
& \iint_{(S)} \frac{x dy \wedge dz + z^2 dx \wedge dy}{x^2 + y^2 + z^2} \\
&= \iint_{S_{\text{bottom}}} + \iint_{S_{\text{top}}} + \iint_{S_{\text{side}}} \\
&= 0 + 0 + \iint_S \frac{x dy \wedge dz}{x^2 + y^2 + z^2} \\
&= 0 + 0 + \iint_{S_{\varphi\theta}} \frac{R \cos \theta}{\frac{R^2}{\sin^2 \varphi}} \cdot \frac{R^2 \cos \theta}{\sin^2 \varphi} d\theta d\varphi \\
&= \left(\int_{-\frac{\pi}{2}}^{-\frac{\pi}{4}} d\varphi + \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} d\varphi \right) \int_0^{2\pi} R \cos^2 \theta d\theta \\
&= \frac{1}{2} \pi^2 R
\end{aligned}$$

6.

$$\text{令} \begin{cases} x = R \sin \varphi \cos \theta \\ y = R \sin \varphi \sin \theta, \text{其中 } 0 \leq \varphi \leq \frac{\pi}{2} \\ z = R \cos \varphi \end{cases}$$

$$\text{则有 } \frac{\partial(y, z)}{\partial(\varphi, \theta)} = \begin{vmatrix} R \cos \varphi \sin \theta & R \sin \varphi \cos \theta \\ -R \sin \varphi & 0 \end{vmatrix} = R^2 \sin^2 \varphi \cos \theta$$

$$\frac{\partial(z, x)}{\partial(\varphi, \theta)} = \begin{vmatrix} -R \sin \varphi & 0 \\ R \cos \varphi \cos \theta & -R \sin \varphi \sin \theta \end{vmatrix} = R^2 \sin^2 \varphi \sin \theta$$

$$\frac{\partial(x, y)}{\partial(\varphi, \theta)} = \begin{vmatrix} R \cos \varphi \cos \theta & -R \sin \varphi \sin \theta \\ R \cos \varphi \sin \theta & R \sin \varphi \cos \theta \end{vmatrix} = R^2 \sin \varphi \cos \varphi$$

$$\begin{aligned} & \iint_{(S)} \vec{F} \cdot d\vec{S} \\ &= - \iint_{S_{\varphi\theta}} \frac{1}{R^2} (R^3 \sin^3 \varphi \cos^2 \theta + R^3 \sin^3 \varphi \sin^2 \theta + R^3 \sin \varphi \cos^2 \varphi) d\varphi d\theta \\ &= -R \int_0^{2\pi} d\theta \int_0^{\frac{\pi}{2}} (\sin^3 \varphi + \sin \varphi \cos^2 \varphi) d\varphi \\ &= -2\pi R \end{aligned}$$

6.8 (A)

1.

(1)

错误. 封闭曲线并非正向.

正确解法:

$$\int_{\overline{OB \cup BA \cup AO}} y dx = - \iint_{(\sigma)} -1 d\sigma = \frac{\pi}{4}$$

$$\text{由于 } \int_{\overline{BA}} y dx = 0, \int_{\overline{AO}} y dx = 0$$

$$\text{所以 } \int_{(C)} y dx = \frac{\pi}{4}$$

(2)

解法一错误, 解法二正确.

函数在点 $(0, 0)$ 处并不可导, 不能使用 Green 公式, 解法一错误.

而解法二没有包括 $(0, 0)$ 点, 所以正确.

对于解法一:

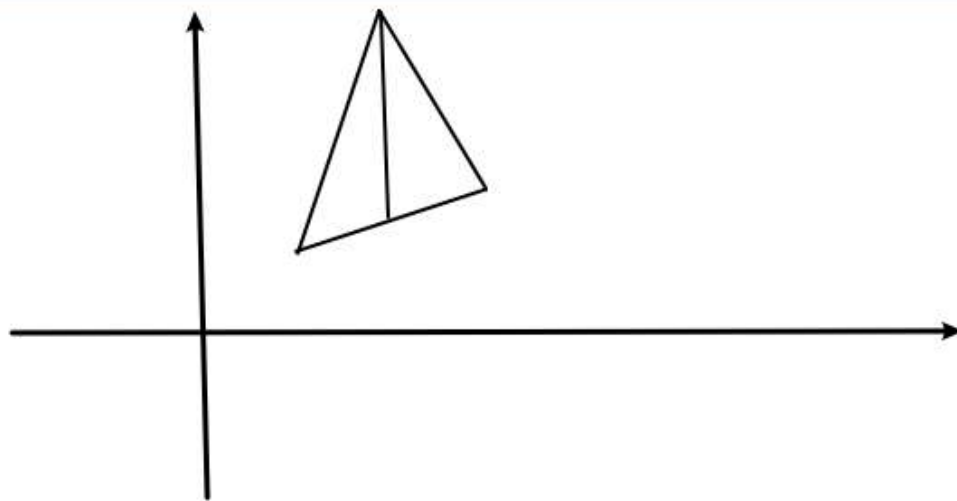
$$\text{设 } \Gamma: x^2 + y^2 = \delta^2$$

$$\begin{aligned} \text{则 } \oint_{(C) \cup \overline{DB'A}} \frac{-y dx + x dy}{x^2 + y^2} &= \oint_{(C) \cup \overline{DB'A} - \Gamma} \frac{-y dx + x dy}{x^2 + y^2} + \oint_{\Gamma} \frac{-y dx + x dy}{x^2 + y^2} = \\ \oint_{\Gamma} \frac{-y dx + x dy}{x^2 + y^2} &= \oint_{\Gamma} \frac{-y dx + x dy}{\delta^2} = -2\pi \end{aligned}$$

$$\text{则 } I = \oint_{\widehat{AB'D}} \frac{-ydx + xdy}{x^2 + y^2} + \oint_{(C) \cup \widehat{DB'A}} \frac{-ydx + xdy}{x^2 + y^2} = -\pi$$

2.

(3)



由 Green 公式可知

$$\begin{aligned} & \oint_{(+C)} (x+y)^2 dx - (x^2 + y^2) dy \\ &= \iint_{D_{xy}} (-2x - 2(x+y)) dx dy \\ &= \int_1^2 dx \int_{\frac{1}{2}x + \frac{1}{2}}^{4x-3} (-4x - 2y) dy + \int_2^3 dx \int_{\frac{1}{2}x + \frac{1}{2}}^{-3x+11} (-4x - 2y) dy \\ &= \int_1^2 \left(-\frac{119x^2}{4} + \frac{77x}{2} - \frac{35}{4} \right) dx + \int_2^3 \left(\frac{21x^2}{4} + \frac{49x}{2} - \frac{483}{4} \right) dx \\ &= -\frac{245}{12} - \frac{105}{4} \\ &= -\frac{140}{3} \end{aligned}$$

(5)

令 $L: y = 0$, 从点 $O(0, 0)$ 到 $A(a, 0)$

$$\text{则 } \int_L (e^x \sin y - my) dx + (e^x \cos y - m) dy = 0$$

那么

$$\begin{aligned}
& \int_{(C)} (e^x \sin y - my) dx + (e^x \cos y - m) dy \\
&= \oint_{C \cup L} (e^x \sin y - my) dx + (e^x \cos y - m) dy - \int_L \\
&= \iint_{C \cup L} (e^x \cos y - e^x \cos y + m) dx dy \\
&= m \iint_{C \cup L} dx dy \\
&= m \cdot \frac{1}{2} \pi \left(\frac{a}{2} \right)^2 \\
&= \frac{m \pi a^2}{8}
\end{aligned}$$

3.

取 $P = -y, Q = x$

$$\text{则 } S = \iint_{D_{xy}} dx dy = \frac{1}{2} \oint_{\Gamma} -y dx + x dy$$

其中 $\Gamma: x^{\frac{2}{3}} + y^{\frac{2}{3}} = a^{\frac{2}{3}}$

进行参数方程变换 $\begin{cases} x = a \cos^3 \theta \\ y = a \sin^3 \theta \end{cases}, 0 \leq \theta \leq 2\pi$

$$\begin{aligned}
S &= \frac{1}{2} \oint_{\Gamma} -y dx + x dy \\
&= \frac{1}{2} \int_0^{2\pi} (-a \sin^3 \theta da \cos^3 \theta + a \cos^3 \theta da \sin^3 \theta) \\
&= \frac{1}{2} \int_0^{2\pi} (3a^2 \sin^4 \theta \cos^2 \theta + 3a^2 \sin^2 \theta \cos^4 \theta) d\theta \\
&= \frac{3}{2} a^2 \int_0^{2\pi} \sin^2 \theta \cos^2 \theta d\theta \\
&= \frac{3\pi}{8} a^2
\end{aligned}$$

8. (2)

由 Green 公式可知

$$\begin{aligned}
& \oint \frac{x dx + y dy}{\sqrt{x^2 + y^2}} \\
&= \iint_{D_{xy}} \left(-\frac{xy}{(x^2 + y^2)^{\frac{3}{2}}} + \frac{xy}{(x^2 + y^2)^{\frac{3}{2}}} \right) dx dy \\
&= 0
\end{aligned}$$

所以与路径无关

从点 (1, 0) 到点 (6, 0), 再到点 (6, 8)

$$\begin{aligned}& \int_{(1,0)}^{(6,8)} \frac{x dx + y dy}{\sqrt{x^2 + y^2}} \\&= \int_1^6 \frac{x}{\sqrt{x^2 + 0}} dx + \int_0^8 \frac{y}{\sqrt{36 + y^2}} dy \\&= 5 + 4 \\&= 9\end{aligned}$$

10.

由 Stokes 公式可知:

$$\begin{aligned}& \oint_{(C)} y dx + dy + x dz \\&= \iint_{\Sigma} (0 - 1) dy \wedge dz + (0 - 1) dz \wedge dx + (0 - 1) dx \wedge dy \\&= -\sqrt{3} \iint_{\Sigma} \frac{\sqrt{3}}{3} dy \wedge dz + \frac{\sqrt{3}}{3} dz \wedge dx + \frac{\sqrt{3}}{3} dx \wedge dy \\&= -\sqrt{3} \pi a^2\end{aligned}$$

16.

(1)

由 Gauss 公式可知

$$\begin{aligned}& \oiint_{(S)} x^2 dy \wedge dz + y^2 dz \wedge dx + z^2 dx \wedge dy \\&= \iiint_{\Omega} (2x + 2y + 2z) dV \\&= 2 \int_0^a dx \int_0^a dy \int_0^a (x + y + z) dz \\&= 3a^4\end{aligned}$$

(3)

$$\text{进行球面坐标代换} \begin{cases} x = \rho \sin \varphi \cos \theta \\ y = \rho \sin \varphi \sin \theta, \text{ 其中 } 0 \leq \varphi \leq \frac{\pi}{2} \\ z = \rho \cos \varphi \end{cases}$$

$$\text{则 } J = \rho^2 \sin \varphi$$

由 Gauss 公式可知

$$\begin{aligned}
& \oint\!\!\!\oint_{(S)} (x^2 - 2xy)dy \wedge dz + (y^2 - 2yz)dz \wedge dx + (1 - 2xz)dx \wedge dy \\
&= \iiint_{\Omega} (2x - 2y + 2y - 2z - 2x)dV \\
&= -2 \iiint_{\Omega} z dV \\
&= -2 \int_0^{2\pi} d\theta \int_0^{\frac{\pi}{2}} d\varphi \int_0^a \rho \cos \varphi \cdot \rho^2 \sin \varphi d\rho \\
&= -\pi a^4 \int_0^{\frac{\pi}{2}} \sin \varphi \cos \varphi d\varphi \\
&= -\frac{\pi}{2} a^4 \\
&\because \iint_{S_{\text{bottom}}} (1 - 2x \cdot 0)dx \wedge dy = \pi a^2 \\
&\quad \iint_{(S)} (x^2 - 2xy)dy \wedge dz + (y^2 - 2yz)dz \wedge dx + (1 - 2xz)dx \wedge dy \\
&= \oint\!\!\!\oint_{(S)} (x^2 - 2xy)dy \wedge dz + (y^2 - 2yz)dz \wedge dx + (1 - 2xz)dx \wedge dy - \iint_{S_{\text{bottom}}} \\
&= \frac{\pi a^2 (2 - a^2)}{2}
\end{aligned}$$

(6)

由 Gauss 公式可知

令 $\Gamma : z = e^a$

$$\begin{aligned}
& \oint\!\!\!\oint_{S \cup \Gamma} 4xz dy \wedge dz - 2yz dz \wedge dx + (1 - z^2)dx \wedge dy \\
&= \iiint_{\Omega} (4z - 2z - 2z)dV \\
&= 0
\end{aligned}$$

$$\begin{aligned}
& \iint_S 4xz dy \wedge dz - 2yz dz \wedge dx + (1 - z^2)dx \wedge dy \\
&= \oint\!\!\!\oint_{S \cup \Gamma} - \iint_{\Gamma} \\
&= - \iint_{\Gamma} 4xz dy \wedge dz - 2yz dz \wedge dx + (1 - z^2)dx \wedge dy \\
&= - \iint_{D_{xy}} (1 - (e^a)^2)dx \wedge dy \\
&= (e^{2a} - 1) \iint_{D_{xy}} dx \wedge dy \\
&= (e^{2a} - 1)\pi a^2
\end{aligned}$$

