Chapter 4

Reasoning in DLs with tableau algorithms

We start with an algorithm for deciding consistency of an ABox without a TBox since this covers most of the inference problems introduced in Chapter 2:

- acyclic TBoxes can be eliminated by expansion
- satisfiability, subsumption, and the instance problem can be reduced to ABox consistency

The tableau-based consistency algorithm tries to generate a finite model for the input ABox A_0 :

- applies expansion rules to extend the ABox one rule per constructor
- checks for obvious contradictions (clashes)
- an ABox that is complete (no rule applies) and clash-free (no obvious contradictions) describes a model

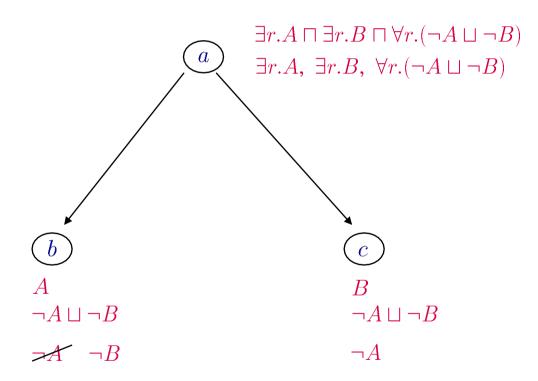
example

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GoodStudent \equiv Smart \sqcap Studious
Subsumption question:
      \existsattended.Smart \sqcap \existsattended.Studious \sqsubseteq_{\mathcal{T}}^? \existsattended.GoodStudent
Reduction to satisfiability: is the following concept unsatisfiable w.r.t. \mathcal{T}?
      \existsattended.Smart \sqcap \existsattended.Studious \sqcap \neg \existsattended.GoodStudent
Reduction to consistency: is the following ABox inconsistent w.r.t. \mathcal{T}?
 \{ a : (\exists attended.Smart \sqcap \exists attended.Studious \sqcap \neg \exists attended.GoodStudent) \}
Expansion: is the following ABox inconsistent?
   \{ a : (\exists attended.Smart \sqcap \exists attended.Studious \sqcap \neg \exists attended.(Smart \sqcap Studious)) \} \}
Negation normal form: is the following ABox inconsistent?
  \{ a : (\exists attended.Smart \sqcap \exists attended.Studious \sqcap \forall attended.(\neg Smart \sqcup \neg Studious)) \} \}
```

example continued

Is the following ABox inconsistent?

 $\{ a : (\exists attended.Smart \sqcap \exists attended.Studious \sqcap \forall attended.(\neg Smart \sqcup \neg Studious)) \} \}$



complete and clash-free ABox yields a model for the input ABox

and thus a counterexample to the subsumption relationship

more formal description

Input: An \mathcal{ALC} -ABox \mathcal{A}_0

Output: "yes" if A_0 is consistent

"no" otherwise

Preprocessing: normalize the ABox

negation only in front of concept names

- transform all concept descriptions in A_0 into negation normal form (NNF) by applying the following equivalence-preserving rules:

$$\neg(C \sqcap D) \leadsto \neg C \sqcup \neg D$$

$$\neg(C \sqcup D) \leadsto \neg C \sqcap \neg D$$

$$\neg \neg C \leadsto C$$

$$\neg(\exists r.C) \leadsto \forall r.\neg C$$

$$\neg(\forall r.C) \leadsto \exists r.\neg C$$

The NNF can be computed in polynomial time, and it does not change the semantics of the concept.

more formal description

Input: An \mathcal{ALC} -ABox \mathcal{A}_0

Output: "yes" if A_0 is consistent

"no" otherwise

Preprocessing: normalize the ABox

negation only in front of concept names

- transform all concept descriptions in A_0 into negation normal form (NNF)
- ensure that the ABox is non-empty by adding $a : \top$ for an arbitrary individual name a if needed
- ensure that every individual name a occurring in the ABox occurs in a concept assertion by adding $a : \top$ if needed

We assume in the following that the input ABox A_0 is normalized in this sense.

more formal description

Application of expansion rules:

- The rules are triggered by the presence of certain assertions in the current ABox,
- and extend the ABox by new assertions.
- Deterministic rule: only one option for how to extend the ABox.
- Nondeterministic rule: several options for how to extend the ABox, where at least one of them must lead to success.

$$\begin{array}{c}
A & b \\
\neg A \sqcup \neg B \\
\Rightarrow A & \neg B
\end{array}$$

more formal description

Application of expansion rules:

- The rules are triggered by the presence of certain assertions in the current ABox,
- and extend the ABox by new assertion.
- Deterministic rule: only one option for how to extend the ABox.
- Nondeterministic rule: several options for how to extend the ABox, where at least one of them must lead to success.
 - Nondeterministic algorithm: always "guesses" the "right" option.
 - Deterministic realization: try options consecutively and backtrack in case of failure.

Expansion rules

one for every constructor (except for negation)

The □-rule

Condition: A contains $a:(C \sqcap D)$, but not both a:C and a:D

Action: $A \longrightarrow A \cup \{a: C, a: D\}$

The ⊔-rule

Condition: A contains $a:(C \sqcup D)$, but neither a:C nor a:D

Action: $A \longrightarrow A \cup \{a : X\}$ for some $X \in \{C, D\}$

The ∃-rule

Condition: \mathcal{A} contains $a:(\exists r.C)$, but there is no b with $\{(a,b):r,b:C\}\subseteq\mathcal{A}$

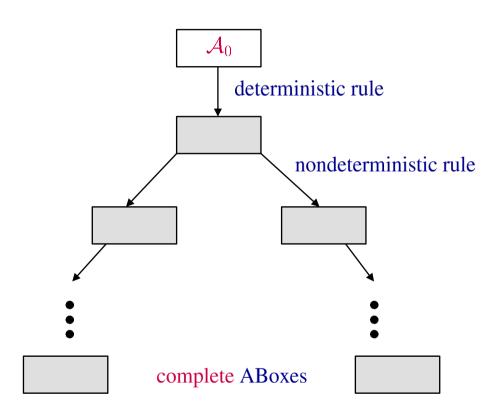
Action: $\mathcal{A} \longrightarrow \mathcal{A} \cup \{(a,d): r, d: C\}$ where d is new in \mathcal{A}

The ∀-rule

Condition: A contains $a:(\forall r.C)$ and (a,b):r, but not b:C

Action: $A \longrightarrow A \cup \{b : C\}$

How does it work?



Return "consistent" iff one of these complete ABoxes is clash-free.

more formally

<u>Definition 4.1</u> (Complete and clash-free ABox)

• An ABox \mathcal{A} contains a clash if

$$\{a:C,a:\neg C\}\subseteq \mathcal{A}$$

for some individual name a, and for some concept C.

• A is complete if it contains a clash, or if none of the expansion rules is applicable.

more formally

The procedure exp:

- takes as input a normalised and clash-free \mathcal{ALC} ABox \mathcal{A} , a rule R and an assertion or pair of assertions α such that R is applicable to α in \mathcal{A} ;
- it returns a set $\exp(A, R, \alpha)$ containing each of the ABoxes that can result from applying R to α in A.

Examples:

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\begin{split} & \exp(\{a: \neg D, a: C \sqcup D\}, \sqcup \text{-rule}, a: C \sqcup D) \\ & \exp(\{b: \neg D, a: \forall r. D, (a,b): r\}, \forall \text{-rule}, (a: \forall r. D, (a,b): r)) \end{split}
```

```
Algorithm consistent()
Input: a normalised \mathcal{ALC} ABox \mathcal{A}
if expand(\mathcal{A}) \neq \emptyset then
return "consistent"
else
return "inconsistent"
```

Definition 4.2

deterministic version of the tableau algorithm

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Algorithm expand()
Input: a normalised \mathcal{ALC} ABox \mathcal{A}
if \mathcal{A} is not complete then
select a rule R that is applicable to \mathcal{A} and an assertion
or pair of assertions \alpha in \mathcal{A} to which R is applicable
if there is \mathcal{A}' \in \exp(\mathcal{A}, R, \alpha) with \exp(\mathcal{A}') \neq \emptyset then
return \exp(\mathcal{A}')
else
return \emptyset
else
if \mathcal{A} contains a clash then
return \emptyset
else
return \mathcal{A}
```

example

$$\mathcal{A}_{ex} = \{ a : A \sqcap \exists s.F, (a,b) : s, \\ a : \forall s.(\neg F \sqcup \neg B), (a,c) : r, \\ b : B, c : C \sqcap \exists s.D \}$$

Expansion rules

one for every constructor (except for negation)

The □-rule

Condition: A contains $a:(C \sqcap D)$, but not both a:C and a:D

Action: $A \longrightarrow A \cup \{a: C, a: D\}$

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Condition: A contains $a:(C \sqcup D)$, but neither a:C nor a:D

Action: $A \longrightarrow A \cup \{a : X\}$ for some $X \in \{C, D\}$

The ∃-rule

Condition: \mathcal{A} contains $a:(\exists r.C)$, but there is no b with $\{(a,b):r,b:C\}\subseteq\mathcal{A}$

Action: $\mathcal{A} \longrightarrow \mathcal{A} \cup \{(a,d): r, d: C\}$ where d is new in \mathcal{A}

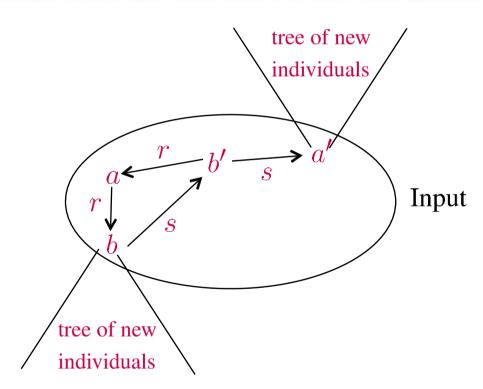
The ∀-rule

Condition: A contains $a:(\forall r.C)$ and (a,b):r, but not b:C

Action: $A \longrightarrow A \cup \{b : C\}$

Trees and forests

In an ABox generated by the algorithm, the individuals generated by the \exists -rule form a tree whose root is an individual from the input ABox.



Trees and forests

In an ABox generated by the algorithm, the individuals generated by the \exists -rule form a tree whose root is an individual from the input ABox.

- Root individual: individual occurring in the input ABox
- Tree individual: individual generated by the application of the \exists -rule
- If the \exists -rule adds a tree individual b and a role assertion (a, b) : r, then b is a (r-) successor of a and a is a predecessor of b
- We use ancestor and and descendant for the transitive closure of predecessor and successor, respectively

Note: root individuals may have successors and hence descendants, but they have no predecessor or ancestors.

Why is it a decision procedure for consistency?

We need to show:

Termination:

consistent(A) terminates for all normalised ALC ABoxes A

Soundness:

if consistent(A) returns "consistent", then A is consistent

Completeness:

if A is consistent, then consistent(A) returns "consistent"

Termination

auxiliary definitions and results

Extend the definition of subconcept to ABoxes and to knowledge bases:

$$\mathsf{sub}(\mathcal{A}) = \bigcup_{a \,:\, C \in \mathcal{A}} \mathsf{sub}(C)$$

and for $\mathcal{K} = (\mathcal{T}, \mathcal{A})$,

$$\mathsf{sub}(\mathcal{K}) = \mathsf{sub}(\mathcal{T}) \cup \mathsf{sub}(\mathcal{A}).$$

Set of concepts occurring in a concept assertion:

$$\mathsf{con}_{\mathcal{A}}(a) = \{ C \mid a : C \in \mathcal{A} \}.$$

Lemma 4.3

For each \mathcal{ALC} ABox \mathcal{A} , we have that $|\operatorname{sub}(\mathcal{A})| \leq \sum_{a: C \in \mathcal{A}} \operatorname{size}(C)$.

linear in the size of A

Termination

Lemma 4.4 (Termination)

For each normalized \mathcal{ALC} ABox \mathcal{A} , consistent(\mathcal{A}) terminates.

Soundness

Lemma 4.5 (Soundness)

If consistent(A) returns "consistent", then A is consistent.

Proof. Let \mathcal{A}' be the set returned by expand(\mathcal{A}).

Since the algorithm returns "consistent", A' is a complete and clash-free ABox.

We use \mathcal{A}' to define an interpretation \mathcal{I} and show that it is a model of \mathcal{A}' .

$$\Delta^{\mathcal{I}} = \{a \mid a : C \in \mathcal{A}'\}$$

$$a^{\mathcal{I}} = a \text{ for each individual name } a \text{ occurring in } \mathcal{A}'$$

$$A^{\mathcal{I}} = \{a \mid A \in \mathsf{con}_{\mathcal{A}'}(a)\} \text{ for each concept name } A \text{ in sub}(\mathcal{A}')$$

$$r^{\mathcal{I}} = \{(a,b) \mid (a,b) : r \in \mathcal{A}'\} \text{ for each role } r \text{ occurring in } \mathcal{A}'$$

Since the expansion rules never delete assertions, we have $A \subseteq A'$, so \mathcal{I} is also a model of A.

Soundness

proof continued

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\Delta^{\mathcal{I}} = \{a \mid a : C \in \mathcal{A}'\}
a^{\mathcal{I}} = a \text{ for each individual name } a \text{ occurring in } \mathcal{A}'
A^{\mathcal{I}} = \{a \mid A \in \mathsf{con}_{\mathcal{A}'}(a)\} \text{ for each concept name } A \text{ in sub}(\mathcal{A}')
r^{\mathcal{I}} = \{(a,b) \mid (a,b) : r \in \mathcal{A}'\} \text{ for each role } r \text{ occurring in } \mathcal{A}'
```

The interpretation \mathcal{I} it is a model of \mathcal{A}' .

Completeness

Lemma 4.6 (Completeness)

If A is consistent, then consistent(A) returns "consistent".

Proof. Let \mathcal{A} be consistent, and consider a model $\mathcal{I} = (\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ of \mathcal{A} .

Since A is consistent, it cannot contain a clash.

Thus, if A is complete, then expand simply returns A and consistent(A) returns "consistent".

If A is not complete, then expand calls itself recursively until A is complete; each call selects a rule and applies it.

It is thus sufficient to show that rule application preserves consistency.

Why is it a decision procedure for consistency?

We have shown:

Termination:

consistent(A) terminates for all normalised ALC ABoxes A

Soundness:

if consistent (A) returns "consistent", then A is consistent

Completeness:

if A is consistent, then consistent(A) returns "consistent"

Theorem 4.7

The tableau algorithm presented in Definition 4.2 is a decision procedure for the consistency of \mathcal{ALC} ABoxes.