CSCI 230 PA 1 Submission

Due Date: 03/01/2022 Late (date and time):_____

Name(s): Nero Li

Exercise 1 -- need to submit source code and I/O

-- check if completely done ✔; otherwise, discuss issues below

Source code below:
exercise_1.cpp:

```
/*  Program: PA_1_exercise_1
    Author: Nero Li
    Class: CSCI 230
    Date: 02/15/2022
    Description:
        Use C++ STL unordered_map or Java HashMap to store the following
        integer keys: 13 21 5 37 15 (reverse the key and use it as a
        string for the value part so first entry would be <13, "31">).
        Perform the following operations to make sure it is working
        properly: search for 10 and 21, remove 20, 37, and then search
        for 37.

        Input data file small1k.txt, containing a list of 1,000 integer
        values, to an array and then insert all the pairs <int, reverse
        key as string> to a new hash map. Collect the time it took to
        insert 1,000 pairs of values to the hash map and output the time
        to the screen.

        Input data file large100k.txt, containing a list of 100,000
        integer values, to an array and then insert all the pairs
        <int, reverse key as string> to another new hash map. Collect the
        time it took to insert 100,000 pairs of values to the hash map
        and output the time to the screen.

    I certify that the code below is my own work.

      Exception(s): N/A

*/

#include <iostream>
#include <fstream>
#include <string>
#include <chrono>
#include <vector>
#include <unordered_map>
```

```
using namespace std;

string changeIntToString(int n)
{
    string s{"\0"};

    while (n > 0)
    {
        s += '0' + n % 10;
        n /= 10;
    }

    return s;
}

void printResult(unordered_map<int, string> m, int n)
{
    if (m.find(n) == m.end())
        cout << "N/A\n";
    else
        cout << "(" << m.find(n)->first << "," << m.find(n)->second <<
")\n";
}

void test()
{
    unordered_map<int, string> m;
    int A[] = {13, 21, 5, 37, 15};

    for (int a : A)
        m[a] = changeIntToString(a);

    printResult(m, 10);
    printResult(m, 21);
    m.erase(20);
    m.erase(37);
    printResult(m, 37);
}

void func(string str)
{
    ifstream fin;
    unordered_map<int, string> m;
    vector<int> v;

    fin.open(str, ios::binary);

    if (!fin)
        return;

    while (!fin.eof())
```

```
    {
        int n;
        fin >> n;
        v.push_back(n);
    }

    auto start = chrono::high_resolution_clock::now();

    for (int a : v)
    {
        m[a] = changeIntToString(a);
    }

    auto end = chrono::high_resolution_clock::now();
    cout << (chrono::duration_cast<chrono::nanoseconds>(end -
start).count() * (double)1e-6) << " ms" << endl;
}

int main()
{
    test();
    func("small1k.txt");
    func("large100k.txt");

    cout << "Author: Nero Li\n";

    return 0;
}
```

Input/output below:

```
N/A
(21,12)
N/A
1.0006 ms
428.911 ms
Author: Nero Li
```

Exercise 2 (with extra credit) -- need to submit source code and I/O

-- check if completely done ✔; otherwise, discuss issues below

Source code below:

HashMap.h:

```
#ifndef HM_H
#define HM_H

#include <list>
#include <vector>
#include <exception>
#include "Entry.h"
```

```
class NonexistentElement
{
public:
    NonexistentElement(const std::string& err)
    : errMsg(err) {}
    std::string getError()
    { return errMsg; }
private:
    std::string errMsg;
};

template <typename K, typename V>
class HashMap {
public:                                     // public types
    typedef Entry<const K,V> Entry;              // a (key,value) pair
    class Iterator;                              // a iterator/position
public:                                     // public functions
    HashMap(int capacity = 100);                 // constructor
    int size() const;                            // number of entries
    bool empty() const;                          // is the map empty?
    Iterator find(const K& k);                   // find entry with key k
    Iterator put(const K& k, const V& v);        // insert/replace (k,v)
    void erase(const K& k);                      // remove entry with key
k
    void erase(const Iterator& p);               // erase entry at p
    Iterator begin();                            // iterator to first
entry
    Iterator end();                              // iterator to end entry
protected:                                  // protected types
    typedef std::list<Entry> Bucket;             // a bucket of entries
    typedef std::vector<Bucket> BktArray;        // a bucket array
    Iterator finder(const K& k);                     // find utility
    Iterator inserter(const Iterator& p, const Entry& e);   // insert
utility
    void eraser(const Iterator& p);                  // remove utility
    typedef typename BktArray::iterator BItor;           // bucket
iterator
    typedef typename Bucket::iterator EItor;             // entry
iterator
    static void nextEntry(Iterator& p)                   // bucket's
next entry
      { ++p.ent; }
    static bool endOfBkt(const Iterator& p)          // end of bucket?
      { return p.ent == p.bkt->end(); }

    int hash(const K& k)
    {
        return k;
    }

private:
```

```
    int n;                                  // number of entries
    BktArray B;                                 // bucket array
public:                                     // public types
    class Iterator {                                    // an iterator (&
position)
    private:
        EItor ent;                          // which entry
        BItor bkt;                          // which bucket
        const BktArray* ba;                         // which bucket array
    public:
        Iterator(const BktArray& a, const BItor& b, const EItor& q =
EItor())
          : ent(q), bkt(b), ba(&a) { }
        Entry& operator*() const;                       // get entry
        bool operator==(const Iterator& p) const;       // are iterators
equal?
        Iterator& operator++();                 // advance to next entry
        friend class HashMap;                   // give HashMap access
    };
};

template <typename K, typename V>           // constructor
HashMap<K,V>::HashMap(int capacity) : n(0), B(capacity) { }

template <typename K, typename V>           // number of entries
int HashMap<K,V>::size() const { return n; }

template <typename K, typename V>           // is the map empty?
bool HashMap<K,V>::empty() const { return size() == 0; }

template <typename K, typename V>           // find utility
typename HashMap<K,V>::Iterator HashMap<K,V>::finder(const K& k) {
  int i = hash(k) % B.size();                   // get hash index i
  BItor bkt = B.begin() + i;                    // the ith bucket
  Iterator p(B, bkt, bkt->begin());             // start of ith bucket
  while (!endOfBkt(p) && (*p).key() != k)       // search for k
    nextEntry(p);
  return p;                                 // return final position
}

template <typename K, typename V>           // find key
typename HashMap<K,V>::Iterator HashMap<K,V>::find(const K& k) {
  Iterator p = finder(k);                       // look for k
  if (endOfBkt(p))                          // didn't find it?
    return end();                           // return end iterator
  else
    return p;                                   // return its position
}

template <typename K, typename V>           // insert utility
typename HashMap<K,V>::Iterator HashMap<K,V>::inserter(const Iterator& p,
const Entry& e) {
```

```
  EItor ins = p.bkt->insert(p.ent, e);           // insert before p
  n++;                                  // one more entry
  return Iterator(B, p.bkt, ins);               // return this position
}

template <typename K, typename V>          // insert/replace (v,k)
typename HashMap<K,V>::Iterator HashMap<K,V>::put(const K& k, const V& v)
{
  Iterator p = finder(k);                       // search for k
  if (endOfBkt(p)) {                            // k not found?
    return inserter(p, Entry(k, v));            // insert at end of
bucket
  }
  else {                                    // found it?
    p.ent->setValue(v);                     // replace value with v
    return p;                                   // return this position
  }
}

template <typename K, typename V>          // remove utility
void HashMap<K,V>::eraser(const Iterator& p) {
    p.bkt->erase(p.ent);                    // remove entry from bucket
    n--;                                    // one fewer entry
}

template <typename K, typename V>          // remove entry at p
void HashMap<K,V>::erase(const Iterator& p)
{ eraser(p); }

template <typename K, typename V>          // remove entry with key k
void HashMap<K,V>::erase(const K& k) {
    Iterator p = finder(k);                     // find k
    if (endOfBkt(p))                            // not found?
      throw NonexistentElement("Erase of nonexistent"); // ...error
    eraser(p);                                  // remove it
}

template <typename K, typename V>          // iterator to end
typename HashMap<K,V>::Iterator HashMap<K,V>::end()
{ return Iterator(B, B.end()); }

template <typename K, typename V>          // iterator to front
typename HashMap<K,V>::Iterator HashMap<K,V>::begin() {
    if (empty()) return end();                  // emtpty - return end
    BItor bkt = B.begin();                      // else search for an
entry
    while (bkt->empty()) ++bkt;                 // find nonempty bucket
    return Iterator(B, bkt, bkt->begin());      // return first of
bucket
}

template <typename K, typename V>          // get entry
```

```
typename HashMap<K,V>::Entry&
HashMap<K,V>::Iterator::operator*() const
{ return *ent; }

template <typename K, typename V>           // advance to next entry
typename HashMap<K,V>::Iterator& HashMap<K,V>::Iterator::operator++() {
    ++ent;                                  // next entry in bucket
    if (endOfBkt(*this)) {                        // at end of bucket?
        ++bkt;                                    // go to next bucket
        while (bkt != ba->end() && bkt->empty())        // find nonempty
bucket
          ++bkt;
        if (bkt == ba->end()) return *this;       // end of bucket array?
        ent = bkt->begin();                       // first nonempty entry
    }
    return *this;                           // return self
}

template <typename K, typename V>           // are iterators equal?
bool HashMap<K,V>::Iterator::operator==(const Iterator& p) const {
    if (ba != p.ba || bkt != p.bkt) return false; // ba or bkt differ?
    else if (bkt == ba->end()) return true;       // both at the end?
    else return (ent == p.ent);                   // else use entry to
decide
}

#endif
```

exercise_2.cpp:

```
/*  Program: PA_1_exercise_2
    Author: Nero Li
    Class: CSCI 230
    Date: 08/24/2021
    Description:
        Put together the C++ HashMap in the book (Chain Hashing; may
        want to eliminate the third template parameter and add a hash
        function) or Java ChainHashing (Java book) with N = 11 and test
        it out with the same data and test cases from above. You might
        want to come up with all relevant test cases to confirm that C++
        HashMap or Java ChainHashing is working correctly.

    I certify that the code below is my own work.

      Exception(s): N/A

*/

#include <iostream>
#include <fstream>
#include <string>
#include <chrono>
```

```
#include <vector>
#include "HashMap.h"

using namespace std;

string changeIntToString(int n)
{
    string s{"\0"};

    while (n > 0)
    {
        s += '0' + n % 10;
        n /= 10;
    }

    return s;
}

void printResult(HashMap<int, string> m, int n)
{
    if (m.find(n) == m.end())
        cout << "N/A\n";
    else
        cout << "(" << (*(m.find(n))).key() << "," <<
(*(m.find(n))).value() << ")\n";

}

void eraseNumber(HashMap<int, string> &m, int n)
{
    try
    {
        m.erase(n);
        cout << "Erased " << n << endl;
    }
    catch(NonexistentElement& e)
    {
        cout << e.getError() << endl;
    }
}

void test()
{
    HashMap<int, string> m(11);
    int A[] = {13, 21, 5, 37, 15};

    for (int a : A)
        m.put(a, changeIntToString(a));

    printResult(m, 10);
    printResult(m, 21);
    eraseNumber(m, 20);
```

```
    eraseNumber(m, 37);
    printResult(m, 37);
}

void func(string str, int size)
{
    ifstream fin;
    HashMap<int, string> m(size);
    vector<int> v;

    fin.open(str, ios::binary);

    if(!fin)
        return;

    while (!fin.eof())
    {
        int n;
        fin >> n;
        v.push_back(n);
    }

    auto start = chrono::high_resolution_clock::now();

    for (int a : v)
    {
        m.put(a, changeIntToString(a));
    }

    auto end = chrono::high_resolution_clock::now();
    cout << (chrono::duration_cast<chrono::nanoseconds>(end -
start).count() * (double)1e-6) << " ms" << endl;
}

int main()
{
    test();
    func("small1k.txt", 2000);
    func("large100k.txt", 200000);

    cout << "Modified by: Nero Li\n";

    return 0;
}
```

Input/output below:

```
N/A
(21,12)
Erase of nonexistent
Erased 37
N/A
```

```
1.0015 ms
199.183 ms
Modified by: Nero Li
```

Answer for Question 1:

The final running time result doesn't seem reasonable since if we got 1 millisecond with 1000 data, we should get 100 milliseconds with 100,000 data since the Big-O notation for hash map insert should be O(n). However, for the result we have seen in the terminal, it has changed much bigger than. Since I didn't find a method to modify or change the hash table inside the unordered map and the bucket that our map has was dynamically added during the process, I think the reason for the result is due to the bigger data brought more collisions and the work for adding buckets cause the problem. It might also be due to the high-resolution clock since when I change the code to directly pass an integer as a value, the final running time is increased.

Answer for Question 2:

Both separate chaining and open addressing are popular ways to solve the hash collision issues.

For separate chaining, we will create a linked list called bucket and an array that stored a bunch of buckets. When we do the insert, we find the index by key mod array capacity, and then add that value to the index targeted linked list. This method will be easier for frequently doing insert and erase work and the situation when we cannot know the quantity of total data, but the running time will count on the key since the situation might happen when all the keys point to the same index.

For open addressing, we won't have a linked list as the bucket. When we see the collision index, we will put the index into a function that makes it become another index until we found the index that doesn't collide. Since we just need an array to store data, we can save more space by using open addressing, but the erasing function will become more complicated and the capacity cannot be dynamically expanded easily.