

Additional Mathematics

Formula that are within the syllabus and which need to be learnt.

The remainder theorem

Given the polynomial $f(x)$, then remainder when $f(x)$ is divided by $(x - a)$ is $f(a)$.

The factor theorem

If the remainder when $f(x)$ is divided by $(x - a)$ is 0, then $(x - a)$ is a factor of $f(x)$ and $x = a$ is a root of the equation $f(x) = 0$

Solution of quadratic equations

By formula and completing the square

For the quadratic equation $ax^2 + bx + c = 0$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Binomial expansion

Know how to derive terms in the expansions of $(1 + x)^n$ and $(a + b)^n$ where n is a positive integer.

$${}^nC_r = \binom{n}{r} = \frac{n!}{r!(n-r)!}$$

The coefficients may be expressed in the form

$${}^nC_r = \binom{n}{r} = {}^nC_{n-r} = \binom{n}{n-r}$$

Be aware that

Coordinate Geometry

Straight line

Know the forms of the straight line, including

$$y = mx + c$$

$$y - y_1 = m(x - x_1)$$

$$\frac{y - y_1}{y_2 - y_1} = \frac{x - x_1}{x_2 - x_1}$$

Condition for parallel lines: $m_1 = m_2$

Condition for perpendicular lines: $m_1 \times m_2 = -1$

Distance between two points $(x_1, y_1), (x_2, y_2) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$

Midpoint of two points $(x_1, y_1), (x_2, y_2) = \left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2} \right)$

The Circle

$(x - a)^2 + (y - b)^2 = r^2$ has centre (a, b) and radius r .

Trigonometry

In a right-angled triangle:

$$\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}, \quad \cos \theta = \frac{\text{adjacent}}{\text{hypotenuse}}, \quad \tan \theta = \frac{\text{opposite}}{\text{adjacent}}$$

Identities:

$$\tan \theta = \frac{\sin \theta}{\cos \theta}$$

$$\sin^2 \theta + \cos^2 \theta = 1$$

Sin rule:

$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

Cos rule:

$$a^2 = b^2 + c^2 - 2bc \cos A$$

$$\cos A = \frac{b^2 + c^2 - a^2}{2bc}$$

Calculus

$$y = ax^n \Rightarrow \frac{dy}{dx} = nax^{n-1}$$

Stationary points occur when $\frac{dy}{dx} = 0$

Area under curve between $x = a$ and $x = b$ is $\int_a^b y \, dx$

Kinematics

Constant acceleration formulae

$$s = ut + \frac{1}{2}at^2$$

$$s = \frac{(u+v)}{2}t$$

$$v = u + at$$

$$v^2 = u^2 + 2as$$