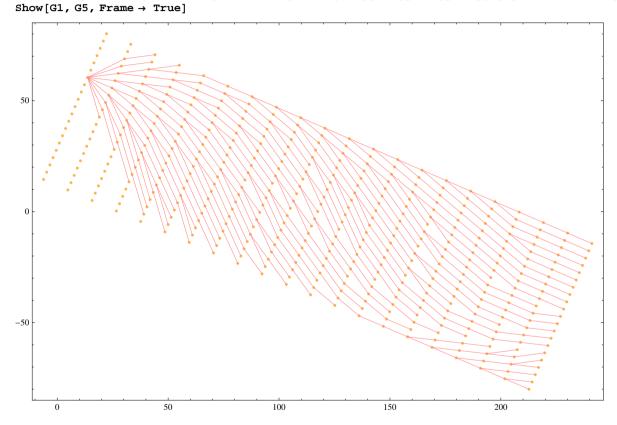
$$\begin{split} & \mathbb{X}[\{\theta_-,\,\phi_-\}] := \left\{ \cos \left[ \frac{\pi}{180} \, \theta \right] \cos \left[ \frac{\pi}{180} \, \phi \right], \, \sin \left[ \frac{\pi}{180} \, \theta \right] \cos \left[ \frac{\pi}{180} \, \phi \right], \, \sin \left[ \frac{\pi}{180} \, \phi \right] \right\}; \\ & \text{Ortho}[\{x1_-,\,y1_-\},\,\{x2_-,\,y2_-\}] := \text{Module}[\{\theta1,\,\phi1,\,\theta2,\,\phi2\},\\ & \{\theta1,\,\phi1,\,\theta2,\,\phi2\} = \frac{\pi}{180} \, \{x1,\,y1,\,x2,\,y2\}; \\ & \mathbb{N}\left[ \frac{360 \, 60}{2 \, \pi} \, \operatorname{ArcCos}[\operatorname{Cos}[\theta1-\theta2] \, \operatorname{Cos}[\phi1] \, \operatorname{Cos}[\phi2] + \operatorname{Sin}[\phi1] \, \operatorname{Sin}[\phi2]] \right] \\ & \mathbb{j}; \\ & \text{Graphe}[\{\theta1_-,\,\phi1_-\},\,\{\theta2_-,\,\phi2_-\}] := \operatorname{Module}\left[ \{\rho,\,e,\,c,\,s,\,M,\,m,\,n\},\\ & \rho = 0.3;\\ & \{m,\,n\} = \{20,\,10\};\\ & e = \sqrt[3]{(\theta2-\theta1)^2 + (\phi2-\phi1)^2};\\ & \{c,\,s\} = \left\{ \frac{\theta2-\theta1}{e},\,\frac{\phi2-\phi1}{e} \right\};\\ & \mathbb{M} := \left( \frac{c}{s} - \frac{s}{s} \right);\\ & \mathbb{M} := \left( \frac{c}{s} - \frac{s}{s} \right);\\ & \operatorname{Table}\left[ \mathbb{N}\left[ \mathbb{M}, \left\{ \frac{e}{m} \, i,\, \rho - \frac{i}{m} \right\} + \{\theta1,\,\phi1\} \right],\,\{i,\,0,\,m\},\,\{j,\,-n,\,n\} \right] \right] \\ & \operatorname{AncreDep} = \{8.05,\,47.3\};\\ & \operatorname{AncreArr} = \{226.88,\,-47.22\};\\ & \operatorname{Loc} = \operatorname{Graphe}[\operatorname{AncreDep},\,\operatorname{AncreArr}];\\ & \{\operatorname{Maxi},\,\operatorname{Maxj},\,\operatorname{Coord}\} = \operatorname{Dimensions}[\operatorname{Loc}] \\ & \{21,\,21,\,2\} \end{split}$$

```
ProgrammationDynamique[Start_] := Module[{ Spread, Graphe, ProgrDyn},
                  Spread = 4;
                 ProgrDyn[r_] := Module[{Etabli, Posi},
                           Do[Etabli = Table[Graphe[[r-1, j, 2]] + Ortho[Loc[[r-1, j]], Loc[[r, k]]], \{j, 1, Maxj\}]; \{\{Posi\}\} = Position[Etabli, Min[Etabli]]; \{\{Posi\}\} = Position[Etabli]]; \{Position[Etabli]]; \{Position[Etabli]] = Position[Etabli]]; \{Position[Etabli]]; \{Position[Etabli]]; 
                                If[Abs[k-Posi] \leq Spread, Graphe[[r,k]] = \{\{\{r-1,Posi\}, \{r,k\}\}, Min[Etabli]\}\}, \{k,1,Maxj\}\}
                      ];
                Graphe = Table [{0, 10^6}, {i, 1, Maxi}, {j, 1, Maxj}];
                 Graphe[[1, Start]] = {1, 0};
                Do[ProgrDyn[r], {r, 2, Maxi}];
                Transpose[Graphe]
           ]; (* Programmation Dynamique *)
 Decision = ProgrammationDynamique[15];
```

```
G1 = Table[Graphics[{RGBColor[1, 0.7, 0.3], Point[Loc[[i, j]]]}], {i, 1, Maxi}, {j, 1, Maxj}];
G2 = Select[Flatten[Decision, 1], (Last[#] < 1000000) && (Last[#] > 0.1) &];
DimG2 = First[Dimensions[G2]];
G3 = Table[First[G2[[i]]], {i, 1, DimG2}];
G4 = Table[{Loc[[First[G3[[i]]][[1]], First[G3[[i]]][[2]]]], Loc[[Last[G3[[i]]][[1]], Last[G3[[i]]][[2]]]], {i, 1, DimG2}];
G5 = Table[Graphics[{RGBColor[1, 0.5, 0.5], Line[{G4[[i, 1]], G4[[i, 2]]}]], {i, 1, DimG2}];
```



```
G6 = Table[{N[X[G4[[i, 1]]]], N[X[G4[[i, 2]]]]}, {i, 1, DimG2}];
G7 = Table[Graphics3D[{RGBColor[1, 0.5, 1], Line[{G6[[i, 1]], G6[[i, 2]]}}], {i, 1, DimG2}];
Earth = Graphics3D[Sphere[{0, 0, 0}]];
Show[Earth, G7]
```

